Quelques modèles mathématiques de contrôle de populations de moustiques et de nuisibles agricoles

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Chaire Modélisation Mathématique et Biodiversité

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- Pathogens: plasmodium (malaria), virus (dengue, chikungunya, Zika), bacteria (Yersinia pestis for the Black Death)
- Other species can be involved, for instance as reservoir (like birds for the west Nile fever or rodents for the Black Death)

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- Mosquitoes of the genus Aedes: dengue fever, Zika, Chikungunya, yellow fever.



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- pprox 3.9 billion people at risk in 129 countries.
- No efficicient vaccine, nor antiviral drugs.
- Expansion of vector's habitat (global trade, global warming, reduction of predator populations ...)



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Dengue vector population : Tiger mosquito in France



• Natural and mechanical control: reduction of egg-laying sites, helping natural predators, removal of larvae - implementation complexity, time-consuming, economic cost...

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- Biological control and Genetically Modified Organisms past experience should lead us to be cautious and avoid when possible.
- Natural to consider both continuous and impulsive controls.

Species-specific methods we will focus on :

- Wolbachia method
 - Reduction of the vector capacity.

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- Cytoplasmic incompatibility.

- Wolbachia vertical transmission.
- Population replacement.

Wild mosquito	Mosquitoes with Wolbachia released	Wolbachia establishes in the	≎\♂	Infecté	Sain
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Source: http://www.eliminatedengue.com/our-research/Wolbachia

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- Sterile insect technique
 - Population reduction/suppression.

- Recurrent intervention

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Mosquito life cycle



Aquatic phase :

egg (few days to several months) larvae (3 days to several weeks) pupa (1-3 days) Adult phase (~ 1 month)

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Mosquito life cycle

The life cycle for mosquitos may be schematized as follows



- $\beta_E(M)$ birth rate (per female);
- τ_E , τ_L , τ_P transition rates; ν sex ratio;
- δ_E , δ_L , δ_P , δ_M , δ_F death rates.

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Mosquito life cycle



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Targeting sexual reproduction: SIT



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Targeting sexual reproduction: SIT

Sterile Insect Technique (SIT) : releases of sterilized male mosquitoes. The release function is denoted u.

Introduce a new compartment for sterilized males, denoted M_s .

Probability for a female to meet a non-sterilized male is proportional to the proportion of them, with a preferential parameter, denoted γ .

$$\begin{aligned} \frac{d}{dt}E &= \beta_E F \frac{M}{M + \gamma M_s} (1 - \frac{E}{K}) - (\tau_E + \delta_E)E \\ \frac{d}{dt}L &= \tau_E E - (cL + \tau_L + \delta_L)L \\ \frac{d}{dt}P &= \tau_L L - (\tau_P + \delta_P)P \\ \frac{d}{dt}F &= \nu \tau_P P - \delta_F F \\ \frac{d}{dt}M &= (1 - \nu)\tau_P P - \delta_M M \qquad \qquad \frac{d}{dt}M_s = u - \delta_s M_s. \end{aligned}$$

Spatial problem - invasive wave propagation



Figure: Expansion of Aedes albopictus in mainland France

Global warming and trade help Aedes mosquitoes to settle in many temperate regions including Europe. They are not only an invasive species but also vectors for many diseases including dengue, Zika and chikungunya.

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A strategy to avoid the epidemic risk is to repulse the invading wave of mosquitoes (including expanding the mosquito-free area) using a *Rolling Carpet* strategy where we act in a band of width L that moves with speed c against the invading front. Mathematical study helps optimizing this strategy (e.g. the amount of mosquitoes released, M)

Used since the 60's and combined with other control methods, the SIT has been successful in controlling various insect pests, including

- fruit flies (Mediterranean fruit fly, Mexican fruit fly, oriental fruit fly, melon fly);
- tsetse fly;
- screwworm;
- moths (codling moth, pink bollworm, false codling moth, cactus moth, and the Australian painted apple moth)
- mosquitoes.

With good "return on investment" according to FAO and IAEA.

Bistable Dynamics and Traveling Wave solutions







$$\partial_t u - \Delta u = g(u) \longrightarrow -c_0 \phi' - \phi'' = g(\phi).$$

 ϕ connects the two stable steady states :

$$\phi(-\infty) = 1$$
 and $\phi(+\infty) = 0$.

The sense of propagation depends on $\operatorname{sign}(c_0) = \operatorname{sign}\left(\int_0^1 g(v) dv\right)$

Assumption : $sign(c_0) > 0$: naturally, the mosquitoes invade the territory



The rolling carpet strategy

The idea is to *act* on a finite interval (0, L) and move this *action* like a rolling carpet in the opposite sense to that of the natural invasion traveling wave.

Aim of the work : generate a traveling wave with a negative speed solution of

$$\left\{egin{aligned} &\partial_t u - \Delta u = g(u) \mathbf{1}_{\{x < ct, x > L + ct\}} + Act(u) \mathbf{1}_{\{ct < x < L + ct\}}, \ &u(-\infty) = 1, \ &u(+\infty) = 0 \end{aligned}
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Fig. 1. The system at time t = 0

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Fig. 1. The system at $t = t_1$

We perform numerical simulations of

$$\partial_t f - \partial_{xx} f = g(f, m_S),$$

for c = -0.1, L = 20 and two sizes of releases M.



Fig. 4. M = 3.3

Fig. 5. M = 3.6

Wolbachia

In this part, we will mainly focus on the spatial spread of *Wolbachia* bacteria into a wild host population.

- Endo-symbiotic bacteria found in most arthropod species.
- Maternally transmitted from mother to offspring.
- Causes cytoplasmic incompatibility (CI) and blocks transmission of some viruses (Dengue, Chikungunya, Zika) by *Aedes* mosquitoes.
- Several side-effects on its host (reduces fecundity, reduces lifespan, ...).



urce: http://www.eliminatedengue.com/our-research/Wolbachia

Then, it is a population replacement problem : replacing the wild population by a population carrying the bacteria *Wolbachia*.

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Only adult mosquitoes can fly and their dispersal is estimated to less than 1km during their life time. Then we consider the simplified model for adult mosquitoes:

- *n_i*: density of Wolbachia-infected mosquitoes;
- *n_u*: density of uninfected mosquitoes;
- $d_u, d_i = \delta d_u$: death rate, $\delta > 1$;
- $F_u, F_i = (1 s_f)F_u$: fecondity;
- s_h: cytoplasmic incompatibility parameter (fraction of uninfected females' eggs fertilized by infected males and which will not hatch);
- K: carrying capacity ;
- D: dispersal coefficient (assumed to be constant and normalized D = 1).

Model

$$\begin{cases} \partial_t n_i - \Delta n_i &= (1 - s_f) F_u n_i \left(1 - \frac{n_i + n_u}{K} \right) - \delta d_u n_i, \\ \partial_t n_u - \Delta n_u &= F_u n_u \left(1 - s_h \frac{n_i}{n_i + n_u} \right) \left(1 - \frac{n_i + n_u}{K} \right) - d_u n_u, \end{cases}$$

Model

$$\begin{cases} \partial_t n_i - \Delta n_i = f_1(n_i, n_u) := (1 - s_f) F_u n_i \left(1 - \frac{n_i + n_u}{K} \right) - \delta d_u n_i, \\ \partial_t n_u - \Delta n_u = f_2(n_i, n_u) := F_u n_u (1 - s_h \frac{n_i}{n_i + n_u}) \left(1 - \frac{n_i + n_u}{K} \right) - d_u n_u, \end{cases}$$

- Nonnegativity: if at t = 0 the densities are nonnegative, then they are nonnegative for any positive time.
- Bound: solutions are clearly bounded uniformly by K (if so at t = 0).
- This model is competitive : $\partial_2 f_1 < 0$ and $\partial_1 f_2 < 0$ on the quadrant $(n_i, n_u) > 0$. Then an increase of n_i (resp. n_u) will affect negatively the population n_u (resp. n_i).

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We first consider the steady states (equilibria) for the associated ODE model, with no diffusion.

Steady states

As soon as $s_f + \delta - 1 < \delta s_h$, there are four distinct nonnegative equilibria:

- Wolbachia invasion $(n^*_{iW}, n^*_{uW}) := (K \frac{d_u}{F_u} \frac{\delta}{1 s_f}, 0)$ is stable;
- Wolbachia extinction $(n_{iE}^*, n_{uE}^*) := (0, K \frac{d_u}{F_u})$ is stable;
- co-existence steady state

 $(n_{iC}^*, n_{uC}^*) := \left(\left(K - \frac{d_u}{F_u} \frac{\delta}{1 - s_f} \right) \frac{\delta - (1 - s_f)}{\delta s_h}, \left(K - \frac{d_u}{F_u} \frac{\delta}{1 - s_f} \right) \frac{\delta (s_h - 1) + (1 - s_f)}{\delta s_h} \right) \text{ is unstable;}$

• extinction (0,0) is unstable.

Dynamical system

The question is to know whether we can pass from the *Wolbachia-free equilibrium* to the *Wolbachia infected equilibrium* thanks to releases of mosquitoes and how to optimize the releases.



Since the study of the spatial system is complicated, we first consider the dynamical system neglecting the spatial dependency.

Mathematical model

Let u denote the release function. The dynamical system reads

$$\begin{cases} \frac{d}{dt}n_{i} &= (1-s_{f})F_{u}n_{i}\left(1-\frac{n_{i}+n_{u}}{K}\right)-\delta d_{u}n_{i}+u,\\ \frac{d}{dt}n_{u} &= F_{u}n_{u}(1-s_{h}\frac{n_{i}}{n_{i}+n_{u}})\left(1-\frac{n_{i}+n_{u}}{K}\right)-d_{u}n_{u},\\ n_{i}(t=0)=0\,,\quad n_{u}(t=0)=n_{uE}^{*}:=K-\frac{d_{u}}{F_{u}}.\end{cases}$$

where $s_h \in (0, 1]$ is CI rate, K is environmental capacity, b_i and d_i are birth and death rates.

Principle : Two competing populations (for breeding sites), with reproductive interference by (unidirectional) CI are exposed to releases $u \ge 0$.

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We want to optimize the release strategy to be as close as possible to the *Wolbachia*-infected equilibrium at the final time of treatment, denoted T:

Cost

$$J(u) = \frac{1}{2}n_u(T)^2 + \frac{1}{2}(n_{iW}^* - n_i(T))_+^2.$$

Constraints

• The local release of mosquitoes is bounded : $0 \le u \le \overline{U}$.

• The total number of mosquitoes used is bounded (production limitation) : $0 \le \int_0^T u(t) dt \le C$.

$$\begin{array}{l} \text{Optimization problem} \\ \min_{u \in \mathcal{U}_{\overline{U},C,T}} J(u), \quad \text{with} \ \ \mathcal{U}_{\overline{U},C,T} = \left\{ 0 \leq u \leq \overline{U} \ \text{a.e.}, \int_0^T u(t) dt \leq C \right\}. \end{array}$$

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Reduction of the optimal problem

As above, we may try to simplify the system by using the large fertility asymptotics, $\varepsilon \ll 1,$

$$\begin{cases} \frac{d}{dt}n_i &= (1-s_f)\frac{F_u^0}{\varepsilon}n_i\left(1-\frac{n_i+n_u}{K}\right) - \delta d_u n_i + u,\\ \frac{d}{dt}n_u &= \frac{F_u^0}{\varepsilon}n_u(1-s_h\frac{n_i}{n_i+n_u})\left(1-\frac{n_i+n_u}{K}\right) - d_u n_u. \end{cases}$$

As above, when $\varepsilon \to 0$, we deduce

$$n_i + n_u = K(1 - \varepsilon n) + o(\varepsilon).$$

Then we may compute the system of equation satisfied by n and the proportion $p := \frac{n_i}{n_i + n_u}$.

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As above, by passing to the limit $\varepsilon \to 0$, the system reduces to Reduced problem

$$\frac{dp}{dt} = f(p) + ug(p),$$

where

$$f(p) = \frac{\delta d_u}{F_u^0} \frac{p(1-p)(p-\theta)}{(1-p)^2 + (1-s_f)p}, \qquad \theta = \frac{s_f + \delta - 1}{\delta},$$
$$g(p) = \frac{1}{K} \frac{(1-p)^2}{(1-p)^2 + (1-s_f)p}.$$

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For the cost functional, we have

$$J(u) = \frac{1}{2}((n_i + n_u)(T)(1 - p(T)))^2 + \frac{1}{2}(K(1 - \varepsilon \frac{d_u \delta}{F_u^0(1 - s_f)}) - ((n_i + n_u)(T)p(T)))^2.$$

Thus, with the fact that $n_i + n_u \rightarrow K$ in $C^0([0,T])$, we deduce that

$$J(u) \xrightarrow[\varepsilon \to 0]{} (K(1-p(T)))^2.$$

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Reduced optimal control problem

Reduced optimization problem

$$\min_{u \in \mathcal{U}_{\overline{U},C,T}} (1 - p(T))^2,$$

with $\mathcal{U}_{\overline{U},C,T} = \{0 \leq u \leq \overline{U} \text{ a.e.}, \int_0^T u(t)dt \leq C\}$, where p solves the differential equation $\frac{d}{dt}p = f(p) + ug(p), \quad f \text{ bistable}, g > 0 \text{ on } (0,1), \ g(1) = 0.$

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As a consequence we may prove the following result:

Theorem (LA, Privat, Strugarek, Vauchelet, SIAM Math. Anal. 2018)

Assume T > C/M and above assumptions on the coefficients.

Then, any solution u^* to the reduced optimal problem satisfies $\int_0^T u^*(t)dt = C$ and is bang-bang (*i.e.* equal a.e. to 0 or \overline{U}).

Moreover, if (u^{ε}) is a family of minimizers for the optimal problem for the full system. Then, as $\varepsilon \to 0$, it converges in $L^1(0,T)$ to a solution of the reduced problem. Moreover, we have

$$\lim_{\varepsilon \to 0} \min_{u \in \mathcal{U}_{\overline{U},C,T}} J^{\varepsilon}(u) = \min_{u \in \mathcal{U}_{\overline{U},C,T}} (1 - p(T))^2.$$

This problem is simpler to study than the full system. Indeed, we observe that when u=0,

- if $0 , then <math>\frac{d}{dt}p < 0$;
- if $\theta , then <math>\frac{d}{dt}p > 0$.

In other words, the basin of attraction of 1 is $(\theta, 1)$, outside this domain, the solution move away from 1. Hence to be optimal one expects the solution to go to this basin of attraction as fast as possible. If the solution cannot reach this basin of attraction, it is better to act at the end of the protocol.

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Reduction of the optimal control problem

Actually, we can get a precise description of the optimum:

Theorem (LA, Privat, Strugarek, Vauchelet, SIAM Math. Anal. 2018)

- If $\overline{U} \leq \max_{p \in [0,\theta]} \frac{f(p)}{g(p)}$ then the unique solution is given by $u^* = \overline{U} \mathbf{1}_{[T-C/\overline{U},T]}$.
- Otherwise, defining $C^*(\overline{U}) = \int_0^\theta \frac{\overline{U}dp}{f(p) + \overline{U}g(p)}$, one has
 - if $C < C^*(\overline{U})$ then the solution is unique and equal to $u^* = \overline{U} \mathbf{1}_{[T-C/\overline{U},T]}$;
 - if $C > C^*(\overline{U})$ then the solution is unique and equal to $u^* = \overline{U} \mathbf{1}_{[0,C/\overline{U}]}$;
 - if $C = C^*(\overline{U})$ then there is a continuum of solutions given by $u_{\lambda}^* = \overline{U} \mathbf{1}_{[\lambda,\lambda+C/\overline{U}]}$ for $\lambda \in [0, T C/\overline{U}]$.



Reduction of the optimal control problem

Interpretation.

- the best release protocol in the framework of the frequency model consists in a single release phase
- If the amount of mosquitoes available is enough to cross the threshold θ , then it is preferable to make the maximum effort at the beginning of the time protocol. Indeed, p is increasing whenever $p > \theta$, thus it is interesting to cross this threshold as soon as possible
- if the amount of mosquitoes is not enough for p to reach the threshold θ , then $p < \theta$ and p is decreasing when u = 0. In this case, the optimum is achieved acting at the end of the time frame to avoid p to decrease



$$S'_{H} = b_{H}H - \frac{\beta_{M}}{H}I_{M}S_{H} - b_{H}S_{H}$$
$$E'_{H} = \frac{\beta_{M}}{H}I_{M}S_{H} - \gamma_{H}E_{H} - b_{H}E_{H}$$
$$I'_{H} = \gamma_{H}E_{H} - \sigma_{H}I_{H} - b_{H}I_{H}$$

$$M' = b_M M \left(1 - \frac{M}{K} \right) - d_M M$$

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Impulsive control: $u(t) = \sum_{i=1}^{n} c_i \delta(t - t_i)$ Constraint: $\sum_{i=1}^{n} c_i = C$

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Impulsive control: $u(t) = \sum_{i=1}^{n} c_i \delta(t - t_i)$ Constraint: $\sum_{i=1}^{n} c_i = C$ Goal: Minimise J(u) during an outbreak

$$J(u) := \int_0^T I_H(t) dt$$

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Use of Wolbachia

We add the mosquitoes with Wolbachia:

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Results: instant releases for Wolbachia

• $C < G(\theta)$: release before the outbreak reaches its peak.

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$$C > G(\theta)$$
: Release at $t = 0$.



Use of Sterile mosquitoes

$$\begin{split} S'_{H} &= b_{H}H - \frac{\beta_{M}}{H}I_{M}S_{H} - b_{H}S_{H} \\ E'_{H} &= \frac{\beta_{M}}{H}I_{M}S_{H} - \gamma_{H}E_{H} - b_{H}E_{H} \\ I'_{H} &= \gamma_{H}E_{H} - \sigma_{H}I_{H} - b_{H}I_{H} \\ S'_{M} &= b_{M}M\left(1 - \frac{M}{K}\right) - \frac{\beta_{M}}{H}S_{M}I_{H} - d_{M}S_{M} \\ E'_{M} &= \frac{\beta_{M}}{H}S_{M}I_{H} - \gamma_{M}E_{M} - d_{M}E_{M} \\ I'_{M} &= \gamma_{M}E_{M} - d_{M}I_{M} \end{split}$$

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Use of Sterile mosquitoes

$$S'_{H} = b_{H}H - \frac{\beta_{M}}{H}I_{M}S_{H} - b_{H}S_{H}$$

$$E'_{H} = \frac{\beta_{M}}{H}I_{M}S_{H} - \gamma_{H}E_{H} - b_{H}E_{H}$$

$$I'_{H} = \gamma_{H}E_{H} - \sigma_{H}I_{H} - b_{H}I_{H}$$

$$S'_{M} = b_{M}M\left(1-\frac{M}{K}\right)\frac{M}{M+s_{c}M_{S}}-\frac{\beta_{M}}{H}S_{M}I_{H}-d_{M}S_{M}$$
$$E'_{M} = \frac{\beta_{M}}{H}S_{M}I_{H}-\gamma_{M}E_{M}-d_{M}E_{M}$$
$$I'_{M} = \gamma_{M}E_{M}-d_{M}I_{M}$$

$$M'_S = u - d_S M_S$$

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Results: 10 instant releases



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Results: 20 instant releases



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Conclusions for the epidemic model

• Wolbachia:

- Optimal strategy: One single release
- If we have enough mosquitoes to trigger a population replacement: release as soon as possible.
- If we don't have enough: release before the peak of the outbreak.

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Conclusions for the epidemic model

• Wolbachia:

- Optimal strategy: One single release
- If we have enough mosquitoes to trigger a population replacement: release as soon as possible.
- If we don't have enough: release before the peak of the outbreak.
- Sterile mosquito:
 - Strategy and results depend highly on the number of releases considered (when low).
 - After ~ 20 releases almost no improvement.
 - With few mosquitoes: spaced releases around the peak.
 - With a lot of mosquitoes: spaced releases from the beginning.

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The real map since 50 B.C. !)



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The real map since 50 B.C. !)





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