# Rigorous Foundations of the Brockett-Wegner Flow for Operators 

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#### Abstract

The Brockett-Wegner diagonalizing flow $\dot{H}_{t}=\left[H_{t},\left[H_{t}, A\right]\right]$ is studied. Global existence and uniqueness of solutions of this evolution equation is proved on the space $\mathcal{B}[\mathscr{H}]$ of bounded operators on a complex Hilbert space $\mathscr{H}$. Local existence is proved for certain unbounded initial operators $H_{0}$. Furthermore, if $H_{0}, A$ are Hilbert-Schmidt operators, it is demonstrated that $H_{t}$ strongly converges to a diagonal operator $H_{\infty}$ which is unitarily equivalent to $H_{0}$.


Keywords : Flow equations for operators, Brockett-Wegner flow, Double bracket flow, Evolution equations.

## I Introduction

Almost two decades ago, Brockett [1] proposed a method to diagonalize selfadjoint complex matrices by means of a flow on the space of matrices, which we briefly outline. (He also used this method to solve linear programs, but this is of no concern here.) The notion of diagonalization he used is given in terms of the commutator $[H, A]=H A-A H$ of two self-adjoint matrices $H=H^{*}$ and $A=A^{*}$, which we assume to be complex $N \times N$ matrices, $H, A \in \operatorname{Mat}(N, \mathbb{C})$, to be specific. The matrix $H$ is called $A$-diagonal iff $[H, A]=0$. So, $A$ is a reference matrix whose eigenspaces determine what is considered diagonal. If $A=\operatorname{diag}\left(\alpha_{1}, \alpha_{2}, \ldots, \alpha_{N}\right)$ is diagonal and possesses $N$ different eigenvalues (of multiplicity one) then $H$ is $A$-diagonal iff $H$ is diagonal in the usual sense, i.e., $H=\operatorname{diag}\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{N}\right)$.

Brockett suggested to study the solution of the Cauchy problem

$$
\begin{equation*}
\forall t>0: \quad \dot{H}_{t}:=i\left[H_{t}, G_{t}\right], \quad H_{0}:=H, \tag{I.1}
\end{equation*}
$$

where $G_{(\cdot)}=G_{(\cdot)}^{*} \in C^{1}\left(\mathbb{R}_{0}^{+} ; \operatorname{Mat}(N, \mathbb{C})\right)$ is chosen later. He introduced a (Lyapunov) function

$$
\begin{equation*}
f_{t}:=\frac{1}{2} \operatorname{Tr}\left\{\left(H_{t}-A\right)^{2}\right\} \geq 0 . \tag{I.2}
\end{equation*}
$$

Note that $\left(H_{t}, G_{t}\right)$ form a Lax pair and the solution $H_{t}$ of (I.1) is unitary equivalent to $H$, for all $t>0$, since $G_{s}$ is self-adjoint, for all $s \geq 0$. Hence

$$
\begin{equation*}
f_{t}=\frac{1}{2} \operatorname{Tr}\left\{H_{t}^{2}+A^{2}-2 H_{t} A\right\}=\frac{1}{2} \operatorname{Tr}\left\{H^{2}+A^{2}\right\}-\operatorname{Tr}\left\{H_{t} A\right\} . \tag{I.3}
\end{equation*}
$$

Assuming the existence of a solution $H_{(\cdot)} \in C^{1}\left(\mathbb{R}_{0}^{+} ; \operatorname{Mat}(N, \mathbb{C})\right)$ of (I.1), a differentiation yields

$$
\begin{equation*}
\dot{f_{t}}:=-\operatorname{Tr}\left\{\dot{H}_{t} A\right\}=-\operatorname{Tr}\left\{i\left[H_{t}, G_{t}\right] A\right\}=-\operatorname{Tr}\left\{i\left[A, H_{t}\right] G_{t}\right\}, \tag{I.4}
\end{equation*}
$$

using the cyclicity of the trace. Brockett's key observation is that upon choosing

$$
\begin{equation*}
G_{t}=G_{t}^{*}:=i\left[A, H_{t}\right] \tag{I.5}
\end{equation*}
$$

we obtain

$$
\begin{equation*}
\forall t \geq 0: \quad f_{t} \geq 0, \quad-\dot{f}_{t}=\operatorname{Tr}\left\{G_{t}^{2}\right\} \geq 0 \tag{I.6}
\end{equation*}
$$

Since $f$ is continuously differentiable, the fundamental theorem of calculus implies that $-\dot{f} \in L^{1}\left(\mathbb{R}^{+} ; \mathbb{R}_{0}^{+}\right)$is a nonnegative, continuous, integrable function. This suggests that in the limit $t \rightarrow \infty$
(i) $\left[i A, H_{t}\right] \rightarrow 0$, as the square of its Hilbert-Schmidt norm equals

$$
\begin{equation*}
\operatorname{Tr}\left\{\left[i A, H_{t}\right]^{2}\right\}=\operatorname{Tr}\left\{G_{t}^{2}\right\}=-\dot{f_{t}} \tag{I.7}
\end{equation*}
$$

(ii) $H_{t}$ converges to a limit matrix $H_{\infty}=\lim _{t \rightarrow \infty} H_{t}=\lim _{t \rightarrow \infty}\left\{U_{t, 0} H U_{t, 0}^{*}\right\}$ which is unitarily equivalent to $H$ and $A$-diagonal. Here, $U_{t, s} \subseteq \mathrm{U}(N)$ is the cocycle (i.e., possessing the cocyclicity, or Chapman-Kolmogorov, property $U_{t, r} U_{r, s}=U_{t, s}$, for all $t \geq r \geq s \geq 0$ ) of unitary matrices generated by $i G_{t}$.

About the same time as Brockett, but independently, Wegner [9] used a similar idea for the diagonalization of self-adjoint operators. In the context of Eqs. (I.1)-(I.6), Wegner's choice for $G_{t}$ is

$$
\begin{equation*}
G_{t}:=i\left[H_{t}^{\text {diag }}, H_{t}\right], \tag{I.8}
\end{equation*}
$$

where $H_{t}^{\text {diag }}$ denotes the diagonal part of $H_{t}$. That is, if $H_{t}(k, \ell):=\left\langle e_{k} \mid H_{t} e_{\ell}\right\rangle$ denotes the matrix elements of $H_{t}$ w.r.t. the standard basis $\left\{e_{n}\right\}_{n=1}^{N} \subseteq \mathbb{C}^{N}$, then $H_{t}^{\text {diag }}(k, \ell):=\delta_{k, \ell} H_{t}(k, k)$. Wegner's method has been successfully applied to analyze a variety of models in theoretical (mostly: condensed matter) physics, see [7]. Brockett's proposal, however, has two obvious mathematical advantages over Wegner's: It is formulated in an invariant way by means of $A$, fixing what is considered diagonal without referring to a particular basis. In fact, it is unclear how to extend (I.8) in case that the operators $H$ and $A$ have continuous spectrum and the diagonalizabilty with respect to a discrete basis is not possible. The second flaw is that Wegner's choice (I.8) for $G_{t}$ is quadratic in $H_{t}$, leading to a cubicly nonlinear evolution equation for $H_{t}$, while Brockett's choice (I.5) for $G_{t}$ leads to a quadratic nonlinearity. We henceforth refer to (I.1) and its solution as the Brockett-Wegner Flow.

We note that a few years before, Deift, Li, and Tomei $[4,5,3]$ studied similar evolution equations in the context of their integrability and what is known as the Toda flow $\dot{L}_{t}=\left[B_{t}, L_{t}\right]$, where $L_{t}$ and $B_{t}$ are tridiagonal real symmetric matrices given as

$$
L=\left(\begin{array}{cccc}
a_{1} & b_{1} & & 0  \tag{I.9}\\
b_{1} & a_{2} & \ddots & \\
& \ddots & \ddots & b_{N-1} \\
0 & & b_{N-1} & a_{N}
\end{array}\right), \quad B=\left(\begin{array}{cccc}
0 & b_{1} & & 0 \\
-b_{1} & 0 & \ddots & \\
& \ddots & \ddots & b_{N-1} \\
0 & & -b_{N-1} & 0
\end{array}\right)
$$

Setting $H_{t}:=L_{t}$ and choosing $A=\operatorname{diag}(1,2, \ldots, N)$, we observe that $G_{t}:=$ $i\left[A, H_{t}\right]=i B_{t}$, and hence the Toda flow is a special case of (I.1) and (I.5).

This is remarkable because in $[4,5,3]$ the Toda flow is explicitly integrated (as an ODE), is compared to the QR-decomposition method of matrices, and variants of it are discussed, some of which become singular in finite time even in finite dimension $N<\infty$

It turns out that even for $N \times N$-matrices, the properties described under (ii) above are not obvious. Ignoring this for the time being, we remark that our outline of the Brockett-Wegner flow for $N \times N$-matrices uses the finiteness of the dimension $N^{2}=\operatorname{dim} \operatorname{Mat}(N, \mathbb{C})<\infty$ at various places:
(a) Inserting the definition (I.5) of $G$ into (I.1) we obtain

$$
\begin{equation*}
\forall t>0: \quad \dot{H}_{t}:=\left[H_{t},\left[H_{t}, A\right]\right], \quad H_{0}:=H \tag{I.10}
\end{equation*}
$$

which is a (quadratically) nonlinear differential equation, for which the global existence of solutions is not obvious, but essentially follows from the fact that the solution is a unitary conjugate of the initial value, see Sec. II.
(b) The very definition (I.2) of the Lyapunov function $f$ employs the trace on $\operatorname{Mat}(N, \mathbb{C})$, and its cyclicity is crucial for the validity of Brockett's observation (I.4)-(I.6).
(c) Thus, in the infinite-dimensional context, the finiteness of $f_{0}$ would require that $H-A$ is a Hilbert-Schmidt operator.
(d) The convergence of the operators is defined in Hilbert-Schmidt norm. For many applications, this norm is not appropriate, as it is known that one can, at best, hope for strong convergence.
(f) In infinite dimensions, the unitary equivalence of all $H_{t}$ and their convergence $H_{t} \rightarrow H_{\infty}$ do not necessarily imply that the limiting operator $H_{\infty}$ is unitarily equivalent to $H=H_{0}$, because the family $U_{t, s}$ of unitary operators generated by $i G_{t}$ may not converge.
(g) In fact, in infinite dimensions, the distinguished spectral types (ac, sc, pp, etc.) characterizing the spectral measure of $H$ are unitary invariants. So, for instance, if $H$ has continuous spectrum then it cannot be forced to become diagonal in any orthonormal basis. Then either $H_{t}$ does not converge at all or it does converge but not to a diagonal operator or its limit is not unitarily equivalent to $H$. Either way, the flow will not diagonalize $H$.

The results in the present paper are the following.

- We first show that (I.10) has a unique, smooth global solution $H_{(\cdot)} \in$ $C^{\infty}\left(\mathbb{R}_{0}^{+} ; \mathcal{B}[\mathscr{H}]\right)$, provided $H_{0}, A \in \mathcal{B}[\mathscr{H}]$ are bounded operators. There is a family $U_{(\cdot)} \in C^{\infty}\left(\mathbb{R}_{0}^{+} ; \mathcal{B}[\mathscr{H}]\right)$ of unitary operators such that all $H_{t}=U_{t} H_{0} U_{t}^{*}$ are (mutually) unitarily equivalent. This is carried out in Sect. II.
- Secondly, using a Nash-Moser type of estimate, we show that (I.10) has a unique, smooth local solution $H_{(\cdot)} \in C^{\infty}([0, T] ; \mathcal{B}[\mathscr{H}])$ in case of unbounded $H_{0}$ provided its iterated commutators with $A$ define bounded operators whose norm tends to zero, as the order increases, sufficiently fast. The precise formulation of the assertion and its proof is the contents of Sect. III.
- Thirdly, under the additional assumption that $H_{0}, A \in \mathcal{L}^{2}[\mathscr{H}]$ are Hilbert-Schmidt operators, we show in Sect. IV that $H_{t}$ strongly converges to a diagonal operator $H_{\infty}$ which is unitarily equivalent to $H_{0}$.

We conclude this introduction with a few remarks. A typical situation encountered in quantum mechanics, say, is that both $H$ and $A$ are unbounded, but bounded below. In this case $H+\lambda$ and $A+\lambda$ are positive and hence bounded invertible, provided $\lambda>0$ is sufficiently big. The $A$-diagonalization of $H$ is clearly equivalent to the $(A+\lambda)^{-1}$-diagonalization of $(H+\lambda)^{-1}$. So, it seems that the diagonalization of unbounded, but semibounded operators can be traced back to the diagonalization of bounded operators. This is, however, not really the case because the differential equation for $H_{t}$ changes - even if $H$ and $A$ are strictly positive. Namely, if

$$
\begin{equation*}
\partial_{t}\left(H_{t}^{-1}\right)=\left[H_{t}^{-1},\left[H_{t}^{-1}, A^{-1}\right]\right] \tag{I.11}
\end{equation*}
$$

then

$$
\begin{equation*}
\dot{H}_{t}=\left[H_{t},\left[H_{t}^{-1}, A^{-1}\right]\right]=-H_{t}^{-1}\left[H_{t},\left[H_{t}, A^{-1}\right]\right] H_{t}^{-1} \tag{I.12}
\end{equation*}
$$

which is not identical to (I.10) - even if we ignore the change from $A$ to $A^{-1}$. In fact, (I.12) is more involved than (I.10) because it additionally requires to invert $H_{t}$ for the computation of its right side.

One may also consider passing from $H$ and $A$ to $e^{-\beta H}$ and $e^{-\beta A}$ in the case of semibounded $H$ and $A$, but this suffers from the same flaw: computing the right side of the differential equation requires the explicit computation of $e^{-\beta H}$ and $e^{-\beta A}$.

Another observation is that without specification of $G_{t}$, Eq. (I.1) is a linear, non-autonomous evolution equation. The theory of these is known to be
much more difficult than the one of autonomous evolution equations. The latter are fully characterized by the Hille-Yoshida theorem which essentially says that the solutions of autonomous evolution equations are precisely strongly continuous hyperbolic semigroups generated by densely defined operators fulfilling Kato's (quasi-)stability condition. In contrast, in the non-autonomous case, only sufficient conditions, basically extending the autonomous case, are known. The necessity of these conditions remains unclear until today. This subject has a long history, and important contributions have been made by Kato, Yosida, Tanabe, Kisynski, Hackman, Kobayasi, Ishii, Goldstein, Acquistapace, Terreni, Nickel, Schnaubelt, Caps, Tanaka, and many more; see for instance [6, 2] and references therein. From this angle, the problem treated in Sect. III seems trivial: the $\left(G_{t}\right)_{t \geq 0}$ is a family of bounded self-adjoint operators. The preservation of the domain of $H_{t}$ under the flow generated by $G_{t}$, however, is difficult to control because $G_{t}$ itself depends on $H_{t}$. This is the achievement of Sect. III.

## II Global Existence on Bounded Operators

Our first task is to show that the Cauchy problem stated in (I.10), that is

$$
\begin{equation*}
\forall t>0: \quad \dot{H}_{t}:=\left[H_{t},\left[H_{t}, A\right]\right], \quad H_{0}:=H, \tag{II.13}
\end{equation*}
$$

possesses a unique global solution $\left(H_{t}\right)_{t \geq 0}$ which is smooth in $t$. We formulate this result in the following theorem

Theorem 1 Let $\left(\mathcal{A},\|\cdot\|_{\mathcal{A}}\right)$ be a Banach subalgebra of the Banach algebra $\mathcal{B}[\mathscr{H}] \supset \mathcal{A}$ of bounded operators on a separable Hilbert space $\mathscr{H}$ such that $\|\cdot\|_{\mathcal{A}}$ is a unitarily invariant norm. Suppose that $H_{0}=H_{0}^{*}, A=A^{*} \in \mathcal{A}$ are two self-adjoint operators such that $A \geq 0$. Then Eq. (II.13) has a unique solution $H_{(\cdot)} \in C^{\infty}\left(\mathbb{R}_{0}^{+} ; \mathcal{A}\right)$, and $H_{t}$ is unitarily equivalent to $H_{0}$, for all $t>0$.

Proof: The assumption on $\mathcal{A}$ to be a Banach algebra with unitarily invariant norm means that $\|A B\|_{\mathcal{A}} \leq\|A\|_{\mathcal{A}} \cdot\|B\|_{\mathcal{A}}$ and $\left\|U A U^{*}\right\|_{\mathcal{A}}=\|A\|_{\mathcal{A}}$, for all $A, B \in \mathcal{A}$ and all unitary operators $U \in \mathcal{B}[\mathscr{H}]$.

The first part of the argument employs the standard contraction mapping principle in connection to the Picard iteration. We fix $A \in \mathcal{A}$ and define $F: \mathcal{A} \rightarrow \mathcal{A}$ by

$$
\begin{equation*}
F(H):=[H,[H, A]] . \tag{II.14}
\end{equation*}
$$

We observe for any $H, \widetilde{H} \in \mathcal{A}$ that

$$
\begin{equation*}
F(H)-F(\widetilde{H})=[H-\widetilde{H},[H, A]]+[\widetilde{H},[H-\widetilde{H}, A]] \tag{II.15}
\end{equation*}
$$

which implies that $F$ is locally Lipschitz continuous and that $t \mapsto F\left(H_{t}\right)$ is differentiable in norm if $t \mapsto H_{t}$ is, namely

$$
\begin{equation*}
\|F(H)-F(\widetilde{H})\|_{\mathcal{A}} \leq 4\|A\|_{\mathcal{A}}\left(\|H\|_{\mathcal{A}}+\|\widetilde{H}\|_{\mathcal{A}}\right)\|H-\widetilde{H}\|_{\mathcal{A}} \tag{II.16}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{d F\left(H_{t}\right)}{d t}=\left[\dot{H}_{t},\left[H_{t}, A\right]\right]+\left[H_{t},\left[\dot{H}_{t}, A\right]\right] \tag{II.17}
\end{equation*}
$$

Denoting by $Y_{T}:=C([0, T] ; \mathcal{A})$ the Banach space w. r. t. the norm $\left\|M_{(\cdot)}\right\|:=$ $\max _{0 \leq t \leq T}\left\|M_{t}\right\|_{\mathcal{A}}$, as usual, we conclude that $\mathcal{F}_{T}: C([0, T] ; \mathcal{A}) \rightarrow C([0, T] ; \mathcal{A})$, defined by

$$
\begin{equation*}
\left(\mathcal{F}_{T}\left(M_{(\cdot)}\right)\right)_{t}:=H_{0}+\int_{0}^{t} F\left(M_{s}\right) d s \tag{II.18}
\end{equation*}
$$

defines a contraction on

$$
\begin{equation*}
D_{T}:=\left\{M_{(\cdot)} \in Y_{T} \mid \max _{0 \leq t \leq T}\left\|M_{t}\right\|_{\mathcal{A}} \leq\left(16\|A\|_{\mathcal{A}} T\right)^{-1}\right\} . \tag{II.19}
\end{equation*}
$$

Thus $M_{(\cdot)}=\mathcal{F}_{T}\left(M_{(\cdot)}\right)$ has a unique smooth solution which we denote $H_{(\cdot)} \in$ $C^{\infty}([0, T] ; \mathcal{A})$ provided

$$
\begin{equation*}
T:=\frac{1}{32\|A\|_{\mathcal{A}}\left\|H_{0}\right\|_{\mathcal{A}}} . \tag{II.20}
\end{equation*}
$$

The key observation is that the self-adjointness of $G_{t}=i\left[A, H_{t}\right] \in \mathcal{A}$ implies that the unique solution $U_{(\cdot)} \in C^{\infty}([0, T] ; \mathcal{A})$ of the linear, non-autonomous evolution equation

$$
\begin{equation*}
\forall t>0: \quad \dot{U}_{t}:=-i G_{t} U_{t}, \quad U_{0}:=\mathbf{1} \tag{II.21}
\end{equation*}
$$

is unitary. Moreover, $H_{t}=U_{t} H_{0} U_{t}^{*}$ and in particular

$$
\begin{equation*}
\left\|H_{T}\right\|_{\mathcal{A}}=\left\|U_{T} H_{0} U_{T}^{*}\right\|_{\mathcal{A}}=\left\|H_{0}\right\|_{\mathcal{A}} . \tag{II.22}
\end{equation*}
$$

We can therefore repeat the argument starting from (II.18), replacing $H_{0}$ by $H_{T}$. Clearly, an iteration of this procedure yields the desired global solution.

## III Local Existence on Unbounded Operators

This section is devoted to proving local existence and uniqueness of solutions of the Brockett-Wegner flow for unbounded operators $H_{0}$ which, together with its iterated commutators, are bounded relative to $A$, where we assume w. l. o. g. that $A \geq 1$. Instead of (I.10), we study

$$
\begin{equation*}
\forall t>0: \quad \dot{H}_{t}:=\left[H_{t},\left[H_{t}, A^{-1}\right]\right], \quad H_{0}:=H \tag{III.23}
\end{equation*}
$$

in this section, i.e., we replace $A$ by $A^{-1}$. The proof of our result in Theorem 2 below was inspired by a similar result of Caps [2] for quasilinear evolution equations on scales of Banach spaces, using estimates of Nash-Moser type, see [8].

To formulate our result, we introduce some notation. We denote by $X$ := $\mathcal{B}[\mathscr{H}]$ the space of bounded operators on a complex, separable Hilbert space $\mathscr{H}$. We assume that $A \geq \mathbf{1}$ is a positive operator and $H$ a closed operator with dense common domain $\mathscr{D} \subseteq \mathscr{H}$ which is itself a Hilbert space w.r.t. $\langle x \mid y\rangle_{\mathscr{D}}:=\langle A x \mid A y\rangle_{\mathscr{H}}$. We denote by $Y:=\mathcal{B}[\mathscr{D}]$ the bounded operators on $\mathscr{D}$ and note the natural identification $\|M\|_{Y}=\left\|A M A^{-1}\right\|_{X}$.

We further assume that $H A^{-1} \in X$ and $R_{n}(H) \in X \cap Y$, for all $n \in$ $\mathbb{N}_{0}:=\{0,1,2,3, \ldots\}$, where $R_{n}(H)$ is recursively defined by $R_{0}(H):=A^{-1}$ and

$$
\begin{equation*}
\forall n \in \mathbb{N}: \quad R_{n}(H):=\left[H, R_{n-1}(H)\right]=\operatorname{Ad}_{H}^{n}\left[A^{-1}\right] \tag{III.24}
\end{equation*}
$$

with $[A, B]:=A B-B A$, as usual. More precisely, for a given $n \in \mathbb{N}$ and $R_{n-1}(H) \in X \cap Y$, we first define $R_{n}(H) \in \mathcal{B}[\mathscr{D} ; \mathscr{H}]$ by

$$
\begin{equation*}
R_{n}(H) A^{-1}:=\left(H A^{-1}\right)\left(A R_{n-1}(H) A^{-1}\right)-R_{n-1}(H)\left(H A^{-1}\right) \tag{III.25}
\end{equation*}
$$

and assume that $R_{n}(H)$ extends to an operator bounded both on $\mathscr{D}$ and on $\mathscr{H}$, i.e., $R_{n}(H) \in X \cap Y$.

Theorem 2 Suppose that $H_{0}=H_{0}^{*}$ and $A=A^{*} \geq 1$ are two self-adjoint operators on $\mathscr{H} \supseteq \mathscr{D}$ and that $R_{n}\left(H_{0}\right): \mathscr{D} \rightarrow \mathscr{H}$ extend to bounded operators $R_{n}\left(H_{0}\right) \in X \cap Y$, for all $n \in \mathbb{N}$, such that $\left\|H_{0} A^{-1}\right\|_{X}<\infty$ and

$$
\begin{equation*}
\sum_{n=0}^{\infty} \frac{e^{\rho n}}{n!}\left(\left\|R_{n}\left(H_{0}\right)\right\|_{X}+\left\|R_{n}\left(H_{0}\right)\right\|_{Y}\right) \leq e^{\eta} \tag{III.26}
\end{equation*}
$$

for some $\rho, \eta \in \mathbb{R}$. Then the following assertions hold true.
(i) Eq. (III.23) has a self-adjoint solution $H_{(\cdot)} \in C^{\infty}\left(\left[0, T_{*}\right) ; \mathcal{B}[\mathscr{D}, \mathscr{H}]\right)$, where $T_{*}:=\frac{1}{8} e^{\rho-\eta-1}$, and there exists a smooth family $U_{(\cdot)} \in C^{\infty}\left(\left[0, T_{*}\right)\right.$; $X \cap Y)$ of unitary tranformations preserving the domain $\mathscr{D}$ of $H_{t}$ such that $H_{t}=U_{t} H_{0} U_{t}^{*}$ is unitarily equivalent to $H_{0}$, for all $t \in\left[0, T_{*}\right)$.
(ii) For all $T<T_{*}$, the solution $H_{(\cdot)} \in C^{\infty}\left(\left[0, T_{*}\right) ; \mathcal{B}[\mathscr{D}, \mathscr{H}]\right)$ obeys

$$
\begin{equation*}
\sum_{n=0}^{\infty} \frac{e^{\rho n}}{n!} \max _{t \in[0, T]}\left\{e^{-n t / T_{*}}\left(\left\|R_{n}\left(H_{t}\right)\right\|_{X}+\left\|R_{n}\left(H_{t}\right)\right\|_{Y}\right)\right\} \leq 2 e^{\eta} \tag{III.27}
\end{equation*}
$$

and $H_{(\cdot)}$ is the only solution with this property.
We break up the proof of Theorem 2 into several steps.
Our first task is to map (III.23) to an auxiliary problem for any solution $H_{(\cdot)} \in C^{1}\left(\mathbb{R}_{0}^{+} ; X\right)$, for which the operators $R_{n}\left(H_{t}\right) \in X \cap Y$. Lemma 3 below derives a system of evolution equations on $\underline{R}(t)$ from (III.23), where $\underline{R}(t):=\left(R_{n}\left(H_{t}\right)\right)_{n=0}^{\infty}$.
Lemma 3 Let $H_{(\cdot)} \in C^{1}\left(\mathbb{R}_{0}^{+} ; \mathcal{B}[\mathscr{D} ; \mathscr{H}]\right)$ be a solution of the Cauchy problem (III.23) such that $R_{n}:=R_{n}\left(H_{(\cdot)}\right) \in C^{1}\left(\mathbb{R}_{0}^{+} ; X \cap Y\right)$, for all $n \in \mathbb{N}_{0}$. Then

$$
\begin{equation*}
\dot{R}_{n}(t)=F_{n}[\underline{R}(t)]:=\sum_{\nu=1}^{n}\binom{n}{\nu}\left[R_{\nu+1}(t), R_{n-\nu}(t)\right], \tag{III.28}
\end{equation*}
$$

for all $n \in \mathbb{N}_{0}$.
Proof: We use an induction in $n \geq 0$. First, $R_{0}(t)=A^{-1}$ is independent of $t$, and so we have 0 on both sides of (III.28) for $n=0$.

Now suppose that (III.28) holds true for $n \geq 0$. To understand the structure of the next computation, assume temporarily that $H_{t} \in X$ is bounded. Then $R_{n+1}\left(H_{t}\right)=\left[H_{t}, R_{n}\left(H_{t}\right)\right]$, Leibniz' rule, and $\dot{H}_{t}=R_{2}(t)$ would yield

$$
\begin{align*}
\dot{R}_{n+1}(t) & =\left[\dot{H}_{t}, R_{n}(t)\right]+\left[H_{t}, \dot{R}_{n}(t)\right]  \tag{III.29}\\
& =\left[R_{2}(t), R_{n}(t)\right]+\sum_{\nu=1}^{n}\binom{n}{\nu}\left[H_{t},\left[R_{\nu+1}(t), R_{n-\nu}(t)\right]\right]
\end{align*}
$$

where we use that all operators are bounded. By Jacobi's identity, we have that

$$
\begin{align*}
& {\left[H_{t},\left[R_{\nu+1}(t), R_{n-\nu}(t)\right]\right]} \\
& \quad=\left[\left[H_{t}, R_{\nu+1}(t)\right], R_{n-\nu}(t)\right]+\left[R_{\nu+1}(t),\left[H_{t}, R_{n-\nu}(t)\right]\right] \\
& \quad=\left[R_{\nu+2}(t), R_{n-\nu}(t)\right]+\left[R_{\nu+1}(t), R_{n-\nu+1}(t)\right] . \tag{III.30}
\end{align*}
$$

Since $H_{t}$ is not bounded but only bounded relative to $A$, carrying out (III.29) and (III.30) require an additional argument, in general. Denoting $H:=H_{t}$, $H^{(A)}:=H_{t} A^{-1}, R_{k}:=R_{k}(t)$, and $R_{k}^{(A)}:=A R_{k}(t) A^{-1}$, we observe that according to (III.25), we have $R_{n+1} A^{-1}:=H^{(A)} R_{n}^{(A)}-R_{n} H^{(A)}$ and thus

$$
\begin{align*}
& \dot{R}_{n+1} A^{-1}=\dot{H}^{(A)} R_{n}^{(A)}-R_{n} \dot{H}^{(A)}+H^{(A)} \dot{R}_{n}^{(A)}-\dot{R}_{n} H^{(A)}  \tag{III.31}\\
& =\left[R_{2}, R_{n}\right] A^{-1}+\sum_{\nu=1}^{n}\binom{n}{\nu}\left(H^{(A)}\left[R_{\nu+1}^{(A)}, R_{n-\nu}^{(A)}\right]-\left[R_{\nu+1}, R_{n-\nu}\right] H^{(A)}\right) .
\end{align*}
$$

Similar to Jacobi's identity, we obtain

$$
\begin{align*}
H^{(A)} & {\left[R_{\nu+1}^{(A)}, R_{n-\nu}^{(A)}\right]-\left[R_{\nu+1}, R_{n-\nu}\right] H^{(A)} }  \tag{III.32}\\
= & H^{(A)} R_{\nu+1}^{(A)} R_{n-\nu}^{(A)}-H^{(A)} R_{n-\nu}^{(A)} R_{\nu+1}^{(A)} \\
& +R_{n-\nu} R_{\nu+1} H^{(A)}-R_{\nu+1} R_{n-\nu} H^{(A)} \\
= & \left(H^{(A)} R_{\nu+1}^{(A)}-R_{\nu+1} H^{(A)}\right) R_{n-\nu}^{(A)}-\left(H^{(A)} R_{n-\nu}^{(A)}-R_{n-\nu} H^{(A)}\right) R_{\nu+1}^{(A)} \\
& +R_{\nu+1}\left(H^{(A)} R_{n-\nu}^{(A)}-R_{n-\nu} H^{(A)}\right)-R_{n-\nu}\left(H^{(A)} R_{\nu+1}^{(A)}-R_{\nu+1} H^{(A)}\right) \\
= & {\left[R_{\nu+2}, R_{n-\nu}\right] A^{-1}+\left[R_{\nu+1}, R_{n-\nu+1}\right] A^{-1} } \tag{III.33}
\end{align*}
$$

and thus

$$
\begin{equation*}
\dot{R}_{n+1}=\left[R_{2}, R_{n}\right]+\sum_{\nu=1}^{n}\binom{n}{\nu}\left(\left[R_{\nu+2}, R_{n-\nu}\right]+\left[R_{\nu+1}, R_{n-\nu+1}\right]\right) \tag{III.34}
\end{equation*}
$$

holds on $\mathscr{D}$ and by continuity hence also on $\mathscr{H}$. Inserting this into (III.29), we obtain

$$
\begin{align*}
& \dot{R}_{n+1}(t)=\left[R_{2}(t), R_{n}(t)\right]+\sum_{\nu=1}^{n}\binom{n}{\nu}\left[R_{\nu+2}(t), R_{n-\nu}(t)\right] \\
& \quad+\sum_{\nu=1}^{n}\binom{n}{\nu}\left[R_{\nu+1}(t), R_{n+1-\nu}(t)\right]  \tag{III.35}\\
& =\sum_{\nu=0}^{n}\binom{n}{\nu}\left[R_{\nu+2}(t), R_{n-\nu}(t)\right]+\sum_{\nu=1}^{n}\binom{n}{\nu}\left[R_{\nu+1}(t), R_{n+1-\nu}(t)\right] \\
& = \\
& =\sum_{\nu=1}^{n+1}\binom{n}{\nu-1}\left[R_{\nu+1}(t), R_{n+1-\nu}(t)\right]+\sum_{\nu=1}^{n}\binom{n}{\nu}\left[R_{\nu+1}(t), R_{n+1-\nu}(t)\right] \\
& =\sum_{\nu=1}^{n+1}\binom{n+1}{\nu}\left[R_{\nu+1}(t), R_{n+1-\nu}(t)\right],
\end{align*}
$$

which completes the induction step and hence the proof of (III.28).
We can rewrite (III.28) as the integral equation

$$
\begin{equation*}
\underline{r}(t)=\mathcal{F}[\underline{r}](t):=\underline{r}^{(0)}+\int_{0}^{t} F[\underline{r}(\tau)] d \tau \tag{III.36}
\end{equation*}
$$

with initial value $\underline{r}^{(0)}=\underline{R}(0)$ and $F(\underline{r}):=\left(F_{n}(\underline{r})\right)_{n=0}^{\infty}$. Next we show that any solution $\underline{R}$ of (III.36) is continuous at $t \searrow 0$ and of moderate growth for small $t$, provided the initial data $\underline{R}(0)$ is sufficiently regular.

For the precise formulation of this statement we fix a triple $\theta:=(\alpha, T, \rho)$ consisting of a positive parameter $\alpha>0$, a time $T>0$, and a real number $\rho \in \mathbb{R}$. Furthermore $(X \cap Y)^{\mathbb{N}_{0}}$ denotes the space of sequences $\left(x_{0}, x_{1}, x_{2}, \ldots\right)$ with $x_{j} \in X \cap Y$. Then we introduce the Banach space

$$
\begin{equation*}
\mathcal{R}_{\theta}:=C\left([0, T] ;(X \cap Y)^{\mathbb{N}_{0}}\right), \tag{III.37}
\end{equation*}
$$

which we equip with the norm

$$
\begin{equation*}
\|\underline{r}\|_{\theta}:=\sum_{n=0}^{\infty} \frac{e^{\rho n}}{n!} \max _{t \in[0, T]}\left\{e^{-\alpha n t}\left\|r_{n}(t)\right\|_{X \cap Y}\right\} \tag{III.38}
\end{equation*}
$$

where $\underline{r}=\left(r_{n}(\cdot)\right)_{n=0}^{\infty} \in \mathcal{R}_{\theta}$ and $\|a\|_{X \cap Y}:=\|a\|_{X}+\|a\|_{Y}$. Note that this norm is again submultiplicative because the norms on $X$ and $Y$ are, i.e.,

$$
\begin{align*}
\|a b\|_{X \cap Y} & =\|a b\|_{X}+\|a b\|_{Y} \leq\|a\|_{X}\|b\|_{X}+\|a\|_{Y}\|b\|_{Y}  \tag{III.39}\\
& \leq\left(\|a\|_{X}+\|a\|_{Y}\right)\left(\|b\|_{X}+\|b\|_{Y}\right)=\|a\|_{X \cap Y}\|b\|_{X \cap Y} .
\end{align*}
$$

Now we are in position to show that $\mathcal{F}$ is locally Lipschitz-continuous on $\mathcal{R}_{\theta}$.
Lemma 4 Let $\theta=(\alpha, T, \rho)$ with $\alpha>0, T<\infty, \rho \in \mathbb{R}$, and $\underline{r}^{(0)} \in \mathcal{R}_{\theta}$. Then, for all $\underline{r}, \underline{\hat{r}} \in \mathcal{R}_{\theta}$, we have

$$
\begin{equation*}
\|\mathcal{F}[\underline{r}]-\mathcal{F}[\underline{\hat{r}}]\|_{\theta} \leq \frac{2 e^{\alpha T-\rho}}{\alpha}\left(\|\underline{r}\|_{\theta}+\|\underline{\hat{r}}\|_{\theta}\right)\|\underline{r}-\underline{\hat{r}}\|_{\theta} \tag{III.40}
\end{equation*}
$$

Proof: We first remark that

$$
\begin{gather*}
F_{n}[\underline{r}]-F_{n}[\underline{\hat{r}}]=\sum_{\nu=1}^{n}\binom{n}{\nu}\left\{\left[r_{\nu+1}, r_{n-\nu}\right]-\left[\hat{r}_{\nu+1}, \hat{r}_{n-\nu}\right]\right\}  \tag{III.41}\\
=\sum_{\nu=1}^{n}\binom{n}{\nu}\left(\left[r_{\nu+1}-\hat{r}_{\nu+1}, r_{n-\nu}\right]+\left[\hat{r}_{\nu+1}, r_{n-\nu}-\hat{r}_{n-\nu}\right]\right)
\end{gather*}
$$

and thus

$$
\left.\begin{array}{l}
\|\mathcal{F}[\underline{r}]-\mathcal{F}[\hat{r}]\|_{\theta}  \tag{III.42}\\
\leq \sum_{n=0}^{\infty} \frac{e^{\rho n}}{n!} \max _{t \in[0, T]} \| e^{-\alpha n t} \sum_{\nu=1}^{n}\binom{n}{\nu} \int_{0}^{t}\left(\left[r_{\nu+1}(\tau)-\hat{r}_{\nu+1}(\tau), r_{n-\nu}(\tau)\right]\right. \\
\\
\left.\quad+\left[\hat{r}_{\nu+1}(\tau), r_{n-\nu}(\tau)-\hat{r}_{n-\nu}(\tau)\right]\right) d \tau \|_{X \cap Y} \\
\leq \sum_{n=0}^{\infty} \sum_{\nu=1}^{n} \max _{t \in[0, T]}\left\{\frac { 2 e ^ { \rho n } e ^ { - \alpha n t } } { \nu ! ( n - \nu ) ! } \int _ { 0 } ^ { t } \left(\left\|r_{\nu+1}(\tau)-\hat{r}_{\nu+1}(\tau)\right\|_{X \cap Y}\left\|r_{n-\nu}(\tau)\right\|_{X \cap Y}\right.\right. \\
\left.+\left\|\hat{r}_{\nu+1}(\tau)\right\|_{X \cap Y}\left\|r_{n-\nu}(\tau)-\hat{r}_{n-\nu}(\tau)\right\|_{X \cap Y}\right) d \tau
\end{array}\right\} \begin{aligned}
& \leq \sum_{n=0}^{\infty} \sum_{\nu=1}^{n} \frac{2(\nu+1)}{e^{\rho}} \max _{t \in[0, T]}\left\{e^{-\alpha n t} \int_{0}^{t} e^{\alpha(n+1) \tau} d \tau\right\}\left(d_{\nu+1} c_{n-\nu}+\hat{c}_{\nu+1} d_{n-\nu}\right),
\end{aligned}
$$

where

$$
\begin{align*}
c_{n} & :=\frac{e^{\rho n}}{n!} \max _{t \in[0, T]}\left\{e^{-\alpha n t}\left\|r_{n}(t)\right\|_{X \cap Y}\right\}  \tag{III.43}\\
\hat{c}_{n} & :=\frac{e^{\rho n}}{n!} \max _{t \in[0, T]}\left\{e^{-\alpha n t}\left\|\hat{r}_{n}(t)\right\|_{X \cap Y}\right\}  \tag{III.44}\\
d_{n} & :=\frac{e^{\rho n}}{n!} \max _{t \in[0, T]}\left\{e^{-\alpha n t}\left\|r_{n}(t)-\hat{r}_{n}(t)\right\|_{X \cap Y}\right\} \tag{III.45}
\end{align*}
$$

We observe that

$$
\begin{equation*}
\frac{\nu+1}{e^{\rho}} \max _{t \in[0, T]}\left\{e^{-\alpha n t} \int_{0}^{t} e^{\alpha(n+1) \tau} d \tau\right\} \leq \frac{\nu+1}{\alpha(n+1)} \max _{t \in[0, T]}\left\{e^{\alpha t-\rho}\right\} \leq \frac{e^{\alpha T-\rho}}{\alpha} \tag{III.46}
\end{equation*}
$$

Inserting this into (III.42) and using $\sum_{n=0}^{\infty} c_{n}=\|\underline{r}\|_{\theta}, \sum_{n=0}^{\infty} \hat{c}_{n}=\|\underline{\hat{r}}\|_{\theta}$, and $\sum_{n=0}^{\infty} d_{n}=\|\underline{r}-\underline{\hat{r}}\|_{\theta}$, we arrive at (III.40).

The following Lemma 5 asserts that $\mathcal{F}$ maps small balls in $\mathcal{R}_{\theta}$ into itself. The proof is omitted, as it is very similar to the one for Lemma 4.

Lemma 5 Let $\theta=(\alpha, T, \rho)$ with $\alpha>0, T<\infty, \rho \in \mathbb{R}$, and $\underline{r}^{(0)} \in \mathcal{R}_{\theta}$. Then, for all $\underline{r} \in \mathcal{R}_{\theta}$, we have

$$
\begin{equation*}
\|\mathcal{F}[\underline{r}]\|_{\theta} \leq\left\|\underline{r}^{(0)}\right\|_{\theta}+\frac{2 e^{\alpha T-\rho}}{\alpha}\|\underline{r}\|_{\theta}^{2} \tag{III.47}
\end{equation*}
$$

## Proof of Theorem 2:

(i) We first choose $\alpha:=8 e^{1+\eta-\rho}=T_{*}^{-1}$ and $T<T_{*}$, so that $\alpha T<1$ and

$$
\begin{equation*}
\frac{2 e^{\alpha T-\rho}}{\alpha}<\frac{e^{1-\rho}}{4 e^{1+\eta-\rho}}=\frac{e^{-\eta}}{4} \tag{III.48}
\end{equation*}
$$

We set $r_{n}^{(0)}:=R_{n}\left(H_{0}\right)$ and $\underline{r}^{(0)}:=\left(r_{n}^{(0)}\right)_{n=0}^{\infty}$. Identifying $\underline{r}^{(0)}$ with the corresponding constant vector $\underline{r}^{(0)}(\cdot):=\underline{r}^{(0)} \in \mathcal{R}_{\theta}$, we have

$$
\begin{equation*}
\left\|\underline{r}^{(0)}\right\|_{\theta} \leq e^{\eta} \tag{III.49}
\end{equation*}
$$

with $\theta=(\alpha, T, \rho)$. In particular,

$$
\begin{equation*}
\underline{r}^{(0)} \in B:=\left\{\underline{r} \in \mathcal{R}_{\theta} \mid\|\underline{r}\|_{\theta} \leq 2 e^{\eta}\right\} \tag{III.50}
\end{equation*}
$$

Moreover, for $\underline{r} \in B$, we observe that due to Lemma 5, (III.48), and (III.49), we have

$$
\begin{equation*}
\|\mathcal{F}[\underline{r}]\|_{\theta} \leq\left\|\underline{r}^{(0)}\right\|_{\theta}+\frac{e^{-\eta}}{4}\|\underline{r}\|_{\theta}^{2} \leq 2 e^{\eta} \tag{III.51}
\end{equation*}
$$

and thus $\mathcal{F}$ leaves $B$ invariant, i.e.,

$$
\begin{equation*}
\mathcal{F}[B] \subseteq B \tag{III.52}
\end{equation*}
$$

Furthermore, for any $\underline{r}, \underline{\hat{r}} \in B$ with $\underline{r} \neq \underline{\hat{r}}$, we have

$$
\begin{equation*}
\frac{\|\mathcal{F}[\underline{r}]-\mathcal{F}[\underline{\hat{r}}]\|_{\theta}}{\|\underline{r}-\underline{\hat{r}}\|_{\theta}} \leq \frac{2 e^{\alpha T-\rho}}{\alpha}\left(2 e^{\eta}+2 e^{\eta}\right)<1 \tag{III.53}
\end{equation*}
$$

and $\mathcal{F}: B \rightarrow B$ is a contraction. By the contraction mapping principle, $\mathcal{F}$ has a unique fixed point in $B$ which we denote $\underline{S}$. Clearly, $\underline{S}=:\left(S_{n}(\cdot)\right)_{n=0}^{\infty}$ is the unique $(X \cap Y)^{\mathbb{N}_{0}}$-valued smooth solution of (III.28) with initial value $\left(S_{n}(0)\right)_{n=0}^{\infty}=\left(R_{n}\left(H_{0}\right)\right)_{n=0}^{\infty}$. In particular,
$i S_{1} \in C^{\infty}([0, T] ; X \cap Y), \quad i S_{1}(t)=-i S_{1}^{*}(t) \in X, \quad\left\|S_{1}(t)\right\|_{X \cap Y} \leq 2 e^{\eta-\rho+\alpha t}$,
for all $t \in[0, T]$, defines a smooth family of bounded self-adjoint operators, and thus

$$
\begin{equation*}
\dot{U}_{t}=-S_{1}(t) U_{t}, \quad U_{0}=1 \tag{III.55}
\end{equation*}
$$

defines a smooth family $U_{(\cdot)} \in C^{\infty}([0, T] ; X \cap Y)$ of unitary operators on $\mathscr{H}$. Equivalently to (III.55), the family $U_{(\cdot)}$ is determined by $\dot{U}_{t}^{*}=U_{t}^{*} S_{1}(t)$ and $U_{0}^{*}=1$. Hence, we have the norm bound

$$
\begin{equation*}
\left\|U_{t}^{*}\right\|_{Y} \leq \exp \left[\int_{0}^{t}\left\|S_{1}(\tau)\right\|_{Y} d \tau\right] \leq \exp \left[\frac{2 e^{\eta-\rho+\alpha t}}{\alpha}\right] \leq \exp \left[\frac{e^{-\alpha(T-t)}}{4}\right] \tag{III.56}
\end{equation*}
$$

Setting

$$
\begin{equation*}
H_{t}:=U_{t} H_{0} U_{t}^{*}, \tag{III.57}
\end{equation*}
$$

we observe that $H_{(\cdot)} \in C^{\infty}([0, T] ; \mathcal{B}[\mathscr{D}, \mathscr{H}])$ is a smooth family of self-adjoint operators defined on $\mathscr{D}$ obeying

$$
\begin{equation*}
\left\|H_{t} A^{-1}\right\|_{X} \leq\left\|H_{0} A^{-1}\right\|_{X} \cdot\left\|U_{t}\right\|_{Y} \leq 2\left\|H_{0} A^{-1}\right\|_{X} \tag{III.58}
\end{equation*}
$$

for all $t \in[0, T]$. (Here we use $e^{s / 4} \leq 2$ for $s \leq 1$.) Moreover, $H_{(\cdot)}$ solves the Cauchy Problem

$$
\begin{equation*}
\dot{H}_{t}=\left[H_{t}, S_{1}(t)\right], \quad H_{0}=H . \tag{III.59}
\end{equation*}
$$

We introduce the family $\underline{Q}:=\left(Q_{n}\right)_{n \in \mathbb{N}} \in C^{\infty}\left([0, T] ;(X \cap Y)^{\mathbb{N}_{0}}\right)$ by

$$
\begin{equation*}
\forall n \in \mathbb{N}_{0}, t \in[0, T]: \quad Q_{n}(t)=\left[H_{t}, S_{n}(t)\right]-S_{n+1}(t) \tag{III.60}
\end{equation*}
$$

Note that the initial value vanishes, $Q_{n}(0)=0$, for all $n \in \mathbb{N}$. We observe that (suppressing the time parameter) by Leibniz' rule and Jacobi's identity

$$
\begin{align*}
& \partial_{t}\left[H, S_{n}\right]=\left[\dot{H}, S_{n}\right]+\left[H, \dot{S}_{n}\right]  \tag{III.61}\\
& \quad=\left[\left[H, S_{1}\right], S_{n}\right]+\sum_{\nu=1}^{n}\binom{n}{\nu}\left[H,\left[S_{\nu+1}, S_{n-\nu}\right]\right] \\
& \quad=\left[\left[H, S_{1}\right], S_{n}\right]+\sum_{\nu=1}^{n}\binom{n}{\nu}\left\{\left[\left[H, S_{\nu+1}\right], S_{n-\nu}\right]+\left[S_{\nu+1},\left[H, S_{n-\nu}\right]\right]\right\}
\end{align*}
$$

while, as in (III.34)

$$
\begin{equation*}
\dot{S}_{n+1}=\left[S_{2}, S_{n}\right]+\sum_{\nu=1}^{n}\binom{n}{\nu}\left(\left[S_{\nu+2}, S_{n-\nu}\right]+\left[S_{\nu+1}, S_{n-\nu+1}\right]\right) . \tag{III.62}
\end{equation*}
$$

Consequently,

$$
\begin{equation*}
\dot{Q}_{n}=\left[Q_{1}, S_{n}\right]+\sum_{\nu=1}^{n}\binom{n}{\nu}\left(\left[Q_{\nu+1}, S_{n-\nu}\right]+\left[S_{\nu+1}, Q_{n-\nu}\right]\right), \tag{III.63}
\end{equation*}
$$

which in turn implies that

$$
\begin{align*}
& \frac{\left\|\dot{Q}_{n}\right\|_{X \cap Y}}{n!} \leq  \tag{III.64}\\
& \quad 2 \sum_{\nu=0}^{n}(\nu+1)\left\{\frac{\left\|Q_{\nu+1}\right\|_{X \cap Y}}{(\nu+1)!} \frac{\left\|S_{n-\nu}\right\|_{X \cap Y}}{(n-\nu)!}+\frac{\left\|S_{\nu+1}\right\|_{X \cap Y}}{(\nu+1)!} \frac{\left\|Q_{n-\nu}\right\|_{X \cap Y}}{(n-\nu)!}\right\} .
\end{align*}
$$

Now, an estimation as in (III.42), taking $Q_{n}(0)=0$ and $\|\underline{S}\|_{\theta} \leq 2 e^{\eta}$ into account, yields

$$
\begin{equation*}
\|\underline{Q}\|_{\theta} \leq 4 \frac{e^{\alpha T-\rho}}{\alpha}\|\underline{S}\|_{\theta}\|\underline{Q}\|_{\theta} \leq \frac{e^{\alpha T-\rho}}{\alpha} \frac{8}{e^{-\eta}}\|\underline{Q}\|_{\theta} \tag{III.65}
\end{equation*}
$$

Since $\frac{e^{\alpha T-\rho}}{\alpha}<\frac{e^{-\eta}}{8}$, this estimate implies that $\|\underline{Q}\|_{\theta}=0$, i.e.,

$$
\begin{equation*}
\forall n \in \mathbb{N}_{0}, t \in[0, T]: \quad\left[H_{t}, S_{n}(t)\right]=S_{n+1}(t) \tag{III.66}
\end{equation*}
$$

This in turn gives

$$
\begin{equation*}
\dot{S}_{1}-\dot{R}_{1}=\left[S_{2}, A^{-1}\right]-\left[\dot{H}, A^{-1}\right]=\left[S_{2}-\left[H, S_{1}\right], A^{-1}\right]=0 \tag{III.67}
\end{equation*}
$$

hence $S_{1}(t)=R_{1}(t)=\left[H_{t}, A^{-1}\right]$ and

$$
\begin{equation*}
\dot{H}_{t}=\left[H_{t},\left[H_{t}, A^{-1}\right]\right] \tag{III.68}
\end{equation*}
$$

for all $t>0$. In other words: $H_{(\cdot)}$ is a smooth solution of the original evolution equation (III.23).
(ii) Let $\widetilde{H}_{(\cdot)} \in C^{\infty}([0, T] ; \mathcal{B}[\mathscr{D}, \mathscr{H}])$ be another solution of (III.23), possibly different from $H_{(\cdot)}$ found in (i). We denote $R_{n}:=R_{n}\left(H_{t}\right)$, as before, and $\widetilde{R}_{n}:=R_{n}\left(\widetilde{H}_{t}\right)$. According to Lemma 3, both $\underline{R}=\left(R_{n}\right)_{n=0}^{\infty}$ and $\underline{\widetilde{R}}=\left(\widetilde{R}_{n}\right)_{n=0}^{\infty}$ solve (III.28). By the uniqueness of its solution, due to the fact that $\mathcal{F}$ is a contraction on $B$, we have $\underline{\widetilde{R}}=\underline{R}$ and in particular $\widetilde{R}_{1}=R_{1}=S_{1}$. This, in turn, implies that

$$
\begin{equation*}
\dot{H}-\dot{\widetilde{H}}=\left[H, R_{1}\right]-\left[\widetilde{H}, \widetilde{R}_{1}\right]=\left[H-\widetilde{H}, S_{1}\right] \tag{III.69}
\end{equation*}
$$

and hence

$$
\begin{equation*}
\left\|(\dot{H}-\dot{\widetilde{H}}) A^{-1}\right\|_{X} \leq\left\|(H-\widetilde{H}) A^{-1}\right\|_{X}\left\|S_{1}\right\|_{Y}+\left\|S_{1}\right\|_{X}\left\|(H-\widetilde{H}) A^{-1}\right\|_{X} \tag{III.70}
\end{equation*}
$$

It follows from $T<T_{*}=e^{\rho-\eta-1} / 8$ and (III.54) that

$$
\begin{align*}
\max _{0 \leq t \leq T}\left\|\left(H_{t}-\widetilde{H}_{t}\right) A^{-1}\right\|_{X} & \leq 2 T\left\|S_{1}\right\|_{X \cap Y} \max _{0 \leq t \leq T}\left\|(H-\widetilde{H}) A^{-1}\right\|_{X} \\
& \leq \frac{1}{2} \max _{0 \leq t \leq T}\left\|(H-\widetilde{H}) A^{-1}\right\|_{X} \tag{III.71}
\end{align*}
$$

which finally implies $\widetilde{H}_{t}=H_{t}$, for all $t \in[0, T]$.

## IV Convergence on Hilbert-Schmidt Operators

In Sect. I it was assumed that $H=H^{*}, A=A^{*} \in \operatorname{Mat}(N, \mathbb{C})$ are two selfadjoint complex $N \times N$-matrices such that $A \geq 0$.

We generalize this now and study Hilbert-Schmidt operators $H=H^{*}, A=$ $A^{*} \in \mathcal{L}^{2}[\mathscr{H}]$, with $A \geq 0$, on a separable Hilbert space $\mathscr{H}$. We define the initial value $H_{0}:=H$ and study the flow equation

$$
\begin{equation*}
\forall t>0: \quad \dot{H}_{t}:=i\left[H_{t}, G_{t}\right], \quad G_{t}:=i\left[A, H_{t}\right] . \tag{IV.72}
\end{equation*}
$$

We use the fact proved in Section II that (IV.72) possesses a unique smooth global solution $H_{(\cdot)} \in C^{\infty}\left(\mathbb{R}_{0}^{+} ; \mathcal{L}^{2}[\mathscr{H}]\right)$. This follows from an application of Theorem 1, taking into account that the norm $\|M\|_{\mathrm{hs}}=\sqrt{\operatorname{Tr}\left\{M^{*} M\right\}}$ on $\mathcal{L}^{2}[\mathscr{H}]$ is unitarily invariant.

Lemma 6 Suppose $H_{0}:=H=H^{*}, A=A^{*} \in \mathcal{L}^{2}[\mathscr{H}]$ are two self-adjoint Hilbert-Schmidt operators on a separable Hilbert space $\mathscr{H}$ such that $A \geq 0$, and let $H_{(\cdot)} \in C^{\infty}\left(\mathbb{R}_{0}^{+} ; \mathcal{L}^{2}[\mathscr{H}]\right)$ be the unique solution of (IV.72). Then

$$
\begin{equation*}
\lim _{t \rightarrow \infty} i\left[A, H_{t}\right]=0 \tag{IV.73}
\end{equation*}
$$

Proof: We introduce

$$
\begin{equation*}
\forall t \geq 0: \quad g_{t}:=-\dot{f}_{t}=\operatorname{Tr}\left\{G_{t}^{2}\right\} \geq 0 \tag{IV.74}
\end{equation*}
$$

and observe that $g$ is integrable, namely

$$
\begin{equation*}
\int_{0}^{\infty} g_{t} d t=f_{0}-f_{\infty} \leq f_{0} \tag{IV.75}
\end{equation*}
$$

The integrability of $g$ alone, however, does not imply that $g(t) \rightarrow 0$, as $t \rightarrow \infty$, since $g$ could in principle have arbitrarily high bumps which are, yet, so narrow that they yield a small integral.

To conclude the convergence of $g$ and then of $H$, we compute

$$
\begin{align*}
\dot{g}(t) & =2 \operatorname{Tr}\left\{G_{t} \dot{G}_{t}\right\}=2 \operatorname{Tr}\left\{G_{t}\left[i A, \dot{H}_{t}\right]\right\} \\
& =2 \operatorname{Tr}\left\{\dot{H}_{t}\left[G_{t}, i A\right]\right\}=2 \operatorname{Tr}\left\{\left[i H_{t}, G_{t}\right]\left[-i A, G_{t}\right]\right\} \\
& \leq 2 \operatorname{Tr}\left\{\left[i\left(H_{t}-A\right), G_{t}\right]\left[-i A, G_{t}\right]\right\} \leq 8\|A\| f_{0}^{1 / 2} g_{t} . \tag{IV.76}
\end{align*}
$$

By Grønwall's Lemma, this differential inequality yields

$$
\begin{equation*}
\frac{g_{t}}{g_{s}} \leq \exp \left(8\|A\| f_{0}^{1 / 2}(t-s)\right) \tag{IV.77}
\end{equation*}
$$

for all $t \geq s \geq 0$. Applying this estimate to $s:=n \in \mathbb{N}_{0}$ and $t \in[n, n+1]$, we obtain

$$
\begin{equation*}
\sum_{n=0}^{\infty} g_{n} \leq e^{8\|A\| \sqrt{f_{0}}} \int_{0}^{\infty} g_{t} d t \leq f_{0} e^{8\|A\| \sqrt{f_{0}}} \tag{IV.78}
\end{equation*}
$$

from which we conclude the existence of a constant $C<\infty$, such that

$$
\begin{equation*}
g_{n} \leq \frac{C}{n+1} \tag{IV.79}
\end{equation*}
$$

Applying Estimate IV. 77 again, but with $t:=n \in \mathbb{N}$ and $s \in[n-1, n]$, we obtain

$$
\begin{equation*}
\forall s \geq 0: \quad g_{s} \leq \frac{C e^{8\|A\| \sqrt{f_{0}}}}{s} \tag{IV.80}
\end{equation*}
$$

and therefore, we arrive at the assertion thanks to

$$
\begin{equation*}
\forall t \geq 0: \quad \operatorname{Tr}\left\{\left[i A, H_{t}\right]^{2}\right\}=g_{t} \leq \frac{C e^{8\|A\| \sqrt{f_{0}}}}{t} \tag{IV.81}
\end{equation*}
$$

In the next theorem we prove the convergence of $H_{t}$, as $t \rightarrow \infty$, under the additional assumption that $A \geq 0$ has full rank. To be more explicit, we assume that $A=\sum_{j=1}^{\infty} \alpha_{j} Q_{j}$, where $Q_{j}=Q_{j}^{2}=Q_{j}^{*}$ are orthogonal projections of rank $n_{j}=\operatorname{Tr}\left\{Q_{j}\right\} \in \mathbb{N}$ and $\alpha_{1}>\alpha_{2}>\ldots>0$, with $\operatorname{Tr}\left\{A^{2}\right\}=$ $\sum_{j=1}^{\infty} \alpha_{j}^{2} n_{j}<\infty$.

Theorem 7 Suppose $H_{0} \equiv H=H^{*}, A=A^{*} \in \mathcal{L}^{2}[\mathscr{H}]$ are two self-adjoint Hilbert-Schmidt operators on a separable Hilbert space $\mathscr{H}$ such that $A>0$ has full rank. Let $H_{(\cdot)} \in C^{\infty}\left(\mathbb{R}_{0}^{+} ; \mathcal{L}^{2}[\mathscr{H}]\right)$ be the unique solution of (IV.72). Then

$$
\begin{equation*}
\lim _{t \rightarrow \infty} H_{t}=: H_{\infty} \tag{IV.82}
\end{equation*}
$$

converges strongly on $\mathscr{H}$, we have $\left[H_{\infty}, A\right]=0$, and there exists a unitary operator $W \in \mathcal{B}[\mathscr{H}]$ such that

$$
\begin{equation*}
H_{\infty}=W H_{0} W^{*} \tag{IV.83}
\end{equation*}
$$

Proof: As mentioned above, we assume without loss of generality that $A=$ $\sum_{j=1}^{\infty} \alpha_{j} Q_{j}$, where $Q_{j}=Q_{j}^{2}=Q_{j}^{*}$ are orthogonal projections of rank $n_{j}=$ $\operatorname{Tr}\left\{Q_{j}\right\} \in \mathbb{N}$ and $\alpha_{1}>\alpha_{2}>\ldots>0$, with $\operatorname{Tr}\left\{A^{2}\right\}=\sum_{j=1}^{\infty} \alpha_{j}^{2} n_{j}<\infty$.

We set $\alpha_{0}:=\infty$ and

$$
\begin{equation*}
\kappa_{j}:=\operatorname{dist}\left[\alpha_{j}, \sigma(A) \backslash\left\{\alpha_{j}\right\}\right]=\min \left\{\alpha_{j-1}-\alpha_{j}, \alpha_{j}-\alpha_{j+1}\right\}>0, \tag{IV.84}
\end{equation*}
$$

for all $j \in \mathbb{N}$. We first observe, for $j \in \mathbb{N}$, that due to (IV.74), we have

$$
\begin{align*}
\operatorname{Tr}\left\{Q_{j} H_{t} Q_{j}^{\perp} H_{t} Q_{j}\right\} & =\sum_{k=1}^{\infty}\left(1-\delta_{j, k}\right) \operatorname{Tr}\left\{Q_{j} H_{t} Q_{k} H_{t} Q_{j}\right\} \\
& \leq \frac{1}{\kappa_{j}^{2}} \sum_{k, \ell=1}^{\infty} \operatorname{Tr}\left\{Q_{\ell} H_{t} Q_{k} H_{t} Q_{\ell}\right\}\left(\alpha_{\ell}-\alpha_{k}\right)^{2} \\
& =\frac{1}{\kappa_{j}^{2}} \operatorname{Tr}\left\{\left[i A, H_{t}\right]^{2}\right\}=\frac{g_{t}}{\kappa_{j}^{2}} \tag{IV.85}
\end{align*}
$$

which shows that the off-diagonal matrix blocks $Q_{j} H_{t} Q_{j}^{\perp}$ and $Q_{j}^{\perp} H_{t} Q_{j}$ of $H_{t}$ tend to 0 , as $t \rightarrow \infty$. Next, we prove the convergence of the diagonal matrix blocks $Q_{j} H_{t} Q_{j}$. To this end, we observe that, for $1 \leq j<\infty$,

$$
\begin{align*}
\left\|Q_{j} \dot{H}_{t} Q_{j}\right\|_{\mathcal{L}^{1}[\mathscr{H}]} & =\left\|Q_{j} H_{t} G_{t} Q_{j}-Q_{j} G_{t} H_{t} Q_{j}\right\|_{\mathcal{L}^{1}[\mathscr{H}]} \\
& =\left\|Q_{j} H_{t} Q_{j}^{\perp} G_{t} Q_{j}-Q_{j} G_{t} Q_{j}^{\perp} H_{t} Q_{j}\right\|_{\mathcal{L}^{1}[\mathscr{H}]} \\
& \leq 2\left\|Q_{j} H_{t} Q_{j}^{\perp} G_{t} Q_{j}\right\|_{\mathcal{L}^{1}[\mathscr{H}]} \\
& =2\left\|\sum_{k=1}^{\infty} Q_{j} H_{t} Q_{k} H_{t} Q_{j}\left(\alpha_{j}-\alpha_{k}\right)\right\|_{\mathcal{L}^{1}[\mathscr{H}]} \\
& \leq 2 \sum_{k=1}^{\infty} \operatorname{Tr}\left\{Q_{j} H_{t} Q_{k} H_{t} Q_{j}\right\}\left|\alpha_{j}-\alpha_{k}\right| \\
& \leq \frac{2}{\kappa_{j}} \sum_{k, \ell=1}^{\infty} \operatorname{Tr}\left\{Q_{\ell} H_{t} Q_{k} H_{t} Q_{\ell}\right\}\left(\alpha_{\ell}-\alpha_{k}\right)^{2} \\
& =\frac{2}{\kappa_{j}} \operatorname{Tr}\left\{\left[i A, H_{t}\right]^{2}\right\}=\frac{2 g_{t}}{\kappa_{j}}, \tag{IV.86}
\end{align*}
$$

using that $Q_{j} G_{t}=Q_{j} G_{t} Q_{j}^{\perp}$ and $Q_{j} H_{t} Q_{k} H_{t} Q_{j} \geq 0$, where the latter implies that $\left\|Q_{j} H_{t} Q_{k} H_{t} Q_{j}\right\|_{\mathcal{L}^{1}[\mathscr{H}]}=\operatorname{Tr}\left\{Q_{j} H_{t} Q_{k} H_{t} Q_{j}\right\}$. Since $g_{t}$ is integrable, so is $\left\|Q_{j} \dot{H}_{t} Q_{j}\right\|_{\mathcal{L}^{1}[\mathscr{H}]}$, which establishes the desired convergence of the diagonal blocks $Q_{j} H_{t} Q_{j}$ in $\mathcal{L}^{1}[\mathscr{H}]$. It follows that $H_{t}$ converges strongly, i.e., (IV.82).

We proceed to proving (IV.83). Given $H_{\infty}:=\lim _{t \rightarrow \infty} H_{t}$, we invoke the spectral theorem to obtain its spectral decomposition

$$
\begin{equation*}
H_{\infty}=: \sum_{\ell=1}^{L} \lambda_{\ell} P_{\ell}, \tag{IV.87}
\end{equation*}
$$

where $\lambda_{1}<\lambda_{2}<\cdots<\lambda_{L}$ are its eigenvalues and $P_{1}, P_{2}, \ldots, P_{L}$ are its spectral projections (possibly $L=\infty$ ), i.e., orthogonal projections $P_{\ell}$ of rank
$n_{\ell} \geq 1$ (possibly, $n_{\ell}=\infty$, too). Choosing $r>0$ sufficiently small, these projections may be written as the Cauchy integral

$$
\begin{equation*}
P_{\ell}=\frac{1}{2 \pi i} \int_{|z|=r} \frac{d z}{z-H_{\infty}} \tag{IV.88}
\end{equation*}
$$

Next, define the simplex $\mathcal{S}:=\left\{(T, t) \in \mathbb{R}^{2} \mid 0 \leq t \leq T\right\}$ and let $\left(U_{T, t}\right)_{T \geq t \geq 0} \in$ $C^{\infty}(\mathcal{S} ; \mathcal{B}[\mathscr{H}])$ be the unique unitary solution of

$$
\begin{equation*}
\forall T>t \geq 0: \quad \partial_{T} U_{T, t}=-i G_{T} U_{T, t}, \quad U_{t, t}=\mathbf{1} \tag{IV.89}
\end{equation*}
$$

Note the cocyclicity $U_{T, t} U_{t, s}=U_{T, s}$, for $T \geq t \geq s \geq 0$. This property implies that

$$
\begin{equation*}
\forall T>t \geq 0: \quad H_{T}=U_{T, 0} H_{0} U_{T, 0}^{*}=U_{T, t} H_{t} U_{T, t}^{*} \rightarrow H_{\infty} \tag{IV.90}
\end{equation*}
$$

as $T \rightarrow \infty$, from which we obtain

$$
\begin{equation*}
\forall t \geq 0: \quad \lim _{T \rightarrow \infty}\left\{U_{T, t}^{*} H_{\infty} U_{T, t}\right\}=H_{t} \tag{IV.91}
\end{equation*}
$$

We then define $P_{\ell}(t)$ by

$$
\begin{equation*}
P_{\ell}(t):=\mathbf{1}\left(\left|H_{t}-\lambda_{\ell}\right|<r\right)=\frac{1}{2 \pi i} \int_{|z|=r} \frac{d z}{z-H_{t}} \tag{IV.92}
\end{equation*}
$$

for $t>0$ and sufficiently small $r>0$. Due to (IV.91), we have

$$
\begin{equation*}
P_{\ell}(t)=\lim _{T \rightarrow \infty}\left\{U_{T, t}^{*} P_{\ell} U_{T, t}\right\} \tag{IV.93}
\end{equation*}
$$

In particular, the rank of $P_{\ell}(t)$ is bounded by

$$
\begin{equation*}
\operatorname{rk}\left\{P_{\ell}(t)\right\} \leq n_{\ell} \tag{IV.94}
\end{equation*}
$$

Moreover,

$$
\begin{equation*}
\sum_{\ell=1}^{L} P_{\ell}(t)=\lim _{T \rightarrow \infty}\left\{U_{T, t}^{*}\left(\sum_{\ell=1}^{L} P_{\ell}\right) U_{T, t}\right\}=\mathbf{1} \tag{IV.95}
\end{equation*}
$$

Eqs. (IV.94) and (IV.95) yield $\operatorname{rk}\left\{P_{\ell}(t)\right\}=n_{\ell}$ and hence

$$
\begin{equation*}
H_{t}=\sum_{\ell=1}^{L} \lambda_{\ell} P_{\ell}(t) \tag{IV.96}
\end{equation*}
$$

is the spectral decomposition of $H_{t}$. For each $\ell$, we can now pick orthonormal bases $\left\{\varphi_{n} \mid 1 \leq n \leq n_{\ell}\right\}$ and $\left\{\psi_{n} \mid 1 \leq n \leq n_{\ell}\right\}$ of $\operatorname{Ran} P_{\ell}(0)$ and $\operatorname{Ran} P_{\ell}$, respectively. We then define a unitary $W \in \mathcal{B}[\mathscr{H}]$ by

$$
\begin{equation*}
\forall n \geq 1: \quad W \varphi_{n}:=\psi_{n} \tag{IV.97}
\end{equation*}
$$

and we clearly have

$$
\begin{equation*}
W H_{0} W^{*}=H_{\infty} . \tag{IV.98}
\end{equation*}
$$

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