

Nonparametric estimation of the division kernel based on a PDE stationary distribution approximation

Van Hà Hoang

LMO - Université Paris-Sud

en collaboration avec

Thanh Mai Pham Ngoc (Paris-Sud), Vincent Rivoirard (Paris Dauphine) et
Viet Chi Tran (Lille 1).


École de recherche de la Chaire MMB, Aussois (28 mai - 1er juin)




- 1 Stochastic individual-based model of size-structured populations
- 2 Estimation of the division kernel

- 1 Stochastic individual-based model of size-structured populations
- 2 Estimation of the division kernel

Introduction

- We study a stochastic individual-based model of size-structured population in continuous time where individuals are cells undergoing binary divisions. (Illustration video: )

Introduction

- We study a stochastic individual-based model of size-structured population in continuous time where individuals are cells undergoing binary divisions. (Illustration video: )
- Size-structured population: Individuals are characterized by their sizes, i.e. variables that grow deterministically with time. Here we have in mind that each cell contains some toxicities which play the role of the size.

Introduction

- We study a stochastic individual-based model of size-structured population in continuous time where individuals are cells undergoing binary divisions. (Illustration video: ▶)
- Size-structured population: Individuals are characterized by their sizes, i.e. variables that grow deterministically with time. Here we have in mind that each cell contains some toxicities which play the role of the size.
 - [Population with age and size structure modelled by branching process](#): Harris (1963), Jagers (1969), Athreya and Ney (1970), Tran (2008), Bansaye et al. (2011), Cloez (2011), Hoffmann and Olivier (2014), Bansaye and Méléard (2015) and Doumic et al. (2015).
 - [PDE models for size-structured population](#): Diekmann et al. (1998), Michel (2006), Perthame (2007), Doumic et al. (2009) and Doumic and Gabriel (2010).

Motivation

Our model is motivated by the detection of the cellular aging in biology such as the one put into light by Stewart et al. (2005).

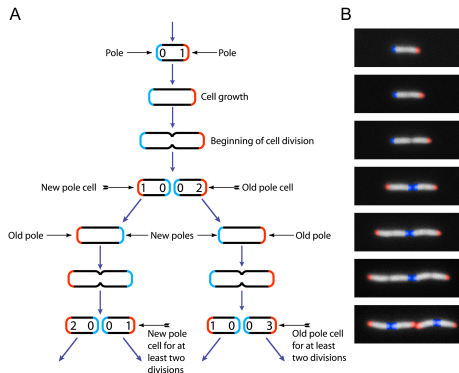


Figure : Cell division of E. Coli *.

*Figure and video are produced by Stewart et al. (2005)

Microscopic model

- Genealogical tree:
 - A cell divides at a rate $R > 0$ and the toxicity grows with rate $\alpha > 0$.
 - Along branches: the toxicity $(X_t, t \geq 0)$ satisfies

$$dX_t = \alpha dt.$$

- When a cell divides, a random fraction Γ of the toxicity goes in the first daughter cell and a fraction $1 - \Gamma$ in the second one. We assume that Γ has a symmetric distribution on $[0, 1]$ with a density h .

Microscopic model

- Genealogical tree:
 - A cell divides at a rate $R > 0$ and the toxicity grows with rate $\alpha > 0$.
 - Along branches: the toxicity $(X_t, t \geq 0)$ satisfies

$$dX_t = \alpha dt.$$

- When a cell divides, a random fraction Γ of the toxicity goes in the first daughter cell and a fraction $1 - \Gamma$ in the second one. We assume that Γ has a symmetric distribution on $[0, 1]$ with a density h .
- We describe the population of cells at time t by a random point measure in $\mathcal{M}_F(\mathbb{R}_+)$ [†]:

$$Z_t(dx) = \sum_{i=1}^{N_t} \delta_{X_t^i}(dx),$$

where $N_t = \langle Z_t, 1 \rangle = \int_{\mathbb{R}_+} Z_t(dx)$ is the number of cells living at time t .

[†] $\mathcal{M}_F(\mathbb{R}_+)$: the space of finite measures on \mathbb{R}_+ embedded with the topology of weak convergence.

Stochastic differential equation

- Z_t is described by a SDE driven by a Poisson point measure.

Stochastic differential equation

- Z_t is described by a SDE driven by a Poisson point measure.
- For all test function $f_t(x) = f(x, t) \in \mathcal{C}_b^{1,1}(\mathbb{R}_+ \times \mathbb{R}_+, \mathbb{R})^\ddagger$, the population of cells is described by:

$$\begin{aligned} \langle Z_t, f_t \rangle = & \langle Z_0, f_0 \rangle + \int_0^t \int_{\mathbb{R}_+} \left(\partial_s f_s(x) + \alpha \partial_x f_s(x) \right) Z_s(dx) ds \\ & + \int_0^t \int_0^1 \left(f_s(\gamma x) + f_s((1-\gamma)x) - f_s(x) \right) R h(\gamma) d\gamma ds + M_t^f, \end{aligned}$$

where M_t^f is a square integrable martingale.

$\ddagger \mathcal{C}_b^{1,1}(\mathbb{R}_+ \times \mathbb{R}_+, \mathbb{R})$: the set of bounded functions of class \mathcal{C}^1 in t and x with bounded derivatives.

Stochastic differential equation

- Z_t is described by a SDE driven by a Poisson point measure.
- For all test function $f_t(x) = f(x, t) \in \mathcal{C}_b^{1,1}(\mathbb{R}_+ \times \mathbb{R}_+, \mathbb{R})^\ddagger$, the population of cells is described by:

$$\begin{aligned} \langle Z_t, f_t \rangle = & \langle Z_0, f_0 \rangle + \int_0^t \int_{\mathbb{R}_+} \left(\partial_s f_s(x) + \alpha \partial_x f_s(x) \right) Z_s(dx) ds \\ & + \int_0^t \int_0^1 \left(f_s(\gamma x) + f_s((1-\gamma)x) - f_s(x) \right) R h(\gamma) d\gamma ds + M_t^f, \end{aligned}$$

where M_t^f is a square integrable martingale.

$\ddagger \mathcal{C}_b^{1,1}(\mathbb{R}_+ \times \mathbb{R}_+, \mathbb{R})$: the set of bounded functions of class \mathcal{C}^1 in t and x with bounded derivatives.

Stochastic differential equation

- Z_t is described by a SDE driven by a Poisson point measure.
- For all test function $f_t(x) = f(x, t) \in \mathcal{C}_b^{1,1}(\mathbb{R}_+ \times \mathbb{R}_+, \mathbb{R})^\ddagger$, the population of cells is described by:

$$\begin{aligned} \langle Z_t, f_t \rangle = & \langle Z_0, f_0 \rangle + \int_0^t \int_{\mathbb{R}_+} \left(\partial_s f_s(x) + \alpha \partial_x f_s(x) \right) Z_s(dx) ds \\ & + \int_0^t \int_0^1 \left(f_s(\gamma x) + f_s((1-\gamma)x) - f_s(x) \right) R h(\gamma) d\gamma ds + M_t^f, \end{aligned}$$

where M_t^f is a square integrable martingale.

$^\ddagger \mathcal{C}_b^{1,1}(\mathbb{R}_+ \times \mathbb{R}_+, \mathbb{R})$: the set of bounded functions of class \mathcal{C}^1 in t and x with bounded derivatives.

- ① Stochastic individual-based model of size-structured populations
- ② Estimation of the division kernel

Estimation of the division kernel: case of incomplete data

Goal: Nonparametric estimation of the density h ruling the divisions.

Estimation of the division kernel: case of incomplete data

Goal: Nonparametric estimation of the density h ruling the divisions.

The interest of estimating h is to detect aging phenomena. (Stewart *et al.* (2005), Lindner *et al.* (2008))

Estimation of the division kernel: case of incomplete data

Goal: Nonparametric estimation of the density h ruling the divisions.

The interest of estimating h is to detect aging phenomena. (Stewart *et al.* (2005), Lindner *et al.* (2008))

Observation scheme

The evolution of cells is observed **at a fixed time T** \rightarrow the whole division tree is not completely observed.

Estimation of the division kernel: case of incomplete data

Goal: Nonparametric estimation of the density h ruling the divisions.

The interest of estimating h is to detect aging phenomena. (Stewart *et al.* (2005), Lindner *et al.* (2008))

Observation scheme

The evolution of cells is observed **at a fixed time T** \rightarrow the whole division tree is not completely observed.

- ▶ When the whole division tree is observed (e.g. observation of the cell population **up to a fixed time T**): Hoang, V. H. (2015). Estimating the division kernel of a size-structured population. preprint arXiv:1509.02872.

Estimation of the division kernel: case of incomplete data

- To estimate h , the idea is to approximate the evolution of the population of cells when the initial population size is large by a [growth-fragmentation equation](#).

Estimation of the division kernel: case of incomplete data

- To estimate h , the idea is to approximate the evolution of the population of cells when the initial population size is large by a [growth-fragmentation equation](#).
- Assume $N_0 = K$, consider the following renormalized stochastic process:

$$Z_t^K(dx) = \frac{1}{K} \sum_{i=1}^{N_t^K} \delta_{X_t^i}(dx),$$

where N_t^K is the number of cells alive at time t .

Estimation of the division kernel: case of incomplete data

- To estimate h , the idea is to approximate the evolution of the population of cells when the initial population size is large by a [growth-fragmentation equation](#).
- Assume $N_0 = K$, consider the following renormalized stochastic process:

$$Z_t^K(dx) = \frac{1}{K} \sum_{i=1}^{N_t^K} \delta_{X_t^i}(dx),$$

where N_t^K is the number of cells alive at time t .

- The parameter K is related to the large population limit which corresponds to $K \rightarrow +\infty$.

Growth-fragmentation equation

- Following the works of Fournier and Méléard (2004) and Tran (2008), we prove that $(Z^K)_{K \in \mathbb{N}^*}$ converges to the (weak) solution of the following PDE:

$$\partial_t n(t, x) + \alpha \partial_x n(t, x) + Rn(t, x) = 2R \int_0^1 n\left(t, \frac{x}{\gamma}\right) \frac{1}{\gamma} h(\gamma) d\gamma, \quad n(0, x) = n_0(x).$$

Growth-fragmentation equation

- Following the works of Fournier and Méléard (2004) and Tran (2008), we prove that $(Z^K)_{K \in \mathbb{N}^*}$ converges to the (weak) solution of the following PDE:

$$\partial_t n(t, x) + \alpha \partial_x n(t, x) + Rn(t, x) = 2R \int_0^1 n\left(t, \frac{x}{\gamma}\right) \frac{1}{\gamma} h(\gamma) d\gamma, \quad n(0, x) = n_0(x).$$

- Setting $y = x/\gamma$, we obtain

$$\partial_t n(t, x) + \alpha \partial_x n(t, x) + Rn(t, x) = 2R \int_0^{+\infty} n(t, y) h\left(\frac{x}{y}\right) \frac{dy}{y}.$$

Growth-fragmentation equation

- Following the works of Fournier and Méléard (2004) and Tran (2008), we prove that $(Z^K)_{K \in \mathbb{N}^*}$ converges to the (weak) solution of the following PDE:

$$\partial_t n(t, x) + \alpha \partial_x n(t, x) + Rn(t, x) = 2R \int_0^1 n\left(t, \frac{x}{\gamma}\right) \frac{1}{\gamma} h(\gamma) d\gamma, \quad n(0, x) = n_0(x).$$

- Setting $y = x/\gamma$, we obtain

$$\partial_t n(t, x) + \alpha \partial_x n(t, x) + Rn(t, x) = 2R \int_0^{+\infty} n(t, y) h\left(\frac{x}{y}\right) \frac{dy}{y}.$$

- By the *general relative entropy* (GRE) (see Perthame and Ryzhik (2005)), the division kernel h satisfies the assumptions for the existence (λ, N) of the following eigenvalue problem

$$\begin{cases} \alpha \partial_x N(x) + (\lambda + R)N(x) = 2R \int_0^{+\infty} N(y) h\left(\frac{x}{y}\right) \frac{dy}{y}, & x \geq 0, \\ N(0) = 0, \quad \int N(x) dx = 1, \quad N(x) \geq 0, \quad \lambda > 0, \end{cases}$$

where λ is the first eigenvalue and N is the first eigenvector.

Asymptotic of the PDE

- By the use of the GRE, we have

$$\int_0^{+\infty} \left| n(t, x) e^{-\lambda t} - \langle n_0, \phi \rangle N(x) \right| \phi(x) dx \xrightarrow{t \rightarrow +\infty} 0,$$

for a non-negative function ϕ called the dual eigenfunction.

Asymptotic of the PDE

- By the use of the GRE, we have

$$\int_0^{+\infty} \left| n(t, x) e^{-\lambda t} - \langle n_0, \phi \rangle N(x) \right| \phi(x) dx \xrightarrow{t \rightarrow +\infty} 0,$$

for a non-negative function ϕ called the dual eigenfunction.

- Since $e^{-\lambda t} n(t, x) \approx N(x)$ as t is large, we assume that we have n i.i.d observations X_1, \dots, X_n where X_i 's have probability distribution $N(x)dx$.
- We estimate h from the data X_1, \dots, X_n and the eigenvalue problem:

$$\begin{cases} \alpha \partial_x N(x) + (\lambda + R)N(x) = 2R \int_0^{+\infty} N(y) h\left(\frac{x}{y}\right) \frac{dy}{y}, & x \geq 0, \\ N(0) = 0, \quad \int N(x) dx = 1, \quad N(x) \geq 0, \quad \lambda > 0, \end{cases}$$

Asymptotic of the PDE

- By the use of the GRE, we have

$$\int_0^{+\infty} \left| n(t, x) e^{-\lambda t} - \langle n_0, \phi \rangle N(x) \right| \phi(x) dx \xrightarrow{t \rightarrow +\infty} 0,$$

for a non-negative function ϕ called the dual eigenfunction.

- Since $e^{-\lambda t} n(t, x) \approx N(x)$ as t is large, we assume that we have n i.i.d observations X_1, \dots, X_n where X_i 's have probability distribution $N(x) dx$.
- We estimate h from the data X_1, \dots, X_n and the eigenvalue problem:

$$\begin{cases} \alpha \partial_x N(x) + (\lambda + R) N(x) = 2R \int_0^{+\infty} N(y) h\left(\frac{x}{y}\right) \frac{dy}{y}, & x \geq 0, \\ N(0) = 0, \quad \int N(x) dx = 1, \quad N(x) \geq 0, \quad \lambda > 0, \end{cases}$$

Estimation of h leads us to an inverse problem with a multiplication convolution defined by the operator

$$(f \vee g)(x) = \int_0^{+\infty} f(y) g\left(\frac{x}{y}\right) \frac{dy}{y}.$$

Asymptotic of the PDE

- By the use of the GRE, we have

$$\int_0^{+\infty} \left| n(t, x) e^{-\lambda t} - \langle n_0, \phi \rangle N(x) \right| \phi(x) dx \xrightarrow{t \rightarrow +\infty} 0,$$

for a non-negative function ϕ called the dual eigenfunction.

- Since $e^{-\lambda t} n(t, x) \approx N(x)$ as t is large, we assume that we have n i.i.d observations X_1, \dots, X_n where X_i 's have probability distribution $N(x)dx$.
- We estimate h from the data X_1, \dots, X_n and the eigenvalue problem:

$$\begin{cases} \alpha \partial_x N(x) + (\lambda + R)N(x) = 2R \int_0^{+\infty} N(y) h\left(\frac{x}{y}\right) \frac{dy}{y}, & x \geq 0, \\ N(0) = 0, \quad \int N(x) dx = 1, \quad N(x) \geq 0, \quad \lambda > 0, \end{cases}$$

Estimation of h leads us to an inverse problem with a multiplication convolution defined by the operator

$$(f \vee g)(x) = \int_0^{+\infty} f(y) g\left(\frac{x}{y}\right) \frac{dy}{y}.$$

Estimation procedure: change of variable

- Setting $x = e^u$ and $y = e^v$, $u, v \in \mathbb{R}$ and introduce the functions

$$g(u) = e^u h(e^u),$$

and

$$M(u) = e^u N(e^u), \quad D(u) = \partial_u (u \mapsto N(e^u)).$$

Estimation procedure: change of variable

- Setting $x = e^u$ and $y = e^v$, $u, v \in \mathbb{R}$ and introduce the functions

$$g(u) = e^u h(e^u),$$

and

$$M(u) = e^u N(e^u), \quad D(u) = \partial_u (u \mapsto N(e^u)).$$

- Then the growth-fragmentation equation (asymptotic form)

$$\alpha \partial_x N(x) + (\lambda + R)N(x) = 2R \int_0^{+\infty} N(y) h\left(\frac{x}{y}\right) \frac{dy}{y}$$

becomes

$$\alpha D(u) + (\lambda + R)M(u) = 2R(M \star g)(u).$$

Estimation procedure: assumptions

Assumptions

(A1) The density h is continuous on $[0, 1]$.

(A2) There exists a positive constant C such that for any $t \in (0, 1)$,

$$\int_0^t h(x) dx \leq \min(1, Ct^4).$$

(A3) For all $\xi \in \mathbb{R}$, $M^*(\xi) \neq 0$.

Estimation procedure

Proposition

Under Assumption (A1)-(A3), the Fourier transform of g is given by

$$g^*(\xi) = \frac{\alpha D^*(\xi)}{2RM^*(\xi)} + \frac{\lambda + R}{2R}, \quad \xi \in \mathbb{R}.$$

Estimation procedure

Proposition

Under Assumption (A1)-(A3), the Fourier transform of g is given by

$$g^*(\xi) = \frac{\alpha D^*(\xi)}{2RM^*(\xi)} + \frac{\lambda + R}{2R}, \quad \xi \in \mathbb{R}.$$

- We first propose an estimator for g^* , then apply Fourier inversion to obtain an estimator for g .

Estimation procedure

Proposition

Under Assumption (A1)-(A3), the Fourier transform of g is given by

$$g^*(\xi) = \frac{\alpha D^*(\xi)}{2RM^*(\xi)} + \frac{\lambda + R}{2R}, \quad \xi \in \mathbb{R}.$$

- We first propose an estimator for g^* , then apply Fourier inversion to obtain an estimator for g .
- A natural estimator of g^* is based on unbiased estimates of $D^*(\xi)$ and $M^*(\xi)$:

Estimation procedure

Proposition

Under Assumption (A1)-(A3), the Fourier transform of g is given by

$$g^*(\xi) = \frac{\alpha D^*(\xi)}{2RM^*(\xi)} + \frac{\lambda + R}{2R}, \quad \xi \in \mathbb{R}.$$

- We first propose an estimator for g^* , then apply Fourier inversion to obtain an estimator for g .
- A natural estimator of g^* is based on unbiased estimates of $D^*(\xi)$ and $M^*(\xi)$:

$$\widehat{M^*(\xi)} = \frac{1}{n} \sum_{j=1}^n e^{i\xi U_j}, \quad \widehat{D^*(\xi)} = (-i\xi) \frac{1}{n} \sum_{j=1}^n e^{(i\xi-1)U_j}.$$

Due to the change of variables, we consider the i.i.d random variables U_1, \dots, U_n where $U_i = \log(X_i)$ having density $M(u) = e^u N(e^u)$.

Estimation procedure

- Let K a kernel function in $\mathbb{L}^2(\mathbb{R})$ such that its Fourier transform K^* exists and is compactly supported. Define $K_\ell(\cdot) := \ell^{-1}K(\cdot/\ell)$ for $\ell > 0$, we set

$$g_\ell = K_\ell \star g.$$

Estimation procedure

- Let K a kernel function in $\mathbb{L}^2(\mathbb{R})$ such that its Fourier transform K^* exists and is compactly supported. Define $K_\ell(\cdot) := \ell^{-1}K(\cdot/\ell)$ for $\ell > 0$, we set

$$g_\ell = K_\ell \star g.$$

Following Neumann (1997), Comte, Samson and Stirnemann (2009) and Comte and Lacour (2011), we propose an estimator \hat{g}_ℓ of g is such that its Fourier transform takes the following form:

$$\widehat{g}_\ell^*(\xi) = K_\ell^*(\xi) \times \left(\frac{\alpha \widehat{D^*}(\xi)}{2R} \frac{\mathbb{1}_{\{|\widehat{M^*}(\xi)| \geq n^{-1/2}\}}}{\widehat{M^*}(\xi)} + \frac{\lambda + R}{2R} \right).$$

Estimation procedure

- Let K a kernel function in $\mathbb{L}^2(\mathbb{R})$ such that its Fourier transform K^* exists and is compactly supported. Define $K_\ell(\cdot) := \ell^{-1}K(\cdot/\ell)$ for $\ell > 0$, we set

$$g_\ell = K_\ell \star g.$$

Following Neumann (1997), Comte, Samson and Stirnemann (2009) and Comte and Lacour (2011), we propose an estimator \hat{g}_ℓ of g is such that its Fourier transform takes the following form:

$$\widehat{g}_\ell^*(\xi) = K_\ell^*(\xi) \times \left(\frac{\alpha \widehat{D^*}(\xi)}{2R} \frac{\mathbb{1}_{\{|\widehat{M^*}(\xi)| \geq n^{-1/2}\}}}{\widehat{M^*}(\xi)} + \frac{\lambda + R}{2R} \right).$$

Estimators of g and h

Taking the inverse Fourier transform of \hat{g}_ℓ^* to obtain the estimator \hat{g}_ℓ of g , then the estimator of the division kernel h as follows:

$$\hat{g}_\ell(u) = \frac{1}{2\pi} \int_{\mathbb{R}} \hat{g}_\ell^*(\xi) e^{-i u \xi} d\xi, \quad \hat{h}_\ell(\gamma) = \gamma^{-1} \hat{g}_\ell(\log(\gamma)), \quad \gamma \in (0, 1).$$

Estimators of g and h

Taking the inverse Fourier transform of \hat{g}_ℓ^* to obtain the estimator \hat{g}_ℓ of g , then the estimator of the division kernel h as follows:

$$\hat{g}_\ell(u) = \frac{1}{2\pi} \int_{\mathbb{R}} \hat{g}_\ell^*(\xi) e^{-i u \xi} d\xi, \quad \hat{h}_\ell(\gamma) = \gamma^{-1} \hat{g}_\ell(\log(\gamma)), \quad \gamma \in (0, 1).$$

Theorem

Suppose Assumptions (A1), (A2) and (A3) are satisfied and the kernel bandwidth ℓ which depends on n satisfies $\lim_{n \rightarrow +\infty} \ell = 0$. Provided that

$$\lim_{n \rightarrow +\infty} \frac{1}{n} \left(\left\| \frac{K_\ell^*(\xi)\xi}{M^*(\xi)} \right\|_2^2 + \left\| \frac{K_\ell^*(\xi)}{M^*(\xi)} \right\|_2^2 \right) = 0,$$

we have

$$\lim_{n \rightarrow +\infty} \mathbb{E} \left[\|\hat{g}_\ell - g\|_2^2 \right] = 0, \quad \lim_{n \rightarrow +\infty} \mathbb{E} \left[\|\hat{h}_\ell - h\|_2^2 \right] = 0$$

Numerical simulations

Bandwidth selection rule:

We apply resampling techniques inspired from the principle of cross-validation: we divide the observations X_1, \dots, X_n into two sub-samples $\mathbf{X}^E := (X_i)_{i \in E}$ and $\mathbf{X}^{E^C} := (X_i)_{i \in E^C}$ where $E \subset \{1, \dots, n\}$ such that $|E| = n/2$ and $E^C = \{1, \dots, n\} \setminus E$.

Let $(E_j, E_j^C)_{1 \leq j \leq V}$, $V \leq V_{\max} = C_n^{n/2}$ be the sequence of subsets selected from $\{1, \dots, n\}$. Let \mathcal{L} be a family of bandwidths possible, define

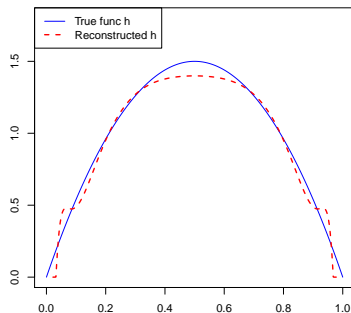
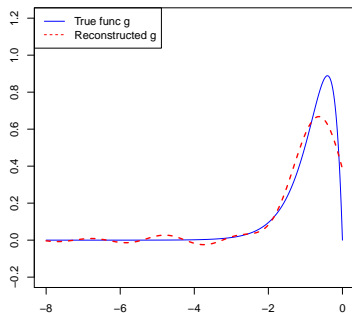
$$\hat{J}(\ell, \ell') := \frac{1}{V} \sum_{i=1}^V \left[\|\hat{g}_\ell^{*(E_j)}\|_2^2 - 2 \langle \hat{g}_\ell^{*(E_j)}, \hat{g}_{\ell'}^{*(E_j^C)} \rangle \right]$$

The the final estimator of g is obtained by putting $\hat{g} := \hat{g}_{\hat{\ell}}$ where

$$\hat{\ell}_{CV} := \operatorname{argmin}_{\ell \in \mathcal{L}} \left\{ \min_{\ell' \in \mathcal{L}} \hat{J}(\ell, \ell') \right\}.$$

Numerical simulations

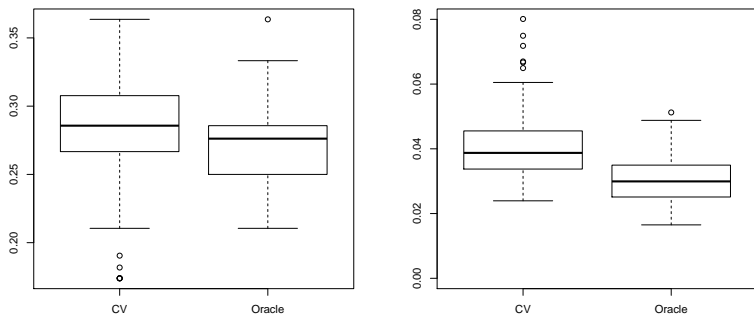
Reconstruction of the density of Beta(2, 2): $h(x) = Cx(1-x)\mathbb{1}_{[0,1]}(x)$.



Left: Reconstruction of $g(x) = e^x h(e^x)$. Right: Reconstruction of $\tilde{h} = \frac{1}{2}(h(x) + h(1-x))$.

Numerical simulations

Reconstruction of the density of Beta(2, 2): $h(x) = Cx(1 - x)\mathbb{1}_{[0,1]}(x)$.



Left: CV bandwidths vs Oracle bandwidths. Right: \mathbb{L}^2 -risk of \hat{g} over $M = 100$ samples of size $n = 30000$.

References

- PhD manuscript: V. H. Hoang. *Adaptive estimation for inverse problems with applications to cell divisions*.
- V. H. Hoang. *Estimating the Division Kernel of a Size-Structured Population*. 2015. Submitted.
- V. H. Hoang, T. M. Pham Ngoc, V. Rivoirard and V. C. Tran. *Nonparametric estimation of the fragmentation kernel based on a stationary distribution approximation*. Work in progress

Merci de votre attention