

PROBLEM

The aim of this work is to study, from a computational point of view, the behaviour of the steady ($\theta = 0$) or unsteady ($\theta = 1$) incompressible Stokes ($\chi = 0$) or Navier-Stokes ($\chi = 1$) equations in the framework of the Discrete Duality Finite Volume method (DDFV for short).

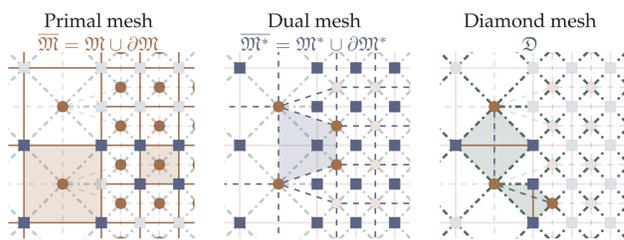
Let $\mathcal{D} \subset \mathbb{R}^2$ be a connected and bounded polygonal domain (here \mathcal{D} is the unit square). For a given final time $T > 0$ the problem we are interested in is the following: Find the velocity $\mathbf{u} : (0, T) \times \mathcal{D} \rightarrow \mathbb{R}^2$ and the pressure $p : (0, T) \times \mathcal{D} \rightarrow \mathbb{R}$ satisfying

$$\begin{cases} \theta \mathbf{u}_t - \nu \Delta \mathbf{u} + \chi (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla p = \mathbf{f}, & (t, \mathbf{x}) \in (0, T) \times \mathcal{D}, \\ \operatorname{div}(\mathbf{u}) = 0, & (t, \mathbf{x}) \in (0, T) \times \mathcal{D}, \\ \int_{\mathcal{D}} p(t, \mathbf{x}) dx = 0, & t \in (0, T), \\ (\text{if } \theta = 1) \quad \mathbf{u}(0, \mathbf{x}) = \mathbf{u}_0(\mathbf{x}), & \mathbf{x} \in \mathcal{D}, \\ \mathbf{u} = \mathbf{g}, & (t, \mathbf{x}) \in (0, T) \times \partial \mathcal{D}, \end{cases}$$

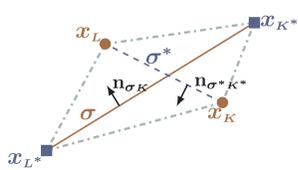
where ν stands for the viscosity, $\mathbf{f} \in (L^2((0, T) \times \mathcal{D}))^2$ and $\mathbf{g} \in (L^2((0, T) \times \partial \mathcal{D}))^2$ and $\mathbf{u}_0 \in L^2(\mathcal{D})$.

DDFV FRAMEWORK

- The DDFV meshes: primal, dual and "diamond"



- Zoom on a diamond cell D :



- Discrete unknowns:

$$\mathbf{u}_{\mathcal{T}} = ((\mathbf{u}_K)_K, (\mathbf{u}_{K^*})_{K^*}) \in (\mathbb{R}^2)^{\mathcal{T}} = (\mathbb{R}^2)^{\mathfrak{M}} \times (\mathbb{R}^2)^{\mathfrak{M}^*},$$

$$p_{\mathcal{D}} = (p_D)_{D \in \mathcal{D}} \in \mathbb{R}^{\mathcal{D}}.$$

- Discrete gradient: $\nabla^{\mathcal{D}}$ constant on each diamond cell,

$$\begin{cases} \nabla^{\mathcal{D}} \mathbf{u}_{\mathcal{T}}(x_L - x_K) = \mathbf{u}_L - \mathbf{u}_K, \\ \nabla^{\mathcal{D}} \mathbf{u}_{\mathcal{T}}(x_{L^*} - x_{K^*}) = \mathbf{u}_{L^*} - \mathbf{u}_{K^*}, \end{cases}$$

$$\nabla^{\mathcal{D}} \mathbf{u}_{\mathcal{T}} = \frac{1}{2m_D} [m_{\sigma}(\mathbf{u}_L - \mathbf{u}_K) \otimes \mathbf{n}_{\sigma, K} + m_{\sigma^*}(\mathbf{u}_{L^*} - \mathbf{u}_{K^*}) \otimes \mathbf{n}_{\sigma^*, K^*}].$$

- Discrete velocity divergence on the diamond mesh:

$$\operatorname{div}^{\mathcal{D}} \mathbf{u}_{\mathcal{T}} = \operatorname{Tr}(\nabla^{\mathcal{D}} \mathbf{u}_{\mathcal{T}}), \quad \forall D \in \mathcal{D}.$$

- Discrete divergence on the primal and dual meshes :

$$\operatorname{div}^{\mathcal{T}}(\xi_{\mathcal{D}}) = \begin{cases} \operatorname{div}^K(\xi_{\mathcal{D}}) = \frac{1}{m_K} \sum_{\sigma \in \partial K} m_{\sigma} \xi_{\sigma} \cdot \mathbf{n}_{\sigma, K}, & \forall K \in \mathfrak{M}, \\ \operatorname{div}^{K^*}(\xi_{\mathcal{D}}) = \frac{1}{m_{K^*}} \sum_{\sigma^* \in \partial K^*} m_{\sigma^*} \xi_{\sigma^*} \cdot \mathbf{n}_{\sigma^*, K^*}, & \forall K^* \in \mathfrak{M}^*. \end{cases}$$

$$\text{Pressure gradient} \rightsquigarrow \nabla^{\mathcal{T}} p_{\mathcal{D}} = \operatorname{div}^{\mathcal{T}}(p_{\mathcal{D}} \operatorname{Id}).$$

APPROXIMATION OF THE TERM $(\mathbf{u} \cdot \nabla) \mathbf{u}$

For any \mathbf{v}, \mathbf{w} s.t. $\operatorname{div} \mathbf{v} = 0$,

$$\int_K (\mathbf{v} \cdot \nabla) \mathbf{w} = \sum_{\sigma \in \partial K} \int_{\sigma} (\mathbf{v} \cdot \mathbf{n}_{\sigma, K}) \mathbf{w}, \quad \forall K \in \mathfrak{M},$$

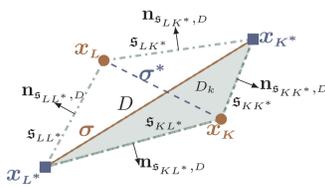
$$\int_{K^*} (\mathbf{v} \cdot \nabla) \mathbf{w} = \sum_{\sigma^* \in \partial K^*} \int_{\sigma^*} (\mathbf{v} \cdot \mathbf{n}_{\sigma^*, K^*}) \mathbf{w}, \quad \forall K^* \in \mathfrak{M}^*.$$

Definition: New operator $b_{\mathcal{T}}(\mathbf{v}_{\mathcal{T}}, \mathbf{w}_{\mathcal{T}})$

$$b_K(\mathbf{v}_{\mathcal{T}}, \mathbf{w}_{\mathcal{T}}) = \frac{1}{m_K} \sum_{\sigma \in \partial K} F_{\sigma, K}(\mathbf{v}_{\mathcal{T}}) \mathbf{w}_{\sigma}, \quad \text{with } \mathbf{w}_{\sigma} = \frac{\mathbf{w}_K + \mathbf{w}_L}{2};$$

$$b_{K^*}(\mathbf{v}_{\mathcal{T}}, \mathbf{w}_{\mathcal{T}}) = \frac{1}{m_{K^*}} \sum_{\sigma^* \in \partial K^*} F_{\sigma^*, K^*}(\mathbf{v}_{\mathcal{T}}) \mathbf{w}_{\sigma^*}, \quad \text{with } \mathbf{w}_{\sigma^*} = \frac{\mathbf{w}_{K^*} + \mathbf{w}_{L^*}}{2};$$

$$\text{where } F_{\sigma, K}(\mathbf{v}_{\mathcal{T}}) \sim \int_{\sigma} \mathbf{v} \cdot \mathbf{n}_{\sigma, K} \quad \text{and} \quad F_{\sigma^*, K^*}(\mathbf{v}_{\mathcal{T}}) \sim \int_{\sigma^*} \mathbf{v} \cdot \mathbf{n}_{\sigma^*, K^*}.$$



$$0 = \int_{D_K} \operatorname{div} \mathbf{v} = \int_{\sigma} \mathbf{v} \cdot \mathbf{n}_{\sigma, K} + \int_{\sigma_{KL^*}} \mathbf{v} \cdot \mathbf{n}_{\sigma_{KL^*}, D} + \int_{\sigma_{KL}} \mathbf{v} \cdot \mathbf{n}_{\sigma_{KL}, D}$$

$$F_{\sigma, K}(\mathbf{v}_{\mathcal{T}}) = - (F_{\sigma_{KL^*}, D}(\mathbf{v}_{\mathcal{T}}) + F_{\sigma_{KL}, D}(\mathbf{v}_{\mathcal{T}}))$$

with

$$F_{\sigma_{KL^*}, D}(\mathbf{v}_{\mathcal{T}}) = m_{\sigma_{KL^*}} \frac{\mathbf{v}_K + \mathbf{v}_{K^*}}{2} \cdot \mathbf{n}_{\sigma_{KL^*}, D}.$$

Properties:

- Conservativity: $0 = \operatorname{div}^{\mathcal{D}} \mathbf{v}_{\mathcal{T}} = \frac{1}{m_D} \sum_{D \in \mathcal{D}} F_{D, D}(\mathbf{v}_{\mathcal{T}})$

$$\Rightarrow F_{\sigma, K}(\mathbf{v}_{\mathcal{T}}) = -F_{\sigma, L}(\mathbf{v}_{\mathcal{T}}) \quad \text{and} \quad F_{\sigma^*, K^*}(\mathbf{v}_{\mathcal{T}}) = -F_{\sigma^*, L^*}(\mathbf{v}_{\mathcal{T}}).$$

- Cancellation property:

$$[b_{\mathcal{T}}(\mathbf{v}_{\mathcal{T}}, \mathbf{w}_{\mathcal{T}}), \mathbf{w}_{\mathcal{T}}]_{\mathcal{T}} = 0,$$

$$\text{where } [\mathbf{u}_{\mathcal{T}}, \mathbf{v}_{\mathcal{T}}]_{\mathcal{T}} = \frac{1}{2} \left(\sum_{K \in \mathfrak{M}} m_K \mathbf{u}_K \cdot \mathbf{v}_K + \sum_{K^* \in \mathfrak{M}^*} m_{K^*} \mathbf{u}_{K^*} \cdot \mathbf{v}_{K^*} \right).$$

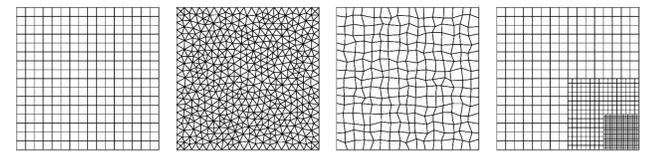
THE DDFV SCHEME

For $\mathbf{u}_{\mathcal{T}}^{n+1} \in (\mathbb{R}^2)^{\mathcal{T}}$ and $p_{\mathcal{D}}^n \in (\mathbb{R}^{\mathcal{D}})^{\mathcal{T}}$ given, we define $(\mathbf{u}_{\mathcal{T}}^{n+1}, p_{\mathcal{D}}^{n+1}) \in (\mathbb{R}^2)^{\mathcal{T}} \times \mathbb{R}^{\mathcal{D}}$ to be a solution to the following problem

$$\begin{cases} \theta \frac{3}{2} \mathbf{u}_{\mathcal{T}}^{n+1} - 2\mathbf{u}_{\mathcal{T}}^n + \frac{1}{2} \mathbf{u}_{\mathcal{T}}^{n-1} - \nu \operatorname{div}^{\mathcal{D}}(\nabla^{\mathcal{D}} \mathbf{u}_{\mathcal{T}}^{n+1}) \\ \quad + \chi \mathbf{b}^{\mathcal{T}}(2\mathbf{u}_{\mathcal{T}}^n - \mathbf{u}_{\mathcal{T}}^{n-1}, \tilde{\mathbf{u}}_{\mathcal{T}}^{n+1}) + \nabla^{\mathcal{T}} p_{\mathcal{D}}^{n+1} = \mathbf{f}_{\mathcal{T}}^{n+1}, \\ \operatorname{div}^{\mathcal{D}}(\mathbf{u}_{\mathcal{T}}^{n+1}) = 0, \quad \sum_{D \in \mathcal{D}} m_D p_D^{n+1} = 0, \\ \mathbf{u}_{\partial \mathfrak{M}}^{n+1} = \mathbf{g}_{\partial \mathfrak{M}}^{n+1}, \quad \mathbf{u}_{\partial \mathfrak{M}^*}^{n+1} = \mathbf{g}_{\partial \mathfrak{M}^*}^{n+1}, \end{cases}$$

$$\text{where } \tilde{\mathbf{u}}_{\mathcal{T}}^{n+1} = \begin{cases} (2\mathbf{u}_{\mathcal{T}}^n - \mathbf{u}_{\mathcal{T}}^{n-1}), & \text{if } \Delta t \|\mathbf{u}_{\mathcal{T}}^n\|_{L^\infty}^2 \leq 2\nu, \\ \mathbf{u}_{\mathcal{T}}^{n+1}, & \text{otherwise.} \end{cases}$$

THE MESHES

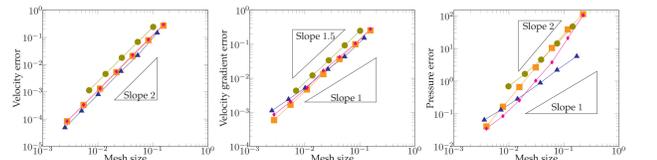


Uniform cartesian ■ Triangular ▲ Quadrangles ◆ Locally refined ●

ERROR ANALYSIS

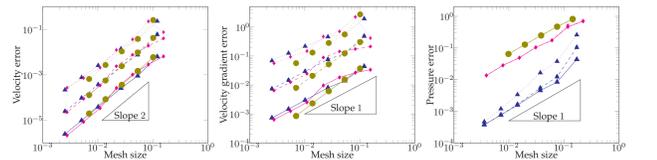
- 2D Steady Stokes tests: Bercovier-Engelman test case

$\theta = 0, \chi = 0, \nu = 1$.



- Steady 2D Navier-Stokes tests

$\theta = 0, \chi = 1, \nu = 10^{-1}, 10^{-2}$ (dash line), 10^{-3} (dot line).

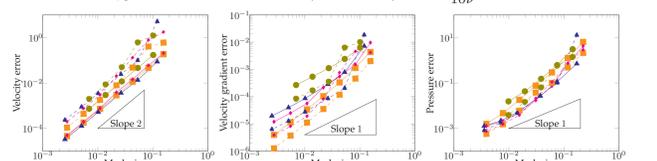


mesh	errgu	erru	errp	ordp
1	8.11406e-16	1.48627e-16	0.678997	nan
2	3.39314e-15	3.47145e-16	0.379343	0.908988
3	1.20171e-14	6.46699e-16	0.199709	0.965408
4	5.95251e-14	1.74916e-15	0.102346	0.985671
5	2.88888e-14	5.78869e-16	0.051792	0.993596
6	5.07121e-14	1.10146e-15	0.0260502	0.996999
7	1.38585e-13	4.21429e-15	0.0130635	0.998543

Rectangular mesh for $\nu = 10^{-3}$

- Unsteady 2D Navier-Stokes tests

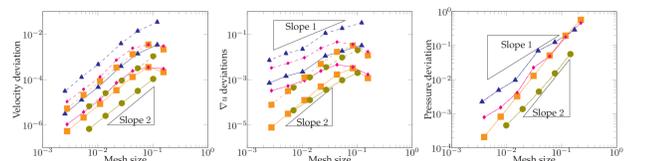
$\theta = 1, \chi = 1, \nu = 10^{-1}, 10^{-2}$ (dash line), $T = \frac{1}{10\nu}, \Delta t = 10^{-3}$.



- Robustness with respect to the invariance property

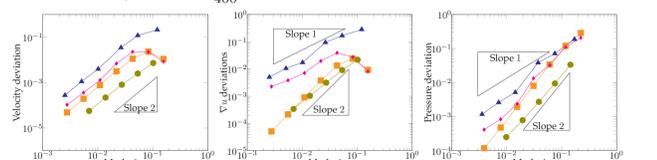
\rightsquigarrow Test on the 2D steady Stokes system:

$\theta = 0, \chi = 0, \nu = 10^{-1}, 10^{-2}$ (dash line).



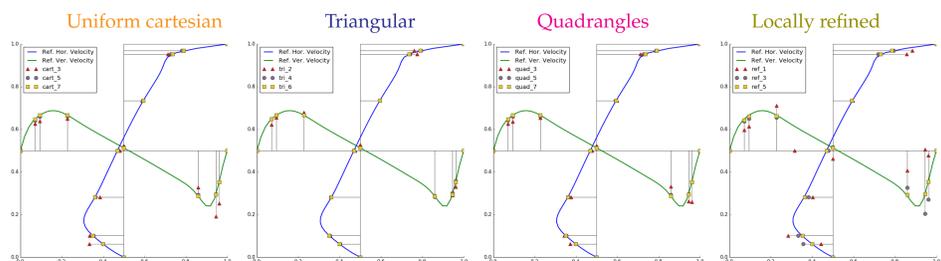
\rightsquigarrow Test on the 2D steady Navier-Stokes system:

$\theta = 0, \chi = 1, \nu = \frac{1}{40}$.

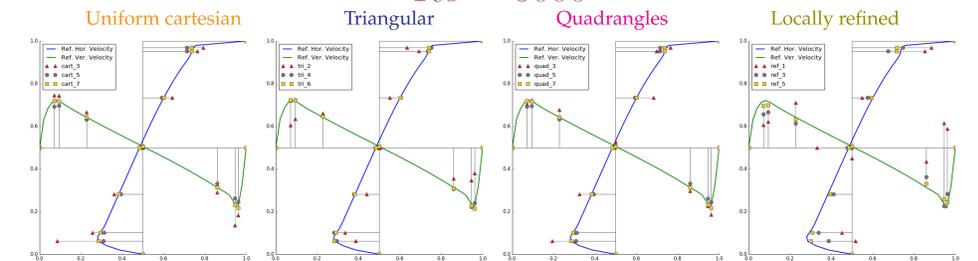


2D LID DRIVEN CAVITY TESTS

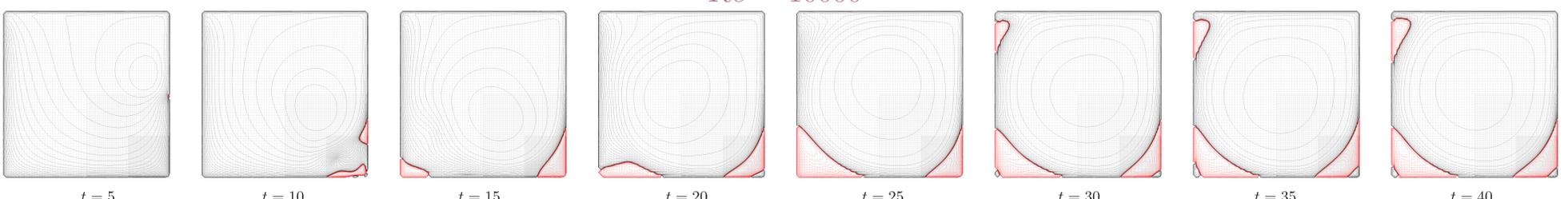
$Re = 1000$



$Re = 5000$



$Re = 10000$



$t = 5 \quad t = 10 \quad t = 15 \quad t = 20 \quad t = 25 \quad t = 30 \quad t = 35 \quad t = 40$

REFERENCES

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