

CONVEX RISK MEASURES UNDER MODEL UNCERTAINTY

Jocelyne Bion-Nadal
CNRS-CMAP Ecole Polytechnique
joint work with Magali Kervarec

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INTRODUCTION

DYNAMIC RISK MEASURES ON A FILTERED PROBABILITY SPACE
 $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in \mathbb{R}^+}, P)$ filtered probability space with a right continuous filtration.

- Coherent Dynamic Risk Measures: Delbaen (2002) and Artzner, Delbaen, Eber, Heath, Ku (2007)
- Convex dynamic risk measures considered in many papers, among them: Frittelli and Rosazza Gianin (2002), Klöppel, Schweizer (2007), Cheredito, Delbaen, Kupper (2006), Bion-Nadal (2008 and 2009), Föllmer and Penner (2006)
- g expectations or Backward Stochastic Differential Equations : Peng (2004), Rosazza Gianin (2004) and Barrieu El Karoui (2009)

DYNAMIC RISK MEASURES

DYNAMIC RISK MEASURES:

on $L^\infty(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in \mathbb{R}^+}, P)$ (or $L^p(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in \mathbb{R}^+}, P)$, $1 < p < \infty$).

$\rho_{\sigma, \tau} : L^\infty(\Omega, \mathcal{F}_\tau, P) \rightarrow L^\infty(\Omega, \mathcal{F}_\sigma, P)$, satisfying monotonicity, convexity, translation invariance and continuity from above.

- Time Consistency :

$$\forall \nu \leq \sigma \leq \tau, \quad \rho_{\nu, \tau}(X) = \rho_{\nu, \sigma}(-\rho_{\sigma, \tau}(X))$$

- Normalized ($\rho_{\sigma, \tau}(0) = 0$) time consistent dynamic risk measures have càdlàg paths (J B N 2009). Regularity is satisfied without the normalization assumption under some continuity assumption on the penalty,
- Families of dynamic risk measures constructed from right continuous BMO martingales generalizing B.S. D. E. and allowing for jumps. (J B N 2008 and 2009).

TIME CONSISTENT DYNAMIC RISK MEASURES FROM BMO MARTINGALES

THEOREM

Let $(M_i)_{i \leq j}$ be strongly orthogonal right continuous BMO martingales. Let $\mathcal{M} = \{\sum H_i \cdot M_i, H_i \text{ predictable}\}$. Let \mathcal{S} be a stable subset of $\mathcal{Q}(\mathcal{M}) = \{Q_M \mid \frac{dQ_M}{dP} = \mathcal{E}(M) \mid M \in \mathcal{M}\}$. Let b_i be measurable on $\mathbf{R}^+ \times \Omega \times \mathbf{R}^j$ admitting a quadratic bound from below. For $M = \sum H_i \cdot M_i$,

$$\alpha_{\sigma, \tau}(Q_M) = E_{Q_M} \left(\int_{\sigma}^{\tau} b_i(s, \omega, H_1(\omega), \dots, H_j(\omega)) d[M_i, M_i]_s(\omega) \mid \mathcal{F}_{\sigma} \right)$$

- If M_i are continuous
- or if the BMO norms of elements of \mathcal{S} are bounded by $m < \frac{1}{16}$,

$$\rho_{\sigma, \tau}(X) = \text{esssup}_{Q_M \in \mathcal{S}, Q_M|_{\mathcal{F}_{\sigma}} = P} (E_{Q_M}(-X \mid \mathcal{F}_{\sigma}) - \alpha_{\sigma, \tau}(Q_M))$$

defines a time consistent dynamic risk measure.

BROWNIAN FILTRATION

These examples generalize the B.S.D.E. (which are convex and translation invariant)

QUADRATIC BACKWARDS Every solution of a BSDE with a convex driver independent of y and quadratic in z admits a dual representation of the preceding form (Barrieu and El Karoui 2009).

NORMALIZED TIME CONSISTENT DYNAMIC RISK MEASURES IN A BROWNIAN FILTRATION For every normalized time consistent dynamic risk measure on the Brownian filtration the penalty term associated to $(\frac{dQ}{dP}) = \mathcal{E}(q.B)$ can be written:

$$c_{\sigma, \tau}(Q) = E_Q\left(\int_{\sigma}^{\tau} f(u, q_u) du \mid \mathcal{F}_{\sigma}\right) \quad \forall 0 \leq \sigma \leq \tau$$

Delbaen Peng and Rosazza Gianin (2009)

MODEL UNCERTAINTY

FINANCIAL FRAMEWORK: No reference probability measure is given.
Instead a weakly relatively compact set of probability measures is given.

Motivations:

EXAMPLE OF UNCERTAIN VOLATILITY

$$dX_t^\sigma = b_t dt + \sigma_t dW_t \quad \sigma_t \in [\underline{\sigma}, \bar{\sigma}]$$

The set of the laws of X_t^σ : weakly relatively compact set \mathcal{P} of probability measures not all absolutely continuous with respect to some probability measure.

DENIS MARTINI (2006)

$\Omega = \mathcal{C}_0(\mathbf{R}^+, \mathbf{R}^d)$, B_t coordinate process.

\mathcal{P} : weakly relatively compact set of orthogonal martingale measures for B_t

Pricing function $\Lambda(f) = \sup_{P \in \mathcal{P}} E_P(f)$.

INTRODUCTION

S. PENG: G-EXPECTATIONS (2007), (2008)

G-expectation \mathbb{E} is defined on Lip , subset of $\mathcal{C}_b(\Omega)$ using PDE.

DENIS HU PENG (2010) Every G expectation admits the representation

$$\forall f \in Lip \quad \mathbb{E}(f) = \sup_{P \in \mathcal{P}^1} E_P(f)$$

\mathcal{P}^1 is weakly relatively compact.

In both cases, $\Pi(f) = \sup_{P \in \mathcal{P}} E_P(f)$ \mathcal{P} weakly relatively compact.

Π is sublinear monotone translation invariant and regular $\Pi(X_n) \rightarrow 0$ when $X_n \downarrow 0$.

SONER, TOUZI, ZHANG (2010), NUTZ (2010)

Same framework $\Omega = \mathcal{C}_0(\mathbf{R}^+, \mathbf{R}^d)$, \mathcal{P} is a set of probability measures.

$$\Pi(f) = \sup_{P \in \mathcal{P}} E_P(f)$$

- Either $f \in \mathcal{C}_b(\Omega)$ and \mathcal{P} is weakly relatively compact.
- Or $f \in \mathcal{UC}_b(\Omega)$ and no restriction on \mathcal{P} .

INTRODUCTION

REGULAR CONVEX RISK MEASURES ON $\mathcal{C}_b(\Omega)$

Ω is a Polish space. For example $\Omega = \mathcal{C}(\mathbf{R}^+, \mathbf{R}^d)$ or $\Omega = D([0, \infty[, \mathbf{R}^d)$ the space of càdlàg functions, endowed with the Skorokhod topology.

Regularity (for sublinear risk measures): $\rho(-X_n) \rightarrow 0$ when $X_n \downarrow 0$.

Regularity \iff continuity with respect to a certain capacity c .

If ρ is sublinear, $c(X) = \rho(-|X|)$

$c(f) = \sup_{P \in \mathcal{P}} E_P(|f|)$ \mathcal{P} weakly relatively compact.

$L^1(c)$ Banach space obtained by completion and separation of $\mathcal{C}_b(\Omega)$ for the semi-norm c .

$L^1(c)$: introduced by Feyel and de la Pradelle (1989).

Thus we study $L^1(c)$ and convex risk measures on $L^1(c)$.

We prove that there is an equivalence class of probability measures canonically associated to ρ , characterizing the riskless elements.

OUTLINE

- 1 $L^1(c)$
 - Topological properties of the dual space of $L^1(c)$
 - Convex risk measures on $L^1(c)$
- 2 EQUIVALENCE CLASS OF PROBABILITY MEASURES ASSOCIATED TO A NON DOMINATED SET OF PROBABILITY MEASURES
- 3 REGULAR CONVEX RISK MEASURES ON $\mathcal{C}_b(\Omega)$
 - Examples

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CAPACITY

Ω : Polish space (metrizable and separable space and complete for some metric defining the topology)

\mathcal{L} : linear vector subspace of $\mathcal{C}_b(\Omega)$ containing the constants, generating the topology of Ω and which is a vector lattice.

CAPACITY

DEFINITION

a capacity on \mathcal{L} is a semi norm c defined on \mathcal{L} satisfying the following properties:

- 1 monotonicity: $\forall f, g \in \mathcal{L}$ such that $|f| \leq |g|$, $c(f) \leq c(g)$
- 2 regularity along sequences: for every sequence $f_n \in \mathcal{L}$ decreasing to 0, $\lim c(f_n) = 0$

THE BANACH SPACE $L^1(c)$

EXTENSION OF THE CAPACITY Feyel and de la Predelle (1989)

The semi-norm c is extended to all real functions on Ω :

$$\forall f \text{ l.s.c.}, f \geq 0, \quad c(f) = \sup\{c(\phi) \mid 0 \leq \phi \leq f, \phi \in \mathcal{L}\} \quad (1)$$

$$\forall g, \quad c(g) = \inf\{c(f) \mid f \geq |g|, f \text{ l.s.c.}\} \quad (2)$$

THE BANACH SPACE $L^1(c)$

$\mathcal{L}^1(c)$: closure of \mathcal{L} in the set $\{g \mid c(g) < \infty\}$.

$\mathcal{L}^1(c)$ contains $\mathcal{C}_b(\Omega)$. (Feyel and de la Pradelle)

Let $L^1(c)$ be the quotient of $\mathcal{L}^1(c)$ by the c null elements.

$L^1(c)$ is a Banach space.

THE DUAL SPACE OF $L^1(c)$

PROPOSITION

Let c be a capacity on a Polish space Ω . Every continuous linear form L on $L^1(c)$ admits a representation:

$$L(f) = \int f d\mu \quad \forall f \in L^1(c) \quad (3)$$

where μ is a regular bounded signed measure defined on a σ -algebra containing the Borel σ -algebra of Ω denoted $\mathcal{B}(\Omega)$.

If L is a non negative linear form, the measure μ is non negative finite.

TOPOLOGICAL PROPERTIES OF THE DUAL SPACE OF $L^1(c)$

WEAK AND WEAK* TOPOLOGIES

- Weak topology on $\mathcal{M}_+(\Omega)$, the set of non negative finite measures on $(\Omega, \mathcal{B}(\Omega))$:
coarsest topology for which the mappings

$$\mu \in \mathcal{M}_+(\Omega) \rightarrow \int f d\mu$$

are continuous for every given f in $\mathcal{C}_b(\Omega)$.

- Weak* topology on $L^1(c)^*$: $\sigma(L^1(c)^*, L^1(c))$ topology
i.e. coarsest topology for which the mappings

$$L \in L^1(c)^* \rightarrow L(X)$$

are continuous for every given X in $L^1(c)$.

TOPOLOGICAL PROPERTIES OF THE DUAL SPACE OF $L^1(c)$

PROPOSITION

Let c be a capacity on a Polish space Ω . On the non negative part K_+ of the unit ball of $L^1(c)^$, the weak* topology coincides with the weak topology.*

PROPOSITION

The set K_+ is compact metrizable for the weak topology, as well as for the weak topology.*

CONVEX RISK MEASURES

DEFINITION

Let $\rho : L^1(c) \rightarrow \mathbf{R}$.

- ρ is monotonic if $\rho(X) \geq \rho(Y)$ for every $X, Y \in L^1(c)$, such that $X \leq Y$.
- ρ is convex if for every $X, Y \in L^1(c)$, for every $0 \leq \lambda \leq 1$,
 $\rho(\lambda X + (1 - \lambda)Y) \leq \lambda \rho(X) + (1 - \lambda)\rho(Y)$
- ρ is translation invariant if $\rho(X + a) = \rho(X) - a$ for every $X \in L^1(c)$
and $a \in \mathbf{R}$.

ρ is a convex risk measure if it satisfies all these conditions.

DEFINITION

A convex risk measure ρ on $L^1(c)$ is normalized if $\rho(0) = 0$.

REPRESENTATION

THEOREM

Assume that c is a capacity on a Polish space Ω . Let ρ be a convex risk measure on $L^1(c)$. Then, ρ is continuous and admits a representation of the form:

$$\forall X \in L^1(c), \rho(X) = \sup_{Q \in \mathcal{P}'} (E_Q[-X] - \alpha(Q)) \quad (4)$$

where

$$\alpha(Q) = \sup_{X \in L^1(c)} (E_Q[-X] - \rho(X)) \quad (5)$$

\mathcal{P}' is the set of probability measures on $(\Omega, \mathcal{B}(\Omega))$ belonging to $L^1(c)^*$.

RISK MEASURES REPRESENTED BY A WEAKLY RELATIVELY COMPACT SET OF PROBABILITY MEASURES

PROPOSITION

Let $\rho : L^1(c) \rightarrow \mathbf{R}$ be a normalized convex risk measure. The following conditions are equivalent:

- 1 ρ is majorized by a sublinear risk measure
- 2 $\forall X \in L^1(c), \sup_{\lambda > 0} \frac{\rho(\lambda X)}{\lambda} < \infty$
- 3 there exists $K > 0$ such that $\forall X \in L^1(c), |\rho(X)| \leq Kc(X)$
- 4 ρ is represented by a set \mathcal{Q} of probability measures in $L^1(c)^*$ relatively compact for the weak* topology, i.e.

$$\forall X \in L^1(c), \rho(X) = \sup_{Q \in \mathcal{Q}} (E_Q[-X] - \alpha(Q)) \quad (6)$$

RISK MEASURES REPRESENTED BY A WEAKLY RELATIVELY COMPACT SET OF PROBABILITY MEASURES

THEOREM

Let ρ be a convex risk measure on $L^1(c)$. Assume that ρ is represented by

$$\rho(X) = \sup_{Q \in \mathcal{Q}} (E_Q(-X) - \alpha(Q))$$

where \mathcal{Q} is a set of probability measures in $L^1(c)^*$ relatively compact for the weak* topology. Let $\overline{\mathcal{Q}}$ be the closure of \mathcal{Q} for the weak* topology. Then for every $X \in L^1(c)$, there is a probability measure $Q_X \in \overline{\mathcal{Q}}$ such that

$$\rho(X) = E_{Q_X}(-X) - \alpha(Q_X) \quad (7)$$

REPRESENTATION WITH A COUNTABLE SET OF PROBABILITY MEASURES

THEOREM

Assume that c is a capacity on a Polish space Ω . Every convex risk measure on $L^1(c)$ can be represented by a countable set of probability measures $\{R_n, n \in \mathbb{N}\}$ belonging to $L^1(c)^*$.

$$\forall X \in L^1(c), \rho(X) = \sup_{n \in \mathbb{N}} (E_{R_n}(-X) - \alpha(R_n)) \quad (8)$$

where

$$\alpha(R) = \sup_{X \in L^1(c)} (E_R[-X] - \rho(X)) \quad (9)$$

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CAPACITY DEFINED FROM A WEAKLY RELATIVELY COMPACT SET OF PROBABILITY MEASURES

\mathcal{P} weakly relatively compact set of probability measures. Capacity $c_{\mathcal{P},\mathcal{P}}$ defined on $\mathcal{C}_b(\Omega)$ by $c_{\mathcal{P},\mathcal{P}}(f) = \sup_{Q \in \mathcal{P}} E_Q(|f|^p)^{\frac{1}{p}}$

LEMMA

For all X in $L^1(c_{\mathcal{P},\mathcal{P}})$, $c_{\mathcal{P},\mathcal{P}}(X) = \sup_{Q \in \mathcal{P}} E_Q(|X|^p)^{\frac{1}{p}}$.

There is $(Q_n)_{n \in \mathbb{N}}$ in \mathcal{P} such that $c_{\mathcal{P},\mathcal{P}}(X) = \sup_{n \in \mathbb{N}} E_{Q_n}(|X|^p)^{\frac{1}{p}}$.

REMARK

It can happen that for a certain Borelian set A , the above equation is not satisfied for $X = 1_A$, i.e. $c_{\mathcal{P},\mathcal{P}}(1_A) \neq \sup_{Q \in \mathcal{P}} Q(A)^{\frac{1}{p}}$. (\geq is always satisfied)

Example: $\Omega = [0, 1]$. Let $x_n \in]0, 1[$ be a sequence converging to 0. Let $A = [0, 1] - \{x_n, n \in \mathbb{N}\}$. Let $Q_n = \delta_{x_n}$. Let $\mathcal{P} = \{Q_n, n \in \mathbb{N}\}$. Then $c_{\mathcal{P},\mathcal{P}}(1_A) = 1$ and $\sup_{Q \in \mathcal{P}} Q(A)^{\frac{1}{p}} = 0$

CANONICAL CLASS OF PROBABILITY MEASURE ASSOCIATED TO $L^1(c_p, \mathcal{P})$

USUAL EQUIVALENCE CLASS OF MEASURES

A non negative measure ν on $(\Omega, \mathcal{B}(\Omega))$ belongs to the (usual) equivalence class of the probability measure P if and only if

$$\forall A \in \mathcal{B}(\Omega), \quad P(A) = 0 \iff \nu(A) = 0$$

Or equivalently if $\nu \in (L^1(\Omega, \mathcal{B}(\Omega), P))^*$,

$$P \sim \nu \iff [\forall X \in L^1(\Omega, \mathcal{B}(\Omega), P)_+, \quad X = 0 \iff \nu(X) = \int X d\nu = 0]$$

EQUIVALENCE CLASS OF PROBABILITY MEASURES ASSOCIATED TO A NON DOMINATED SET OF PROBABILITY MEASURES

EQUIVALENCE RELATION ON $\mathcal{M}^+(c_p)$

When \mathcal{P} is fixed, write c_p instead of $c_{p,\mathcal{P}}$. $\mathcal{M}^+(c_p)$: set of non negative finite measures on $(\Omega, \mathcal{B}(\Omega))$ defining an element of $L^1(c_p)^*$. Define on $\mathcal{M}^+(c_p)$ the relation \mathcal{R}_{c_p} by

$$\mu \mathcal{R}_{c_p} \nu \iff \tag{10}$$

$$\forall X \in L^1(c_p), X \geq 0, \quad \{\mu(X) = 0 \iff \nu(X) = 0\}$$

LEMMA

\mathcal{R}_{c_p} defines an equivalence relation on $\mathcal{M}^+(c_p)$.

CANONICAL EQUIVALENCE CLASS OF PROBABILITY MEASURES ASSOCIATED TO c_p, \mathcal{P}

THEOREM

Ω Polish space. \mathcal{P} weakly relatively compact.

There is a unique \mathcal{R}_{c_p} equivalence class in $\mathcal{M}^+(c_p)$ such $\mu \in \mathcal{M}^+(c_p)$ belongs to this class if and only if

$$\forall X \in L^1(c_p), X \geq 0, \quad \{\mu(X) = 0\} \iff \{X = 0 \text{ in } L^1(c_p)\}$$

This class is referred as the canonical c_p -class.

For every countable weakly relatively compact set $\{Q_n, n \in \mathbb{N}\}$ such that for every $X \in L^1(c_p)$ $c_p(X) = \sup_{n \in \mathbb{N}} (E_{Q_n}(|X|^p))^{\frac{1}{p}}$, for $\alpha_n > 0$ such that $\sum_{n \in \mathbb{N}} \alpha_n = 1$ the probability measure $\sum_{n \in \mathbb{N}} \alpha_n Q_n$ belongs to the canonical c_p -class.

THE CANONICAL c_p -CLASS

PROPERTY

Let P be a probability measure belonging to the canonical c_p -class. Let X be an element of $L^1(c_p)$. Then $X \geq 0$ (for the order in $L^1(c_p)$) if and only $X \geq 0$ P a.s.

REMARK

When $\mathcal{P} = \{P\}$ the canonical c_p -class is the restriction to $\mathcal{M}^+(c_p)$ of the usual equivalence class of the probability measure P .

When \mathcal{P} is a finite set, $\mathcal{P} = \{P_1, \dots, P_n\}$ the canonical c_p -class is the restriction to $\mathcal{M}^+(c_p)$ of the equivalence class (in the usual sense) of the probability measure $P = \frac{\sum_{1 \leq i \leq n} P_i}{n}$.

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REGULARITY

\mathcal{L} : linear vector subspace of $\mathcal{C}_b(\Omega)$ containing the constants, generating the topology of Ω and which is a vector lattice.

DEFINITION

- A sublinear risk measure ρ on \mathcal{L} is regular if for every decreasing sequence X_n of elements of \mathcal{L} with limit 0, $\rho(-X_n)$ tends to 0.
- A normalized convex risk measure is uniformly regular if for all X $\sup_{\lambda>0} \frac{\rho(\lambda X)}{\lambda} < \infty$, and for every decreasing sequence X_n of elements of \mathcal{L} with limit 0, $\frac{\rho(-\lambda X_n)}{\lambda}$ converges to 0 uniformly in $\lambda > 0$.

LEMMA

Let ρ be a normalized convex risk measure uniformly regular.

$\rho_{\min}(X) = \sup_{\lambda>0} \frac{\rho(\lambda X)}{\lambda}$ defines a regular sublinear risk measure. It is the minimal sublinear risk measure on \mathcal{L} majorizing ρ .

EXTENSION OF A RISK MEASURE

LEMMA

ρ : normalized convex risk measure uniformly regular on \mathcal{L} .

$c_\rho(X) = \rho_{\min}(-|X|)$ defines a capacity on \mathcal{L} .

ρ (resp ρ_{\min}) has a unique continuous extension into a normalized convex risk measure $\bar{\rho}$ (resp a sublinear risk measure $\bar{\rho}_{\min}$) on $L^1(c_\rho)$. $\bar{\rho}$ is majorized by $\bar{\rho}_{\min}$.

DEFINITION

Let $X \in \mathcal{C}_b(\Omega)$, X is riskless if for all $\lambda > 0$, $\rho(\lambda X) \leq 0$.

For $X \leq 0$ this is equivalent to $\rho(\lambda X) = 0$ for every $\lambda > 0$

REPRESENTATION OF UNIFORMLY REGULAR CONVEX RISK MEASURES

THEOREM

Let ρ be a normalized uniformly regular convex risk measure on \mathcal{L} . Then ρ extends uniquely to $\mathcal{C}_b(\Omega)$. There is a countable weakly relatively compact set $\{Q_n, n \in \mathbb{N}\}$ such that

$$\forall X \in \mathcal{C}_b(\Omega) \quad \rho(X) = \sup_{n \in \mathbb{N}} (E_{Q_n}(-X) - \alpha(Q_n)) \quad (11)$$

Furthermore for $\alpha_n > 0$ such that $\sum_{n \in \mathbb{N}} \alpha_n = 1$ the probability measure $P = \sum_{n \in \mathbb{N}} \alpha_n Q_n$ characterizes the riskless non positive elements of $\mathcal{C}_b(\Omega)$, that is $X \leq 0$ is riskless iff $X = 0$ P a.s.

For every $X \in \mathcal{C}_b(\Omega)$, there is a probability measure Q_X in the weak closure of $\{Q_n, n \in \mathbb{N}\}$, such that

$$\rho(X) = E_{Q_X}(-X) - \alpha(Q_X) \quad (12)$$

G-EXPECTATIONS

$\Omega = \mathcal{C}_0([0, T], \mathbf{R}^d)$, G-expectations were introduced by S. Peng (2007).
 From Denis Hu and Peng (2009) $\mathbb{E}(f) = \sup_{P \in \mathcal{P}} E_P(f)$ \mathcal{P} is weakly relatively compact
 $\rho(f) = \mathbb{E}(-f)$ is a sublinear regular risk measure on $\mathcal{C}_b(\Omega)$.

PROPOSITION

There is a countable weakly relatively compact set $\{Q_n, n \in N\}$ of probability measures, $Q_n \in \mathcal{P}$ such that

$$\forall X \in \mathcal{C}_b(\Omega) \quad \mathbb{E}(X) = \sup_{n \in N} E_{Q_n}(X) \quad (13)$$

Let $P = \sum_{n \in N^} \alpha_n Q_n$ ($\alpha_n > 0$ and $\sum \alpha_n = 1$). For all $f \geq 0$ in $\mathcal{C}_b(\Omega)$, $\mathbb{E}(f) = 0$ iff $f = 0$ P a.s.*

For every $X \in \mathcal{C}_b(\Omega)$, there is a probability measure Q_X in the weak closure of $\{Q_n, n \in N^\}$, such that $\mathbb{E}(X) = E_{Q_X}(X)$.*

$$\Omega = \mathcal{C}_0([0, T], \mathbf{R}^d)$$

$\mathcal{C}_b(\Omega)$, \mathcal{P} IS WEAKLY RELATIVELY COMPACT

$\Pi(f) = \sup_{P \in \mathcal{P}} E_P(f)$ or $\rho(f) = \sup_{P \in \mathcal{P}} E_P(-f)$ All our previous results apply. Framework considered in Denis and Martini, also in Soner Touzi Zhang.

$\mathcal{UC}_b(\Omega)$, \mathcal{P} IS NOT NECESSARILY WEAKLY RELATIVELY COMPACT

Framework considered by Soner Touzi Zhang, and Nutz.

$n(f) = \sup_{P \in \mathcal{P}} E_P(|f|)$ is a semi-norm.

The closure of $\mathcal{UC}_b(\Omega)$ for the semi-norm n leads to a separable Banach space $L^1(n)$.

Thus the unit ball of the dual space is metrizable compact for the weak* topology. Notice that in this case the unit ball itself and not only its non negative part is metrizable compact. Therefore we get similar results:

The norm on $L^1(n)$ can be defined using a numerable subset in \mathcal{P} , there is a canonical class of probability measures...