

Optimal investment under multiple defaults: a BSDE-decomposition approach

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Workshop “New advances in Backward SDEs for financial engineering
applications”
Tamerza, October 25-28, 2010

The basic problem

- Assets portfolio subject to **multiple defaults risk**
 - ▶ In addition to the default-free assets model (e.g. diffusion model with Brownian W), introduce jumps at random times modelled by a marked point process $(\tau_i, \zeta_i)_i \leftrightarrow$ random measure $\mu(dt, de)$.
- Optimal investment by classical stochastic control methods:
 - ▶ (Quadratic) BSDEs with jumps: this relies on martingale representation in the global filtration generated by W and μ .

Optimal investment problem with defaults revisited

- Approach by using:
 - Point of view of global filtration as **progressive enlargement of filtration** of the default-free filtration
 - **Decomposition in the default-free filtration**
- ▶ Backward system of BSDEs in Brownian filtration
 - ▶ Get rid of the jump terms and overcome the technical difficulties in BSDEs with jumps
 - ▶ Existence and uniqueness results in a general formulation under weaker conditions

Multiple defaults times and marks

On a probability space $(\Omega, \mathcal{G}, \mathbb{P})$:

- **Reference filtration** $\mathbb{F} = (\mathcal{F}_t)_{t \geq 0}$: default-free information

Progressive information provided, when they occur, by:

- a family of n **random times** $\tau = (\tau_1, \dots, \tau_n)$ associated to a family of n **random marks** $\zeta = (\zeta_1, \dots, \zeta_n)$.
 - ▶ τ_i default time of name $i \in \mathbb{I}_n = \{1, \dots, n\}$.
 - ▶ The mark ζ_i , valued in E Borel set of \mathbb{R}^P , represents a jump size at τ_i , which cannot be predicted from the reference filtration, e.g. the loss given default.

Progressive enlargement of filtrations

The **global market information** is defined by:

$$\mathbb{G} = \mathbb{F} \vee \mathbb{D}^1 \vee \dots \vee \mathbb{D}^n,$$

where \mathbb{D}^i is the default filtration generated by the **observation of τ_i and ζ_i when they occur**, i.e.

$$\mathbb{D}^i = (\mathcal{D}_t^i)_{t \geq 0}, \quad \mathcal{D}_t^i = \sigma\{\mathbf{1}_{\tau_i \leq s}, s \leq t\} \vee \sigma\{\zeta_i \mathbf{1}_{\tau_i \leq s}, s \leq t\}.$$

$\rightarrow \mathbb{G} = \mathbb{F} \vee \mathbb{F}^\mu$, where \mathbb{F}^μ is the filtration generated by the jump random measure $\mu(dt, de)$ associated to (τ_i, ζ_i) .

Successive defaults

For simplicity of presentation, we assume that

$$\tau_1 \leq \dots \leq \tau_n$$

Remarks.

- This means that we do not distinguish specific credit names, and only observe the ordered defaults: relevant for classical portfolio derivatives, e.g. basket default swaps.
- The general multiple random times case for (τ_1, \dots, τ_n) can be derived from the ordered case by considering the filtration generated by the corresponding ranked times $(\hat{\tau}_1, \dots, \hat{\tau}_n)$ and the index marks ι_i , $i = 1, \dots, n$ so that $(\hat{\tau}_1, \dots, \hat{\tau}_n) = (\tau_{\iota_1}, \dots, \tau_{\iota_n})$.

Notations

- For any $k = 0, \dots, n$:

$$\begin{aligned}\Omega_t^k &= \{\tau_k \leq t < \tau_{k+1}\}, \\ \Omega_{t-}^k &= \{\tau_k < t \leq \tau_{k+1}\},\end{aligned}$$

with the convention $\Omega_t^0 = \{t < \tau_1\}$, $\Omega_t^n = \{\tau_n \leq t\}$.

→ Scenario of k defaults before time t , the other names having not yet defaulted.

Ω_t^k : **k -default scenario** at time t , $(\Omega_t^k)_{k=0, \dots, n}$ partition of Ω .

- For $k = 0, \dots, n$,

$$\tau_k = (\tau_1, \dots, \tau_k), \quad \zeta_k = (\zeta_1, \dots, \zeta_k),$$

with the convention $\tau_0 = \emptyset$, $\zeta_0 = \emptyset$.

Decomposition of \mathbb{G} -adapted and predictable processes

Lemma

Any \mathbb{G} -adapted process Y is represented as:

$$Y_t = \sum_{k=0}^n 1_{\Omega_t^k} Y_t^k(\tau_k, \zeta_k), \quad (1)$$

where Y_t^k is $\mathcal{F}_t \otimes \mathcal{B}(\mathbb{R}_+^k) \otimes \mathcal{B}(E^k)$ -measurable.

Remarks. • A similar decomposition result holds for \mathbb{G} -predictable processes: $\Omega_t^k \leftrightarrow \Omega_{t-}^k$, and $Y^k \in \mathcal{P}_{\mathbb{F}}(\mathbb{R}_+^k, E^k)$ -measurable in (1).

- Extension of Jeulin-Yor result (case of single random time without mark).
- We identify Y with the $n + 1$ -tuple (Y^0, \dots, Y^n) .

- **Portfolio of N assets** with \mathbb{G} -adapted value process S :

$$S_t = \sum_{k=0}^n 1_{\Omega_t^k} S_t^k(\tau_k, \zeta_k),$$

where $S^k(\theta_k, \mathbf{e}_k)$, $\theta_k = (\theta_1, \dots, \theta_k) \in \mathbb{R}_+^k$, $\mathbf{e}_k = (e_1, \dots, e_k) \in E^k$, **indexed \mathbb{F} -adapted process** valued in \mathbb{R}_+^N , represents the assets value given the past default events $\tau_k = \theta_k$ and marks at default $\zeta_k = \mathbf{e}_k$.

Change of regimes with jumps at defaults

- Dynamics of $S = S^k$ between $\tau_k = \theta_k$ and $\tau_{k+1} = \theta_{k+1}$:

$$dS_t^k(\boldsymbol{\theta}_k, \mathbf{e}_k) = S_t^k(\boldsymbol{\theta}_k, \mathbf{e}_k) * (b_t^k(\boldsymbol{\theta}_k, \mathbf{e}_k)dt + \sigma_t^k(\boldsymbol{\theta}_k, \mathbf{e}_k)dW_t),$$

where W is a m -dimensional (\mathbb{P}, \mathbb{F}) -Brownian motion, $m \geq N$.

- Jumps at $\tau_{k+1} = \theta_{k+1}$:

$$S_{\theta_{k+1}}^{k+1}(\boldsymbol{\theta}_{k+1}, \mathbf{e}_{k+1}) = S_{\theta_{k+1}}^k(\boldsymbol{\theta}_k, \mathbf{e}_k) * (\mathbf{1}_N + \gamma_{\theta_{k+1}}^k(\boldsymbol{\theta}_k, \mathbf{e}_k, \mathbf{e}_{k+1})),$$

Credit derivative

- A credit derivative of maturity T is represented by a \mathcal{G}_T -measurable random variable H_T :

$$H_T = \sum_{k=0}^n 1_{\Omega_T^k} H_T^k(\tau_k, \zeta_k),$$

where $H_T^k(\cdot, \cdot)$ is $\mathcal{F}_T \otimes \mathcal{B}(\mathbb{R}_+^k) \otimes \mathcal{B}(E^k)$ -measurable, and represents the option payoff in the k -default scenario.

Exogenous counterparty default

- One default time τ ($n = 1$) inducing jumps in the price process S of N -assets portfolio:

$$S_t = S_t^0 \mathbf{1}_{t < \tau} + S_t^1(\tau, \zeta) \mathbf{1}_{t \geq \tau},$$

where S^0 is the price process before default, governed by

$$dS_t^0 = S_t^0 * (b_t^0 dt + \sigma_t^0 dW_t)$$

and $S^1(\theta, e)$, $(\theta, e) \in \mathbb{R}_+ \times E$, is the indexed price process after default at time θ and with mark e :

$$\begin{aligned} dS_t^1(\theta, e) &= S_t^1(\theta, e) * (b_t^1(\theta, e) dt + \sigma_t^1(\theta, e) dW_t), \quad t \geq \theta, \\ S_\theta^1(\theta, e) &= S_\theta^0 * (\mathbf{1}_N + \gamma_\theta(e)). \end{aligned}$$

Multilateral counterparty risk

- Assets family (e.g. portfolio of defaultable bonds) in which each underlying name is subject to **its own default** but also to the defaults of the other names (**contagion effect**).
- ▶ number of defaults $n = N$ number of assets $S = (P^1, \dots, P^n)$
 - ▶ τ_i default time of name P^i , and ζ_i its (random) recovery rate (P^i is not traded anymore after τ_i)
 - ▶ τ_i induces jump on $P^j, j \neq i$.

Admissible control strategies

- A trading strategy in the N -assets portfolio is a \mathbb{G} -predictable process $\pi = (\pi^0, \dots, \pi^n)$:

$\pi^k(\boldsymbol{\theta}_k, \mathbf{e}_k)$ is valued in A^k closed convex set of \mathbb{R}^N ,

denoted $\pi^k \in \mathcal{P}_{\mathbb{F}}(\mathbb{R}_+^k, E^k; A^k)$, and representing the amount invested given the past default events $(\boldsymbol{\tau}_k, \boldsymbol{\zeta}_k) = (\boldsymbol{\theta}_k, \mathbf{e}_k)$, $k = 0, \dots, n$, and until the next default time.

- ▶ The set of *admissible controls*: $\mathcal{A}_{\mathbb{G}} = \mathcal{A}_{\mathbb{F}}^0 \times \dots \times \mathcal{A}_{\mathbb{F}}^n$, where $\mathcal{A}_{\mathbb{F}}^k$ includes some integrability conditions

Remark on the control set

- In this modelling, we allow the control set A^k to vary after each default time. This means that we allow the investor to update her portfolio constraint after each default time.

→ More general than standard formulation where the control set A is invariant in time.

Wealth process

- Given an admissible trading strategy $\pi = (\pi^k)_{k=0, \dots, n}$, the controlled wealth process is given by:

$$X_t = \sum_{k=0}^n 1_{\Omega_t^k} X_t^k(\tau_k, \zeta_k), \quad t \geq 0,$$

where X^k is the wealth process with an investment π^k in the assets of price S^k given the past defaults events (τ_k, ζ_k) .

- Dynamics between $\tau_k = \theta_k$ and $\tau_{k+1} = \theta_{k+1}$:

$$dX_t^k(\theta_k, \mathbf{e}_k) = \pi_t^k(\theta_k, \mathbf{e}_k)' (b_t^k(\theta_k, \mathbf{e}_k) dt + \sigma_t^k(\theta_k, \mathbf{e}_k) dW_t).$$

- Jumps at default time $\tau_{k+1} = \theta_{k+1}$:

$$X_{\theta_{k+1}}^{k+1}(\theta_{k+1}, \mathbf{e}_{k+1}) = X_{\theta_{k+1}^-}^k(\theta_k, \mathbf{e}_k) + \pi_{\theta_{k+1}}^k(\theta_k, \mathbf{e}_k)' \gamma_{\theta_{k+1}}^k(\theta_k, \mathbf{e}_k, \mathbf{e}_{k+1}).$$

Random terminal utility function

- A nonnegative map G_T on $\Omega \times \mathbb{R}$ such that $(\omega, x) \mapsto G_T(\omega, x)$ is $\mathcal{G}_T \otimes \mathcal{B}(\mathbb{R})$ -measurable

$$G_T(x) = \sum_{k=0}^n 1_{\Omega_T^k} G_T^k(x, \tau_k, \zeta_k)$$

where G_T^k is $\mathcal{F}_T \otimes \mathcal{B}(\mathbb{R}) \otimes \mathcal{B}(\mathbb{R}^k) \otimes \mathcal{B}(E^k)$ -measurable.

- Remarks.** 1) Interpretation: there is a change of regimes in the utility after each default time (state-dependent utility functions)
 2) Other example: utility function U with option payoff H_T ,

$$G_T(x) = U(x - H_T) = \sum_{k=0}^n 1_{\Omega_T^k} U(x - H_T^k(\tau_k, \zeta_k)).$$

Value function

- **Value function** of the optimal investment problem:

$$V_0(x) = \sup_{\pi \in \mathcal{A}_G} \mathbb{E} \left[G_T(X_T^{x, \pi}) \right], \quad x \in \mathbb{R}.$$

Remark. One can also deal with running gain function, involving e.g. utility from consumption.

- ▶ How to solve this problem?

Global approach

- Write the dynamics of assets and wealth process in the global filtration \mathbb{G}
 - Jump-Itô controlled process under \mathbb{G} in terms of W and μ (random measure associated to $(\tau_k, \zeta_k)_k$).
- Use a martingale representation theorem for (W, μ) w.r.t. \mathbb{G} under intensity hypothesis on the default times
 - ▶ Derive the dynamic programming Bellman equation in the \mathbb{G} filtration
 - BSDE with jumps or Integro-Partial-differential equations

Global approach: some references

- Single default time: Ankirchner, Blanchet-Scalliet, and Eyraud-Loisel (09), Lim and Quenez (09)
- Multiple default times: Jeanblanc, Matoussi, Nguoupeyou (10)
 - ▶ BSDE with jumps and quadratic generators
 - ▶ Existence and uniqueness under a boundedness condition on portfolio strategies
 - ▶ This approach does not allow to change the control portfolio set after default: π_t valued in A for all t

Our solutions approach

- By relying on the \mathbb{F} -decomposition of \mathbb{G} -processes,
and
- **density hypothesis** on the defaults: El Karoui, Jeanblanc, Jiao (09,10)
- ▶ find a suitable **decomposition** of the \mathbb{G} -control problem on each default scenario \rightarrow **sub-control problems in the \mathbb{F} -filtration**

Density approach

- **Conditional density hypothesis on the joint distribution of default times and marks:** There exists a map $(t, \omega, \boldsymbol{\theta}, \mathbf{e}) \mapsto \alpha_t(\omega, \boldsymbol{\theta}, \mathbf{e})$, $\mathcal{O}(\mathbb{F}) \otimes \mathcal{B}(\mathbb{R}_+^n) \otimes \mathcal{B}(E^n)$ -measurable s.t. for all $t \geq 0$,

$$\text{(DH)} \quad \mathbb{P}[(\boldsymbol{\tau}, \zeta) \in d\boldsymbol{\theta}d\mathbf{e} | \mathcal{F}_t] = \alpha_t(\boldsymbol{\theta}, \mathbf{e})d\boldsymbol{\theta}\eta(d\mathbf{e})$$

where $d\boldsymbol{\theta} = d\theta_1 \dots d\theta_n$ is the Lebesgue measure on \mathbb{R}^n , and $\eta(d\mathbf{e}) = \eta_1(de_1) \dots \eta_n(de_n)$, with $\eta_i(de_i)$ nonnegative Borel measure on E .

Comments on density hypothesis

- Under **(DH)**, $\tau = (\tau_1, \dots, \tau_n)$ admits a \mathbb{F} -conditional density w.r.t. the Lebesgue measure:
 - ▶ τ_i totally inaccessible: default events arrive by surprise
 - ▶ $\tau_i \neq \tau_j$ a.s. for $i \neq j$: non simultaneous default times
- By considering a density process $\alpha_t(\cdot)$, one can take into account some dependence between default times and basic assets price information \mathbb{F}
- More general setting than intensity approach: one can express the intensity of each default time in terms of the density. Immersion hypothesis **(H)** (martingale invariance property) is not required.

Conditional survival density processes

- Under the density hypothesis, let us define the indexed survival density processes α^k , $k = 0, \dots, n-1$, by:

$$\alpha_t^k(\boldsymbol{\theta}_k, \mathbf{e}_k) = \int_{[t, \infty)^{n-k} \times E^{n-k}} \alpha_t(\boldsymbol{\theta}, \mathbf{e}) d\boldsymbol{\theta}_{n-k} \eta(d\mathbf{e}_{n-k}), \quad t \geq 0,$$

where $d\boldsymbol{\theta}_{n-k} = \prod_{j=k+1}^n d\theta_j$, $\eta(d\mathbf{e}_{n-k}) = \prod_{j=k+1}^n \eta_j(d\mathbf{e}_j)$.



$$\mathbb{P}[\tau_{k+1} > t | \mathcal{F}_t] = \int_{\mathbb{R}_+^k \times E^k} \alpha_t^k(\boldsymbol{\theta}_k, \mathbf{e}_k) d\boldsymbol{\theta}_k \eta(d\mathbf{e}_k).$$

Decomposition result

The value function V_0 is obtained by backward induction from the optimization problems in the \mathbb{F} -filtration:

$$\begin{aligned}
 V_n(x, \boldsymbol{\theta}, \mathbf{e}) &= \operatorname{ess\,sup}_{\pi^n \in \mathcal{A}_{\mathbb{F}}^n} \mathbb{E} \left[G_T^n(X_T^{n,x}, \boldsymbol{\theta}, \mathbf{e}) \alpha_T(\boldsymbol{\theta}, \mathbf{e}) \mid \mathcal{F}_{\theta_n} \right] \\
 V_k(x, \boldsymbol{\theta}_k, \mathbf{e}_k) &= \operatorname{ess\,sup}_{\pi^k \in \mathcal{A}_{\mathbb{F}}^k} \mathbb{E} \left[G_T^k(X_T^{k,x}, \boldsymbol{\theta}_k, \mathbf{e}_k) \alpha_T^k(\boldsymbol{\theta}_k, \mathbf{e}_k) \right. \\
 &\quad \left. + \int_{\theta_k}^T \int_E V_{k+1}(X_{\theta_{k+1}}^{k,x} + \pi_{\theta_{k+1}}^k \cdot \gamma_{\theta_{k+1}}^k(\mathbf{e}_{k+1}), \boldsymbol{\theta}_{k+1}, \mathbf{e}_{k+1}) \right. \\
 &\quad \left. \eta_{k+1}(d\mathbf{e}_{k+1}) d\theta_{k+1} \mid \mathcal{F}_{\theta_k} \right].
 \end{aligned}$$

Comments

- This recursive decomposition can be viewed as a dynamic programming relation by considering value functions between two consecutive default times: V_k interpreted as the value function after k defaults.
- This \mathbb{F} -decomposition of the \mathbb{G} -control problem can be viewed as a **nonlinear extension of Dellacherie-Meyer and Jeulin-Yor formula**, which relates linear expectation under \mathbb{G} in terms of linear expectation under \mathbb{F} , and is used in option pricing for credit derivatives.

Remarks

- Each step in the backward induction \longleftrightarrow stochastic control problem in the \mathbb{F} -filtration (solved e.g. by dynamic programming and BSDE)
- In the particular case where all A^k are identical, our method provides an alternative to the dynamic programming method in the \mathbb{G} -filtration, by “getting rid of” the jump terms.

Exponential utility

- Consider the indifference pricing problem of (bounded) defaultable claim:

$$G_T(x) = U(x - H_T) = \sum_{k=0}^n 1_{\Omega_T^k} U(x - H_T^k(\tau_k, \zeta_k)),$$

with an exponential utility function

$$U(x) = -\exp(-px), \quad p > 0, \quad x \in \mathbb{R}.$$

- Assume that $\mathbb{F} = \mathbb{F}^W$ Brownian filtration generated by W .

BSDEs formulation

► Then, the value functions V_k , $k = 0, \dots, n$, are given by

$$V_k(x, \theta_k, \mathbf{e}_k) = U(x - Y_{\theta_k}^k(\theta_k, \mathbf{e}_k)),$$

where Y^k , $k = 0, \dots, n$, are characterized by means of a recursive system of (indexed) BSDEs, derived from dynamic programming arguments in the \mathbb{F} -filtration.

BSDE after n defaults

$$Y_t^n(\boldsymbol{\theta}, \mathbf{e}) = H_T^n(\boldsymbol{\theta}, \mathbf{e}) + \frac{1}{p} \ln \alpha_T(\boldsymbol{\theta}, \mathbf{e}) + \int_t^T f^n(r, Z_r^n, \boldsymbol{\theta}, \mathbf{e}) dr - \int_t^T Z_r^n \cdot dW_r, \quad t \geq \theta_n,$$

with a (quadratic) generator f^n :

$$f^n(t, z, \boldsymbol{\theta}, \mathbf{e}) = \inf_{\pi \in A^n} \left\{ \frac{p}{2} |z - \sigma_t^n(\boldsymbol{\theta}, \mathbf{e})' \pi|^2 - b^n(\boldsymbol{\theta}, \mathbf{e}) \cdot \pi \right\}.$$

Remark. Similar BSDE as in El Karoui, Rouge (00), Hu, Imkeller, Müller (04), Sekine (06), for default-free market

BSDE after k defaults, $k = 0, \dots, n - 1$

$$\begin{aligned}
 Y_t^k(\boldsymbol{\theta}_k, \mathbf{e}_k) &= H_T^k(\boldsymbol{\theta}_k, \mathbf{e}_k) + \frac{1}{\rho} \ln \alpha_T^k(\boldsymbol{\theta}_k, \mathbf{e}_k) \\
 &+ \int_t^T f^k(r, Y_r^k, Z_r^k, \boldsymbol{\theta}_k, \mathbf{e}_k) dr - \int_t^T Z_r^k \cdot dW_r, \quad t \geq \theta_k
 \end{aligned}$$

with a generator

$$\begin{aligned}
 f^k(t, y, z, \boldsymbol{\theta}_k, \mathbf{e}_k) &= \inf_{\pi \in \mathcal{A}^k} \left\{ \frac{\rho}{2} |z - \sigma_t^k(\boldsymbol{\theta}_k, \mathbf{e}_k)' \pi|^2 - b_t^k(\boldsymbol{\theta}_k, \mathbf{e}_k) \cdot \pi \right. \\
 &+ \frac{1}{\rho} U(y) \int_E U(\pi \cdot \gamma_t^k(\mathbf{e}_{k+1}) - Y_t^{k+1}(\boldsymbol{\theta}_k, t, \mathbf{e}_k, \mathbf{e}_{k+1})) \\
 &\left. \eta_{k+1}(d\mathbf{e}_{k+1}) \right\}.
 \end{aligned}$$

BSDE characterization of the optimal investment problem

Theorem. Under standard boundedness conditions on the coefficients of the model $(b, \sigma, \gamma, \alpha, H_T)$, there exists a unique solution $(\mathbf{Y}, \mathbf{Z}) = (Y^0, \dots, Y^n, Z^0, \dots, Z^n) \in \mathbf{S}^\infty \times \mathbf{L}^2$ to the recursive system of quadratic BSDEs. The initial value function is

$$V_0(x) = U(x - Y_0^0),$$

and the optimal strategies between τ_k and τ_{k+1} by

$$\begin{aligned} \pi_t^k \in \arg \min_{\pi \in A^k} & \left\{ \frac{p}{2} |Z_t^k - (\sigma_t^k)' \pi|^2 - b_t^k \cdot \pi \right. \\ & \left. + \frac{1}{p} U(Y_t^k) \int_E U(\pi \cdot \gamma_t^k(e_{k+1}) - Y_t^{k+1}(t, e_{k+1})) \eta_{k+1}(de_{k+1}) \right\}. \end{aligned}$$

Technical remarks

- Existence for the system of recursive BSDEs: quadratic term in z + exponential term in y :
 - ▶ Kobylanski techniques + approximating sequence + convergence
- Uniqueness: verification arguments + BMO techniques
- We don't need to assume boundedness condition on the portfolio control set

Practical remarks

- In the particular case where:
 - ▶ (τ, ζ) independent of \mathbb{F} \rightarrow the density α is deterministic
 - ▶ the assets price coefficients are deterministic, and the payoff H_T^k are constants (e.g. for constant recovery rates)

then the BSDEs reduce to a recursive system of ordinary differential equations, which can be easily solved numerically.

\rightarrow Numerical results in Jiao, P (09) illustrating the impact of a single default time w.r.t. Merton problem

- Further practical use
 - ▶ explicit models for the default density process
 - ▶ numerical resolution of quadratic BSDEs or in a Markovian case (factor models to be specified) of semilinear PDEs

Concluding remarks (I)

- Beyond the optimal investment problem considered here, we provide a general formulation of stochastic control under progressive enlargement of filtration with multiple random times and marks:
 - ▶ Change of regimes in the state process, control set and gain functional after each random time
 - ▶ Includes in particular the formulation via jump-diffusion controlled processes
- Recursive decomposition on each default scenario of the \mathbb{G} -control problem into \mathbb{F} -stochastic control problems by relying on the density hypothesis

Concluding remarks (II)

- Solution characterized by dynamic programming in the \mathbb{F} -filtration: BSDE, Bellman PDE, ...
- \mathbb{F} -decomposition method \rightarrow another perspective for the study of (quadratic) BSDEs with (finite number of) jumps
 - \rightarrow Get rid of the jump terms \rightarrow obtain comparison theorems under weaker conditions
 - \rightarrow Work in progress by Kharroubi and Lim (10).

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