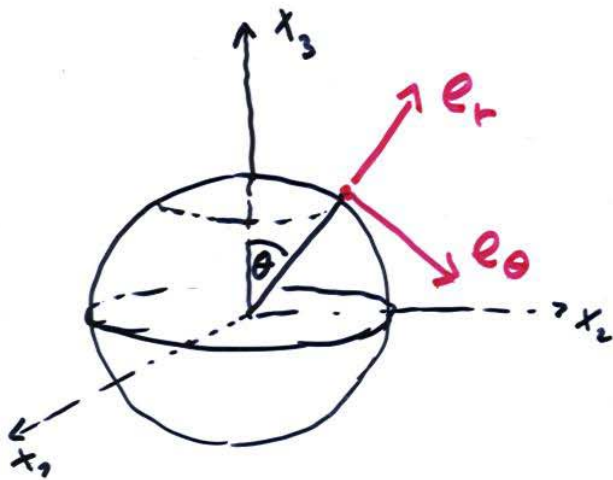


# Landau's solutions

(Landau-Lifschitz, p. 82  
Batchelor, p. 206)



$$u = \frac{f(\theta)}{r} e_r + \frac{g(\theta)}{r} e_\theta$$

$$p = \frac{\pi(\theta)}{r^2}$$

$$r = |x|$$

$$\left. \begin{aligned} -\Delta u + u \nabla u + \nabla p &= 0 \\ \operatorname{div} u &= 0 \end{aligned} \right\} \Rightarrow \text{ODE for } f, g, \pi$$

**Explicit solutions** (L.D. Landau 1944, H.B. Squire 1951,  
further works: G. Tian - Z. Xin 1997, M. Cannone - G. Karch 2002)

$$f(\theta) = 2 \left[ \frac{\lambda^2 - 1}{(\lambda - \cos \theta)^2} - 1 \right]$$

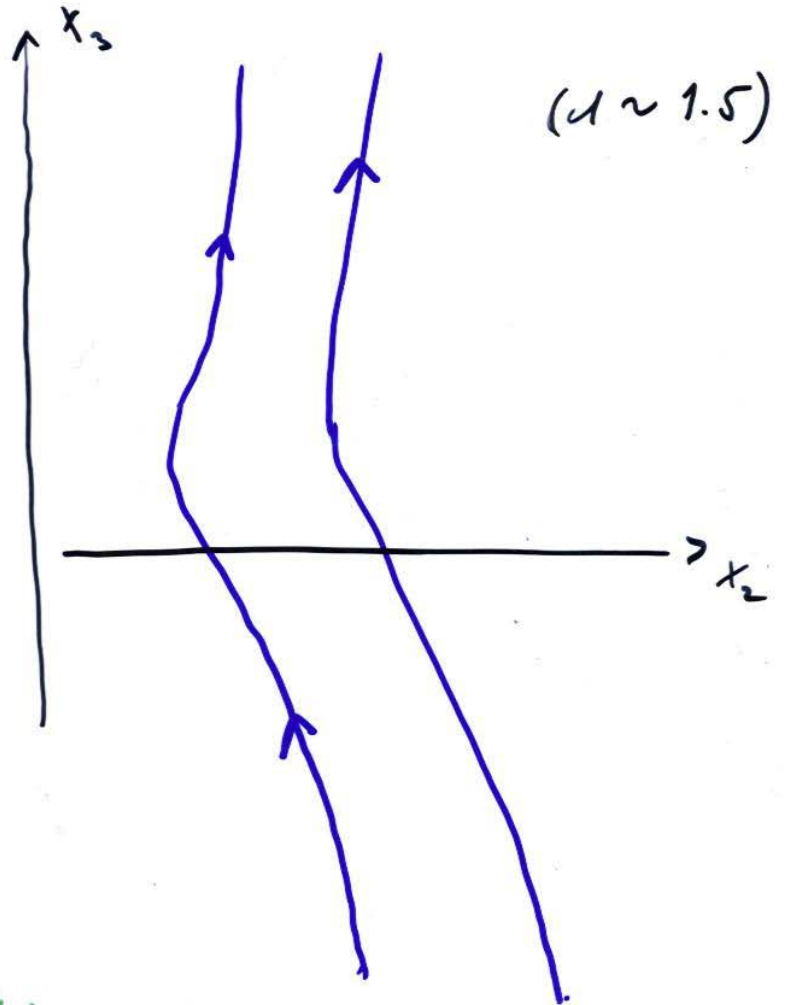
$$g(\theta) = -2 \frac{\sin \theta}{\lambda - \cos \theta}$$

$$|\lambda| > 1$$

$$\pi(\theta) = 4 \frac{(1 - \lambda \cos \theta)}{(\lambda - \cos \theta)^2}$$

# Streamlines ( $x_2, x_3$ - plane )

symmetric with respect to rotations about  $x_3$



Behavior for large  $u$ :

$$u = \frac{1}{\Lambda} \left[ \begin{array}{l} \text{"fund. solution"} \\ \text{of Stokes"} \end{array} \right] + O\left(\frac{1}{\Lambda^2}\right)$$

general  $u$ :

$u \sim$  deformation of the fund. solution of the (linear) Stokes system by the N-S non-linearity

At the singularity:

$$-\Delta u + u \cdot \nabla u + \nabla p =$$

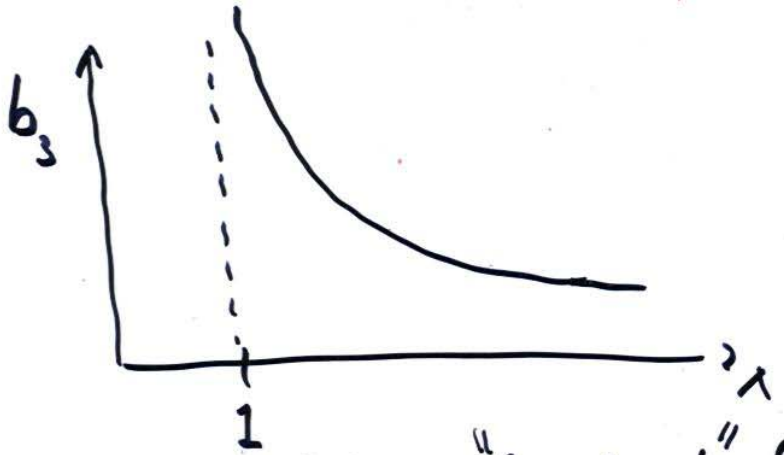
$$\operatorname{div} \left( \underbrace{-\nabla u + u \otimes u + p \cdot I}_{\in L^1_{loc}} \right) = \text{well-defined element} = \text{of } \mathcal{D}'(\mathbb{R}^3)$$

$$= b \cdot \delta(x)$$

↙ ↘  
 $\in \mathbb{R}^3$  Dirac function

$$b = \begin{pmatrix} 0 \\ 0 \\ b_3(u) \end{pmatrix}$$

$$b_3(u) = \frac{32}{3} \frac{u}{u^2-1} + 4\lambda^2 \log\left(\frac{u-1}{u+1}\right) + 8\lambda \quad \left( \text{Batchelor, p. 209} \right)$$



Possible interpretation: "fund. sol." of steady state NS.

Motivation for further study  
of similar classes of solutions:

1. Regularity theory
2. Asymptotic behavior  
of solutions of steady-state  
NSE as  $|x| \rightarrow \infty$

# Regularity theory - a model problem

(ME)  $-\Delta u = |u|^{2\sigma} u$  in  $\Omega = B_1 \subset \mathbb{R}^n$

- well-defined in  $\mathcal{D}'$  when  $u \in L_{loc}^{2\sigma+1}$
- scaling symmetry  $u(x) \rightarrow \lambda^{1/\sigma} u(\lambda x)$

- Invariant solution  $\bar{u} = \frac{A(\delta, n)}{|x|^{1/\sigma}}$

works for  $2 + \frac{1}{\sigma} < n$

- $\bar{u} \in L_{weak}^{2n}$

Theorem: (standard reg. theory)

$u \in L_{loc}^{2n}$  solves (ME) in  $\mathcal{D}'$ ,  $2 + \frac{1}{\sigma} < n$

$\Rightarrow u$  is regular

Interpretation: Regularity is governed by the invariant solution.



6

Steady-state NS, (very) weak formulation:

$$\int_{\Omega} \left( u_i \Delta \varphi_i + u_j u_i \frac{\partial \varphi_i}{\partial x_j} \right) dx = 0$$

for each  $\varphi = (\varphi_1, \dots, \varphi_n) \in \mathcal{D}(\Omega)$ ,  $\text{div } \varphi = 0$ .

- well-defined for  $u \in L^2_{loc}$

Question: Regularity of such solutions?

Motivation:

(i) The real problem: 3+1 -dim NS, with energy estimates

However, the eq. is super-critical and the energy estimates have not found much use for full regularity so far

(ii) 3d steady-state NS with energy est.  $\rightarrow$  no problem (subcritical)

(iii) 3d steady-state NS without energy est.  
 $\rightarrow$  very weak solutions  $u \in L^2_{loc}$

? Is this a good model problem?

⑦

Theorem: (standard regularity theory)

$u \in L^n_{loc}$  is a very weak solution of  
steady-state  $n$ -dimensional NS,  $n \geq 3$ ,  
 $\Rightarrow u$  is regular

Scaling symmetry of NS:  $u(x) \rightarrow \lambda u(\lambda x)$

Question: Is there a scale-invariant  
(very weak) steady-state solution,  
smooth in  $\mathbb{R}^n \setminus \{0\}$ ?

If so, the above theorem is more or less  
optimal.

Theorem: (Frehse-Růžička, Struwe, Tsai-US)

$n \geq 4$ ,  $u: \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}^n$  is

(-1) - homogeneous, smooth away from 0,

solves steady-state NSE

$$\Rightarrow u \equiv 0$$

This cannot be true for  $n=3$ ,  
due to Landau's solutions

However, Landau's solutions  
are not (very weak) solutions of NS  
across the origin.



### Theorem: (VS)

If  $u: \mathbb{R}^3 \setminus \{0\} \rightarrow \mathbb{R}^3$  is  $(-1)$ -homogeneous, smooth away from 0, and solves the steady-state N-S in  $\mathbb{R}^3 \setminus \{0\}$ , then  $u$  is a Landau solution

(An alternative formulation:

$(-1)$ -homogeneous solution must be axis-symmetric with respect to a suitable axis, and hence a Landau sol.)

Corollary: There are no obstructions to regularity of very weak solutions coming from  $(-1)$ -homog. (= scale invariant) solutions (smooth away from 0).

Possible implications for long-range behavior:

$$\left. \begin{aligned} -\Delta u + u \cdot \nabla u + \nabla p &= f \\ \operatorname{div} u &= 0 \end{aligned} \right\} \text{ in } \mathbb{R}^3$$

comp. supported

Problem: behavior of  $u$  at  $\infty$

Plausible scenario:

$$u_\lambda(x) = \lambda u(\lambda x), \quad f_\lambda(x) = \lambda^3 f(\lambda x)$$

Note:  $f_\lambda \xrightarrow{\lambda \rightarrow \infty} \bar{f} = b \cdot \delta$ ,  $b = \int f$

Dirac function

If  $u_\lambda \xrightarrow{\lambda \rightarrow \infty} \bar{u}$ ,  $\bar{u} \in L^3_{loc}(\mathbb{R}^3 \setminus \{0\})$

then  $\bar{u}$  is  $(-1)$ -homogeneous, smooth away from 0  $\Rightarrow \bar{u}$  is a Landau sol.

Conclusion: If a simple asymptotics for  $u$  at  $\infty$  exists, it must be given by a Landau solution

Remark: the same situation

$$-\Delta u + u \cdot \nabla u + \nabla p = f$$

$$\operatorname{div} u = 0$$

If  $u_n(x) = \lambda u(\lambda x)$  have a limit  $\bar{u}$  ( $\lambda \rightarrow \infty$ )

and  $\int f = 0$ , then  $\bar{u} \equiv 0$

$\Rightarrow u$  decays faster than  $\frac{1}{|x|}$

This is standard and expected behavior for the linear Stokes, but it seems it might carry over to the N-S! This seems to be surprising. (In fact, it would be natural to suspect that the non-linear effects can produce a non-symm. invariant solution!)



# Proof of the main theorem

(12)

$$u(x) = \frac{1}{|x|} u\left(\frac{x}{|x|}\right), \quad \rho(x) = \frac{1}{|x|^2} \rho\left(\frac{x}{|x|}\right)$$

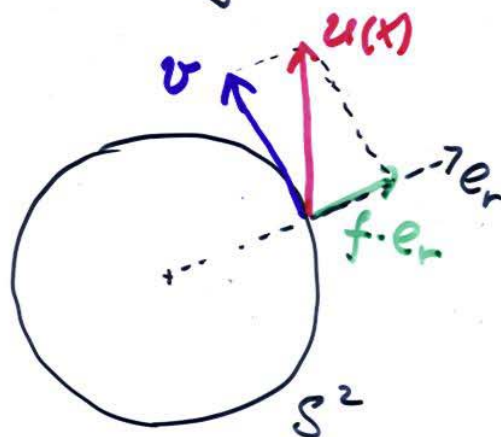
$\Rightarrow$  can only consider  $u|_{S^2}, \rho|_{S^2}$

On  $S^2$ :

$$u(x) = v(x) + f(x) \cdot e_r(x)$$

vector field  
on  $S^2$

function  
on  $S^2$



Equations on  $S^2$  for  $v, f, \rho$ :

$$(1) \quad \operatorname{div} v + f = 0 \quad (\text{continuity})$$

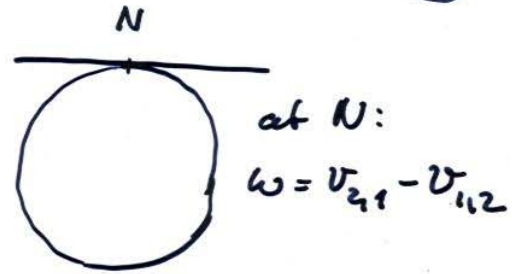
$$(2) \quad \Delta f + v \cdot \nabla f - f^2 - |v|^2 - 2\rho = 0 \quad (e_r\text{-comp. of N-S})$$

$$(3) \quad -\Delta_H v + v \cdot \nabla v + \nabla(\rho - 2f) = 0 \quad (\text{tangential comp. of N-S})$$

Hodge Laplacian  $-\Delta_H = dd^* + d^*d$



Define  $\omega = \text{curl } v$   
 (as a 2-form:  $\omega = dv$ )



Calculation: (take curl of (3))

$$(VE) \quad -\Delta \omega + \text{div } v (\omega) = 0$$

Lemma 1:  $\omega \equiv 0$

Proof:

(i) (VE)  $\Rightarrow$   $\omega$  does not change sign

$$(ii) \quad \int_{S^2} \omega = 0$$

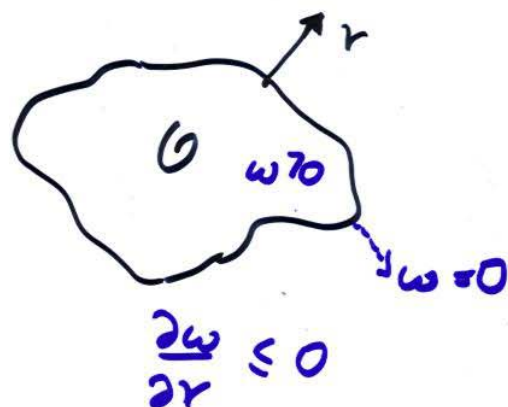
$$(ii) \text{ is easy: } \int_{S^2} \omega = \int_{S^2} dv = 0$$

Heuristics for (i):

$\mathcal{O} = \{\omega > 0\}$ , assume  $\partial\mathcal{O} \neq \emptyset$

$$(VE) \Rightarrow 0 = \int_{\mathcal{O}} \operatorname{div} v (-\nabla\omega + v\omega) =$$

$$= - \int_{\partial\mathcal{O}} \underbrace{\frac{\partial\omega}{\partial r}}_{\leq 0}$$



$$\Rightarrow \left. \frac{\partial\omega}{\partial r} \right|_{\partial\mathcal{O}} = 0 \Rightarrow \text{conceptually } \omega \equiv 0$$

in  $\mathcal{O}$  by strong max. princ.  
(modulo technicalities)



With  $\omega \equiv 0$ , (3) simplifies:

$$-\Delta_H v = dcl^*v + cl^*dv = -\nabla \operatorname{div} v = \nabla f$$

$$v \cdot \nabla v = \frac{1}{2} \nabla |v|^2$$

$$(3) \Rightarrow \frac{1}{2} |v|^2 + p - f = c$$

(2) now gives

$$(RE) \quad -\Delta f - 2f + \operatorname{div}(f \cdot v) = 2c$$

Integrate over  $S^2$ , use  $f = -\operatorname{div} v \Rightarrow c = 0$

$$\text{Set } v = \nabla \varphi \quad ; \quad f = -\operatorname{div} v = -\Delta \varphi$$

$$(\varphi E) \quad \Delta^2 \varphi + 2\Delta \varphi - \operatorname{div}(\nabla \varphi \Delta \varphi) = 0$$

Set  $w = 2 - \Delta \varphi$  and re-write  $(\varphi E)$  as

$$(wE) \quad -\Delta w + \operatorname{div}(\nabla \varphi w) = 0$$

Lemma 2: The solutions of (wE),

$-\Delta w + \operatorname{div}(\nabla\varphi w) = 0$ , are exactly  
the functions  $w = f \cdot e^\varphi$  ( $f = \text{const.}$ )

Proof: (i)  $e^\varphi$  solves (wE)

(ii) write  $w = f(x) e^\varphi$  to get

$$-\Delta f + b_j f_{,j} = 0 \Rightarrow f \equiv \text{const} \quad (\text{max. princ.})$$

///

$$\text{Also, } \int_{S^2} f e^\varphi = \int_{S^2} 2 - \Delta\varphi = 8\pi > 0 \Rightarrow f > 0$$

Therefore

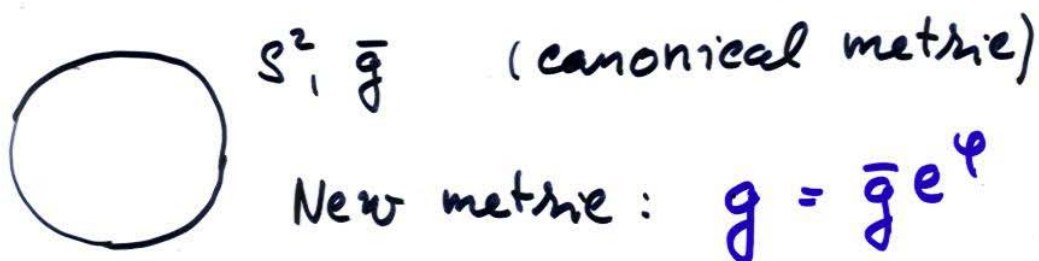
$$-\Delta\varphi + 2 = f e^\varphi \quad (f = \text{const.} > 0)$$

Change  $\varphi \longrightarrow \varphi + \text{const.}$  to get

$$(GE) \quad \boxed{-\Delta\varphi + 2 = 2e^\varphi}$$



Meaning of (GE):



(GE): Gauss curvature of  $g$  is  $\equiv 1$ ,

or:  $g$  is isometric to  $\bar{g}$

$\Rightarrow \exists h: S^2 \rightarrow S^2$ , a diffeomorphism with

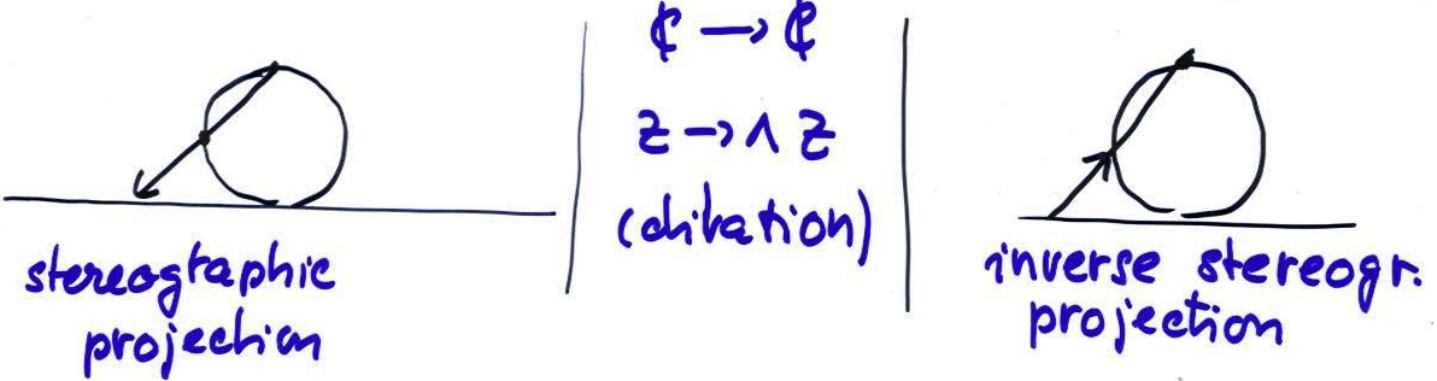
$$e^\varphi \bar{g} = h^* g$$

$\Rightarrow h$  is conformal or anti-conformal, and

$$\varphi(x) = \log |h'(x)|^2$$

Conformal diffeom. of  $S^2$  are known explicitly:

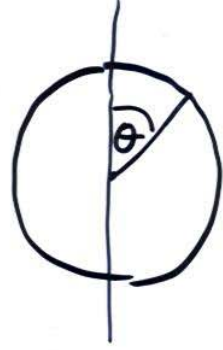
the nontrivial ones can be obtained by composing



The corresponding  $\varphi$  (in suitable co-ord.)

$$\varphi(x) = -2 \log(\cosh x - \sinh x \cos \theta)$$

$x \in \mathbb{R}$  is a parameter



Gives exactly the Landau solutions

Remark:

Let  $h: S^2 \rightarrow S^2$  be a conformal map  
(perhaps with branch points where  $h'(x)=0$ )

Then  $\varphi = \log |h'(x)|^2$  is well-defined

in  $S^2 \setminus \{a_1, \dots, a_m\}$ , and gives a

$(-1)$ -homogeneous solution of N.S.

in  $\mathbb{R}^3 \setminus \{ \text{finitely many rays from } O \}$

# Beyond (-1) - homogeneous solutions

(-1) - homog. functions  $\rightarrow$  continuous (scaling) symmetry group  
 $u f(ut) = f(t)$

Consider  $f(t) = \frac{1}{t^{1+\alpha}}$   $\rightarrow$   $\left\{ \begin{array}{l} \text{is } t f(t) \\ \text{in } \log t \end{array} \right.$

discrete (scaling) symmetry group

$$u_0^k f(u_0^k t) = f(t), \quad u_0 = e^{\frac{2\pi}{\alpha}}$$

Example:  $-\Delta u = u^3$  in  $\mathbb{R}^3$

The invariant solution  $\bar{u} = \frac{A}{|x|}$  can

bifurcate into non-trivial, discretely invariant solutions (periodic in  $\log r$ )

Question: Is such behavior possible for Landau solutions?

Numerical evidence: No



## Conclusions :

The study of Landau solution suggests:

- (i) non-trivial regularity results for very weak solutions of steady state NS
- (ii) conjectures for long-range behavior of st. state sol. in  $\mathbb{R}^3$
- (iii) Landau sol. are rigid, perhaps even in the class of discretely invariant solutions.  
(numerically this seems to be true for infinitesimal perturbations)