

# Modeling the evolution of ecological interaction networks

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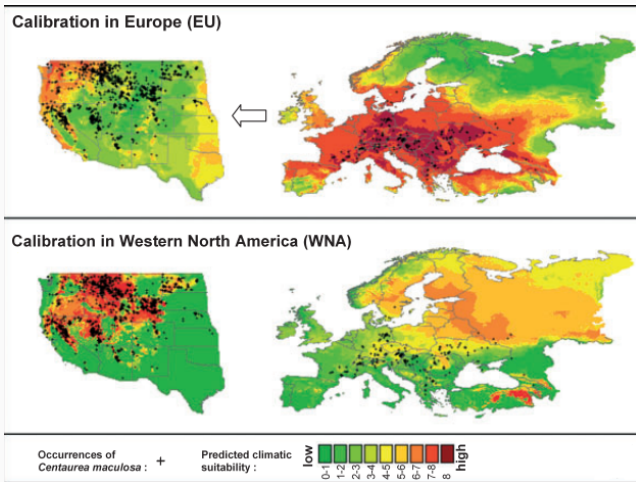
- We want to understand changes in **species distributions** in a global change context.
- Popular used models are **niche models** which
  - Project present species niche into the future.
  - Do not consider species interactions.
- We want a model capable of capturing these two phenomena.

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Spotted knapweed (*Centaurea maculosa*) is an invasive species in North America introduced from Europe in the 1890s.

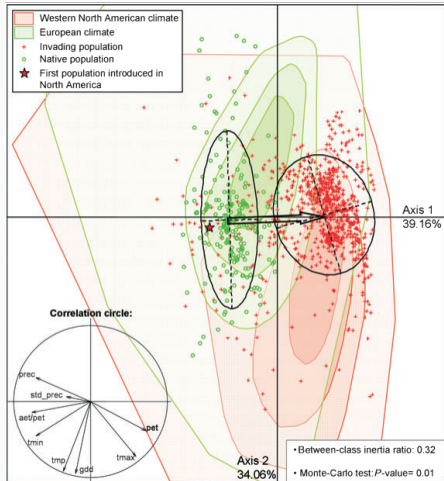


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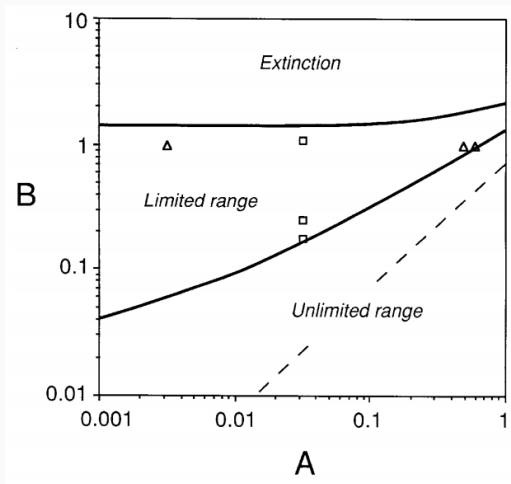
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Where  $i = 1$  denotes the **prey population**:

$$r_1(x, t) = r_1^{\max} - \frac{1}{2V_1^s} (\bar{z}_1(x, t) - \theta(x))^2 + l_1(x, t)$$

and

$$l_1(x, t) = -\alpha_1 r_1^{\max} \frac{N_1(x, t)}{K} - \beta_{12} N_2(x, t).$$

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And  $i = 2$  denotes the predator population:

$$r_2(x, t) = l_2(x, t) - \frac{1}{2V_2^s} (\bar{Z}_2(x, t) - \theta(x))^2 - d$$

and

$$l_2(x, t) = \beta_{21} N_1(x, t) - \alpha_2 N_2(x, t),$$

we choose  $\beta_{21} = c\beta_{12}$ .

## Predation model proposition

- The traits  $\bar{Z}_i = \bar{Z}_i(x, t)$  follow the same dynamics given by population genetics:

$$\frac{\partial \bar{Z}_i}{\partial t} = \frac{\sigma_i^2}{2} \frac{\partial^2 \bar{Z}_i}{\partial x^2} + \sigma_i^2 \frac{\partial \log N_i}{\partial x} \frac{\partial \bar{Z}_i}{\partial x} - \frac{G_i}{V_i^s} (\bar{Z}_i - \theta(x))$$

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It is a generalization of Lotka and Volterra's predation equations.

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It is a generalization of Kirkpatrick and Barton's equations.

## Solution example

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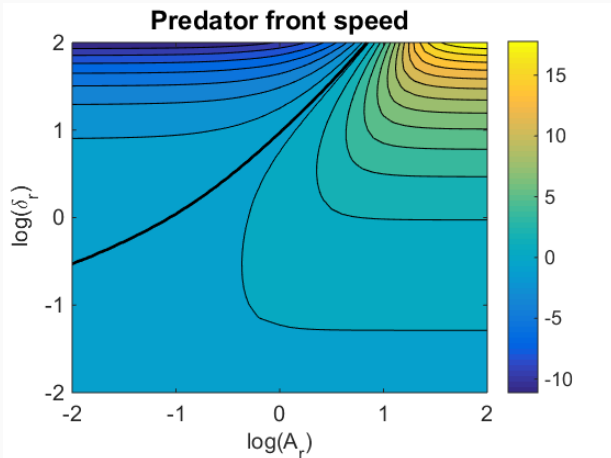
We want to study propagation speeds these states.





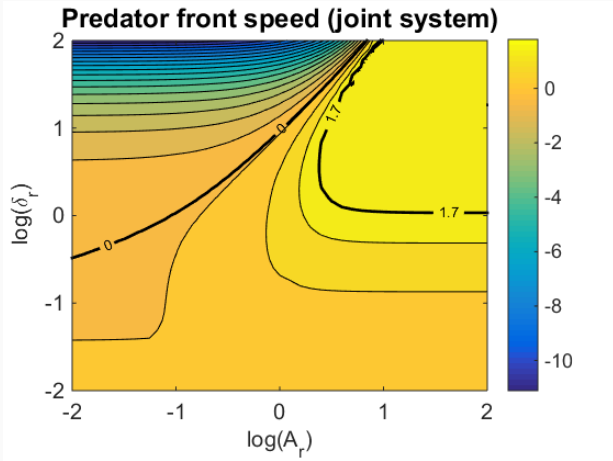


# Results



Predator invasion front. The zero speed line is thickened.

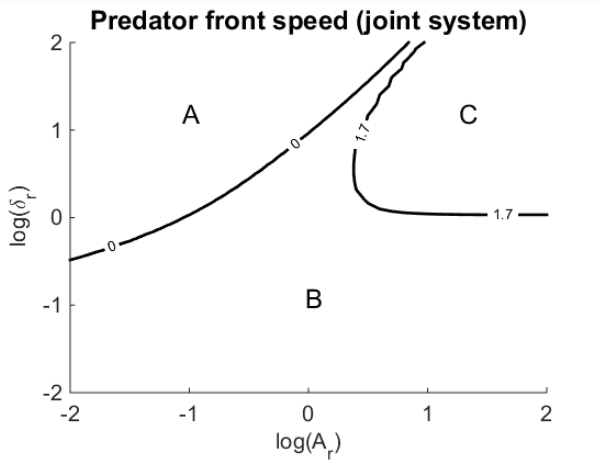
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Transition between extinction and coexistence.

$$(A_r = A_2/A_1, \delta_r = \sigma_2^2/\sigma_1^2)$$





Three phases can be identified.

$$(A_r = A_2/A_1, \delta_r = \sigma_2^2/\sigma_1^2)$$

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- Advancing predator fronts can be of one out of two types, implying different geographical distributions.
- The studied parameters do not seem to allow predators to control the prey's geographical range.

## Further questions

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- Does this model allow predators to control prey range?
- How does global change affect the dynamics of the model?

$$\theta(x, t) = b_1x + b_2t.$$

- How can we generalize the model to other kinds of interaction?

Questions?

Thank you!