

Convergence of Bender/Denk algorithm

L^2 -error estimates and rate of convergence for Monte Carlo
projection

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Approximate the following BSDE using a discretized scheme:

$$\begin{aligned} -dY_s &= f(s, X_s, Y_s, Z_s)ds - Z_s dW_s, \quad 0 \leq t < T \\ Y_T (= \xi) &= \Phi(X_T) \end{aligned}$$

- ▶ $(X_t)_{0 \leq t \leq T}$ diffusion with Lipschitz data (b, σ) ,
 $t \mapsto b(t, 0), \sigma(t, 0)$ bounded
- ▶ $(x, y, z) \mapsto f(t, x, y, z)$ and $x \mapsto \Phi(x)$ are Lipschitz continuous, $t \mapsto f(t, 0, 0, 0)$ bounded

Discretization: Time-grid with N points, $\Delta_k := t_{k+1} - t_k$,
 $|\pi| := \max_{0 \leq k \leq N-1} \Delta_k, \Delta W_{t_k} := W_{k+1} - W_k$

1. Select regression basis $p(x) = (\phi^1(x), \dots, \phi^M(x))$ such that for Euler simulation $(X_{t_k}^{(\pi)})_{0 \leq k \leq N}$, $\phi^i(X_{t_k}^{(\pi)}) \in L^2$ and $\mathbb{E}[p(X_{t_k}^{(\pi)})[p(X_{t_k}^{(\pi)})]^{tr}]$ invertible
Transform $v_{t_k} := (p(X_{t_k}^{(\pi)}), \frac{\Delta W_{t_k}}{\sqrt{\Delta_k}} p(X_{t_k}^{(\pi)})) \in \mathbb{R}^M \times \mathbb{R}^M$
2. Perform n Picard iterations for regression coefficients
 $\hat{\theta}_{t_k}^{(n)} = (\hat{\theta}_{Y,t_k}^{(n)}, \hat{\theta}_{Z,t_k}^{(n)}) \in \mathbb{R}^M \times \mathbb{R}^M$:

$$\hat{Y}_{t_j}^{(m)} := \hat{\theta}_{Y,t_j}^{(m)} \cdot p(X_{t_j}^{(\pi)}), \quad \hat{Z}_{t_j}^{(m)} := \frac{1}{\sqrt{\Delta_k}} \hat{\theta}_{Z,t_j}^{(m)} \cdot p(X_{t_j}^{(\pi)})$$

$$\hat{\theta}_{t_k}^{(m+1)} := \arg \min_{\theta} \mathbb{E} \left[\left| \xi^{(\pi)} - \sum_{j=k}^{N-1} f(t_j, X_{t_j}^{(\pi)}, \hat{Y}_{t_j}^{(m)}, \hat{Z}_{t_j}^{(m)}) \Delta_j - \theta \cdot v_{t_k} \right|^2 \right]$$

4. Projection estimators:

$$\hat{Y}_{t_j}^{(n)} := \hat{\theta}_{Y,t_j}^{(n)} \cdot p(X_{t_j}^{(\pi)}), \quad \hat{Z}_{t_j}^{(n)} := \frac{1}{\sqrt{\Delta_k}} \hat{\theta}_{Z,t_j}^{(n)} \cdot p(X_{t_j}^{(\pi)})$$

1. Select regression basis $p(x) = (\phi^1(x), \dots, \phi^M(x))$ such that for Euler simulation $(X_{t_k}^{(\pi)})_{0 \leq k \leq N}$, $\phi^i(X_{t_k}^{(\pi)}) \in L^2$ and $\mathbb{E}[p(X_{t_k}^{(\pi)})[p(X_{t_k}^{(\pi)})]^{tr}]$ invertible
2. Generate L independent simulations $\{(W_{t_k}^{(\pi,l)})_{0 \leq k \leq N}\}_{1 \leq l \leq L}$ of $(W_{t_k})_{0 \leq k \leq N}$ and Euler simulations $\{(X_{t_k}^{(\pi,l)})_{0 \leq k \leq N}\}_{1 \leq l \leq L}$
Transform $v_{t_k}^l := (p(X_{t_k}^{(\pi,l)}), \frac{\Delta W_{t_k}^l}{\sqrt{\Delta_k}} p(X_{t_k}^{(\pi,l)})) \in \mathbb{R}^M \times \mathbb{R}^M$
3. Perform n Picard iterations for regression coefficients
 $\hat{\theta}_{t_k}^{(n,L)} = (\hat{\theta}_{Y,t_k}^{(n,L)}, \hat{\theta}_{Z,t_k}^{(n,L)}) \in \mathbb{R}^M \times \mathbb{R}^M$:

$$\hat{Y}_{t_j}^{(m,L,l)} := \hat{\rho}_j \left(\hat{\theta}_{Y,t_j}^{(m,L)} \cdot p(X_{t_j}^{(\pi,l)}) \right), \quad \hat{Z}_{t_j}^{(m,L,l)} := \hat{\rho}_j \left(\frac{\hat{\theta}_{Z,t_k}^{(m,L)}}{\sqrt{\Delta_k}} \cdot p(X_{t_j}^{(\pi,l)}) \right)$$

$$\hat{\theta}_{t_k}^{(m+1,L)} := \arg \min_{\theta} \frac{1}{L} \sum_{l=1}^L \left[\left| \xi^{(\pi,l)} - \right.$$

$$\left. \sum_{j=k}^{N-1} f(t_j, X_{t_j}^{(\pi,l)}, \hat{Y}_{t_j}^{(m,L,l)}, \hat{Z}_{t_j}^{(m,L,l)}) \Delta_j - \theta \cdot v_{t_k}^l \right|^2 \Big]$$

4. Monte Carlo estimators:

$$\hat{Y}_{t_k}^{(n,L)} := \hat{\rho}_k \left(\hat{\theta}_{Y,t_k}^{(n,L)} \cdot p(X_{t_k}^{(\pi)}) \right), \quad \hat{Z}_{t_k}^{(n,L)} := \hat{\rho}_k \left(\frac{\hat{\theta}_{Z,t_k}^{(n,L)}}{\sqrt{\Delta_k}} \cdot p(X_{t_k}^{(\pi)}) \right)$$

Construction of truncation functions:

1. Take \mathbb{R} -valued functions $\rho(\cdot) := \max(1, C_0 |p(\cdot)|)$, with C_0 appropriately chosen
2. Choose $\phi \in C_b^2(\mathbb{R})$ such that $\phi(x) \mathbf{1}_{[-3/2, 3/2]}(x) = x$, $\|\phi\|_\infty \leq 2$, and $\|\phi'\|_\infty \leq 1$
3. $\hat{\rho}_k(x) := \rho \left(X_{t_k}^{(\pi)} \right) \cdot \phi \left(\frac{x}{\rho(X_{t_k}^{(\pi)})} \right)$

Properties:

- ▶ $\hat{\rho}_k(\hat{Y}_{t_k}^{(n)}) = \hat{Y}_{t_k}^{(n)}$ and $\hat{\rho}_k(\sqrt{\Delta_k} \hat{Z}_{t_k}^{(n)}) = \sqrt{\Delta_k} \hat{Z}_{t_k}^{(n)}$
- ▶ $|\hat{\rho}_k(x)| \leq 2\rho(X_{t_k}^{(\pi)}) \in L^2(X_{t_k}^{(\pi)}) \quad \forall x \in \mathbb{R}, 0 \leq k \leq N-1$
- ▶ Lipschitz continuous with Lipschitz constant 1

Normal equations: Set $V_{t_k}^L := \frac{1}{L} \sum_{l=1}^L v_{t_k}^l [v_{t_k}^l]^{tr}$

$$\mathbb{E} [v_{t_k} [v_{t_k}]^{tr}] \hat{\theta}_{t_k}^{(n+1)} = \mathbb{E} \left[v_{t_k} \left(\xi^{(\pi)} - \sum_{j=k}^{N-1} f(t_j, X_{t_j}^{(\pi)}, \hat{Y}_{t_j}^{(n)}, \hat{Z}_{t_j}^{(n)}) \Delta_j \right) \right]$$

$$V_{t_k}^L \hat{\theta}_{t_k}^{(n+1,L)} = \frac{1}{L} \sum_{l=1}^L v_{t_k}^l \left(\xi^{(\pi,l)} - \sum_{j=k}^{N-1} f(t_j, X_{t_j}^{(\pi,l)}, \hat{Y}_{t_j}^{(n,L,l)}, \hat{Z}_{t_j}^{(n,L,l)}) \Delta_j \right)$$

Want invertible $V_{t_k}^L$:

$$\mathcal{A}_{t_0}^L := \left\{ \begin{array}{l} |V_{t_k}^L - \mathbb{E}[v_{t_k} [v_{t_k}]^{tr}]| \leq |\pi|, \\ \forall q = 0, \dots, D, \text{ and } 0 \leq k \leq N-1 \end{array} \right\}$$

Task:

Find estimate for
$$\mathbf{Err}(n, \pi, L) = \max_{0 \leq k \leq N-1} \mathbb{E} |\hat{Y}_{t_k}^{(n)} - \hat{Y}_{t_k}^{(n,L)}|^2 + \sum_{k=0}^{N-1} \mathbb{E} |\hat{Z}_{t_k}^{(n)} - \hat{Z}_{t_k}^{(n,L)}|^2 \Delta_k$$

Use estimate to prove convergence and find rate of convergence
w.r.t. L

Theorem

Assume:

- ▶ $(X_{t_k}^{(\pi)})_{0 \leq k \leq N-1}, (p(X_{t_k}^{(\pi)}))_{0 \leq k \leq N-1}$ have fourth moments
- ▶ $|\pi| < \min(1, \bar{V})$ for $\bar{V} := \min_{0 \leq k \leq N-1} \lambda_{\text{MIN}}(\mathbb{E}[v_{t_k} [v_{t_k}]^{tr}])$

$$\mathbf{Err}(n, \pi, L) \leq C \sum_{k=0}^{N-1} \mathbb{E} \left[|\rho(P_{t_k}^{(\pi)})|^2 \mathbf{1}_{[\mathcal{A}_{t_0}^L]^c} \right] + \left(\frac{CN}{(1 - |\pi|)^2 L} + \frac{CN}{(\bar{V} - |\pi|) L} \right) \left(1 + e^{2KN} \sum_{m=1}^{n-1} (C|\pi|)^m \right)$$

First estimate of the error:

$$\mathbf{Err}(n, \pi, L) \leq C \sum_{k=0}^{N-1} \mathbb{E} \left[|\rho(X_{t_k}^{(\pi)})|^2 \mathbf{1}_{[\mathcal{A}_{t_0}^L]^c} \right] + \\ CN \max_{0 \leq k \leq N-1} \mathbb{E} \left[|\mathbf{1}_{\mathcal{A}_{t_0}^L} (\hat{\theta}_{t_k}^{(n,L)} - \hat{\theta}_{t_k}^{(n)})|^2 \right]$$

Decomposition:

$$\mathbf{1}_{\mathcal{A}_{t_0}^L} (\hat{\theta}_{t_k}^{(n,L)} - \hat{\theta}_{t_k}^{(n)}) = B_k^{(1,n)} + B_k^{(2,n)} + B_k^{(3,n)}$$

$$\text{Set } \hat{Y}_{t_j}^{(n-1,l)} := \hat{\theta}_{Y,t_j}^{(n-1)} \cdot p(X_{t_j}^{(\pi,l)}), \quad \hat{Z}_{t_j}^{(n-1,l)} := \frac{\hat{\theta}_{Z,t_j}^{(n-1)}}{\sqrt{\Delta_j}} \cdot p(X_{t_j}^{(\pi,l)})$$

$$B_k^{(1,n)} := \left([\mathbf{1}_{\mathcal{A}_{t_0}^L} V_{t_k}^L]^{-1} - \mathbb{E}[v_{t_k} [v_{t_k}]^{tr}]^{-1} \right) \times \\ \mathbb{E} \left[v_{t_k} \left(\xi^{(\pi)} - \sum_{j=k}^{N-1} f(t_j, X_{t_j}^{(\pi)}, \hat{Y}_{t_j}^{(n-1)}, \hat{Z}_{t_j}^{(n-1)}) \Delta_j \right) \right]$$

$$B_k^{(2,n)} := [\mathbf{1}_{\mathcal{A}_{t_0}^L} V_{t_k}^L]^{-1} \times \\ \left(\frac{1}{L} \sum_{l=1}^L v_{t_k}^l \left(\xi^{(\pi,l)} - \sum_{j=k}^{N-1} f(t_j, X_{t_j}^{(\pi,l)}, \hat{Y}_{t_j}^{(n-1,l)}, \hat{Z}_{t_j}^{(n-1,l)}) \Delta_j \right) \right. \\ \left. - \mathbb{E} \left[v_{t_k} \left(\xi^{(\pi)} - \sum_{j=k}^{N-1} f(t_j, X_{t_j}^{(\pi)}, \hat{Y}_{t_j}^{(n-1)}, \hat{Z}_{t_j}^{(n-1)}) \Delta_j \right) \right] \right)$$

$$B_k^{(3,n)} := \frac{[\mathbf{1}_{\mathcal{A}_{t_0}^L} V_{t_k}^L]^{-1}}{L} \sum_{l=1}^L v_{t_k}^l \left(\sum_{j=k}^{N-1} \left(f(t_j, X_{t_j}^{(\pi,l)}, \hat{Y}_{t_j}^{(n-1,l)}, \hat{Z}_{t_j}^{(n-1,l)}) \right. \right. \\ \left. \left. - f(t_j, X_{t_j}^{(\pi,l)}, \hat{Y}_{t_j}^{(n-1,L,l)}, \hat{Z}_{t_j}^{(n-1,L,l)}) \right) \Delta_j \right)$$

k -uniform L^2 -bounds for $B_k^{(q,n)}$

Define $\|\theta\|^2 = \max_{0 \leq k \leq N-1} \mathbb{E} \left[|\theta_k|^2 \mathbf{1}_{\mathcal{A}_{t_0}^L} \right]$

Assume:

- ▶ $(X_{t_k}^{(\pi)})_{0 \leq k \leq N-1}$, $(p(X_{t_k}^{(\pi)}))_{0 \leq k \leq N-1}$ have fourth moments
- ▶ $|\pi| < \min(1, \bar{V})$ for $\bar{V} := \min_{0 \leq k \leq N-1} \lambda_{MIN}(\mathbb{E}[v_{t_k}[v_{t_k}]^{tr}])$

$$(a) \quad \|(B_k^{(1,n)})\|^2 \leq C(1 - |\pi|)^{-2} L^{-1}$$

$$(b) \quad \|(B_k^{(2,n)})\|^2 \leq C(\lambda_{MIN}(\mathbb{E}[v_{t_k}[v_{t_k}]^{tr}]) - |\pi|)^{-1} L^{-1}$$

$$(c) \quad \mathbb{E} \|(B_k^{(3,n)})\|_0^2 \leq C|\pi|(\bar{V} - |\pi|)^{-1} \|(\hat{\theta}^{(n-1)} - \hat{\theta}^{(n-1,L)})\mathbf{1}_{\mathcal{A}_{t_0}^L}\|_0^2,$$

where $\|\theta\|_0 := \max_{0 \leq k \leq N-1} (e^{-2K(N-k)} |\theta_k|)$

Proof (c).

$$\begin{aligned}(\bar{V} - |\pi|) \| (B_k^{(3,n)}) \|_0^2 &\leq \max_{0 \leq k \leq N-1} e^{-2K(N-k)} \times \\ &\mathbb{E} \left[\mathbf{1}_{\mathcal{A}_{t_0}^L} \frac{1}{L} \sum_{l=1}^L \left| \sum_{j=k}^{N-1} (f_j^{(1,n-1,l)} - f_j^{(2,n-1,l)}) \Delta_j \right|^2 \right] \\ &\leq C |\pi| \max_{0 \leq k \leq N-1} e^{-2K(N-k)} \times \\ &\mathbb{E} \left[\sum_{j=k}^{N-1} e^{-2K(N-j)} \| (\hat{\theta}^{(n-1)} - \hat{\theta}^{(n-1,L)}) \mathbf{1}_{\mathcal{A}_{t_0}^L} \|_0^2 \right] \\ &\leq C |\pi| \| (\hat{\theta}^{(n-1)} - \hat{\theta}^{(n-1,L)}) \mathbf{1}_{\mathcal{A}_{t_0}^L} \|_0^2 \quad \square\end{aligned}$$

2-dimensional Brownian motion $(W_t)_{0 \leq t \leq T}$

- ▶ $dX_t = X_t \sigma dW_t$, $x = 1$, $\sigma = (1, 0)$
- ▶ $-dY_t = P(Z_t)dt - Z_t dW_t$, $P(z) = |z_2|$, $\Phi(x) = (x_1 - K)_+$
with $K = 0.7$, $T = 1$

Statistical tool: average residual sum of squares (RSS) between the true and simulated Y -solution at each time point

$$RSS = \frac{1}{1000} \sum_{l=0}^{1000} \sum_{k=0}^{N-1} |\hat{Y}_{t_k}^{(n,L)}(\omega_l) - Y_{t_k}(\omega_l)|^2$$

Table containing mean and standard deviation of RSS over 50 runs of the algorithm for different sample size L and time-grid sizes N

Basis: "Ideal basis"

$$\phi^1(x) = x\Phi(d_+(x, T - t_k)) - K\Phi(d_-(x, T)), \quad \phi^2(x) = \Phi(d_-(x, t_k))$$
$$d_+(x, t) = \frac{\log(\frac{x}{K}) + t/2}{\sqrt{t}}, \quad d_-(x, t) = \frac{\log(\frac{x}{K}) - t/2}{\sqrt{t}}$$

Number of Picard iterations: $n = 6$

Grid size N	5	10	15
Mean	0.240	0.568	2.13
Std dev.	0.225	0.571	3.48

Table containing mean and standard deviation of RSS over 50 runs of the algorithm for different sample size L and time-grid sizes N

Basis: log-Hermite polynomials up to degree 8

Number of Picard iterations: $n = 7$

	Sample size L	10^3	10^4	10^5
$N = 5$	Mean	20.1	0.325	2.02×10^{-2}
	Std Dev.	57.5	1.29	1.05×10^{-2}
$N = 10$	Mean	38.8	2.58	3.01×10^{-2}
	Std Dev.	69.1	10.1	2.59×10^{-2}
$N = 15$	Mean	58.2	3.89	0.114
	Std Dev.	116.9	8.41	4.89×10^{-2}

Table containing mean and standard deviation of RSS over 50 runs of the algorithm for different sample size L

Basis: log-Hermite polynomials up to degree 20

Number of Picard iterations: $n = 7$

	Sample size L	10^3	10^4	10^5
$N = 10$	Mean	2.8×10^{12}	2.97×10^5	4.03×10^{-2}
	Std Dev.	1.38×10^{13}	1.35×10^6	2.42×10^{-2}

Thank you for your attention!

References

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