

# Introduction to dual quantization and first applications

GILLES PAGÈS and BENEDIKT WILBERTZ

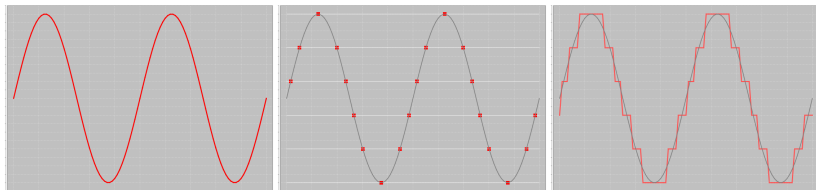
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October 25-28, 2010

# What is Quantization?

- Has its origin in the fields of signal processing in the late 1940's
- Describes the discretization of a random signal and analyses the recovery of the original signal from the discrete one



- Examples: Pulse-Code-Modulation(PCM), JPEG-Compression
- Extensive Survey about the IEEE-History: [Gray/Neuhoff '98]
- Mathematical Foundation of Quantization Theory: [Graf/Luschgy '00]

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The  $p$ -th *quantization error* for a grid  $\Gamma \subset \mathbb{R}^d$  with size  $|\Gamma| \leq n$ ,  $n \in \mathbb{N}$  is given by

$$e^p(X; \Gamma) = \mathbb{E} \operatorname{dist}(X, \Gamma)^p = \mathbb{E} \min_{x \in \Gamma} \|X - x\|^p. \quad (1)$$

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The optimal quantization problem consists in minimizing (1) over all grids of size  $|\Gamma| \leq n$ .

We define the *optimal quantization error* of level  $n$  as

$$e_n^p(X) := \inf \left\{ \mathbb{E} \min_{x \in \Gamma} \|X - x\|^p : \Gamma \subset \mathbb{R}^d, |\Gamma| \leq n \right\}.$$

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Theorem (Zador, Kiefer, Bucklew & Wise, Graf & Luschgy, cf. [Graf/Luschgy '00])

Let  $X \in L^r(\mathbb{R}^d)$ ,  $r > p$  and denote by  $\varphi$  the  $\lambda^d$ -density of the absolutely continuous part of  $\mathbb{P}_X$ .

Then

$$\lim_{n \rightarrow \infty} n^{p/d} \cdot e_n^p(X) = Q_{p, \|\cdot\|} \cdot \left( \int_{\mathbb{R}^d} \|\varphi\|^{d/(d+p)} d\lambda^d \right)^{(d+p)/d}$$

where  $Q_{p, \|\cdot\|} = \lim_{n \rightarrow \infty} n^{p/d} \cdot e_n^p(U([0, 1]^d))$ .



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- Let  $(C_i(\Gamma))_{1 \leq i \leq n}$  be a *Voronoi partition* of  $\mathbb{R}^d$  generated by  $\Gamma$ , i.e.  $(C_i(\Gamma))$  is a Borel partition of  $\mathbb{R}^d$  satisfying

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- Let  $\pi_\Gamma : \mathbb{R}^d \rightarrow \Gamma$  the Nearest Neighbor projection,

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$\Rightarrow$  We define the *Voronoi Quantization* as

$$\widehat{X}^\Gamma = \pi_\Gamma(X) = \sum_{i=1}^n x_i \mathbf{1}_{C_i(\Gamma)}(X).$$

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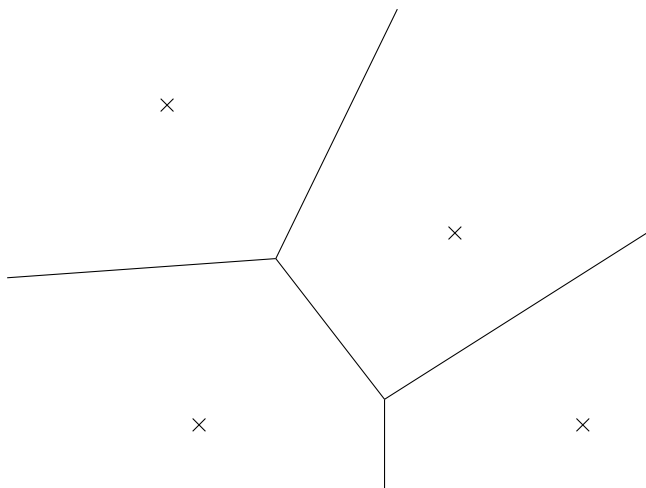
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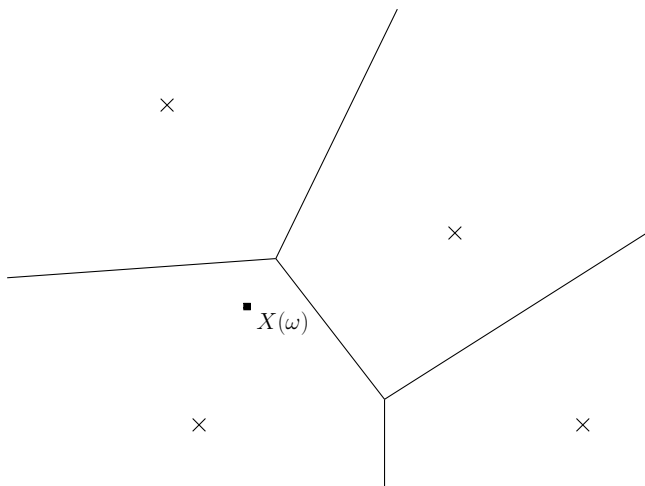
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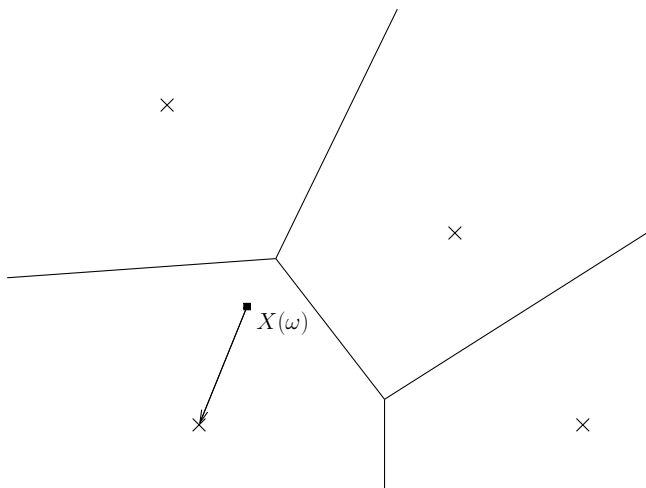
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A further characterization for the optimal quantization error is given by

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⇒ The Nearest Neighbor projection is the coding rule, which yields the smallest  $L^p$ -mean approximation error for  $X$ .

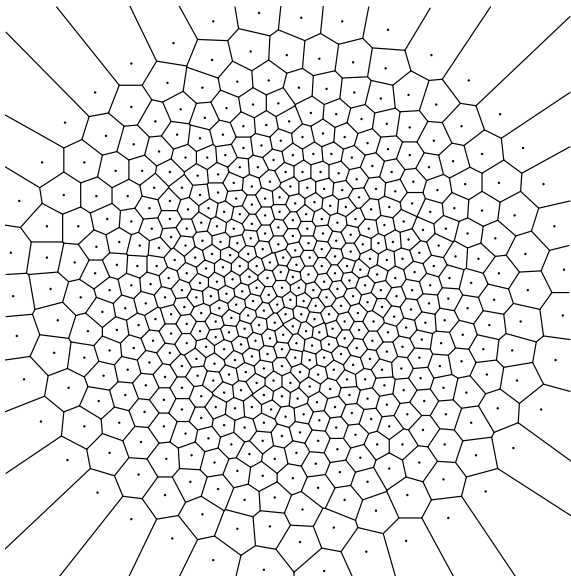


Figure: A Quantizer for  $\mathcal{N}(0, I_2)$  of size 500 in  $(\mathbb{R}^2, \|\cdot\|_2)$ .

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$$\mathbb{E}F(\widehat{X}^\Gamma) = \mathbb{E}F\left(\sum_{i=1}^n x_i \mathbf{1}_{C_i(\Gamma)}(X)\right) = \sum_{i=1}^n w_i(\Gamma) F(x_i).$$

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As a first error estimate, we clearly have

$$|\mathbb{E}F(X) - \mathbb{E}F(\hat{X}^\Gamma)| \leq [F]_{\text{Lip}} \mathbb{E}\|X - \hat{X}^\Gamma\|.$$



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## Second order rate

If  $F \in C_{\text{Lip}}^1$  and the grid  $\Gamma$  is a *stationary*, i.e.

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then a Taylor expansion yields

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$$|\mathbb{E}F(X) - \mathbb{E}F(\widehat{X}^\Gamma)| \leq [F']_{\text{Lip}} \cdot \mathbb{E}\|X - \widehat{X}^\Gamma\|^2.$$

Furthermore, if  $F$  is convex, then Jensen's inequality implies for stationary  $\Gamma$

$$\mathbb{E}F(\widehat{X}^\Gamma) \leq \mathbb{E}F(X).$$

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- Obstacle Problems: Valuation of Bermudan and American options ([Bally/Pagès '03])
- $\delta$ -Hedging for American options ([Bally/Pagès/Printems '05])
- Optimal Stochastic Control problems, e.g. Pricing of Swing options ([Bronstein/Pagès/W. '09] and [Bardou/Bouthemy/Pagès '09])



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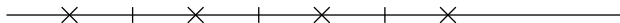
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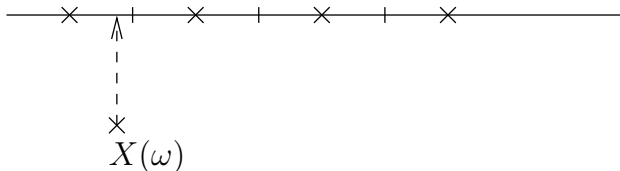


$$\begin{matrix} \times \\ X(\omega) \end{matrix}$$

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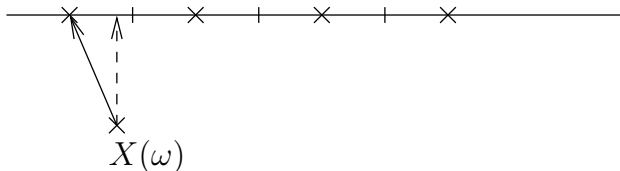
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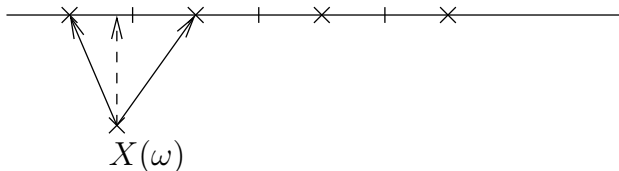
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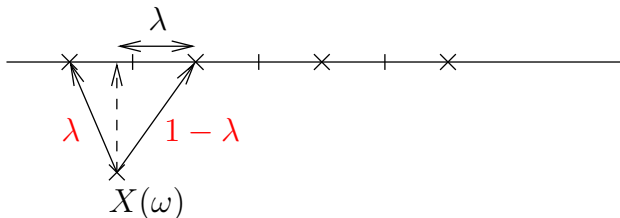
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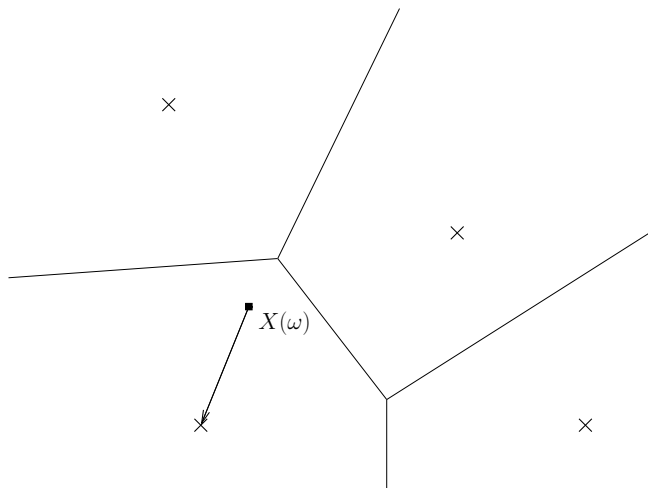
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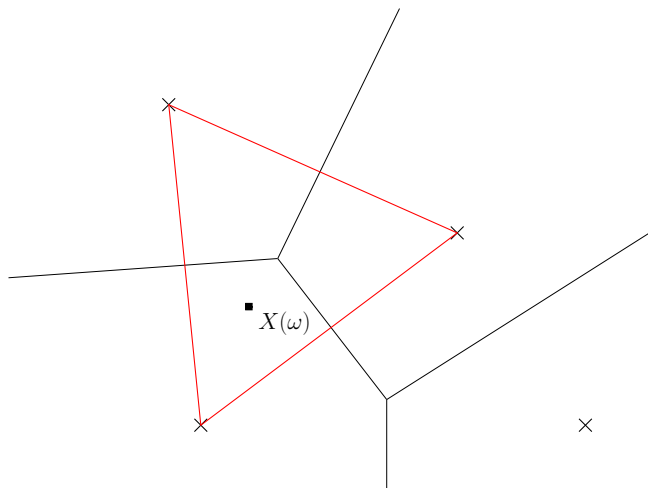


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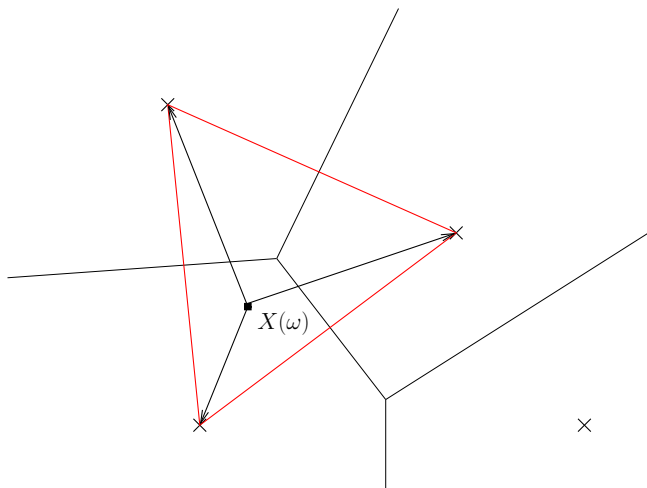




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# Ideas behind Dual Quantization

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Moreover, let  $U \sim \mathcal{U}[0, 1]$  be defined on some exogenous probability space  $(\Omega_0, \mathcal{S}_0, \mathbb{P}_0)$ .

Denoting by  $\lambda(\xi)$  the barycentric coordinate of  $\xi \in \text{conv}\{\tau\}$ , we define a dual quantization operator  $\mathcal{J}_\tau^U : \text{conv}\{\tau\} \rightarrow \tau$  as

$$\xi \mapsto \sum_{i=1}^{d+1} t_i \mathbf{1}_{\left\{ \sum_{j=1}^{i-1} \lambda_j(\xi) \leq U < \sum_{j=1}^i \lambda_j(\xi) \right\}}.$$

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This operator satisfies a mean preserving property:

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Similarly, we can construct such an operator for any triangulation on a grid  $\Gamma = \{x_1, \dots, x_n\}$ , so that (2) holds for any  $\xi \in \text{conv}\{\Gamma\}$ .

# Stationarity

Motivated by this observation, we call a random splitting operator  $\mathcal{J}_\Gamma : \Omega_0 \times \mathbb{R}^d \rightarrow \Gamma$  for a grid  $\Gamma \subset \mathbb{R}^d$  *intrinsic stationary*, if

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The deeper meaning of this definition is revealed by the following Proposition.

## Proposition

$\mathcal{J}_\Gamma$  is *intrinsic stationary*, if and only if it satisfies the *stationarity condition*

$$\mathbb{E}_{\mathbb{P} \otimes \mathbb{P}_0}(\mathcal{J}_\Gamma(Y)|Y) = Y$$

for any r.v.  $Y : (\Omega, \mathcal{S}, \mathbb{P}) \rightarrow (\mathbb{R}^d, \mathcal{B}^d)$  with  $\text{supp}(\mathbb{P}_Y) \subset \text{conv}\{\Gamma\}$ .



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Note that this kind of stationarity now is very robust, since it holds by construction for any r.v.  $Y$  with support in  $\Gamma$ .

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(b) If  $F$  is convex, then Jensen's inequality implies

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For every  $\xi \in \text{conv}(\Gamma)$  we choose the best “triangle” in  $\Gamma$  which contains  $\xi$ .



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$$\text{s.t. } \begin{bmatrix} x_1 & \dots & x_n \\ 1 & \dots & 1 \end{bmatrix} \lambda = \begin{bmatrix} \xi \\ 1 \end{bmatrix}, \lambda \geq 0$$

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▷ The optimal  $p$ -th dual quantization error is then defined as

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Therefore,  $I^*(\xi) := \{i : \lambda_i^*(\xi) > 0\}$  defines an affinely independent family  $(x_i)_{i \in I^*(\xi)}$  which can be completed into a  $\Gamma$ -valued affine basis.

$$D_I(\Gamma) = \{\xi \in \mathbb{R}^d : \exists I^*(\xi) \subset I\},$$



or equivalently in term of linear programming

$$D_I(\Gamma) = \left\{ \xi \in \mathbb{R}^d : \lambda^I = A_I^{-1} \begin{bmatrix} \xi \\ 1 \end{bmatrix} \geq 0 \text{ and } \sum_{i \in I} \lambda_i^I \|\xi - x_i\|^p = F^p(\xi; \Gamma) \right\},$$

where

$$I \in \mathcal{I}(\Gamma) = \left\{ J \subset \{1, \dots, n\} : |J| = d + 1, \text{rk}(A_J) = d + 1 \right\}$$

and  $A_I$  denotes the submatrix of  $\begin{bmatrix} x_1 & \dots & x_n \\ 1 & \dots & 1 \end{bmatrix}$  whose columns are given by  $I$ .



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The following theorem is an extension of an important theorem by Rajan ([Rajan '91]).

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Let  $\|\cdot\| = |\cdot|_2$ ,  $p = 2$ , and  $\Gamma = \{x_1, \dots, x_n\} \subset \mathbb{R}^d$  with  $\text{aff. dim}\{\Gamma\} = d$ .

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The *optimal dual quantization operator*  $\mathcal{J}_\Gamma^*$  is defined as

$$\mathcal{J}_\Gamma^*(\xi) = \sum_{I \in \mathcal{I}(\Gamma)} \left[ \sum_{i=1}^k x_i \cdot \mathbf{1}_{\left\{ \sum_{j=1}^{i-1} \lambda_j^I(\xi) \leq U < \sum_{j=1}^i \lambda_j^I(\xi) \right\}} \right] \mathbf{1}_{C_I(\Gamma)}(\xi).$$



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One easily checks that this operator is intrinsic stationary.

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 &\quad \left. \text{supp}(\mathbb{P}_X) \subset \text{conv}\{\Gamma\}, |\Gamma| \leq n \right\} \\
 &= \inf \left\{ \mathbb{E} \|X - \hat{Y}\|^p : \hat{Y} \text{ is a r.v. on } (\Omega \times \Omega_0, \mathcal{S} \otimes \mathcal{S}_0, \mathbb{P} \otimes \mathbb{P}_0), \right. \\
 &\quad \left. |\hat{Y}(\Omega \times \Omega_0)| \leq n, \mathbb{E}(\hat{Y}|X) = X \right\}.
 \end{aligned}$$

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Since it is not possible to obtain intrinsic stationarity for  $\xi \notin \text{conv}\{\Gamma\}$ , we have to limit the claim for stationarity to a subset of  $\text{supp}(\mathbb{P}_X)$  in order to extend the dual quantization problem to distributions with unbounded support.



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This means that we use a Nearest Neighbor projection beyond  $\text{conv}\{\Gamma\}$  while preserving stationarity in the interior of  $\text{conv}\{\Gamma\}$ .

# Existence of optimal dual quantizers

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## Theorem ([Pagès/W. '10a])

(a) *Let  $p > 1$  and assume that  $\mathbb{P}_X$  has a compact support. Then for every  $n \geq d + 1$  optimal dual quantizers actually exist, i.e. the dual quantization problem  $d_n^p(X)$  attains its infimum. Moreover,  $d_n^p(X)$  is (strictly) decreasing to 0 as  $n \rightarrow \infty$ , if it does not vanish.*

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- (b) *Let  $p > 1$  and assume that the distribution  $\mathbb{P}_X$  is strongly continuous. Then also optimal quantizers for  $\bar{d}_n^p(X)$  exists and  $\bar{d}_n^p(X)$  is (strictly) decreasing to 0 as  $n \rightarrow \infty$ , if it does not vanish.*

# Asymptotic behavior

Theorem ([Pagès/W. '10b])

(a) *Let  $X \in L^{p^+}(\mathbb{R}^d)$  and denote by  $\varphi$  the  $\lambda^d$ -density of the absolutely continuous part of  $\mathbb{P}_X$ .*

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$$\lim_{n \rightarrow \infty} n^{p/d} \cdot \bar{d}_n^p(X) = Q_{d,p,\|\cdot\|} \cdot \left( \int_{\mathbb{R}^d} \varphi^{d/(d+p)} d\lambda^d \right)^{\frac{d+p}{d}}$$

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(b) If  $d = 1$ ,  $Q_{d,p,\|\cdot\|} = \frac{2^{p+1}}{p+2} \lim_{n \rightarrow \infty} n^{p/d} \cdot e_n^p(U([0,1]))$ . If  $d \geq 2$ , ???

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- Use Differentiation of measure to cover the general case (still compact support)
- Random dual quantization argument (so-called extended Pierce Lemma) to get the unbounded case.

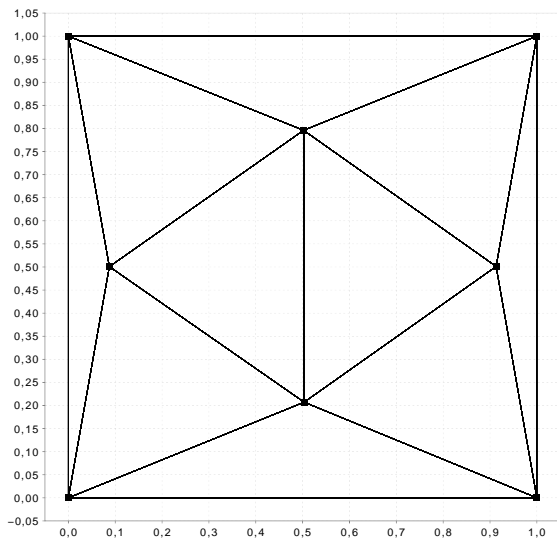


Figure: Dual Quantization for  $\mathcal{U}([0, 1]^2)$  and  $n = 8$

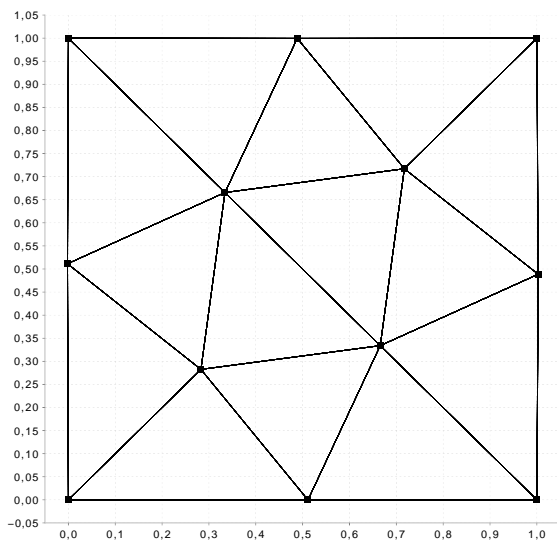


Figure: Dual Quantization for  $\mathcal{U}([0, 1]^2)$  and  $n = 12$



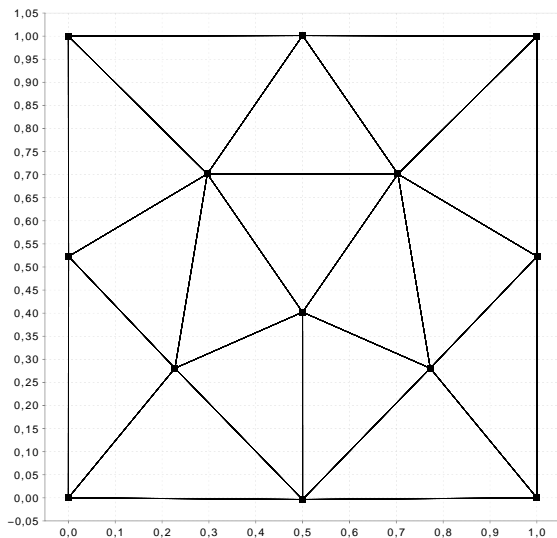


Figure: Dual Quantization for  $\mathcal{U}([0, 1]^2)$  and  $n = 13$

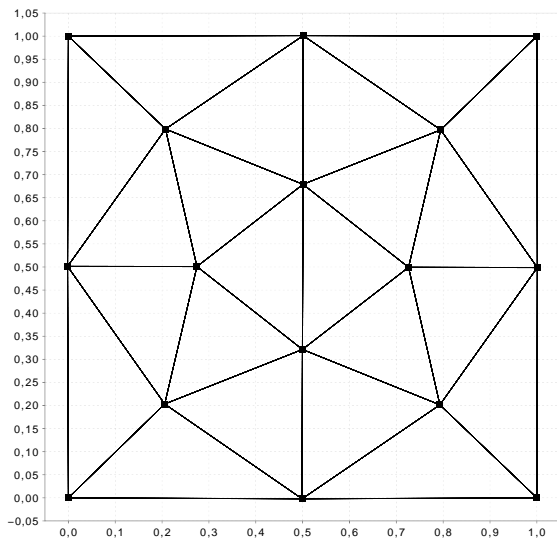


Figure: Dual Quantization for  $\mathcal{U}([0, 1]^2)$  and  $n = 16$

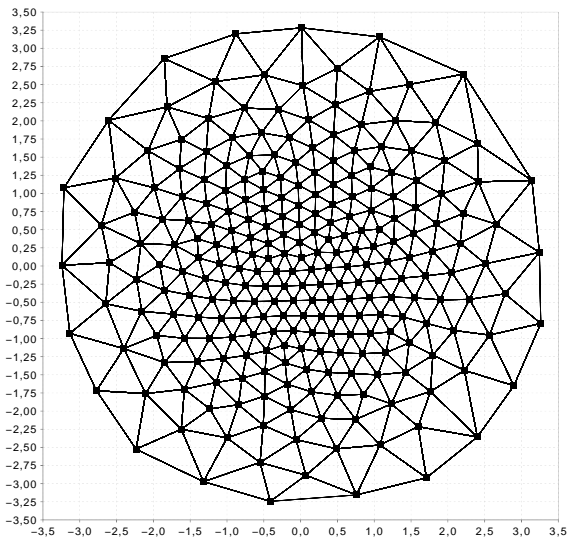


Figure: Dual Quantization for  $\mathcal{N}(0, I_2)$  and  $N = 250$

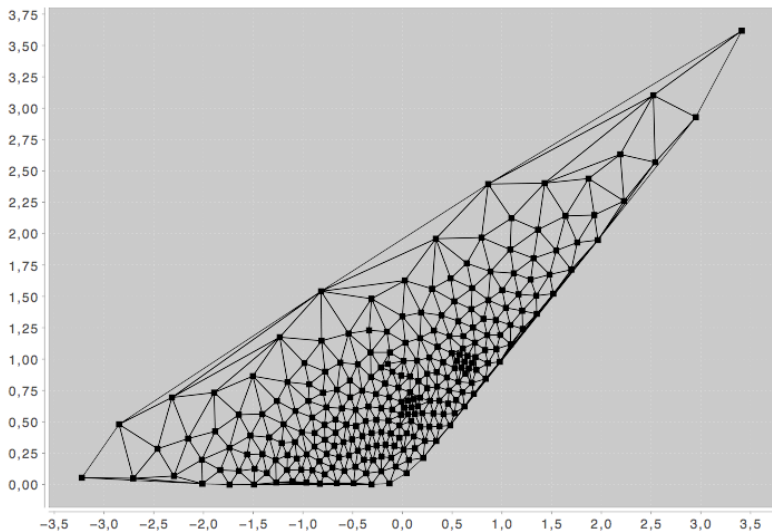


Figure: Joint Dual Quantization of the BM and its supremum,  $N = 250$

# Numerical Applications

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Using a Backward-Dynamic-Programming principle for the valuation of early exercise options with underlying Markov dynamics  $(X_k)_{1 \leq k \leq N}$  the numerical challenge in this approach consists in the approximation of conditional expectations

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As in the case of Quantization for numerical cubature, we may replace the Markov chain  $(X_k)$  by a Quantization  $(\hat{X}_k)$ , so that the the computation of  $\mathbb{E}(f(X_{k+1})|X_k)$  becomes straightforward as

$$\mathbb{E}(f(\hat{X}_{k+1})|\hat{X}_k = x_i^k) = \sum_{j=1}^{n_{k+1}} f(x_j^{k+1})\pi_{ij}^k,$$

with transition probabilities

$$\pi_{ij}^k = \mathbb{P}(\hat{X}_{k+1} = x_j^{k+1}|\hat{X}_k = x_i^k).$$

# Numerical Applications



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For the approximation error the following result can be derived.

## Proposition

If the mappings  $f : \mathbb{R}^d \rightarrow \mathbb{R}$  and

$$\Phi_{f,k} : \mathbb{R}^d \rightarrow \mathbb{R}, x \mapsto \mathbb{E}(f(X_{k+1})|X_k = x)$$

are Lipschitz, then it holds

$$\begin{aligned} \|\mathbb{E}(f(X_{k+1})|X_k) - \mathbb{E}(f(\hat{X}_{k+1})|\hat{X}_k)\|_p &\leq [\Phi_{f,k}]_{Lip} \cdot \|X_k - \hat{X}_k\|_p \\ &\quad + [f]_{Lip} \cdot \|X_{k+1} - \hat{X}_{k+1}\|_p. \end{aligned}$$

# Valuation of Swing options

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The right to buy every day a certain quantity of gas/electricity for a given price, where the bought quantity has to respect certain daily and global constraints.

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The right to buy every day a certain quantity of gas/electricity for a given price, where the bought quantity has to respect certain daily and global constraints.

The fair premium of such an contract leads to a stochastic control problem (SCP)

$$\text{esssup} \left\{ \mathbb{E} \left( \sum_{k=0}^{n-1} q_k v_k(X_k) \middle| \mathcal{F}_0 \right), q_k : (\Omega, \mathcal{F}_k) \rightarrow [0, 1], \bar{q}_n \in [Q_{\min}, Q_{\max}] \right\}$$

$$\text{for } \bar{q}_k := \sum_{l=0}^{k-1} q_l.$$

# Backward Dynamic Programming Principle

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It was shown in [Bardou/Bouthemy/Pagès '09] that (SCP) can be solved by the Backward Dynamic Programming Principle with bang-bang control, i.e we set

$$P_n^n \equiv 0$$

$$P_k^n(Q^k) = \max \left\{ x v_k(X_k) + \mathbb{E}(P_{k+1}^n(\chi^{n-k-1}(Q^k, x)) | X_k), x \in \{0, 1\} \cap I_{Q^k}^{n-k-1} \right\}$$

with admissible set  $I_{Q^k}^M := [(Q_{\min}^k - M)^+ \wedge 1, Q_{\max}^k \wedge 1]$  and  $\chi^M(Q^k, x) := ((Q_{\min}^k - x)^+, (Q_{\max}^k - x) \wedge M)$ .

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Then  $P_0^n(Q_{\min}, Q_{\max})$  is a solution to (SCP).

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Using the Quantization ( $\hat{X}_k$ ) we define an approximation of ( $P_k$ ) as

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Under the same assumptions on ( $X_k$ ) and  $f = v_k$  as in the above Proposition about the approximation power of  $\mathbb{E}(f(\hat{X}_{k+1}) | \hat{X}_k)$  one gets

$$|P_0^n(Q) - \hat{P}_0^n(Q)| \leq C \sum_{k=0}^{n-1} \mathbb{E} \|X_k - \hat{X}_k\|$$

for any reasonable initial global constraints  $Q = (Q_{\min}, Q_{\max})$  (see [Bardou/Bouthemy/Pagès '10]).

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In this model, the dynamics of the underlying are given as

$$S_t = s_0 \exp\left(\sigma_1 \int_0^t e^{-\alpha_1(t-s)} dW_s^1 + \sigma_2 \int_0^t e^{-\alpha_2(t-s)} dW_s^2 - \frac{1}{2}\mu t\right)$$

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$$S_t = s_0 \exp\left(\sigma_1 \int_0^t e^{-\alpha_1(t-s)} dW_s^1 + \sigma_2 \int_0^t e^{-\alpha_2(t-s)} dW_s^2 - \frac{1}{2}\mu t\right)$$

for Brownian Motions  $W^1$  and  $W^2$  with some correlation parameter  $\rho$ . For a time-step parameter  $\Delta t$  we consider the 2-dimensional Markov process

$$X_k = \left( \int_0^{k\Delta t} e^{-\alpha_1(k\Delta t-s)} dW_s^1, \int_0^{k\Delta t} e^{-\alpha_2(k\Delta t-s)} dW_s^2 \right).$$

# Numerical Results

## Example

Gaussian 2-factor with parameters

$$s_0 = 20, \alpha_1 = 1.11, \alpha_2 = 5.4, \sigma_1 = 0.36, \sigma_2 = 0.21, \rho = -0.11$$

and  $n = 30$  exercise days for the swing contract.

Results in the Benchmark case of a Call-Strip, i.e. the global consumption constraints are

$$(Q_{\min}, Q_{\max}) = (0, n).$$

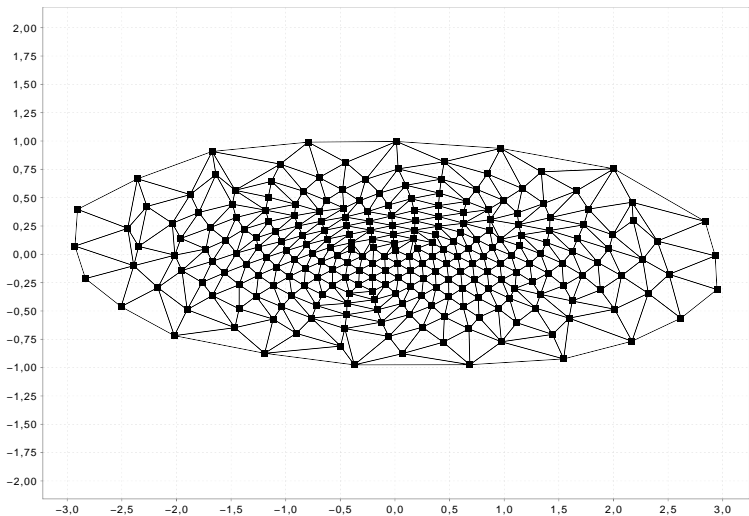
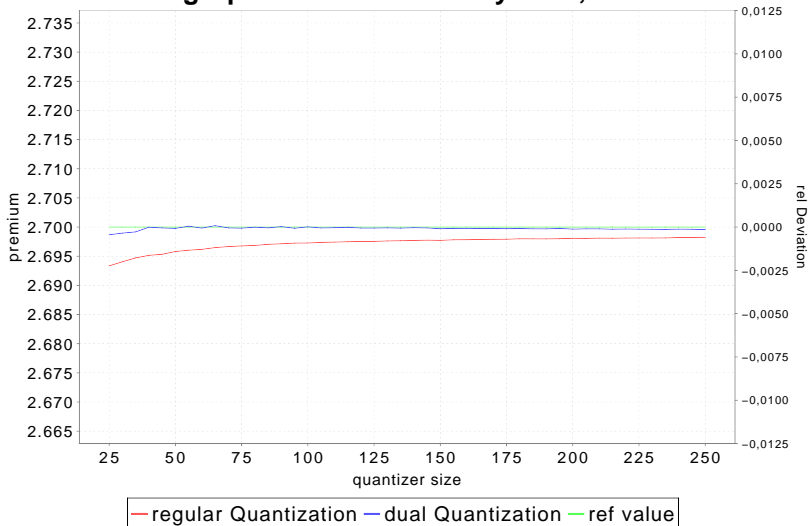
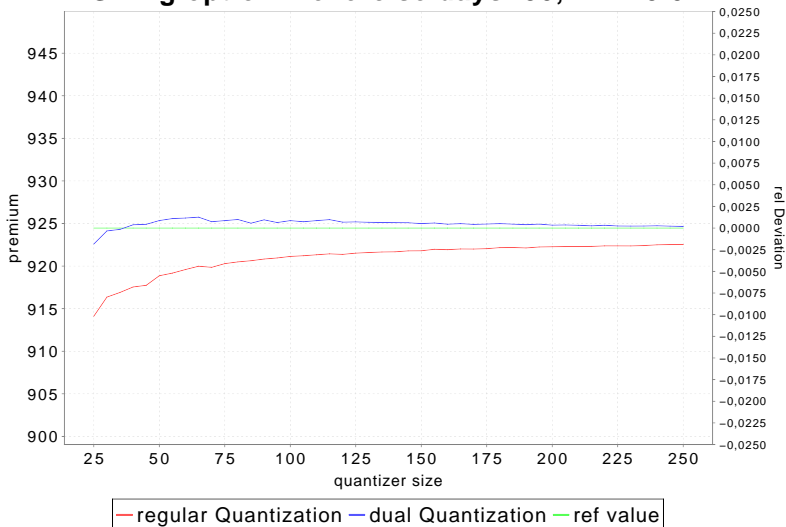


Figure: Triangulation for  $X_n$  and  $N = 250$  in Gaussian 2-factor model

**Swing option: #exercise days: 30,  $K = 5.0$** 

**Swing option: #exercise days: 30,  $K = 15.0$** 



# Bermudan options

In the same way we use the BDP-Principle for the valuation of Bermudan options:

## BDP for Bermudan options

$$\begin{aligned}\widehat{V}_n &= \varphi_{t_n}(\widehat{X}_n) \\ \widehat{V}_k &= \max\left\{\varphi_{t_k}(\widehat{X}_k); \mathbb{E}(\widehat{V}_{k+1}|\widehat{X}_k)\right\}, \quad 0 \leq k \leq n-1,\end{aligned}$$

so that  $\widehat{V}_0$  yields an approximation to the Bermudan option premium

$$V_0 = \text{esssup}\{\mathbb{E}\varphi(X_\tau) : \tau \text{ is } \{t_0, \dots, t_n\}\text{-valued stopping time}\}.$$

# Numerical Results

## Example

2-asset Black-Scholes model with

$$s_0^1 = s_0^2 = 40, r = 0.05, \sigma_1 = 0.2, \sigma_2 = 0.3, \rho = 0.5, K = 40,$$

for a put on the min, i.e. payoff

$$\varphi(S_t^1, S_t^2) = (K - \min\{S_t^1, S_t^2\})^+.$$

# Numerical Results

## Example

2-asset Black-Scholes model with

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As underlying Markov process we have chosen a 2-dimensional Brownian Motion with correlation  $\rho$ .

# Numerical Results

## Example

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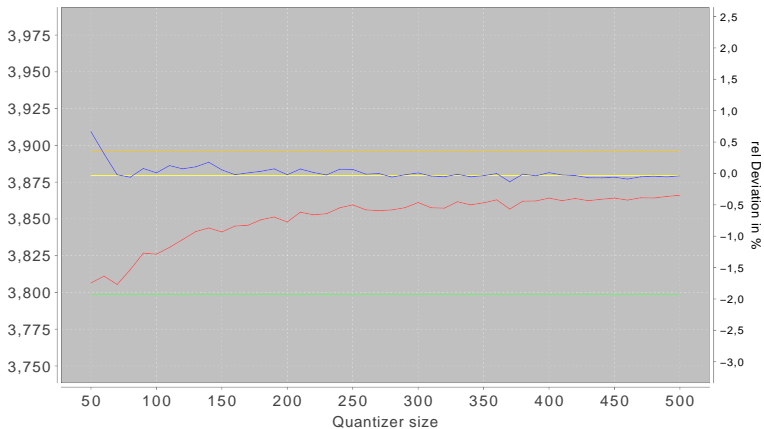
$$\varphi(S_t^1, S_t^2) = (K - \min\{S_t^1, S_t^2\})^+.$$

As underlying Markov process we have chosen a 2-dimensional Brownian Motion with correlation  $\rho$ .

Reference values were computed using a Boyle-Evnine-Gibbs tree with 10.000 timesteps.

# Martingale Adjustment

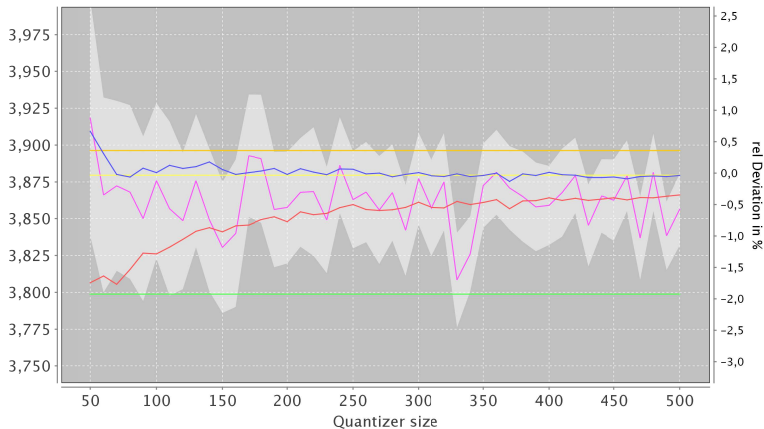
## Bermudan option: #exercise days: 10



— regular + martgl adj — dual + martgl adj — European ref value  
— American ref value — Bermudan ref value

# Martingale Adjustment

## Bermudan option: #exercise days: 10



— regular + martgl adj   
 — dual + martgl adj   
 — european ref value  
— american ref value   
 — bermudan ref value   
 — LS 95%-Intervall

# Conclusion / Outlook

## Conclusion / Summary

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- Interesting and challenging extension of regular Quantization



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- Application to 3-factor models, etc.

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