Selection-mutation models: diversification of populations

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Introduction

Darwinian evolution of a structured population density

- We study the Darwinian evolution
 - of a population structured by phenotypical traits, and(or) space,
 - under selection and mutation



Selection-mutation models: diversification of populations

- Introduction

- We study the long time behavior of a population density, assuming that mutations are rare or small.
- We expect to observe: speciation, extinction and branching





Figure: Morbidostat : a selective pressure is applied continuously to the bacterial population

Rosenthal et Elowitz, Nature Genetics 2012

Introduction

- Game theory: Maynard Smith, Hofbauer, Sigmund,...
- Classical adaptive dynamics: Dieckmann, Gertiz, J. A. J. Metz, Kisdi, Meszéna, Diekmann, Jacobs, Gyllenberg, H. Metz,...
- Stochastic methods: Méléard, Champagnat, Ferrière, Fournier, Bolker, Pacala, Lambert,...
- Integro-differential models: Perthame, Desvillettes, Jabin, Mischler, Carrillo, Calsina, Cuadrado, Barles, Raoul, Génieys,...

Introduction



1 Introduction

- 2 Models structured by phenotypical traits
- 3 The Hamilton-Jacobi approach

4 Spatial models

-Models structured by phenotypical traits

A model with a single nutrient

$$\begin{cases} \frac{\partial}{\partial t}n_{\varepsilon} = \frac{n_{\varepsilon}}{\varepsilon}R\left(x, I_{\varepsilon}\right) + \frac{1}{\varepsilon}\int\frac{1}{\varepsilon^{d}}K\left(\frac{y-x}{\varepsilon}\right)b(y, I_{\varepsilon})n_{\varepsilon}(y, t)\,dy,\\ n_{\varepsilon}(\cdot, t=0) = n_{\varepsilon}^{0}(\cdot), \end{cases}$$

$$I_{\varepsilon}(t) = \int_{\mathbb{R}^d} \eta(x) \, n_{\varepsilon}(x,t) \, dx.$$

- $x \in \mathbb{R}^d$: phenotypical trait
- $n_{\varepsilon}(x, t)$: density of trait x
- K(z): mutation probability kernel
- $\eta(x)$: consumption rate

- $I_{\varepsilon}(t)$: total consumption
- $R(x, I_{\varepsilon})$: growth rate
- b(x, l_ε): mutation birth rate
- ε : a small parameter

-Models structured by phenotypical traits

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└─ Models structured by phenotypical traits

Another way to model the mutations

$$\begin{cases} \frac{\partial}{\partial t} n_{\varepsilon} - \varepsilon \Delta n_{\varepsilon} = \frac{n_{\varepsilon}}{\varepsilon} R(x, I_{\varepsilon}), \\ n_{\varepsilon}(\cdot, t = 0) = n_{\varepsilon}^{0}(\cdot), \end{cases}$$

$$I_{\varepsilon}(t) = \int_{\mathbb{R}^d} \eta(x) \, n_{\varepsilon}(x,t) \, dx.$$

Selection-mutation models: diversification of populations

—Models structured by phenotypical traits

A simple typical growth rate:

$$R(x,I)=1-\frac{x^2}{2}-I$$



Dynamics of the dominant trait

└─ Models structured by phenotypical traits

No blow up, no extinction

$$\min_{x\in\mathbb{R}^d}\left[R(x, I_m)+b(x, I_m)\right]=0,$$

$$\max_{x\in\mathbb{R}^d} \left[R(x, I_M) + b(x, I_M) \right] = 0,$$

$$I_m \leq I_{\varepsilon}(0) \leq I_M.$$

—Models structured by phenotypical traits

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$$\implies$$
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—Models structured by phenotypical traits

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$$\implies I_m \leq I_{\varepsilon}(t) \leq I_M.$$

Limited resource \implies competition between traits.

└─ Models structured by phenotypical traits

Further assumptions

•
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└─ Models structured by phenotypical traits

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$$-C \leq \frac{\partial (R+b)}{\partial I}(x,I) \leq -C^{-1} < 0$$

—Models structured by phenotypical traits

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• and some regularity assumptions...

└─ Models structured by phenotypical traits

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- and some regularity assumptions...
- \implies after extraction of a subsequence, $(I_{\varepsilon})_{\varepsilon}$ converges a.e. to I(t).

Some notations

•
$$n(x, t)$$
: weak limit of $n_{\varepsilon}(x, t)$ as ε vanishes

• We expect *n* to concentrate as Dirac masses

• Hopf-Cole transformation:
$$n_{\varepsilon}(x,t) = \exp\left(rac{u_{\varepsilon}(x,t)}{arepsilon}
ight)$$

Theorem (Barles, M., Perthame - 2009)

Under the previous assumptions, after extraction of a subsequence, u_{ε} converges locally uniformly to a continuous function u, a viscosity solution to

$$\begin{cases} \frac{\partial}{\partial t}u = R(x, I(t)) + b(x, I(t)) \int K(z) \exp(\nabla u \cdot z) \, dz, \\ \max_{x \in \mathbb{R}^d} u(x, t) = 0, \\ u(0, x) = u^0(x), \end{cases}$$

$$I_{\varepsilon}(t) \underset{\varepsilon \to 0}{\longrightarrow} I(t)$$
 a.e., $\int \eta(x) n(x,t) dx = I(t)$ a.e..

The case of Laplacian

After extraction of a subsequence, u_{ε} converges locally uniformly to a continuous function u, a viscosity solution to

$$\begin{cases} \frac{\partial}{\partial t}u = |\nabla u|^2 + R(x, I(t))\\ \max_{x \in \mathbb{R}^d} u(x, t) = 0,\\ u(0, x) = u^0(x). \end{cases}$$

Barles, M., Perthame - 2009

Consequences...

$$\bar{x}(t) \in \operatorname{supp} n(t, \cdot)$$

$$\implies u(\bar{x}(t), t) = 0$$

$$\implies$$
 $R(\bar{x}(t), I(t)) = 0$

Convergence to a monomorphic population

In 1-d : Under monotonicity conditions on R, weakly in the sense of measures and after extraction of a subsequence, we have

$$n_{\varepsilon}(x,t) \xrightarrow[\varepsilon \to 0]{} n(x,t) = \overline{\rho}(t) \, \delta(x - \overline{x}(t)),$$

with $R(\bar{x}(t), I(t)) = 0$ and $\bar{\rho}(t) = \frac{I(t)}{\eta(\bar{x}(t))}$.

G. Barles, B. Perthame - 2008

Selection-mutation models: diversification of populations

└─ The Hamilton-Jacobi approach



Multi-d: Concavity assumptions

$$-2\underline{K}_1 \leq D^2 R(x,l) \leq -2\overline{K}_1 < 0$$

as symmetric matrices for $0 \leq I \leq I_M$,

$$-2\underline{L}_1 \leq D^2 u_{\varepsilon}^0 \leq -2\overline{L}_1,$$

$$4\,\overline{L}_1^2 \leq \overline{K}_1 \leq \underline{K}_1 \leq 4\,\underline{L}_1^2.$$

Convergence to a monomorphic population [competitive exclusion]

Theorem (Lorz, M., Perthame - 2011)

Under the previous assumptions, after extraction of a subsequence, the sequence $(n_{\varepsilon})_{\varepsilon}$ converges weakly in the sense of measures to a single Dirac mass

$$n_{arepsilon} \xrightarrow[arepsilon o 0]{}
ho(t) \,\delta\left(x - ar{x}(t)
ight),$$
 $ho(t) = rac{I(t)}{\eta(ar{x}(t))}, \qquad R(ar{x}(t), I(t)) = 0 \quad a.e.,$

and I(t) is non-decreasing.



$$R(x, y, l) = 3 - 1.5l - 5.6(y^2 + 1.1x^2).$$

Canonical equation

"Canonical equation" refers to a differential equation for the position of the dominant trait(s) in trait space.

$$D^3R(\cdot, I) \in L^{\infty}(\mathbb{R}^d), \qquad D^3u_{\varepsilon}^0 \in L^{\infty}(\mathbb{R}^d).$$

Theorem (Lorz, M., Perthame - 2011)

Under the previous assumptions, $\bar{x}(\cdot)$ belongs to $W^{1,\infty}(\mathbb{R}^+;\mathbb{R}^d)$ and satisfies

$$\dot{ar{x}}(t) = \left(-D^2uig(ar{x}(t),tig)
ight)^{-1}\cdot
abla_{ imes} Rig(ar{x}(t),I(t)ig), \quad ar{x}(0) = ar{x}^0.$$

Furthermore, we have $I(t) \in W^{1,\infty}(\mathbb{R}^+)$.



$$R(x, y, I) = 2 - I - 0.6(x^2 + y^2).$$

Dynamics of the density n with asymmetric initial data (left) and symmetric initial data (right).

A model with several resources

$$\begin{cases} \frac{\partial}{\partial t} n_{\varepsilon} - \varepsilon \Delta n_{\varepsilon} = \frac{n_{\varepsilon}}{\varepsilon} R\left(x, l_{\varepsilon}^{1}, \cdots, l_{\varepsilon}^{K}\right), \\ n_{\varepsilon}(\cdot, t = 0) = n_{\varepsilon}^{0}(\cdot), \end{cases}$$

$$J^{j}_{\varepsilon}(t) = \int_{\mathbb{R}^{d}} \eta^{j}(x) n_{\varepsilon}(x, t) dx.$$

In this model we can observe polymorphism and branching. Champagnat, Jabin, 2011

$$\partial_t n - \alpha \Delta_x n - \beta \Delta_v n = \frac{n}{\gamma} R(x, v, I(t, x)),$$

$$I(t,x) = \int \psi(v) n(t,x,v) dv.$$

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A model with two favorable habitable zones:

$$\begin{cases} \partial_t n_{\varepsilon}^1 - \varepsilon \Delta n_{\varepsilon}^1 &= \frac{1}{\varepsilon} n_{\varepsilon}^1 R^1(x, l_{\varepsilon}^1) + \frac{1}{\varepsilon} \nu^2 n_{\varepsilon}^2 - \frac{1}{\varepsilon} \nu^1 n_{\varepsilon}^1, \\ \partial_t n_{\varepsilon}^2 - \varepsilon \Delta n_{\varepsilon}^2 &= \frac{1}{\varepsilon} n_{\varepsilon}^2 R^2(x, l_{\varepsilon}^2) + \frac{1}{\varepsilon} \nu^1 n_{\varepsilon}^1 - \frac{1}{\varepsilon} \nu^2 n_{\varepsilon}^2, \\ l_{\varepsilon}^1 &= \int \psi(x) n_{\varepsilon}^1 dx, \quad l_{\varepsilon}^2 = \int \psi(x) n_{\varepsilon}^2 dx. \end{cases}$$

• One can write a similar model for K favorable habitable zones.

The stationary problem

$$\begin{cases} -\varepsilon^2 \Delta n_{\varepsilon}^1 &= n_{\varepsilon}^1 R^1(x, l_{\varepsilon}^1) + \nu^2 n_{\varepsilon}^2 - \nu^1 n_{\varepsilon}^1 & \text{in } B_L(0), \\ -\varepsilon^2 \Delta n_{\varepsilon}^2 &= n_{\varepsilon}^2 R^2(x, l_{\varepsilon}^2) + \nu^1 n_{\varepsilon}^1 - \nu^2 n_{\varepsilon}^2 & \text{in } B_L(0), \\ \nabla n_{\varepsilon}^i \cdot \vec{n} &= 0 & \text{in } \partial B_L(0), \end{cases}$$
$$I_{\varepsilon}^1 = \int \psi(x) n_{\varepsilon}^1 dx, \quad I_{\varepsilon}^1 = \int \psi(x) n_{\varepsilon}^2 dx.$$

$$n_{\varepsilon}^{i} = \exp\left(rac{u_{\varepsilon}^{i}}{arepsilon}
ight), \quad i = 1, 2.$$

Theorem (M. - 2012)

Under some assumptions, after extraction of a subsequence, both sequences $(u_{\varepsilon}^1)_{\varepsilon}$ and $(u_{\varepsilon}^2)_{\varepsilon}$ converge to a continuous function u that is a viscosity solution to the following equation

$$\begin{cases} -|\nabla u|^2 = H(x, l^1, l^2), & \text{ in } B_L(0), \\ \max_{x \in B_L(0)} u(x) = 0, \end{cases}$$

with $H(x, I^1, I^2)$ the largest eigenvalue of the matrix

$$\mathcal{A} = \left(\begin{array}{cc} R^{1}(x, l^{1}) - \nu^{1} & \nu^{2} \\ \nu^{1} & R^{2}(x, l^{2}) - \nu^{2} \end{array} \right).$$

Consequences...

$$n_{\varepsilon}^{1} \xrightarrow[\varepsilon \to 0]{} n^{1}, \quad n_{\varepsilon}^{2} \xrightarrow[\varepsilon \to 0]{} n^{2}.$$

supp $n^{i} \subset \Omega \cap \Gamma$, for $i = 1, 2$
 $\Omega = \{x \in B_{L}(0) \mid u(x) = 0\}$

$$\Gamma = \{x \in B_L(0) \mid H(x, l^1, \cdots, l^K) = \max_{x \in B_L(0)} H(x, l^1, \cdots, l^K) = 0\}$$

In particular, the population has an Evolutionary Stable Distribution (ESD)

If the support of n^i , for i = 1, 2, is a set of distinct points: supp $n^i \subset \{x_1, x_2, \cdots, x_l\}$, we then have

$$n^{i} = \sum_{j=1}^{l} \rho_{j}^{i} \delta(x - x_{j}), \quad \text{for } i = 1, 2,$$

with $\begin{pmatrix} \rho_j^1\\ \rho_j^2 \end{pmatrix}$ is the eigenvector corresponding to the largest eigenvalue of the matrix \mathcal{A} at the point x_j , which is 0, and

 $\sum_{j} \rho_{j}^{i} \psi(x_{j}) = I^{i}.$



- The gray layers represent the value of $n_{\varepsilon}^{1}(\text{left})$ and $n_{\varepsilon}^{2}(\text{right})$.
- Migration rates : $\nu^1 = \nu^2 = 1$.
- $R^1(x, I) = 5 (x+1)^2 + x I$, $R^2(x, I) = 5 (x-1)^2 x I$
- The optimal trait in the first patch is x = -0.5 and in the second patch is x = 0.5.
- Initially: the trait in the first patch is x = -0.3 and in the second patch is x = 0.3.
- At the final time: the trait in both patches is x = 0.



The gray layers represent the value of n¹_ε(left) and n²_ε(right).
 Migration rates : ν¹ = ν² = 0.5.

$$R^{1}(x, l) = 3.2 - (x+1)^{2} + .1 \times x - l, R^{2}(x, l) = 3.2 - (x-1)^{2} - .1 \times x - l$$

- The optimal trait in the first patch is x = -0.95 and in the second patch is x = 0.95.
- Initially: the trait in the first patch is x = -0.2 and in the second patch is x = 0.2.
- At the final time: two traits x = -0.6 and x = 0.6 are present in both patches.

Thank you for your attention !