

CLASS 2 - LINEAR ALGEBRA 2

PRE2 - MATH FOR DATASCIENCE

We come back on the example from last time

$$L : \begin{cases} \mathbb{R}^2 \\ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \end{cases} \longrightarrow \mathbb{R}^2 \\ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \longrightarrow \begin{pmatrix} x_1 \\ 5 \end{pmatrix}$$

This is not a linear transformation because

$$L \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 5 \end{pmatrix} \neq 0$$

Proposition: If L is a linear transformation then

$$\boxed{L(0_V) = 0_W}$$

$$L : V \longrightarrow W$$

Since L is linear, $L(x+y) = L(x) + L(y)$

Hence $L(\underline{0_V + 0_V}) = L(0_V) + L(0_V)$

$$\Rightarrow L(\overline{0_V}) = L(0_V) + L(0_V) \Rightarrow L(0_V) = 0_W$$

MATRIX

A matrix is a rectangular array of numbers.

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & a_{22} & & | \\ \vdots & \vdots & & \vdots \\ \vdots & \vdots & & \vdots \\ a_{m1} & & a_{ij} & \\ & & a_{m,m} & \end{pmatrix}$$

↑
m rows
← m columns

A is a $m \times m$ matrix

$$A = (a_{ij})_{\substack{1 \leq i \leq m \\ 1 \leq j \leq n}}$$

Example:

$$A = \begin{pmatrix} 3 & 2 \\ 5 & 0 \end{pmatrix}$$

is a 2×2 matrix

If $m = n$, we talk about a square matrix.

Adding two matrices

Let A be a $m \times n$ matrix

B \longrightarrow $m \times n$ matrix

$$A + B = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m,1} & & a_{mn} \end{bmatrix} + \begin{bmatrix} b_{11} & \dots & b_{1n} \\ \vdots & & \vdots \\ b_{m,1} & & b_{mn} \end{bmatrix} = \begin{bmatrix} a_{11} + b_{11} & \dots & a_{1n} + b_{1n} \\ \vdots & & \vdots \\ a_{m,1} + b_{m,1} & & a_{mn} + b_{mn} \end{bmatrix}$$

$$A + B = (a_{ij} + b_{ij}) \quad \begin{matrix} 1 \leq i \leq m \\ 1 \leq j \leq n \end{matrix}$$

Examples:

$$\begin{bmatrix} 2 & 0 \\ 1 & 1 \\ 0 & 3 \end{bmatrix} + \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 0 & 5 \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ 1 & 2 \\ 0 & 8 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix} + \begin{bmatrix} 1 & 3 \\ 0 & 1 \\ 1 & 2 \end{bmatrix} =$$

Impossible to add

MULTIPLICATION BY A SCALAR

$$tA = \begin{bmatrix} tam_1 & \dots, tam_1 \\ \vdots & \vdots \\ tam_1 & \dots, tam_m \end{bmatrix}$$

ex : $3 \begin{bmatrix} 2 & 0 \\ 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 6 & 0 \\ 3 & 3 \\ 0 & 3 \end{bmatrix}$

MATRIX-VECTOR MULTIPLICATION

Let A a $m \times n$ matrix ; x a n -dim vector

(that we can also see as
a $n \times 1$ matrix)

$$A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix}$$

$$Ax = \begin{bmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n \end{bmatrix}$$

$$A \times \begin{pmatrix} m \times n \\ n \times 1 \end{pmatrix}$$

Example:

$$A = \begin{bmatrix} 2 & 1 \\ 2 & 0 \end{bmatrix} ; x = \begin{bmatrix} 1 \\ -3 \end{bmatrix}, \text{ compute } Ax = ?$$

$$\begin{bmatrix} 2 & 1 \\ 2 & 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -3 \end{bmatrix}$$

$$Ax = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$$

2x1 matrix
or 2-dim vector

Another way to see the matrix-vector multiplication:

$$A = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ \vdots \\ x_m \end{bmatrix}$$

$$Ax = \underbrace{x_1^T A_1 + \dots + x_n^T A_n}_R$$

linear combination of the columns
of A (which are vectors) with weights
 x_1, \dots, x_m (coordinates of vector x)

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \quad x = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$Ax = 2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 3 \end{bmatrix}$$

Let A be a $m \times n$ matrix , $A = \begin{bmatrix} A_1, \dots, A_n \end{bmatrix}$

$$\begin{bmatrix} m \\ n \end{bmatrix} \xrightarrow{\text{def}} \mathbb{R}^m$$

$$x \xrightarrow{\text{def}} Ax \left(= x_1 A_1 + \dots + x_m A_m\right)$$

PROPOSITION: $x \xrightarrow{\text{def}} Ax$ is a linear transformation from \mathbb{R}^n to \mathbb{R}^m

PROOF : Verify : $L(x+y) = L(x) + L(y)$
 $L(\lambda x) = \lambda L(x)$

We have seen that we can associate to a matrix a linear transformation.
 The converse is true, we can associate to a linear transformation from two vector spaces of finite dimension a matrix.

Let $L: E \rightarrow V$ be a linear transformation. E : is a n dim- vector space

V : a m dim- vector space

Let $\{e_1, \dots, e_n\}$ be a basis of vectors of E

Let $\{b_1, \dots, b_m\}$ _____ of V

$L(e_1) \in V$, I can decompose it in a unique way on $\{b_1, \dots, b_m\}$

$$L(e_1) = d_{11}b_1 + \dots + d_{m1}b_m$$

$$L(e_2) = d_{12}b_1 + \dots + d_{m2}b_m$$

:

:

We say that B is the representation of L in the basis $\{e_1, \dots, e_n\}; \{b_1, \dots, b_m\}$

$$B = \begin{bmatrix} d_{11} & d_{12} & \dots & d_{1m} \\ \vdots & \vdots & & \vdots \\ d_{n1} & d_{n2} & \dots & d_{nm} \end{bmatrix} \begin{matrix} b_1 \\ \vdots \\ b_m \end{matrix}$$

$\xleftarrow{n} \quad \xrightarrow{m}$

B is a $m \times n$ matrix

EXERCICE : Find the matrix corresponding to the linear transformation
 $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ in the standard basis.

$$T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} z \\ x \\ y \end{pmatrix}$$

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

Standard basis in \mathbb{R}^3 , $\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$

$$\begin{aligned} T(e_1) &= \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, & T(e_2) &= \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}; & T(e_3) &= \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \\ &= 0e_1 + 1e_2 + 0e_3 & &= 0e_1 + 0e_2 + 1e_3 & &= 1e_1 + 0e_2 + 0e_3 \end{aligned}$$

$$A = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{matrix} e_1 \\ e_2 \\ e_3 \end{matrix}$$

A is the representation of T in the standard basis.

In \mathbb{R}^n the standard basis is $\{e_1, \dots, e_n\}$

$$e_i = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \in \mathbb{R}^n$$

 There is not an unique way to represent a linear transformation as a matrix. If you change the basis, this will change the matrix representation.

If you consider the basis $\tilde{e}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \tilde{e}_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \tilde{e}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \tilde{e}_3$ will be different.

If $L: E \rightarrow V$ is a linear transformation, B its matrix representation in $\{e_1, \dots, e_n\}$ and $\{b_1, \dots, b_m\}$
 $x \in E$ represented $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$ in $\{e_1, \dots, e_n\}$

Then $L(x)$ is represented as $\underbrace{Bx}_{\text{Product: matrix, vector.}}$ in $\{b_1, \dots, b_m\}$

MATRIX MULTIPLICATIONS:

let A be a $m \times m$ matrix

Let B be a $n \times p$ matrix

Then AB , is a $m \times p$ matrix such that

$$(m \times n) \times (n \times p)$$

\downarrow

$$(m, p)$$

$$\forall x \in \mathbb{R}^p \quad (AB)x = A(Bx)$$

Concretely:

$$A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix}$$

$$B = \begin{bmatrix} b_{11} & \dots & b_{1p} \\ \vdots & & \vdots \\ b_{m1} & \dots & b_{mp} \end{bmatrix}$$

$$(AB)_{ij} = \sum_{k=1}^m a_{ik} b_{kj}$$

$$a_{11}b_{11} + a_{12}b_{21} + \dots + a_{1n}b_{n1}$$

Multiply :

$$\begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 4 & 1 \\ 6 & 0 & 12 & 3 \\ 1 & 0 & 0 & 1 \\ 2 & 0 & 4 & 1 \end{bmatrix}$$

⚠ Be careful about sizes , you can't multiply a (2×2) & (3×4) matrix

impossible

Remember:

$$(m \times n) \quad (m \times p)$$

(Same)
(m \times p) \quad \text{matrix}

RANK, KERNEL (NULLSPACE), INVERSE OF A MATRIX

DEFINITION : The rank of a matrix A is defined as the rank of the linear transformation

$$A \begin{cases} \mathbb{R}^n \\ x \end{cases} \longrightarrow \mathbb{R}^m$$

$$\text{rank}(A) = \dim \underbrace{A(\mathbb{R}^n)}_{\text{Range of } A \text{ or Image of } A}$$

Since $Ax = \underbrace{x_1 A_1 + x_2 A_2 + \dots + x_n A_n}_{\text{linear combinations of columns of } A}$

Then $\text{rank}(A)$ is the dimension of the $\text{span}(A_1, \dots, A_n)$

Example :- $\text{rank} \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} = 2$

$$\text{rank} \begin{pmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} = 1 \quad \text{rank} \begin{pmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} = 2$$

DEFINITION: The kernel or nullspace of a $m \times n$ matrix A is the kernel of $x \in \mathbb{R}^n \mapsto Ax \in \mathbb{R}^m$. That is

$$\text{Ker}(A) = \left\{ x \in \mathbb{R}^n \mid Ax = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix} \right\}$$

Example: Rank and Kernel of

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

rank ?

$$\text{Span} \left\{ \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 2 \end{pmatrix} \right\} = \mathbb{R}^2$$

$$\text{rank}(A) = 2$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\text{Ker}(A) = \left\{ x \in \mathbb{R}^3 \mid Ax = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix} \right\}$$

$$= \left\{ x \in \mathbb{R}^3 \mid \begin{bmatrix} x_1 \\ x_2 \\ 2x_3 \end{bmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix} \right\}$$

$$= \left\{ x \in \mathbb{R}^3 \mid x_2 = x_3 = 0 \right\}$$

$$= \left\{ \begin{pmatrix} x_1 \\ 0 \\ 0 \end{pmatrix} \mid x_1 \in \mathbb{R} \right\} = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\}$$

$$\dim(\text{Ker } A) = 1$$

$$Ax = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ 2x_3 \end{bmatrix}$$

The rank(A) and dim Ker(A) are consistent with the RANK NULLITY Theorem

$$\text{rank}(A) + \dim(\text{Ker}(A)) = \dim(\mathbb{R}^3)$$

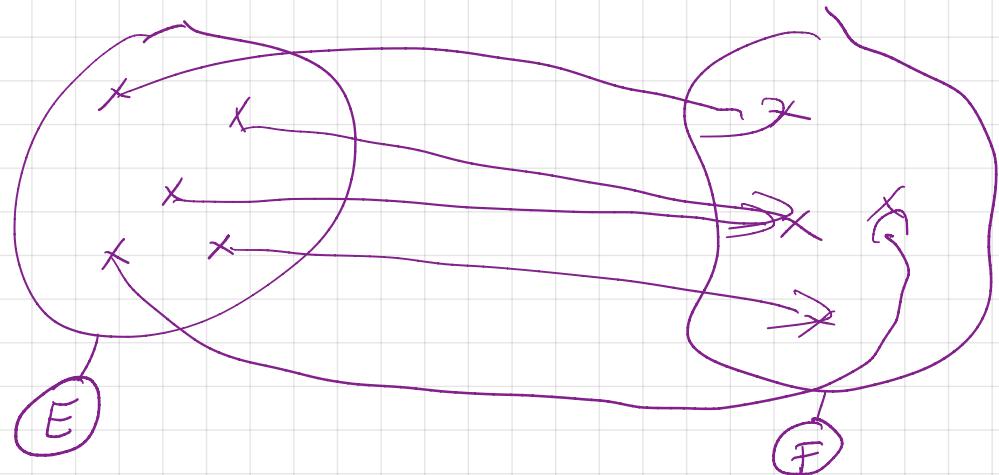
11
2

11
1

11
3

We forgot about matrix, linear transformation and we want to talk
 for a mapping $f: E \rightarrow F$ bijection, surjection , injection .
 set set

f can be $f: \exp \{ \mathbb{R} \rightarrow \mathbb{R}_{\geq 0}$
 $x \mapsto \exp(x)$



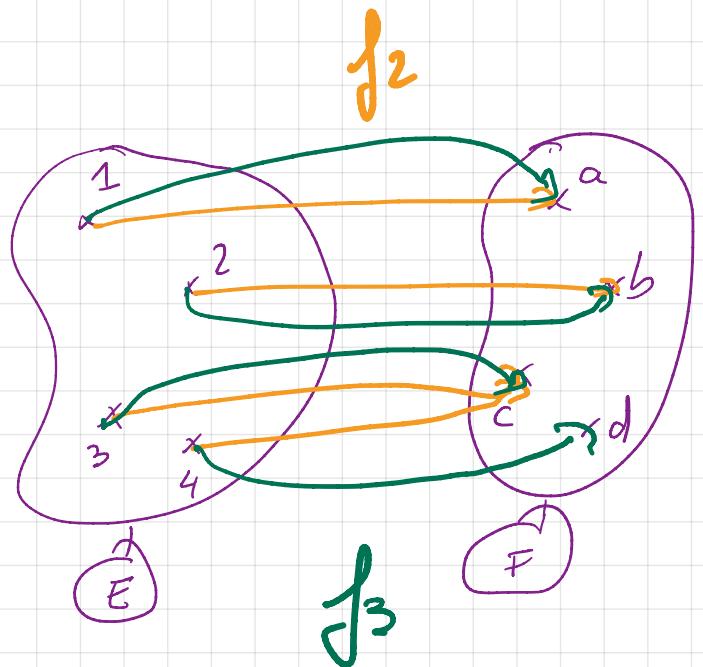
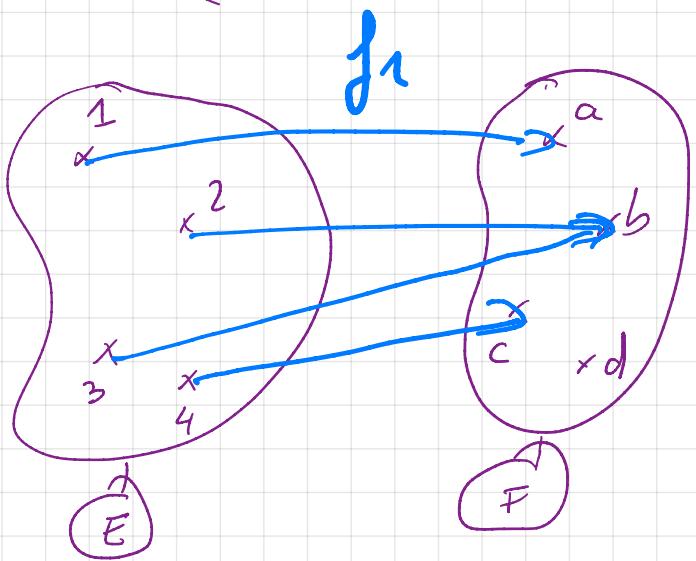
DEFINITION: We say that f is **surjective** if all elements of F have a

| pre-image by f , i.e. $\forall y \in F, \exists x \in E, f(x) = y$
 | "antecedent" IN FRENCH

DEFINITION: We say that f is **injective** if two elements of E are sent on different elements of F

I.E. $\forall x_1, x_2 \in E, f(x_1) = f(x_2) \Rightarrow x_1 = x_2$

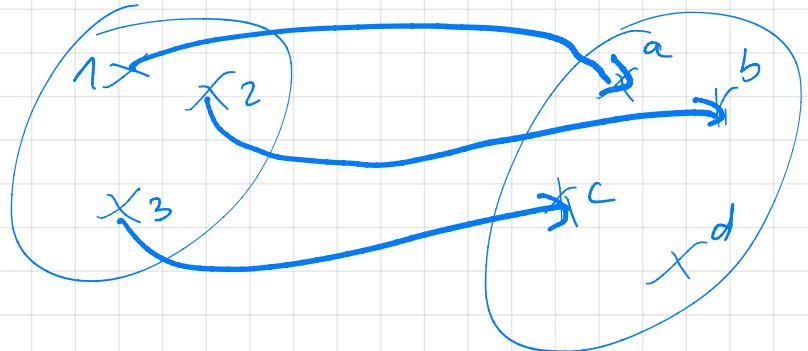
EXAMPLES



f_1 , injective, surjective ?
 f_2 ?
 f_3 ?

$\rightarrow f_1$ is not surjective because d has no pre-image.
 $f_1 \rightarrow$ injective because $f_1(2) = f_1(3)$

Same for f_2 : not injective and not surjective.
 f_3 is both injective and surjective



This is injective but not surjective

DEFINITION : If $f: E \rightarrow F$ is both injective and surjective, we say that f is **bijection**.

If f is bijective then $\forall y \in F$ there exist an unique $x \in E$ such that $y = f(x)$

$\exists !$
P exists & unique

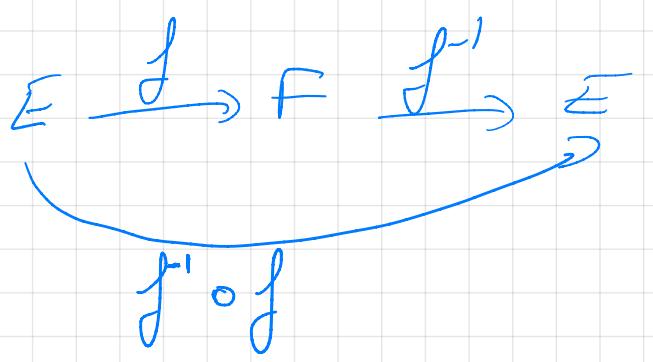
If f is bijective there exists an inverse mapping denoted f^{-1} such that

$$f \circ f^{-1} = f^{-1} \circ f = \text{id}$$

$\underbrace{f^{-1}(f(x))}_{} = x$

$$\begin{array}{c} f \\ \downarrow \\ E \xrightarrow{\quad} F \xrightarrow{\quad f^{-1} \quad} E \end{array}$$

$x \rightarrow f(x) \rightarrow f^{-1}(f(x)) = x$

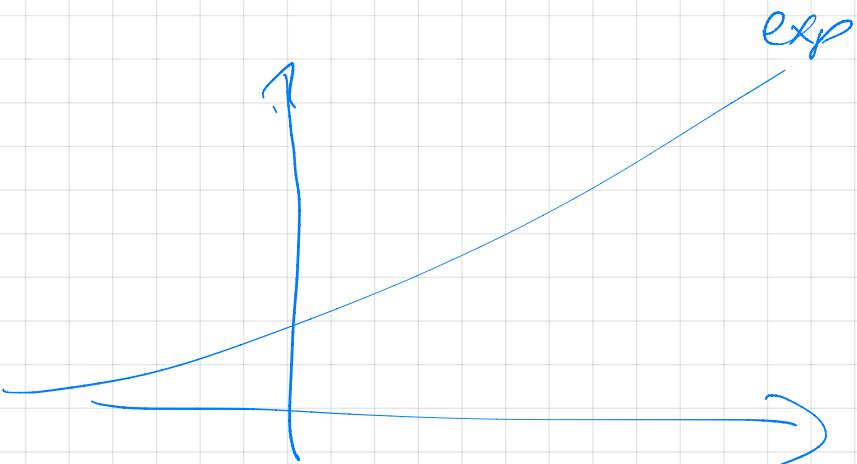


Example:

$$\begin{aligned} \exp : & \mathbb{R} \longrightarrow \mathbb{R}_{\geq 0} \\ & x \longmapsto \exp(x) \end{aligned}$$

$$\exp^{-1} = \ln$$

$$\exp(\ln(x)) = x$$



We go back to matrices.

Proposition: Let A be a $m \times m$ matrix, Then

$$\boxed{(x \in \mathbb{R}^n \mapsto Ax \text{ is injective}) \Leftrightarrow (\text{Ker } A = \{0\})}$$

PROOF: Look for the proof for the next class [EXERCISE]

$$(x \xrightarrow{A} Ax \text{ is surjective}) \Leftrightarrow \begin{matrix} \text{range}(A) = \mathbb{R}^m \\ A(\mathbb{R}^n) \end{matrix}$$

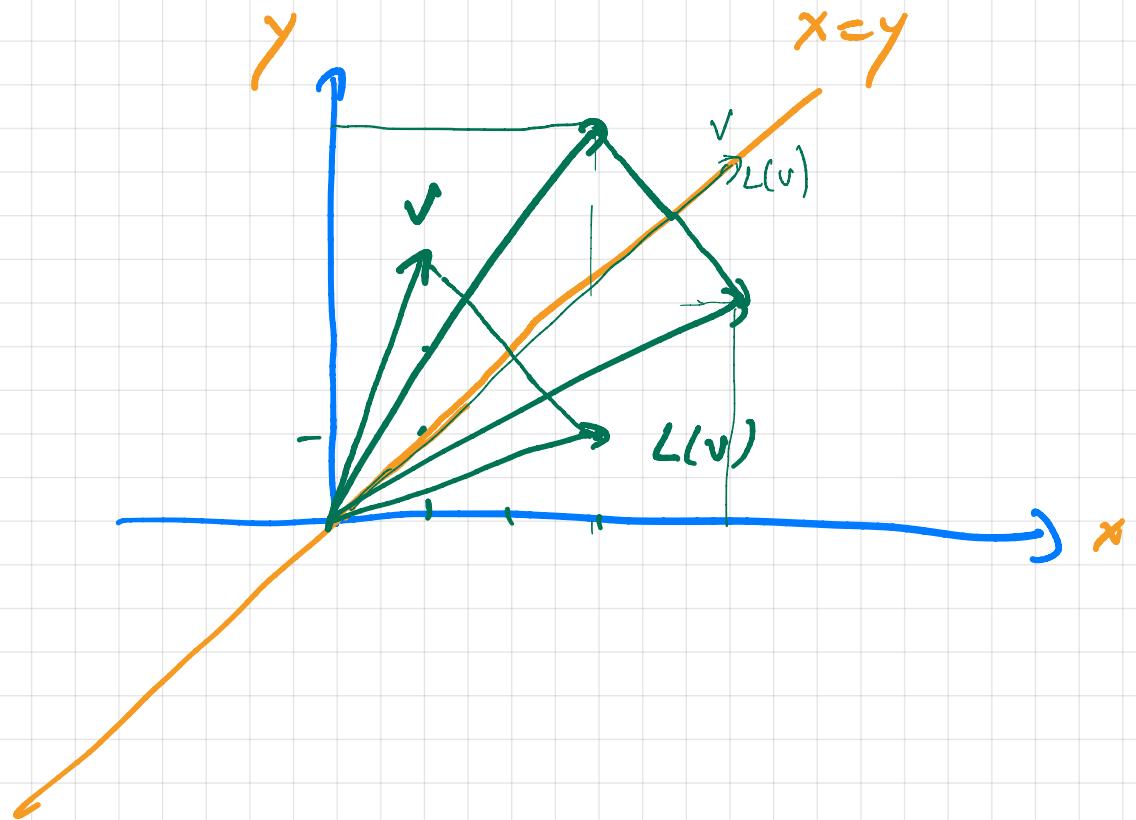
THEOREM: If A is a $n \times n$ matrix (square). Then the following one equivalent:

- (i) the transformation $x \mapsto Ax$ is bijective
- (ii) $\text{range}(A) = \mathbb{R}^n$ ($x \mapsto Ax$ is surjective)
- (iii) $\text{Ker } A = \{0\}$ ($x \mapsto Ax$ is injective)

PROOF: EXERCISE

ELEMENTS FOR THE
CORRECTION OF EXERCICES

$$L_1 : \begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} y \\ x \end{pmatrix}$$



L_1 the symmetry with respect
to " $x = y$ "