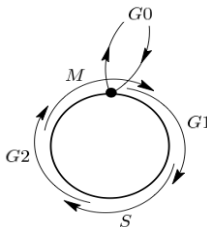
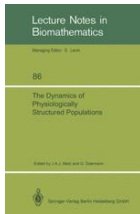


Structured eq. in biology

entropy and Monge-Kantorovich distance

Benoît Perthame

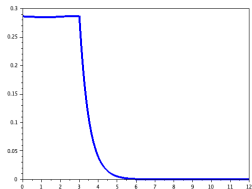


1. Motivations
2. Generalised relative entropy
3. Monge-Kantorovich distance and PDEs
4. Sexual reproduction

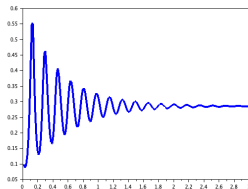
$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x)n(t, x) = 0, & t \geq 0, x \geq 0 \\ N(t) := n(t, x = 0) = \int_0^\infty b(y)n(t, y)dy \\ n(t = 0, x) = n^{init}(x) \end{cases}$$

$$b, d \in L_+^\infty(0, \infty).$$

- Very useful (demography, cell cycle, anomalous diffusions)
- Very standard (Feller, Kermack-McKendrick)
- Many extensions



Left : $b = d$



Right : $N(t)$

Other useful equation

$$\begin{cases} \frac{\partial n(t, x)}{\partial t} + \frac{\partial [g(x)n(t, x)]}{\partial x} + b(x)n(t, x) = k \int_x^\infty b(y)\kappa(x, y)n(t, y)dy \\ n(t, x=0) = 0, \quad g(0) > 0 \end{cases}$$

- $b(y)$ = is the division rate of cells ($k = 2$),
of polymers ($k \geq 2$),
of messages of sizes ($k = 1$),
- $\kappa(x, y) = 0$ for $x > y$ (x = size after division)



Remark : The renewal equation : jumps are to 0

Other useful equation

$$\begin{cases} \frac{\partial n(t, x)}{\partial t} + \frac{\partial [g(x)n(t, x)]}{\partial x} + b(x)n(t, x) = k \int_x^\infty b(y)\kappa(x, y)n(t, y)dy \\ n(t, x=0) = 0, \quad g(0) > 0 \end{cases}$$

- $b(y)$ = is the division rate of cells/polymers/messages of sizes y
- $\kappa(x, y) = 0$ for $y > x$ (x = size after division)

- $\frac{d}{dt} \int_0^\infty n(t, x)dx = (k - 1) \int_0^\infty b(x)n(t, x)dx$
- $\frac{d}{dt} \int_0^\infty xn(t, x)dx = \int_0^\infty g(x)n(t, x)dx.$

Assuming : $\int_0^y \kappa(x, y)dx = 1, \quad k \int_0^y x\kappa(x, y)dx = y$

Immunity distribution by waning and boosting

$$\begin{aligned}\frac{\partial n(t, x)}{\partial t} - \frac{\partial [xn(t, x)]}{\partial x} + bl(t)n(t, x) \\ = bl(t) \int_0^x \kappa(x, y)n(t, y)dy\end{aligned}$$

- $n(t, x)$ = population density with immune level x
- $I(t)$ = infected population
- b = encounter rate



- 0. Diekmann, Rost-Barbarossa, Heffernan-Keeling

Age and size structured

$$\left\{ \begin{array}{l} \frac{\partial n(t,x,z)}{\partial t} + \frac{\partial n(t,x,z)}{\partial x} + \frac{\partial [g(z)n]}{\partial z} + d(x,z)n(t,x,z) = 0, \quad x > 0, z > 0, \\ n(t,x,z=0) = 0, \\ n(t,x=0,z) = \int_{x=0}^{\infty} \int_{z'=z}^{\infty} d(x',z')\kappa(z,z')n(t,x',z')dx'dz \end{array} \right.$$

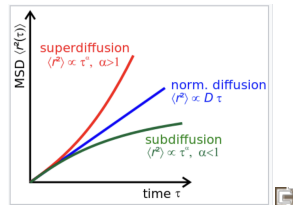
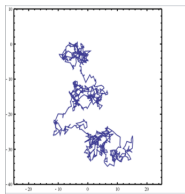
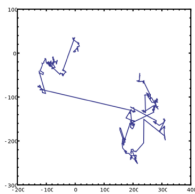
- Doumic, M. ; Hoffmann, M. ; Krell, N. ; Robert, L. et al (2015)
- D. Chafai, F. Malrieu, and K. Paroux (2010)
- J. Bertoin and A. R. Watson, (2020)
- J.-B. Bardet, A. Christen, A. Guillin, F. Malrieu, and P.-A. Zitt (2013)

Age and space structured (subdiffusions)

- Berry, H. ; Lepoutre, T. ; González, A. ; *Acta Appl. Math.* (2016)
- Calvez, V. ; Gabriel, P. ; Mateos G. ; *Asymptot. Anal.* (2019)
- Franck M. ; Goudon T. ; *KRM* (2018), • Min Tang et al ; *Phys Rev. Res.* (2022)

$$\begin{cases} \frac{\partial n(t,x,z)}{\partial t} + \frac{\partial n(t,x,z)}{\partial x} + d(x)n(t,x,z) = 0, & x > 0, z \in \mathbb{R}^d \\ n(t, x = 0, z) = \int_0^\infty \int_{\mathbb{R}^d} d(x)n(t, x, z - \varepsilon\eta)\kappa(\eta)dx d\eta \end{cases}$$

■ Different limits as $\varepsilon \rightarrow 0$



$$D_t^\alpha \rho = \Delta \rho$$

subdiffusion eq.

The multi-time renewal equation

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} n(t, x_1, \dots, x_N) + \sum_{i=1}^N \frac{\partial}{\partial x_i} n(t, x_N) + d(x_N) n(t, x_N) = 0 \\ n(t, x_1 = 0, x_2, \dots, x_N) = \int_0^\infty dn(t, x_2, \dots, x_N, y) dy \\ n(t, x_1, x_2, \dots, x_i, \dots, x_N) = 0, \quad i = 2, \dots, N \end{array} \right.$$

- Used to evaluate efficiency of the Covid tracing Apps
- Spikes in neuroscience
- Non-Markovian processes

And systems of such eq.

They share the properties

- non necessarily conservative
- solutions are non-negative
- not necessarily compact
- not self-adjoint

1. Motivations
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All (linear) equations preserving positivity satisfy the GRE when there are

$$\mathcal{L}\varphi + \lambda_0\varphi = 0, \quad \varphi > 0, \quad \mathcal{L}^*\psi + \lambda_0\psi = 0, \quad \psi > 0,$$

and

$$\int \varphi\psi = 1.$$

For the renewal equation it is enough that

$$\int b(x)e^{-\int_0^x d} dx > 1$$

or

$$\int b(x)e^{-\int_0^x d} dx = 1 \quad \text{and} \quad \int e^{-\int_0^x d} < \infty$$

All (linear) equations preserving positivity satisfy the GRE

$$\mathcal{L}\varphi + \lambda_0\varphi = 0, \quad \varphi > 0, \quad \mathcal{L}^*\psi + \lambda_0\psi = 0, \quad \psi > 0,$$

Let

$$\frac{\partial n(t)}{\partial t} + \mathcal{L}n(t, x) = 0.$$

GRE Principle. For all $H(\cdot)$ convex, $u(t, x) = e^{-\lambda_0 t} \frac{n(t, x)}{\varphi(x)}$ satisfies

$$\frac{d}{dt} \int \psi(x) \varphi(x) H(u(t, x)) dx = -D_H(t) \leq 0$$

■ $\psi \varphi H(u(t, x))$ is a subsolution (P. Michel, S. Mischler, BP)

■ **Loskot and Rudnicki (1991)** : abstract semi-group inequality

■ The important information is in D_H

All (linear) equations preserving positivity satisfy the GRE

$$\mathcal{L}\varphi + \lambda_0\varphi = 0, \quad \varphi > 0, \quad \mathcal{L}^*\psi + \lambda_0\psi = 0, \quad \psi > 0,$$

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Why is it useful ?

- Various estimates as in Perron-Froebenius theory
- Convergence to steady state (Poincaré inequality)

$$\mathcal{L}\varphi + \lambda_0\varphi = 0, \quad \varphi > 0, \quad \mathcal{L}^*\psi + \lambda_0\psi = 0, \quad \psi > 0,$$

$$\frac{\partial n(t)}{\partial t} + \mathcal{L}n(t, x) = 0.$$

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$$\frac{d}{dt} \int \psi(x) \varphi(x) H(u(t, x)) dx = -D_H(t) \leq 0$$

■ $\int \psi(x) n(t, x) dx = e^{\lambda_0 t} \int \psi(x) n^{init}(x) dx$ (Conservation law)

Take $H(u) = u$ and $H(u) = -u$

$$\mathcal{L}\varphi + \lambda_0\varphi = 0, \quad \varphi > 0, \quad \mathcal{L}^*\psi + \lambda_0\psi = 0, \quad \psi > 0,$$

$$\frac{\partial n(t)}{\partial t} + \mathcal{L}n(t, x) = 0.$$

GRE Principle. For all $H(\cdot)$ convex, $u(t, x) = e^{-\lambda_0 t} \frac{n(t, x)}{\varphi(x)}$ satisfies

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- $\int \psi(x) n(t, x) dx = e^{\lambda_0 t} \int \psi(x) n^{init}(x) dx$ (Conservation law)
- $\int \psi(x) |n(t, x)| dx \leq e^{\lambda_0 t} \int \psi(x) |n^{init}(x)| dx$ (L^1 contraction)

Take $H(u) = |u|$

$$\mathcal{L}\varphi + \lambda_0\varphi = 0, \quad \varphi > 0, \quad \mathcal{L}^*\psi + \lambda_0\psi = 0, \quad \psi > 0,$$

$$\frac{\partial n(t)}{\partial t} + \mathcal{L}n(t, x) = 0.$$

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- $\int \psi(x) n(t, x) dx = e^{\lambda_0 t} \int \psi(x) n^{init}(x) dx$ (Conservation law)
- $\int \psi(x) |n(t, x)| dx \leq e^{\lambda_0 t} \int \psi(x) |n^{init}(x)| dx$ (L^1 contraction)
- $u^{init} \leq C^{init} \implies u(t, x) \leq C^{init}$ (Max. principle)

Take $H(u) = (u - C^{init})_+^2$

$$\mathcal{L}\varphi + \lambda_0\varphi = 0, \quad \varphi > 0, \quad \mathcal{L}^*\psi + \lambda_0\psi = 0, \quad \psi > 0,$$

$$\frac{\partial n(t)}{\partial t} + \mathcal{L}n(t, x) = 0.$$

GRE Principle. For all $H(\cdot)$ convex, $u(t, x) = e^{-\lambda_0 t} \frac{n(t, x)}{\varphi(x)}$ satisfies

$$\frac{d}{dt} \int \psi(x) \varphi(x) H(u(t, x)) dx = -D_H(t) \leq 0$$

- $\int \psi(x) n(t, x) dx = e^{\lambda_0 t} \int \psi(x) n^{init}(x) dx$ (Conservation law)
- $\int \psi(x) |n(t, x)| dx \leq e^{\lambda_0 t} \int \psi(x) |n^{init}(x)| dx$ (L^1 contraction))
- $u^{init} \leq C^{init} \implies u(t, x) \leq C^{init}$ (Max. principle)
- $\partial_t \ln n(t, x) \leq \max_x -\mathcal{L}n^{init}(x)$ (for coef. independent of time)

Because $\partial_t n$ satisfies the same equation

More generally, one can compare solutions

$$\frac{\partial n(t)}{\partial t} + \mathcal{L}n(t, x) = 0.$$

GRE Principle. For all $H(\cdot)$ convex, $u(t, x) = e^{-\lambda_0 t} \frac{n(t, x)}{\Phi(t, x)}$ satisfies

$$\frac{d}{dt} \int \Psi(t, x) \Phi(x) H(u(t, x)) dx = -D_H(t) \leq 0$$

Whenever

$$\frac{\partial \Phi(t)}{\partial t} + \mathcal{L}\Phi(t, x) = 0$$

$$\frac{\partial \Psi(t)}{\partial t} + \mathcal{L}^*\Psi(t, x) = 0$$

Example. Periodic coefficients and λ_0 is replaced by the Floquet eigenvalue

Examples. $u(t, x) = e^{-\lambda_0 t} \frac{n(t, x)}{\varphi(x)}$

Fokker-Planck eq.

$$\frac{\partial n(t, x)}{\partial t} - \Delta n + \operatorname{div}(n \nabla V) = 0$$
$$\lambda_0 = 0, \quad \psi = 1, \quad \varphi = e^V,$$

conservative pb. have just relative entropy

$$\frac{d}{dt} \int \frac{n(t, x)^2}{\varphi} dx = -D_2$$

$$D_H = \int \varphi H''(u) |\nabla u|^2$$

Examples. $u(t, x) = e^{-\lambda_0 t} \frac{n(t, x)}{\varphi(x)}$

Fokker-Planck eq.

$$\frac{\partial n(t, x)}{\partial t} - \Delta n - \operatorname{div}(n \nabla V) = 0$$
$$\lambda_0 = 0, \quad \psi = 1, \quad \varphi = e^{-V},$$

conservative pb. have just relative entropy

$$\frac{d}{dt} \int \frac{n(t, x)^2}{\varphi} dx = -D_2, \quad D_H = \int \varphi H''(u) |\nabla u|^2$$

The Poincaré inequality : When $D^2 V \geq \nu Id$, then

$$\nu \int u(x)^2 \varphi dx \leq \int |\nabla u|^2 \varphi dx, \quad \forall u \text{ s.t. } \int u \varphi dx = 0$$

Examples : Renewal eq. $u(t, x) = e^{-\lambda_0 t} \frac{n(t, x)}{\varphi(x)}$

$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x)n(t, x) = 0, \\ N(t) := n(t, x = 0) = \int_0^\infty b(y)n(t, y)dy \end{cases}$$

$$\frac{\partial}{\partial x} \varphi(x) + [d(x) + \lambda_0] \varphi(x) = 0$$

$$-\frac{\partial}{\partial x} \frac{1}{\varphi(x)} + [d(x) + \lambda_0] \frac{1}{\varphi(x)} = 0$$

Note that the adjoint eq. is

$$-\frac{\partial}{\partial x} \psi(x) + [d(x) + \lambda_0] \psi(x) = \psi(0)b(x)$$

Examples : Renewal eq. $u(t, x) = e^{-\lambda_0 t} \frac{n(t, x)}{\varphi(x)}$

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$$-\frac{\partial}{\partial x} \frac{1}{\varphi(x)} + [d(x) + \lambda_0] \frac{1}{\varphi(x)} = 0$$

$$\frac{\partial}{\partial t} u(t, x) + \frac{\partial}{\partial x} u(t, x) = 0$$

$$\frac{\partial}{\partial t} \varphi H(u(t, x)) + \frac{\partial}{\partial x} \varphi H(u(t, x)) + [d(x) + \lambda_0] \varphi H(u(t, x)) = 0$$

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$$-\frac{\partial}{\partial x} \psi(x) + [d(x) + \lambda_0] \psi(x) = \psi(0)b(x)$$

$$\frac{\partial}{\partial t} \psi \varphi H(u(t, x)) + \frac{\partial}{\partial x} \psi \varphi H(u(t, x)) = -\psi(0)b(x) \varphi H(u(t, x))$$

Examples : Renewal eq. $u(t, x) = e^{-\lambda_0 t} \frac{n(t, x)}{\varphi(x)}$

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$$\frac{\partial}{\partial t} \psi \varphi H(u(t, x)) + \frac{\partial}{\partial x} \psi \varphi H(u(t, x)) = -\psi(0)b(x)\varphi H(u(t, x))$$

$$\frac{d}{dt} \int_0^\infty \psi \varphi H(u(t, x)) = \psi(0) [\varphi(0)H(u(t, 0)) - \int_0^\infty b(x)\varphi H(u(t, x))]]$$

Normalise $\varphi(0) = 1 = \int_0^\infty b\varphi$ to simplify and

$$\begin{aligned} \frac{d}{dt} \int_0^\infty \psi \varphi H(u(t, x)) &= \psi(0) [H(\int b\varphi u) - \underbrace{\int b\varphi H(u)}_{\text{proba.}}] \\ &\leq 0 \quad (\text{Jensen's inequality}) \end{aligned}$$

Examples : Growth-fragmentation eq.

The spectral theory is not so easy (see M. Doumic, P. Gabriel)

$$\frac{\partial n(t, x)}{\partial t} + \frac{\partial [g(x)n(t, x)]}{\partial x} + b(x)n(t, x) = 2 \int_x^\infty b(y)\kappa(x, y)n(t, y)dy$$

$$D_H = 2 \iint \overbrace{\psi(x)\varphi(y)b(y)\kappa(x, y)}^{\text{possibly degenerate}} \\ \left[H(u(y)) - H(u(x)) - H'(u(x))(u(y) - u(x)) \right] dx dy$$

A general consequence of GRE is

'Theorem' With a non-degeneracy condition*, it holds

$$\|e^{-\lambda_0 t} n(t, x) - \rho^{init} \varphi\| \rightarrow 0 \quad \text{as } t \rightarrow \infty.$$

$$\rho^{init} := \frac{\int n^{init}(x) \psi(x) dx}{\int \varphi(x) \psi(x) dx}$$

* When the entropy dissipation vanishes and eq. holds, we should have $u = 1$

Spectral gap. Next step is to know if there is $\lambda_1 > 0$ such that

$$\|e^{-\lambda_0 t} n(t, x) - \rho^{init} \varphi\| \leq C e^{-\lambda_1 t} ?$$

By linearity, we work with $u = \frac{n e^{-\lambda_0 t}}{\varphi} - \rho^{init}$

■ **Poincaré inequality** : when $\int \psi \varphi u(x) = 0$

$$\lambda_1 \int \psi \varphi H(u) dx \leq D_H(u)$$

If it holds, then

$$\frac{d}{dt} \int \psi(x) \varphi(x) H(u(t, x)) dx = -D_H(t) \leq -\lambda_1 \int \psi \varphi H(u) dx$$

Spectral gap. Next step is to know if there is $\lambda_1 > 0$ such that

$$\|e^{-\lambda_0 t} n(t, x) - \rho^{init} \varphi\| \leq C e^{-\lambda_1 t} ?$$

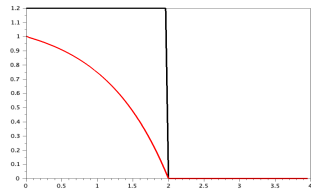
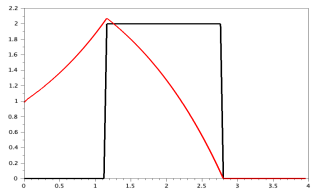
■ **Poincaré inequality** : when $\int \psi(x) \varphi(x) u(x) = 0$

$$\lambda_1 \int \psi \varphi H(u) dx \leq D_H(u)$$

Theorem : Assume there is $\lambda_1 > 0$ such that

$$\lambda_1 \psi(x) \leq b(x) \psi(0)$$

then the Poincaré inequality holds



Theorem : Assume there is $\lambda_1 > 0$ such that

$$\lambda_1 \psi(x) \leq b(x) \psi(0)$$

then the Poincaré inequality holds

$$\lambda_1 \int \psi \varphi H(u) dx \leq D_H(u), \quad \forall u \text{ s.t. } \int \psi(x) \varphi(x) u(x) = 0$$

Proof : Set $\mu(x) = \frac{b(x)\varphi(x)}{\psi(0)}$ (proba.) and $h(u) = |u|$

$$\begin{aligned} & \left| \int \mu(x) |u(t, x)| dx - \left| \int \mu(x) u(t, x) dx \right| \right| \\ &= \left| \int \mu(x) |u(t, x)| dx - \left| \int \left[\mu(x) - \frac{\lambda_1}{\psi(0)} \varphi(x) \psi(x) \right] u(t, x) dx \right| \right| \\ &\geq \left| \int \mu(x) |u(t, x)| dx - \underbrace{\int \left[\mu(x) - \frac{\lambda_1}{\psi(0)} \varphi(x) \psi(x) \right] |u(t, x)| dx}_{\geq 0} \right| \\ &= \frac{\lambda_1}{\psi(0)} \int |u(t, x)| \varphi(x) \psi(x) dx. \end{aligned}$$

Spectral gap. Aim is to find $\lambda_1 > 0$ such that

$$\|e^{-\lambda_0 t} n(t, x) - \rho^{init} \varphi\| \leq C e^{-\lambda_1 t}$$

■ Poincaré inequality : when $\int \psi \varphi u(x) = 0$

$$\lambda_1 \int \psi \varphi H(u) dx \leq D_H(u)$$

■ Doeblin's method

■ Method of integral equation

(Ryzhik-BP, Doumic, Hairer-Mattingly, Gabriel, Mischler, Cañizo-Yoldas, Laurencot, Salort...)

■ **Very useful** : Allows to prove global stability for 'small' nonlinearities

In a model, all is perfect.

It is in reality that everything falls apart

Italo Calvino

For a non-degenerate equation as

$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x)n(t, x) = 0, & x \geq 0 \\ N(t) := n(t, x = 0) = \int_0^\infty b(y)n(t, y)dy \end{cases}$$

with eigenelements

$$\mathcal{L}\varphi + \lambda_0\varphi = 0, \quad \mathcal{L}^*\psi + \lambda_0\psi = 0, \quad \varphi, \psi > 0, \quad \int \varphi\psi = 1$$

GRE Principle : For all $H(\cdot)$ convex, $u(t, x) = e^{-\lambda_0 t} \frac{n(t, x)}{\varphi(x)}$ satisfies

$$\frac{d}{dt} \int \psi(x)\varphi(x)H(u(t, x))dx = -D_H(t) \leq 0$$

With eigenelements

$$\mathcal{L}\varphi + \lambda_0\varphi = 0, \quad \mathcal{L}^*\psi + \lambda_0\psi = 0, \quad \varphi, \psi > 0, \quad \int \varphi\psi = 1$$

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$$\frac{d}{dt} \int \psi(x) \varphi(x) H(u(t, x)) dx = -D_H(t) \leq 0$$

A priori estimates : $u(t, x) \leq C$

Large time convergence : $\|n(t)e^{-\lambda_0 t} - \rho^{ini}\varphi\| \rightarrow 0$

$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x) n(t, x) = 0, & x \geq 0 \\ N(t) := n(t, x = 0) = \int_0^\infty d(y) n(t, y) dy \end{cases}$$

$$b(x) = d(x) = \frac{\alpha}{1+x}$$

$$\frac{\partial}{\partial x} \varphi(x) + d(x) \varphi(x) = 0,$$

$$\varphi(x) = \frac{1}{(1+x)^\alpha}, \quad \lambda_0 = 0, \quad \psi = 1$$

For $0 < \alpha < 1$

$$\int \varphi(x) dx = \infty$$

$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x)n(t, x) = 0, & x \geq 0 \\ N(t) := n(t, x = 0) = \int_0^\infty d(x)n(t, y)dy \end{cases}$$

$$b(x) = d(x) = \frac{\alpha}{1+x}$$

$$\varphi(x) = \frac{1}{(1+x)^\alpha}, \quad \lambda_0 = 0, \quad \psi = 1$$

$$\int n(t, x) dx = 1$$

Theorem For $\alpha < 1$, we have

$$N(t) \approx O(t^{-1+\alpha})$$

Similar to the heat equation in $\mathbb{R}^d$, $n(t, x)$ spreads in $(0, \infty)$

$$\frac{\partial}{\partial t} n(t, x) - \Delta n = 0,$$

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^d} n^2(t, x) dx = - \int_{\mathbb{R}^d} |\nabla n|^2 dx$$

Nash inequality : for $\theta = \frac{2}{d+2}$

$$\int_{\mathbb{R}^d} n^2(t, x) dx \leq C(d) \left(\int_{\mathbb{R}^d} |\nabla n|^2 dx \right)^{1-\theta} \left(\int_{\mathbb{R}^d} n dx \right)^\theta$$

Therefore, one concludes

$$\frac{1}{2} \frac{d}{dt} \int_{\mathbb{R}^d} n^2(t, x) dx \leq -C(d, M) \left(\int_{\mathbb{R}^d} n^2 dx \right)^{\frac{1}{\theta}}$$

$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x)n(t, x) = 0, & x \geq 0 \\ N(t) := n(t, x=0) = \int_0^\infty d(x)n(t, y)dy \\ d(x) = \frac{\alpha}{1+x}, \quad \varphi(x) = \frac{1}{(1+x)^\alpha} \end{cases}$$

Theorem : For $\alpha < 1$, we have $N(t) \approx O(t^{-1+\alpha})$

By the entropy method, with $\int_0^\infty d(x)\varphi(x) = 1$

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \int_0^\infty \varphi \left(\frac{n}{\varphi} \right)^2 &= - \int_0^\infty d(x) \varphi(x) \frac{n^2}{\varphi^2} + \left(\int_0^\infty d(x) \varphi(x) \frac{n}{\varphi} \right)^2 \\ &\leq -\nu \left(\int_0^\infty \varphi \left(\frac{n}{\varphi} \right)^2 \right)^q \quad ??? \end{aligned}$$

$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x)n(t, x) = 0, & x \geq 0 \\ N(t) := n(t, x=0) = \int_0^\infty d(x)n(t, y)dy \\ d(x) = \frac{\alpha}{1+x}, & \varphi(x) = \frac{1}{(1+x)^\alpha} \end{cases}$$

Theorem : For $\alpha < 1$, we have $N(t) \approx O(t^{-1+\alpha})$

Proof : Laplace transform : $D(x) = \int_0^x d$

$$\frac{\partial}{\partial x} \hat{n}(s, x) + [s + d(x)]\hat{n}(s, x) = \delta(s)n^0(x)$$

$$\hat{n}(s, x) = \hat{N}(s)e^{-(s+D(x))} + \text{Initial}(s)$$

$$\hat{N}(s) = \hat{N}(s) \int_0^\infty d(x)e^{-(s+D(x))} + \text{Initial}(s)$$

$$\int_0^t \frac{N(\tau)}{(t-\tau)^\alpha} d\tau = \text{Initial}(t)$$

$$\begin{cases} \varepsilon^\beta \frac{\partial}{\partial t} n(t, x, z) + \frac{\partial}{\partial x} n(t, x, z) + d(x) n(t, x, z) = 0, & x \geq 0, z \in \mathbb{R}^d \\ N(t) := n(t, x = 0, z) = \int_0^\infty d(x) n(t, y, z - \varepsilon \eta) \kappa(\eta) dy d\eta \end{cases}$$

$$d(x) = \frac{\alpha}{1+x}$$

Theorem (BP, Min Tang) as $\varepsilon \rightarrow 0$, we have

- (i) For $\alpha > 1$, $\beta = 2$, $\rho(t, z) = \int n(t, x, z) dx$ satisfies the heat equation
- (ii) For $\alpha < 1$, $\alpha\beta = 2$, $\rho(t, z) = \int n(t, x, z) dx$ satisfies the *subdiffusion* eq.

$$\frac{\partial}{\partial t} \int_0^t \frac{\rho(s, z)}{(s-t)^\alpha} ds = \Delta \rho(t, z) + \text{Initial}$$

The multi-time renewal equation

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} n(t, x_1, \dots, x_N) + \sum_{i=1}^N \frac{\partial}{\partial x_i} n(t, X_N) + d(X_N) n(t, X_N) = 0 \\ n(t, x_1 = 0, x_2, \dots, x_N) = \int_0^\infty dn(t, x_2, \dots, x_N, y) dy \end{array} \right.$$

- Used to evaluate efficiency of the Covid tracing Apps
- Spikes in neuroscience
- Non-Markovian processes

What happens when $N \rightarrow \infty$?

Meaning of the boundary condition

$$\begin{cases} \frac{\partial}{\partial t} n_N(t, x_1, \dots, x_N) + \sum_{i=1}^N \frac{\partial}{\partial x_i} n_N(t, X_N) + d_N(X_N) n_N(t, X_N) = 0 \\ n_N(t, x_1 = 0, x_2, \dots, x_N) = \int_0^\infty d_N n_N(t, x_2, \dots, x_N, y) dy \end{cases}$$

Define and assume

■ $X_N = (x_1, \dots, x_N)$

■ $d_N(X_N) = \sum_{i=1}^N r_i(x_1, \dots, x_i), \quad \sum_{i=1}^{\infty} \|r_i\|_{\infty} < \infty$

■ $n_N^{(K)}(X_K) = \int n_N(X_N) dx_{k+1} \dots dx_N$

$$\begin{cases} \frac{\partial}{\partial t} n_N(t, x_1, \dots, x_N) + \sum_{i=1}^N \frac{\partial}{\partial x_i} n_N(t, X_N) + d_N(X_N) n_N(t, X_N) = 0 \\ n_N(t, x_1 = 0, x_2, \dots, x_N) = \int_0^\infty d_N n_N(t, x_2, \dots, x_N, y) dy \end{cases}$$

■ $X_N = (x_1, \dots, x_N)$

■ $d_N(X_N) = \sum_{i=1}^N r_i(x_1, \dots, x_i), \quad \sum_{i=1}^{\infty} \|r_i\|_{\infty} < \infty$

■ $n_N^{(K)}(X_K) = \int n_N(X_N) dx_{K+1} \dots dx_N$

The marginals satisfy

$$\frac{\partial}{\partial t} n_N^{(K)}(t, x_1, \dots, x_K) + \sum_{i=1}^K \frac{\partial}{\partial x_i} n_N^{(K)}(t, X_K) + d_K(X_K) n_N^{(K)}(t, X_K) = \varepsilon_N^{(K)} \leq \sum_{i=K}^{\infty} \|r_i\|_{\infty} < \infty$$

$$\frac{\partial}{\partial t} n_N^{(K)}(t, x_1, \dots, x_K) + \sum_{i=1}^K \frac{\partial}{\partial x_i} n_N^{(K)}(t, X_K) + d_K(X_K) n_N^{(K)}(t, X_K) = \varepsilon_N^{(K)} \leq \sum_{i=K}^{\infty} \|r_i\|_{\infty} < \infty$$

One can pass to the limit because one has a Cauchy sequence

$$\|n_M^{(K)} - n_N^{(K)}(t)\|_1 \leq \sum_{i=M}^N \|r_i\|_{\infty} < \infty \rightarrow 0$$

One gets

$$\frac{\partial}{\partial t} n_{\infty}^{(K)}(t, x_1, \dots, x_K) + \sum_{i=1}^K \frac{\partial}{\partial x_i} n_{\infty}^{(K)}(t, X_K) + d_K(X_K) n_{\infty}^{(K)}(t, X_K) = \varepsilon^{(K)} \leq \sum_{i=K}^{\infty} \|r_i\|_{\infty} < \infty$$

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} n_{\infty}^{(K)}(t, x_1, \dots, x_K) + \sum_{i=1}^K \frac{\partial}{\partial x_i} n_{\infty}^{(K)}(t, X_K) + d_K(X_K) n_{\infty}^{(K)}(t, X_K) = \varepsilon^{(K)} \rightarrow 0 \quad \text{as } K \rightarrow \infty \\ n_{\infty}^{(K)}(t, x_1 = 0, x_2, \dots, x_K) = \int_0^{\infty} n_{\infty}^{(K)}(t, x_2, \dots, x_K, y) dy \end{array} \right.$$

Theorem : For a 'consistent' initial data, the solution of this hierarchy is unique.

The nonlinear renewal equation

For instance : time elapsed eq. in neuroscience with K. Pakadman,
D. Salort, C. Rieutord

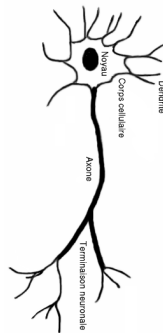
$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x, N(t))n(t, x) = 0, & x \geq 0 \\ N(t) := n(t, x = 0) = \int_0^\infty d(y, N(t))n(t, y)dy \end{cases}$$

x = time elapsed since the last discharge

$N(t)$ = activity of the network

$$\frac{\partial d(x, N)}{\partial N} > 0 \quad (\text{Excitatory})$$

$$\frac{\partial d(x, N)}{\partial N} < 0 \quad (\text{Inhibitory})$$



What should the solution do in these circumstances?

The nonlinear renewal equation



In general nonlinearities appear in the form

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x, l_1(t)) n(t, x) = 0, \quad x \geq 0 \\ N(t) := n(t, x = 0) = \int_0^\infty b(y, l_2(t)) n(t, y) dy \\ l_j(t) = \int q_j(x) n(t, x) dx, \quad j = 1, 2 \end{array} \right.$$

What should the solution do in these circumstances?

In general nonlinearities appear in the form

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x, l_1(t)) n(t, x) = 0, \quad x \geq 0 \\ N(t) := n(t, x = 0) = \int_0^\infty b(y, l_2(t)) n(t, y) dy \\ l_j(t) = \int q_j(x) n(t, x) dx, \quad j = 1, 2 \end{array} \right.$$

'Theorem' When there is a **spectral gap** and **nonlinearity is small** then

(i) there is a unique steady state $\bar{n}(x)$

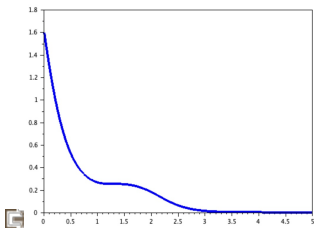
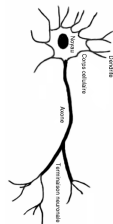
(ii) $\|n(t, x) - \bar{n}(x)\|_{L^1(\psi)} \rightarrow 0$

Easy for self-adjoint operators.

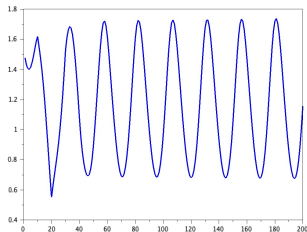
The nonlinear renewal equation

For large nonlinearities periodic solutions may appear

$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x)n(t, x) = 0, & x \geq 0 \\ N(t) := n(t, x = 0) = \int_0^\infty b(y, I(t))n(t, y)dy \\ I(t) = \int q(x)n(t, x)dx \end{cases}$$



Periodic solution : Left $n(t, x)$.



Right : $N(t)$

For large nonlinearities periodic solutions may appear

$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x)n(t, x) = 0, & x \geq 0 \\ N(t) := n(t, x = 0) = \int_0^\infty b(y, I(t))n(t, y)dy \\ I(t) = \int q(x)n(t, x)dx \end{cases}$$

Are there examples where global relaxation appears?

The Kermack-McKendrick renewal eq.



The SI model of epidemiology was proposed in 1927 as :

$$\left\{ \begin{array}{l} \frac{d}{dt}S(t) = B - \mu_S S(t) - I(t)S(t) \\ I(t) := \int_0^\infty \beta(s)n_I(t,s)ds \\ \frac{\partial}{\partial t}n_I(t,s) + \frac{\partial}{\partial s}n_I(t,s) + (\mu_I + \gamma(s))n_I(t,s) = 0 \\ n_I(t,s=0) = I(t)S(t) \end{array} \right.$$

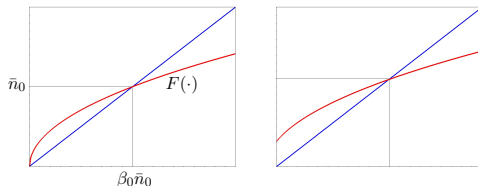
Theorem (Magal, McCluskey, Webb, 2010). Define

$$\mathcal{E}(t) = \int_0^\infty \psi(s)\bar{n}_I(s) \left[\frac{n_I(t,s)}{\bar{n}_I(s)} - \ln \frac{n_I(t,s)}{\bar{n}_I(s)} \right] ds + \bar{S} \ln S(t) - S(t).$$

Then, we have

$$\frac{d}{dt}\mathcal{E}(t) \leq -D(t) \leq 0, \quad D(t) = \frac{\mu_S}{S(t)}(\bar{S} - S(t))^2.$$

$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x)n(t, x) = 0, & t \geq 0, x \geq 0, \\ n(t, 0) = F\left(\int_0^\infty b(x)n(t, x)dx\right), & 0 < \beta_0 := \int_0^\infty b(x)e^{-D(x)}dx \end{cases}$$



Theorem (P. Michel) For this nonlinear equation

- There is a uniqueness steady state $\bar{n}(x)$
- $n^{init} \leq C_+ \bar{n}(x)$, then $\forall t \geq 0, n(t, x) \leq C_+ \bar{n}(x)$,
- $n^{init} \geq C_- \bar{n}(x)$, then $\forall t \geq 0, n(t, x) \geq C_- \bar{n}(x)$,
- $\int_0^\infty |n(t) - \bar{n}_0| \psi \leq e^{-at} \int_0^\infty |n^{init} - \bar{n}_0| \psi.$

Inhibitory time elapsed eq. in neuroscience with D. Salort, C. Rieutord

$$\begin{cases} \frac{\partial}{\partial t} n(t, x) + \frac{\partial}{\partial x} n(t, x) + d(x, N(t))n(t, x) = 0, & x \geq 0 \\ N(t) := n(t, x = 0) = \int_0^\infty d(y, N(t))n(t, y)dy \end{cases}$$

Theorem Assume a non-degeneracy condition and the inhibitory condition

$$\frac{\partial d(x, N)}{\partial N} < 0.$$

Then there is L^1 non-expansion and $\|n(t, x) - \bar{n}(x)\|_{L^1(\psi)} \rightarrow 0$

1. Motivations
2. Generalised relative entropy
3. Monge-Kantorovich distance and PDEs
4. Sexual reproduction

Restriction : Conservative problems (probability measures)

Ackleh, Carrillo, Gwiazda, Gabriel, Datong Zhou,...

Fournier, Locherbach, Monmarché, Guillin, Zitt, Eberle..



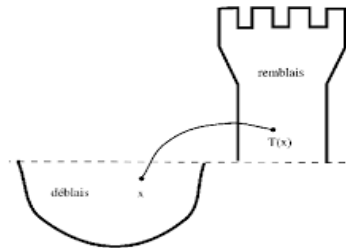
With Nicolas Fournier

Motivations :

- measure solutions are possible
- weak topology vs strong topology (entropy)
- weak topology is useful (long time behaviour)
- approximation by particles ($N \rightarrow \infty$)
- Used in data science

Theorem : For all the problems of yesterday, there is a choice of a such that

$$d_{MK,a}(n_1(t), n_2(t)) \leq d_{MK,a}(n_1(0), n_2(0))$$



M É M O I R E
S U R L A
T H É O R I E D E S D É B L A I S
E T D E S R E M B L A I S.

Par M. M O N G E.

LORSQU'ON doit transporter des terres d'un lieu dans un autre, on a coutume de donner le nom de *Déblai* au volume des terres que l'on doit transporter, & le nom de *Remblai* à l'espace qu'elles doivent occuper après le transport.

Le prix du transport d'une molécule étant, toutes choses d'ailleurs égales, proportionnel à son poids & à l'espace qu'on lui fait parcourir, & par conséquent le prix du transport total devant être proportionnel à la somme des produits des molécules multipliées chacune par l'espace parcouru, il s'en suit que le déblai & le remblai étant donnés de figure & de position, il n'est pas indifférent que telle molécule du déblai soit transportée dans tel ou tel autre endroit du remblai, mais qu'il y a une certaine distribution à faire des molécules du premier dans le second, d'après laquelle la somme de ces produits fera la moindre possible, & le prix du transport total fera un *minimum*.

- G. Monge formulated the 'excavation and embankments' problem in 1781
- Minimize the **transportation cost**

- Ω open subset of $\mathbb{R}^d$
- Cost function $c(x, y) \geq 0$, $x, y \in \Omega$, $c(x, x) = 0$
- n_1, n_2 probability measures on Ω
- **G. Monge (1781)** : find $T : \Omega \rightarrow \Omega$ such that

$$T_{\#}n_1 = n_2 \quad (\text{push forward})$$

$$c(x, y) = |x - y|$$

$$\min_T \int_{\Omega} c(x, T(x)) n_1(x) dx$$

- Ω open subset of $\mathbb{R}^d$
- Cost function $c(x, y) \geq 0$, $x, y \in \Omega$, $c(x, x) = 0$
- n_1, n_2 probability measures on Ω
- **G. Monge (1781) :** $T : \Omega \rightarrow \Omega$, $T_{\#}n_1 = n_2$

$$\min_T \int_{\Omega} c(x, T(x)) n_1(x) dx$$

$T_{\#}n_1 = n_2$ means 'incompressibility', for all measurable function u

$$\int u(T(x)) n_1(dx) = \int u(y) n_2(dy) = \int u(T(x)) n_2(T(x)) |\text{Det} DT(x)|$$

$$\text{Det} DT(x) = \frac{n_1(x)}{n_2(T(x))}, \quad y = T(x)$$

if this makes sense

- Ω open subset of $\mathbb{R}^d$
- Cost function $c(x, y) \geq 0$, $x, y \in \Omega$, $c(x, x) = 0$
- n_1, n_2 probability measures on Ω
- **G. Monge (1781) :** $T : \Omega \rightarrow \Omega$, $T_{\#}n_1 = n_2$

$$c(x, y) = |x - y|$$

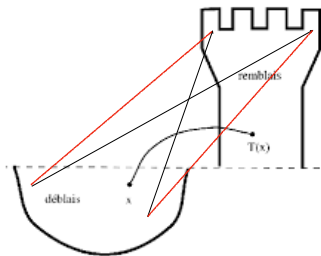
$$\min_T \int_{\Omega} c(x, T(x)) n_1(x) dx$$

G. Monge makes two important observations

- Ω open subset of $\mathbb{R}^d$
- Cost function $c(x, y) \geq 0$, $x, y \in \Omega$, $c(x, x) = 0$
- n_1, n_2 probability measures on Ω
- **G. Monge (1781) :** $T : \Omega \rightarrow \Omega$, $T_{\#}n_1 = n_2$

$$c(x, y) = |x - y|,$$

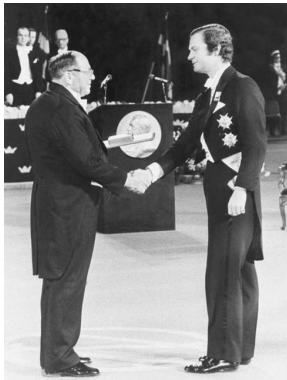
$$\min_T \int_{\Omega} c(x, T(x)) n_1(x) dx$$



l'équation de la surface à laquelle toutes les routes doivent être normales, sera

$$\left. \begin{aligned} & \frac{1}{3} [(Z-z)^3 - (Z'-z')^3 - (Z''-z'')^3 + (Z'''-z''')^3] \left[\frac{ddz'}{dx^2} \frac{ddz'}{dy^2} - \left(\frac{ddz'}{dx dy} \right)^2 \right] \\ & - \frac{1}{2} [(Z-z)^2 - (Z'-z')^2 - (Z''-z'')^2 + (Z'''-z''')^2] \left\{ \left[1 + \left(\frac{dz'}{dy} \right)^2 \right] \frac{ddz'}{dx^2} \right. \\ & - 2 \frac{dz'}{dx} \frac{dz'}{dy} \frac{ddz'}{dx dy} + \left[1 + \left(\frac{dz'}{dx} \right)^2 \right] \frac{ddz'}{dy^2} \right\} \\ & + (Z - Z' - Z'' + Z''') \left[1 + \left(\frac{dz'}{dx} \right)^2 + \left(\frac{dz'}{dy} \right)^2 \right] \end{aligned} \right\} = 0.$$

L. Kantorovich (1912-1986)



- L. Kantorovich was an economist (Nobel Pr. 1975)
- He was interested in economy (mines-factories)
- Kantorovich published his first paper in 1939
- not aware of Monge's paper
- In 1946, the world marked the bicentenary of Gaspard Monge (1746-1818)

- Ω open subset of $\mathbb{R}^d$
- Cost function $c(x, y) \geq 0$, $x, y \in \Omega$, $c(0, 0) = 0$
- n_1, n_2 probability measures on Ω
- **G. Monge :** $T : \Omega \rightarrow \Omega$, $T_{\#}n_1 = n_2$

$$\min_T \int_{\Omega} c(x, T(x)) n_1(x) dx$$

has a solution only when n_1, n_2 are 'smooth' enough

- **L. Kantorovich :**

$$d_c(n_1, n_2) := \min_{v(\cdot, \cdot)} \int_{\Omega} c(x, y) v(x, y) dx dy$$

the *min* taken for probability measures $v(\cdot, \cdot)$ with marginales

$$\int_{\Omega} v(x, y) dy = n_1(x), \quad \int_{\Omega} v(x, y) dx = n_2(y)$$

■ n_1, n_2 probability measures

■ cost $c(x, y)$

• **G. Monge :** $T : \Omega \rightarrow \Omega, \quad T_{\#}n_1 = n_2$

$$\min_T \int_{\mathbb{R}^d} c(x, T(x))n_1(x)dx$$

• **L. Kantorovich :**

$$d_c(n_1, n_2) := \min_v \int_{\mathbb{R}^d} c(x, y)v(x, y)dxdy$$

$$\int_{\Omega} v(x, y)dy = n_1(x), \quad \int_{\Omega} v(x, y)dx = n_2(y)$$

■ Monge is equivalent to choose $v(x, y) = n_1(x)\delta(y = T(x))$

■ $d_c(n_1, n_2) = \mathbb{E}[c(X, Y)]$ with $\mathcal{L}X = n_1, \mathcal{L}Y = n_2$

■ n_1, n_2 probability measures

■ cost $c(x, y)$

• **G. Monge :** $T : \Omega \rightarrow \Omega, \quad T_{\#}n_1 = n_2$

$$\min_T \int_{\mathbb{R}^d} c(x, T(x))n_1(x)dx$$

• **L. Kantorovich :**

$$d_c(n_1, n_2) := \min_v \int_{\mathbb{R}^d} c(x, y)v(x, y)dxdy$$

$$\int_{\Omega} v(x, y)dy = n_1(x), \quad \int_{\Omega} v(x, y)dx = n_2(y)$$

■ Monge is equivalent to choose $v(x, y) = n_1(x)\delta(y = T(x))$

Indeed with such a T , we have $\forall u : \Omega \rightarrow \Omega$

$$\int u(T(x))n_1(x)dx = \int u(y)n_1(x)\delta(y - T(x)) = \int u(y)v(x, y)dxdy$$

■ n_1, n_2 probability measures

■ cost $c(x, y)$

• **G. Monge :** $T : \Omega \rightarrow \Omega, \quad T_{\#}n_1 = n_2$

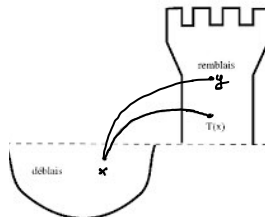
$$\min_T \int_{\mathbb{R}^d} c(x, T(x)) n_1(x) dx$$

• **L. Kantorovich :**

$$d_c(n_1, n_2) := \min_v \int_{\mathbb{R}^d} c(x, y) v(x, y) dx dy$$

■ Monge is equivalent to choose $v(x, y) = n_1(x) \delta(y = T(x))$

■



Kantorovich allows to 'cut big stones in small pieces'

■ n_1, n_2 probability measures

■ cost $c(x, y)$

• **G. Monge :** $T : \Omega \rightarrow \Omega, \quad T_{\#}n_1 = n_2$

$$\min_T \int_{\Omega} c(x, T(x)) n_1(x) dx$$

• **L. Kantorovich :**

$$d_c(n_1, n_2) := \min_{v(\cdot, \cdot)} \int_{\Omega} c(x, y) v(x, y) dx dy$$

$$\int_{\Omega} v(x, y) dy = n_1(x), \quad \int_{\Omega} v(x, y) dx = n_2(y)$$

- Monge is equivalent to choose $v(x, y) = n_1(x) \delta(y = T(x))$
- Kantorovich can be seen as $v(x, y) = n_1(x) \sum a_i \delta(y = T_i(x))$

■ n_1, n_2 probability measures

■ cost $c(x, y)$

• **G. Monge :** $T : \Omega \rightarrow \Omega, \quad T_{\#}n_1 = n_2$

$$\min_T \int_{\Omega} c(x, T(x)) n_1(x) dx$$

• **L. Kantorovich :**

$$d_c(n_1, n_2) := \min_{v(\cdot, \cdot)} \int_{\Omega} c(x, y) v(x, y) dx dy$$

$$\int_{\Omega} v(x, y) dy = n_1(x), \quad \int_{\Omega} v(x, y) dx = n_2(y)$$

■ When $c(x, y)$ is a distance, then d_c is a distance on $\mathcal{P}(\Omega)$

■ For $c(x, y) = |x - y|^p$, then $d_p^{\frac{1}{p}}$ is a distance (Wasserstein distance) on $\mathcal{P}^p(\Omega)$

- **G. Monge :** $T : \Omega \rightarrow \Omega, \quad T_{\#}n_1 = n_2$

$$d_c(n_1, n_2) := \min_T \int_{\Omega} c(x, T(x)) n_1(x) dx$$

- **L. Kantorovich :** $d_c(n_1, n_2) := \min_v \int_{\Omega} c(x, y) v(x, y) dx dy$

$$\int_{\Omega} v(x, y) dy = n_1(x), \quad \int_{\Omega} v(x, y) dx = n_2(y)$$

- **Y. Brenier :** For $\Omega = \mathbb{R}^d$, $c(x, y) = |x - y|^2$,
 n_i 'smooth', T is optimal if and only if

$$T(x) = \nabla \phi(x) \quad \text{with} \quad \phi : \mathbb{R}^d \rightarrow \mathbb{R} \text{ convex}$$

$$\det D^2 \phi(x) = \frac{n_1(x)}{n_2(T(x))} \quad \text{Monge-Ampere eq.}$$

Two other contributions for completeness

- **Kantorovich dual problem :**

$$d_c(n_1, n_2) = \sup_{\Phi, \Psi} \left\{ \int_{\mathbb{R}^d} \Phi(x) n_1(dx) + \int_{\mathbb{R}^d} \Psi(y) n_2(dy) \right\}$$

with the **Kantorovich potentials** Φ, Ψ such that

$$\Phi(x) + \Psi(y) \leq c(x, y)$$

■ The truck problem... Φ or Ψ can be negative

Monge-Kantorovich is a linear optimisation problem !

Quadratic is better

■ **Benamou-Brenier (2000)** For $c(x, y) = \frac{|x-y|^2}{2}$

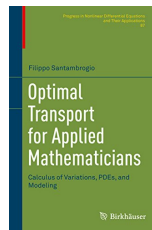
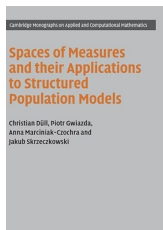
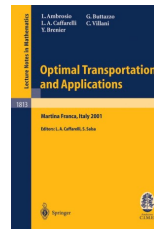
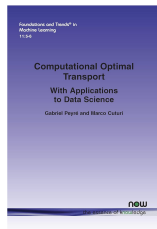
$$d_2(n_1, n_2) := \min \left\{ \int_0^1 \int_{\Omega} |v(s, x)|^2 \mu(s, x) dx ds \right.$$

with the constraint

$$\begin{cases} \partial_s \mu + \operatorname{div}(v\mu) = 0, \\ \mu(0, x) = n_1(x), \quad \mu(1, x) = n_2(x) \end{cases}$$

Important computational tool

Monge-Kantorovich problem



$$\partial_t n - \Delta n = 0, \quad x \in \mathbb{R}^d, \quad t \geq 0$$

Theorem : For all costs $c(x - y)$,

$$d_c(n_1(t), n_2(t)) \leq d_c(n_1^{init}, n_2^{init})$$

Proof : Consider v solution of

$$\frac{\partial v}{\partial t} - \Delta_x v - \Delta_y v - 2\nabla_x \cdot \nabla_y v = 0, \quad x, y \in \mathbb{R}^d, \quad t \geq 0$$

with a compatible initial data

$$\int v^{init}(x, y) dy = n_1^{init}(x) \quad \int v^{init}(x, y) dx = n_2^{init}(y)$$

Step 1. $v \geq 0$ because $\begin{pmatrix} I & -I \\ -I & I \end{pmatrix}$ is nonnegative

$$\partial_t n - \Delta n = 0, \quad x \in \mathbb{R}^d, \quad t \geq 0$$

Theorem : For costs $c(x - y)$, we have

$$d_c(n_1(t), n_2(t)) \leq d_c(n_1^{init}, n_2^{init})$$

Proof : Consider v solution of

$$\frac{\partial v}{\partial t} - \Delta_x v - \Delta_y v - 2\nabla_x \cdot \nabla_y v = 0, \quad x, y \in \mathbb{R}^d, \quad t \geq 0$$

$$\int v^{init}(x, y) dy = n_1^{init}(x) \quad \int v^{init}(x, y) dx = n_2^{init}(y)$$

Step 2. Marginals are correct. Integrate in y :

$$\frac{\partial v_1(x, t)}{\partial t} - \Delta_x v_1 = 0$$

$$\partial_t n - \Delta n = 0, \quad x \in \mathbb{R}^d, \quad t \geq 0$$

Theorem : For costs $c(x - y)$, we have

$$d_c(n_1(t), n_2(t)) \leq d_c(n_1^{init}, n_2^{init})$$

Proof : Consider v solution of

$$\frac{\partial v}{\partial t} - \Delta_x v - \Delta_y v - 2\nabla_x \cdot \nabla_y v = 0, \quad x, y \in \mathbb{R}^d, \quad t \geq 0$$

Step 3. The distance diminishes

$$\begin{aligned} \frac{d}{dt} \int c(x - y) v(x, y, t) dx dy &= \\ \int v(x, y, t) \left(\Delta_x c(x - y) + \Delta_y c(x - y) + 2\nabla_x \nabla_y c(x - y) \right) dx dy &= \\ = \int v(x, y, t) \left(\Delta_{x+y} c(x - y) \right) dx dy &= 0 \end{aligned}$$

$$\partial_t n - \Delta n = 0, \quad x \in \mathbb{R}^d, \quad t \geq 0$$

Theorem : For costs $c(x - y)$, we have

$$d_c(n_1(t), n_2(t)) \leq d_c(n_1^{init}, n_2^{init})$$

Step 4. Conclusion. For all initial coupling v^{init}

$$\begin{aligned} d_c(n_1(t), n_2(t)) &\leq \int c(x - y) v(x, y, t) dx dy \\ &= \int c(x - y) v^{init}(x, y) dx dy \\ &\approx d_c(n_1^{init}, n_2^{init}) \end{aligned}$$

$$\partial_t n - \Delta n = 0, \quad x \in \mathbb{R}^d, \quad t \geq 0$$

Theorem : For costs $c(x - y)$, we have

$$d_c(n_1(t), n_2(t)) \leq d_c(n_1^{init}, n_2^{init})$$

Not completely convincing because

- The solution is a convolution of initial data
- Large choice of possible $c(x, y)$
- Question : $\partial_t n - \Delta(A(x)n) = 0$?

- **Kinetic scattering** Particles moving with velocity v , density $n(t, x, v)$

$$\partial_t n + v \cdot \nabla_x n + n = \int n(t, x, V(v; h)) \det D_v V d\mu(h)$$

Assume that jumps reduce distance

$$\int |V^{-1}(W, h) - V^{-1}(W', h)|^p d\mu(h) \leq L |W - W'|, \quad \forall h$$

Theorem : For $L < 1$, this equation is non-expansive for the distance

$$c(x, v; y, w) = \alpha |x - y| + |v - w|$$

α small enough compared to $1 - L$.

Proof :

$$\partial_t F + v \cdot \nabla_x F + w \cdot \nabla_y F + F(x, v, y, w, t) =$$
$$\int F(x, V(v, h), y, V(w, h), t) \det(D_v V(v, h)) \det(D_v V(w, h)) d\mu(h)$$

Step 1. $F \geq 0$

Step 2. Marginales are correct

Step 3.

$$\frac{d}{dt} \int [\alpha |x - y| + |v - w|] F \leq \alpha \int |v - w| F - (1 - L) \int |v - w| F$$

$$\partial_t n(t, x) + \operatorname{div}(n \nabla K \star n) = 0$$

$$K \star n = \int_{\mathbb{R}^d} K(x - y) n(t, y) dy.$$

It is important for particle systems.

A measure solution is

$$n(t, x) = \frac{1}{N} \sum_{i=1}^N \delta(x - X_i(t))$$

with

$$\frac{d}{dt} X_i(t) = \frac{1}{N} \sum_{j=1}^N K(X_i(t) - X_j(t))$$

$$\partial_t n(t, x) + \operatorname{div}(n \nabla K \star n) = 0$$

Theorem : When K is even and concave, it is non-expansive for $\mathbf{d}_2$

Proof : Consider the coupling

$$\partial_t v(t, x, y) + \operatorname{div}_x(v \nabla_x K \star v_1(t, x)) + \operatorname{div}_y(v \nabla_y K \star v_2(t, y)) = 0$$

with $v^{init} \geq 0$ having the marginales $n_1^{init}(x)$, $n_2^{init}(y)$ and

$$v_1(t, x) = \int v(t, x, y) dy, \quad v_2(t, y) = \int v(t, x, y) dx$$

Step 1. Obviously $v(t) \geq 0$

$$\partial_t n(t, x) + \operatorname{div}(n \nabla K \star n) = 0$$

Theorem : When K is even and concave, it is non-expansive for $\mathbf{d}_2$

Proof : Consider the coupling

$$\partial_t v(t, x, y) + \operatorname{div}_x(v \nabla_x K \star v_1(t, x)) + \operatorname{div}_y(v \nabla_y K \star v_2(t, y)) = 0$$

with $v^{init} \geq 0$ having the marginales $n_1^{init}(x)$, $n_2^{init}(y)$ and

$$v_1(t, x) = \int v(t, x, y) dy, \quad v_2(t, y) = \int v(t, x, y) dx$$

Step 2. $v(t)$ has the correct marginales, because integrating in y for instance

$$\partial_t v_1(t, x) + \operatorname{div}_x(v_1 \nabla_x K \star v_1(t, x)) = 0$$

and thus $v_1 = n_1$

$$\partial_t n(t, x) + \operatorname{div}(n \nabla K \star n) = 0$$

Theorem : When K is even and concave, it is non-expansive for $\mathbf{d}_2$

$$\partial_t v(t, x, y) + \operatorname{div}_x(v \nabla_x K \star v_1(t, x)) + \operatorname{div}_y(v \nabla_y K \star v_2(t, y)) = 0$$

Step 3. One computes

$$\begin{aligned} \frac{d}{dt} \int \frac{|x - y|^2}{2} v dx dy &= \int v \left(x - y, \nabla K \star v_1(t, x) - \nabla K \star v_2(t, y) \right) \\ &= \int v v' \left(x - y, \nabla K(x - x') - \nabla K(y - y') \right) \\ &= \frac{1}{2} \int v v' \left(x - x' - y + y', \nabla K(x - x') - \nabla K(y - y') \right) \quad \text{exchange } x, x'; y, y' \\ &\leq 0 \end{aligned}$$

Theorem (N. Fournier, BP)

■ The Renewal and Growth-Fragmentation equations, and all others, are non-expansive for the cost

$$c(x - y) = \min(|x - y|, a), \quad a \text{ related to Lipschitz bounds on coef.}$$

■ For renewal it is a strict contraction and $d_c(n(t), \bar{n}) \rightarrow 0$

History

Fournier and Locherbach (neural networks)

Chafai, Malrieu, Paroux, Guillin, Zitt... (TCP connections)

Renewal equation as an example.

$$\begin{cases} \frac{\partial n(x,t)}{\partial t} + \frac{\partial [g(x)n]}{\partial x} + d(x)n = b(x)N(t), & t \geq 0, x \geq 0, \\ n(x=0, t) = 0, & N(t) = \int_0^\infty d(x)n(x, t)dx. \end{cases}$$

$$g' \leq 0, \quad g(0) \geq 0, \quad \int_0^\infty b = 1$$

$$0 < a < 1 \quad \text{and} \quad a = \inf_{|x-y|<1} \frac{|x-y| \max(d(x), d(y))}{|d(x) - d(y)|}$$

Example : $d(x) = \alpha + \beta x^p$, $p \geq 1$.

$$c(x-y) = \min(|x-y|, a)$$

$$d_c(n_1(t), n_2(t)) \leq d_c(n_1^{init}, n_2^{init})$$

$$\begin{aligned} & \frac{\partial v}{\partial t} + \frac{\partial g(x)v}{\partial x} + \frac{\partial g(y)v}{\partial y} + \max(d(x), d(y))v \\ &= b(x)\delta(x-y) \int \min(d(x'), d(y')) v(dx', dy', t) \\ &+ b(x) \int (d(x') - d(y))_+ v(dx', y, t) \\ &+ b(y) \int (d(y') - d(x))_+ v(x, dy', t) \end{aligned}$$

with an initial data v^{init} whose marginals are n_1^{init} and n_2^{init} .

Step 1. $v \geq 0$

Step 2. Marginales are correct (more tricky to see)

$$\begin{aligned} & \frac{\partial v}{\partial t} + \frac{\partial g(x)v}{\partial x} + \frac{\partial g(y)v}{\partial y} + \max(d(x), d(y))v \\ &= b(x)\delta(x-y) \int \min(d(x'), d(y')) v(dx', dy', t) \\ &+ b(x) \int (d(x') - d(y))_+ v(dx', y, t) + \dots \end{aligned}$$

Step 3.

$$\begin{aligned} & \frac{d}{dt} \int c(x-y)v + \int c(x,y) \max(d(x), d(y))v = 0 \\ &+ \int c(x,y)b(x)(d(x') - d(y))_+ v(dx', y, t) + \dots \end{aligned}$$

one needs

$$\begin{aligned} \max(d(x), d(y))c(x,y) &\geq \int c(z,y)b(z)dz(d(x) - d(y))_+ \\ &+ \int c(x,z)b(z)dz(d(y) - d(x))_+ \end{aligned}$$

1. Motivations
2. Generalised relative entropy
3. Monge-Kantorovich distance and PDEs
4. Sexual reproduction

$$\partial_t n(x, t) + n(x, t) = \int_{\mathbb{R}^{2d}} K(x; x', x'_*) n(x', t) n(x'_*, t) dx' dx'_*,$$

$t \geq 0$, $x \in \mathbb{R}^d$ with

$$\int_{\mathbb{R}^d} K(x; x', x'_*) dx = 1$$

to preserve total number $\int n(x, t) dx = 1$

For instance, with $h(\cdot)$ a probability measure

$$K(x; x', x'_*) = \int_0^1 \delta_{x'\sigma + x'_*(1-\sigma)}(x) h(\sigma) d\sigma$$

Magal, Raoul, Mirrahimi, Calvez-Garnier-Patout, Poyato, Degond, Frouvelle, Schmeiser-Kanzler

Theorem For $c(x, y) = |x - y|^p$, $1 \leq p < \infty$, we have

$$d_c(n_1(t), n_2(t)) \leq d_c(n_1^{init}, n_2^{init})$$

for n_1^{init}, n_2^{init} probability measures.

Proof by coupling

$$\begin{aligned} \partial_t v(x, y, t) + v(x, y, t) &= \\ &= \int \bar{K}(x, y; x', x'_*, y', y'_*) v(x', y') v(x'_*, y'_*) dx' dy' dx'_* dy'_* \end{aligned}$$

with

$$\bar{K}(x, y; x', x'_*, y', y'_*) = \int_0^1 h(\sigma) \delta_{\sigma x' + (1-\sigma)x'_*}(x) \delta_{\sigma y' + (1-\sigma)y'_*}(y) d\sigma.$$

Homogeneous Boltzmann Eq.

$$\begin{cases} \partial_t f(v, t) = \int_{\mathbb{R}^3 \times \mathbb{S}^2} [f(v', t)f(v'_*, t) - f(v, t)f(v_*, t)] B(\theta) dv_* d\sigma \\ v' = \frac{1}{2}(v + v_*) + \frac{1}{2}|v - v_*|\sigma, \quad v'_* = \frac{1}{2}(v + v_*) - \frac{1}{2}|v - v_*|\sigma \\ \cos(\theta) = \frac{v - v_*}{|v - v_*|} \cdot \frac{v' - v'_*}{|v' - v'_*|}, \quad \int_0^\pi B(\theta) d\theta = 1 \end{cases}$$

Theorem (Tanaka, 1978).

The Boltzmann equation is non-expansive for d_2 .

Coupled homogeneous Boltzmann Eq. : $F(v, w, t)$

$$\begin{aligned} & \frac{d}{dt} \int_{(\mathbb{R}^3)^2} \Psi(v, w) F(v, w, t) dv dw \\ &= \int_{(\mathbb{R}^3)^4} \int_0^\pi \int_0^{2\pi} \left[\Psi(v', w') + \Psi(v'_*, w'_*) - \Psi(v_*, w_*) - \Psi(v, w) \right] \\ & \quad B(\theta) F(v, w, t) F(v_*, w_*, t) dv dw dv_* dw_* d\theta d\varphi \end{aligned}$$

Coupled homogeneous Boltzmann Eq. : $F(v, w, t)$

$$\begin{aligned} \frac{d}{dt} \int_{(\mathbb{R}^3)^2} \Psi(v, w) F(v, w, t) dv dw \\ = \int_{(\mathbb{R}^3)^4} \int_0^\pi \int_0^{2\pi} \left[\Psi(v', w') + \Psi(v'_*, w'_*) - \Psi(v_*, w_*) - \Psi(v, w) \right] \\ B(\theta) F(v, w, t) F(v_*, w_*, t) dv dw dv_* dw_* d\theta d\varphi \end{aligned}$$

$$\begin{aligned} v' &= \frac{1}{2}(v + v_*) + \frac{1}{2}|v - v_*|\sigma, & v'_* &= \frac{1}{2}(v + v_*) - \frac{1}{2}|v - v_*|\sigma \\ w' &= \frac{1}{2}(w + w_*) + \frac{1}{2}|w - w_*|\omega, & w'_* &= \frac{1}{2}(w + w_*) - \frac{1}{2}|w - w_*|\omega \end{aligned}$$

How to couple σ and ω ?

and the sphere is parametrized as

$$\sigma = \cos(\theta) \frac{v - v_*}{|v - v_*|} + \sin(\theta)[I \cos(\varphi) + l_1 \sin(\varphi)]$$

$$\omega = \cos(\theta) \frac{w - w_*}{|w - w_*|} + \sin(\theta)[I \cos(\varphi) + l_2 \sin(\varphi)],$$

where $I = \frac{(v-v_*) \wedge (w-w_*)}{|(v-v_*) \wedge (w-w_*)|}$,

and l_1, l_2 are chosen so that

$$\left(\frac{v - v_*}{|v - v_*|}, I, l_1 \right), \quad \left(\frac{w - w_*}{|w - w_*|}, I, l_2 \right)$$

are two direct orthonormal bases

- **Theorem (Otto)** The porous media equation is non-expansive for d_2

$$\frac{\partial n}{\partial t} - \Delta A(n) = 0$$

I recommend the proof by **Bolley-Carrillo**

No proof known by 'global coupling'

Thanks to :

Ph. Michel, S. Mischler

K. Pakdaman, D. Salort, N. Torres, C. Rieutord

Z. Zhou, X. Dou, C. Qi, M. Tang

N. Fournier, L. Kanzler

THANK YOU