



INSTITUT  
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# Sustainable spatial management strategies of agricultural areas

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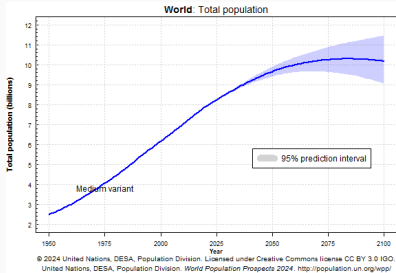
*Joint work with Manon Costa (IMT) and Nicolas Loeuille (iEES, SU)*

JOURNÉE WORKSHOP DE LA CHAIRE MMB, 21/11/2025

# Introduction

Agricultural management strategies need to reconcile two key objectives:

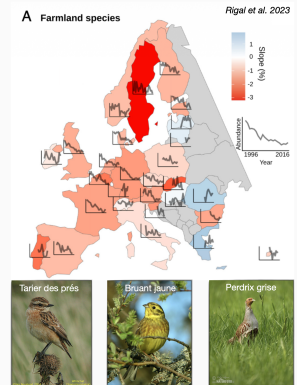
- **Yield goal:** feed a growing humanity (2024-2050: +1.5 billion people).



# Introduction

Agricultural management strategies need to reconcile two key objectives:

- **Yield goal:** feed a growing humanity
- **Conservation goal:** biodiversity crisis.
  - Bird abundance decreased by 25% (1980-2016).
  - Main driver: agricultural intensification (Rigal et al., 2023).

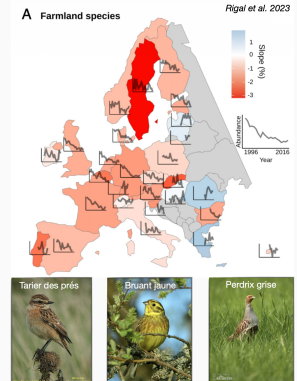


# Introduction

Agricultural management strategies need to reconcile two key objectives:

- **Yield goal:** feed a growing humanity
- **Conservation goal:** biodiversity crisis.

⇒ Can we design agricultural landscapes that feed us without silencing nature?





# Introduction

## Land sharing versus land sparing framework (Green et al., 2005)



### Land sparing :

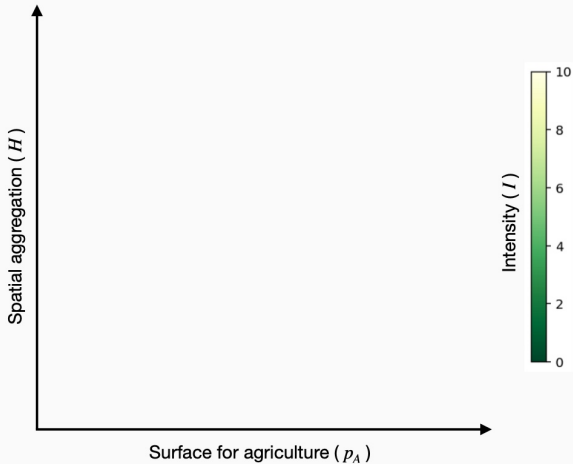
- Smaller surface used for agriculture.
- High spatial aggregation.
- Intensive agriculture.

### Land sharing :

- Larger surface used for agriculture.
- Low spatial aggregation.
- Agroecological practices.

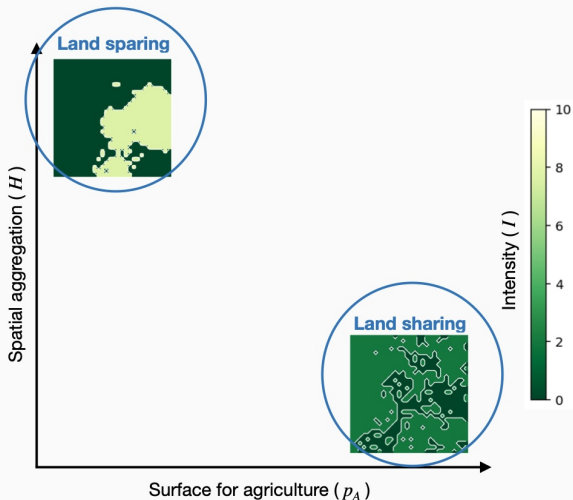
# Introduction

Agricultural landscape → 3 parameters:



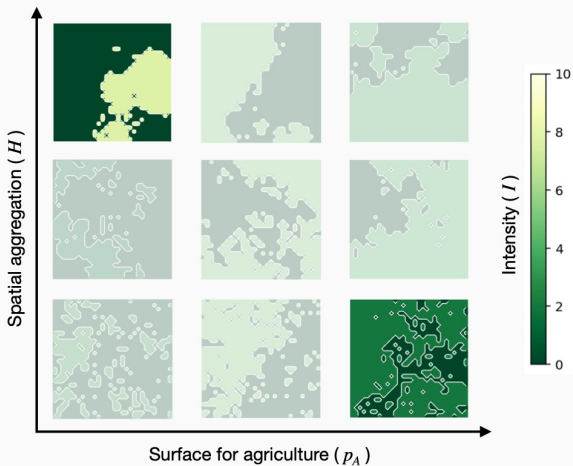
# Introduction

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Agricultural landscape → 3 parameters:



How does this spatial heterogeneity impact both conservation and yield goals?

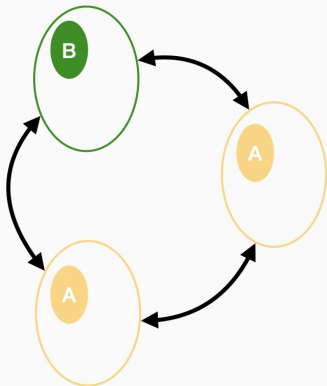
1. **The metacommunity model:** how to model the ecological dynamics of several species in an agricultural landscape?
2. **Metacommunity persistence:** can we predict which species survive in the long run?
3. **Biodiversity-yield trade-off:** which spatial management strategies allow to reconcile conservation and yield goals?

# The metacommunity model

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# What is a metacommunity?

**Metacommunity:** a set of local communities that are linked by dispersal of multiple interacting species (Leibold et al., 2004; Mouquet and Loreau, 2003).

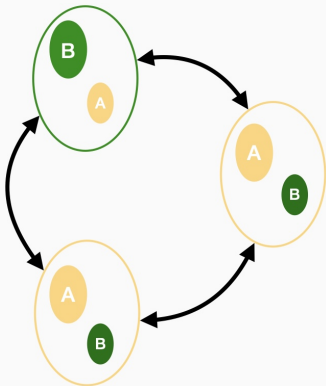


Ecological equilibrium:

- Species sorting.

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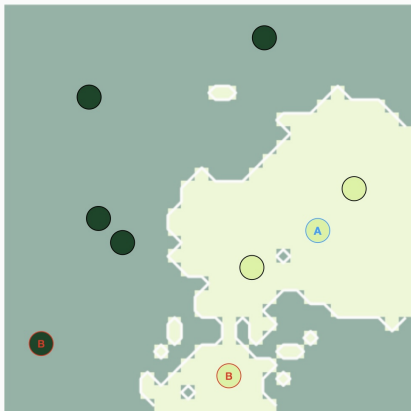
Ecological equilibrium:

- Species sorting.
- Mass effects (source-sink).

⇒ Biodiversity depends on heterogeneity between habitats and their spatial arrangement.



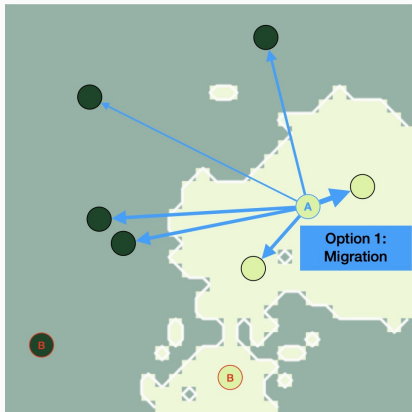
# A spatial metacommunity model



## Patch occupancy model:

- $K$  patches uniformly distributed over the landscape.
- Pool of  $S$  species who differ in dispersal and local extinction rates.
- Absence/presence of each species in each patch.

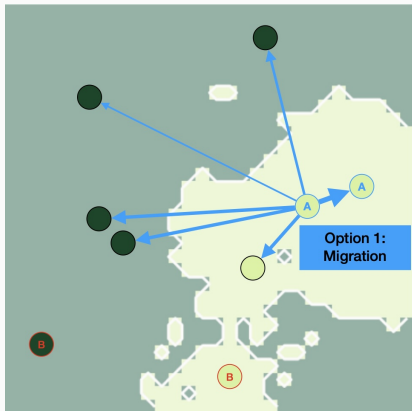
# A spatial metacommunity model



**Patch occupancy model:** Species  $j$  inhabiting a patch at  $x$  may...

- Colonise an empty patch at  $y \rightarrow$  rate  $K^{-1}c_j(x, y)$  depends on distance.

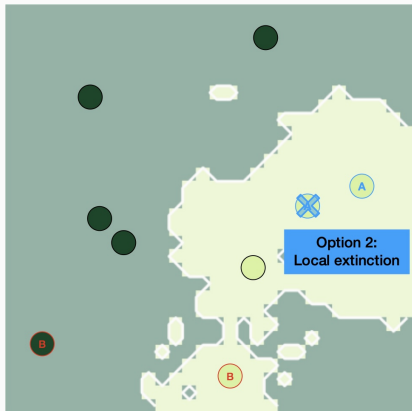
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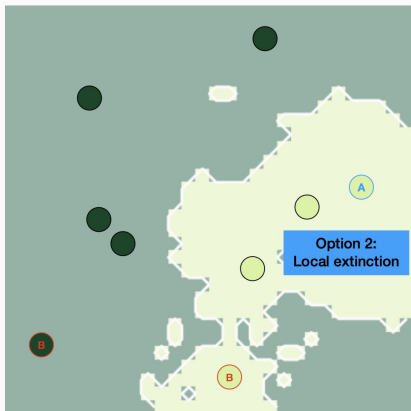
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- Go locally extinct  $\rightarrow$  rate  $\tau_j(x)$  depends on patch type.

# A spatial metacommunity model



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# A spatial metacommunity model

Saturate the landscape with patches  $\implies$  the model becomes continuous in space.

For  $i \in \{1, \dots, S\}$ , let  $u_i(t, x) \in [0, 1]$  be the probability of observing species  $i$  at point  $x \in \Omega$  at time  $t \geq 0$ .

In particular,  $\sum_{i=1}^S u_i \leq 1$ .

Remark: this corresponds to a graphon limit of a stochastic process, similar to (Delmas, Frasca, et al., 2024).

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$$\partial_t u_i(t, x) = -\tau_i(x) u_i(t, x) +$$

$$\underbrace{\hspace{1.5cm}}_{\text{Local extinction}}$$

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$$\partial_t u_i(t, x) = \underbrace{-\tau_i(x)u_i(t, x)}_{\text{Local extinction}} + \underbrace{\left(1 - \sum_{j=1}^S u_j(t, x)\right)}_{\text{Probability that } x \text{ is empty}} \underbrace{\int_{\Omega} u_i(t, y)c_i(x, y)dy}_{\text{Colonization by dispersal}}.$$

Remark: this corresponds to a graphon limit of a stochastic process, similar to (Delmas, Frasca, et al., 2024).



## Persistence criterion

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# What is persistence?

Focus on the case  $S = 2$ :

$$\partial_t u(t, x) = -\tau u + (1 - u - v) \int_{\Omega} u(t, y) c(x, y) dy,$$

$$\partial_t v(t, x) = -\sigma v + (1 - u - v) \int_{\Omega} v(t, y) \gamma(x, y) dy,$$

with  $c, \gamma \in \mathcal{C}(\Omega^2, \mathbb{R}_+^*)$  and  $\tau, \sigma \in \mathcal{C}(\Omega, \mathbb{R}_+^*)$  for  $\Omega \subset \mathbb{R}^2$  compact.

**Persistence:** species  $u$  persists (strongly, uniformly) if there exists  $\varepsilon > 0$  such that, for any non trivial initial condition, for any  $x \in \Omega$ ,

$$\liminf_{t \rightarrow +\infty} u(t, x) > \varepsilon.$$

$\Rightarrow$  Given a landscape, can we predict if neither, one or both species persist?

## The mono-specific case (Delmas, Dronnier, et al., 2022)

For a single species,

$$\partial_t u(t, x) = -\tau u + (1 - u) \int_{\Omega} u(t, y) c(x, y) dy.$$

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**Intuition :** if  $u$  is capable of invading the landscape when it is empty (i.e. the zero equilibrium), then  $u$  persists in the long run  $\rightarrow$  invasion fitness?

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For a single species,

$$\partial_t u(t, x) = -\tau u + (1 - u) \int_{\Omega} u(t, y) c(x, y) dy.$$

Define the following operator by its action on  $g \in L^\infty(\Omega, \mathbb{R}_+)$ :

$$\mathcal{T}_u(g)(x) = \int_{\Omega} \frac{c(x, y)}{\tau(y)} g(y) dy$$

For related work, see also (Lajmanovich and Yorke, 1976; Thieme, 2011).

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If its spectral radius  $r(\mathcal{T}_u) > 1$  ( $\approx$  **positive invasion fitness**), then for any non trivial initial condition,

$$u(t, \cdot) \xrightarrow{t \rightarrow \infty} \bar{u} > 0 \text{ uniformly on } \Omega.$$

Else,  $u$  converges uniformly to zero.

For related work, see also (Lajmanovich and Yorke, 1976; Thieme, 2011).

## The mono-specific case (Delmas, Dronnier, et al., 2022)

If further any spot  $x$  is unavailable with probability  $p(x)$ :

$$\partial_t u(t, x) = -\tau u + (1 - u - p) \int_{\Omega} u(t, y) c(x, y) dy.$$



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Define the following operator by its action on  $g \in L^\infty(\Omega, \mathbb{R}_+)$ :

$$\mathcal{T}_u(g)(x) = \int_{\Omega} \frac{c(x, y)g(y)}{\tau(y)} dy \text{ and } \mathcal{S}_p(g)(x) = (1 - p(x))g(x).$$

If the spectral radius  $r(\mathcal{T}_u \circ \mathcal{S}_p) > 1$  ( $\approx$  positive invasion fitness), then for any non trivial initial condition,

$$u(t, \cdot) \xrightarrow{t \rightarrow \infty} \bar{u}_p > 0 \text{ uniformly on } \Omega.$$

Else,  $u$  converges uniformly to zero.

## Back to $S = 2$

- Let  $\mathcal{T}_u$  and  $\mathcal{T}_v$  be the linear operators associated to the invasion of the trivial equilibrium by  $u$  and  $v$  alone.
- We let  $\bar{u}$  and  $\bar{v}$  designate the mono-specific equilibria of  $u$  and  $v$ , if they exist.
- **Intuition:** in the long run, coexistence of  $u$  and  $v$  is possible if and only if each species can invade the other's mono-specific equilibrium. (Chesson, 2000)

## Theorem

*The persistence of the bi-specific metacommunity system is characterized as follows.*

1. *If  $r(\mathcal{T}_u) \leq 1$  and  $r(\mathcal{T}_v) \leq 1$ , then  $(u, v) \rightarrow (0, 0)$  uniformly.*
2. *If  $r(\mathcal{T}_u) \leq 1$  and  $r(\mathcal{T}_v) > 1$  then  $(u, v) \rightarrow (0, \bar{v})$  uniformly, and conversely.*
3. *If  $r(\mathcal{T}_u \circ S_{\bar{v}}) > 1$  and  $r(\mathcal{T}_v \circ S_{\bar{u}}) > 1$ , then both  $u$  and  $v$  persist.*
4. *(Conjecture) If  $r(\mathcal{T}_u \circ S_{\bar{v}}) \leq 1$  and  $r(\mathcal{T}_v \circ S_{\bar{u}}) > 1$  then  $(u, v) \rightarrow (0, \bar{v})$ , and conversely.*

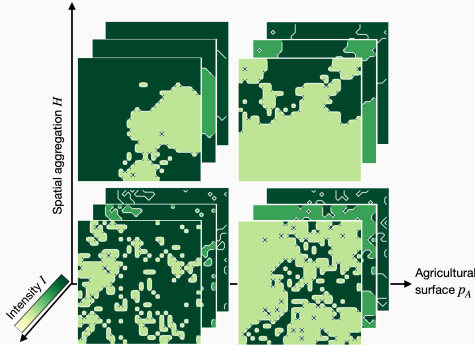
- The proof essentially relies on two ingredients:
  - If for any  $x$ ,  $p(x) \leq q(x)$ , then  $r(\mathcal{T}_u \circ \mathcal{S}_p) \geq r(\mathcal{T}_u \circ \mathcal{S}_q)$ .
  - Control of  $u$  and  $v$  by comparing them to solutions of the mono-specific system with well-chosen values of  $p$ .
- Coexistence scenario: does the system converge to a coexistence equilibrium?

## Exploring the biodiversity-yield trade-off

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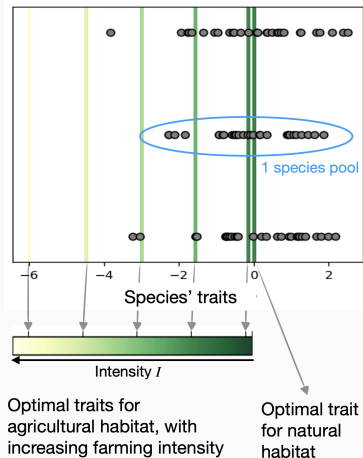
# Management strategies of agricultural landscapes

**Aim:** evaluate the impact of a diverse family of management strategies on yield and biodiversity.



- Low to high values of agricultural surface and aggregation.
- Farming intensity ranges from hunter-gatherer to intensive agriculture.

# Species pool



- Pools of 30 species who compete for space.
- Same dispersal kernel.
- Traits condition extinction rates in natural and agricultural patches (Kisdi, 2002).
- A species may colonize a patch occupied by a less adapted one.

# Model outputs of interest

**Yield:** depends on farming intensity and local biodiversity, reflecting ecosystem services e.g. pollination (Burian et al., 2024).

At any point  $x$ , local yield is defined by

$$r(x) = \underbrace{i(x)}_{\text{Impact of farming intensity}} \times \underbrace{b(x)}_{\text{Ecosystem service}}.$$

Global yield:

$$Y = \int_A r(x) dx.$$



## Model outputs of interest

**Regional biodiversity:** Many possible indicators may be considered (species richness, Shannon diversity...).

Here, we want to account for species' rareness, and the risk of spots being empty.

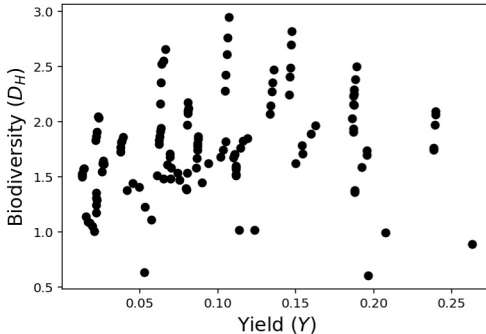
⇒ Hill diversity (Roswell et al., 2021):

$$D_H = \left( \sum_{i=0}^S \left( \int_{\Omega} u_i \right)^{1/2} \right)^2$$

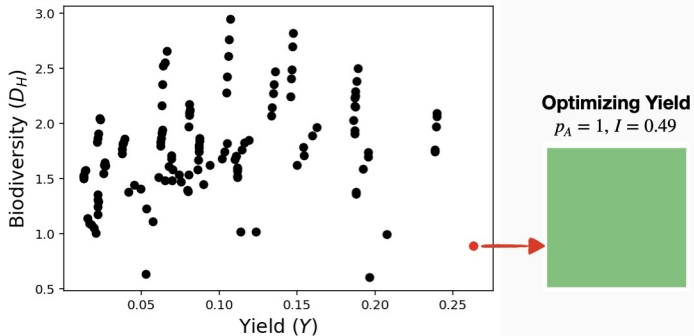
↪ intermediate between species richness and Shannon diversity.

# Optimal management strategies

- Average values of achieved yield and biodiversity for each management strategy (131 strategies total).
- **Trade-off:** overall, biodiversity tends to decrease with high yield.



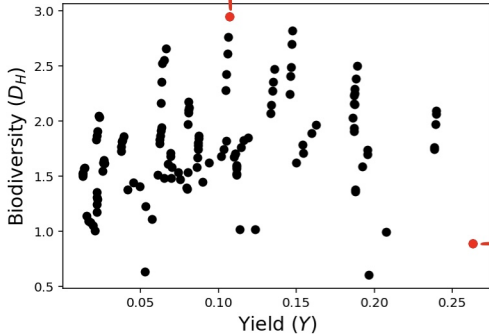
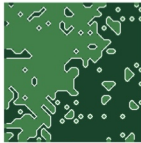
# Optimal management strategies



# Optimal management strategies

## Optimizing Biodiversity

$$p_A = 0.5, I = 0.18, H = 0.01$$



## Optimizing Yield

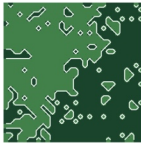
$$p_A = 1, I = 0.49$$



# Optimal management strategies

## Optimizing Biodiversity

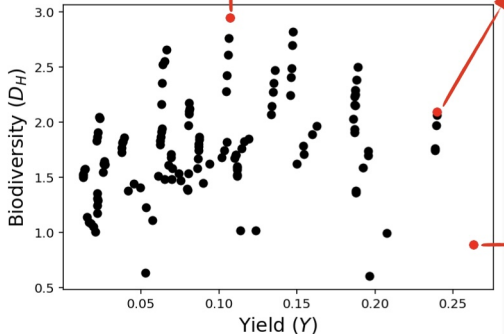
$$p_A = 0.5, I = 0.18, H = 0.01$$



## Compromise

$$\text{Optimize: } Y/\max(Y) + D_H/\max(D_H)$$

$$p_A = 0.9, I = 0.49, H = 0.01$$



## Optimizing Yield

$$p_A = 1, I = 0.49$$



## Conclusion and perspectives

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# Conclusion and perspectives

Ongoing work in progress:

- Persistence criterion: conjecture, numerical exploration.
- Further analysis of simulation results, e.g. **pretty good yield** (Hilborn, 2010): if we accept to reduce yield by 20-25%, does this allow for a significant gain in biodiversity?

Future directions:

- Impact of the agricultural landscape on the **evolution** of the specialization trait? → M2 internship of Lisa Paruit.
- Mutualistic or trophic **interaction networks**?

**Thank you for your attention**

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