

Time harmonic Maxwell's equations with sign changing coefficients

Workshop : Around scattering by obstacles and billiards

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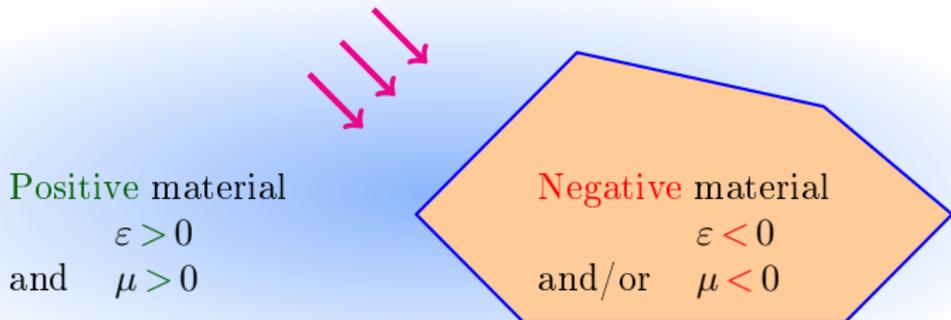
[†]POems team, Ensta, Paris, France

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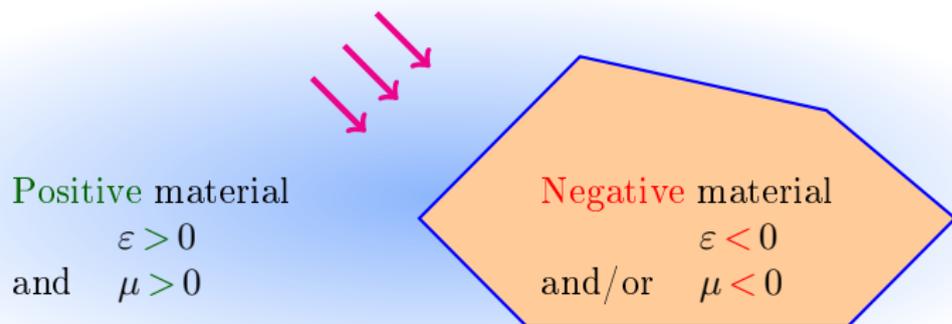
Introduction: objective

Scattering by a **negative material** in electromagnetism in 3D in **time-harmonic** regime (at a given frequency):



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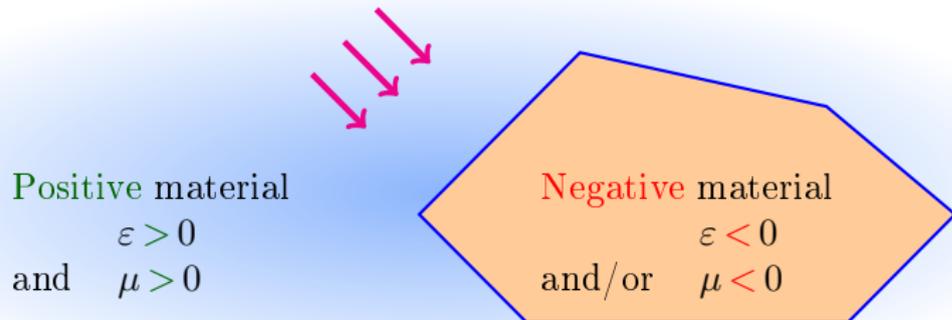
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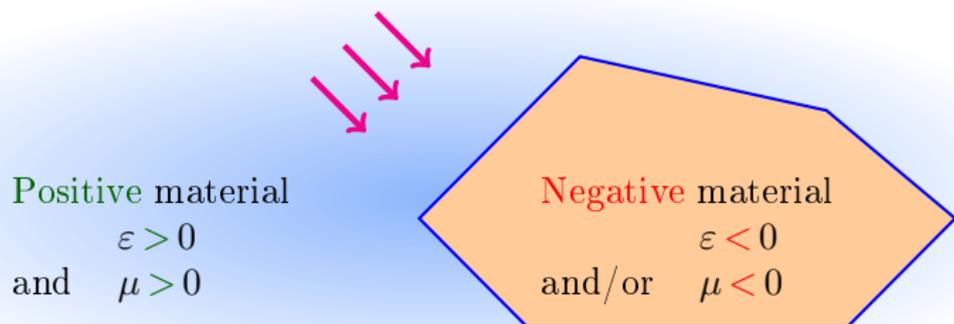


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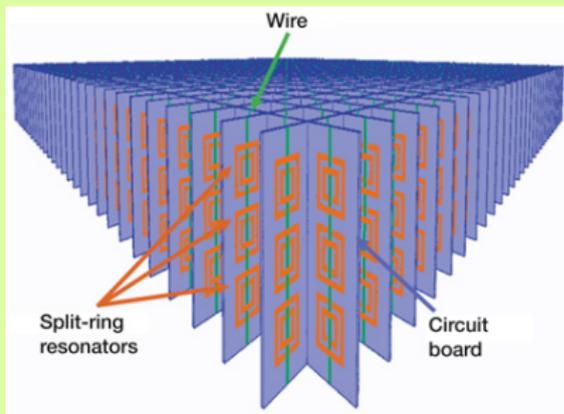
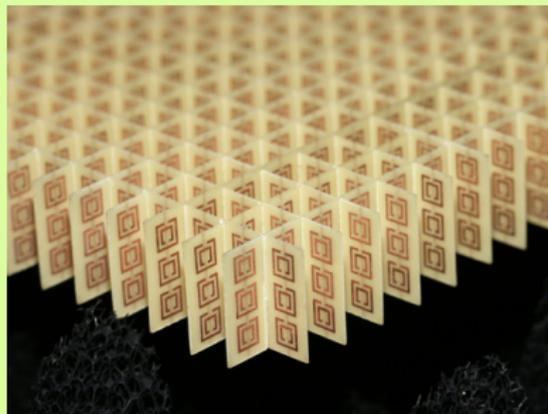
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Zoom on a metamaterial: practical realizations of metamaterials are achieved by a **periodic** assembly of small **resonators**.

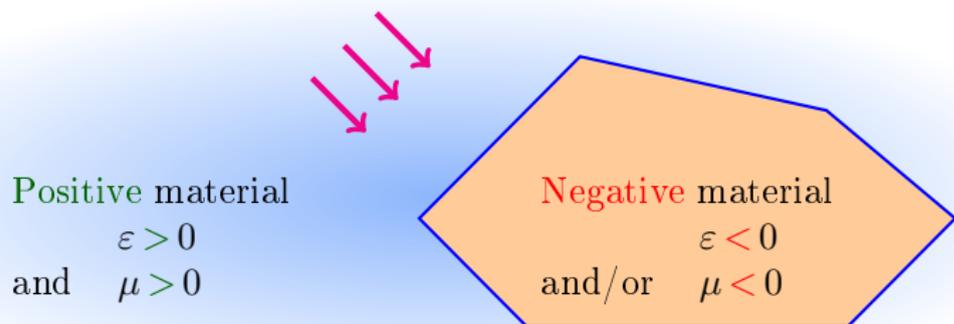


EXAMPLE OF METAMATERIAL (NASA)

Mathematical justification of the homogenized model: Bouchitté, Bourel and Felbacq, 09.

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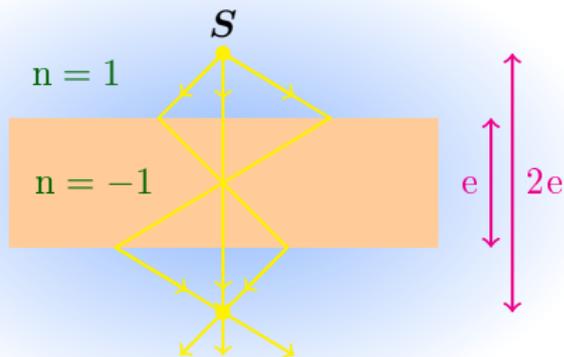
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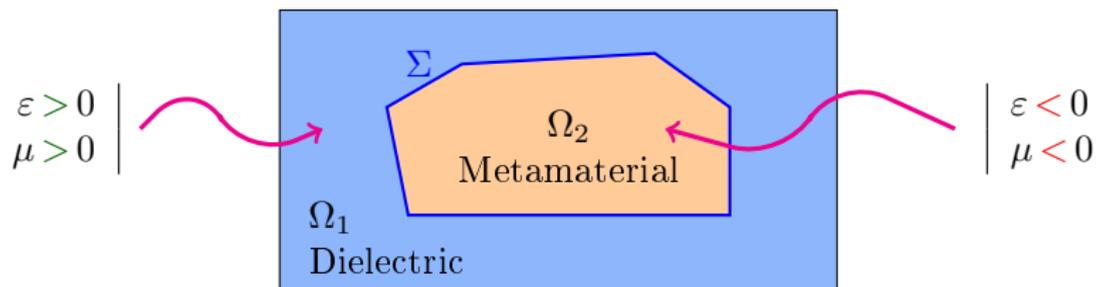
- ▶ **Surface Plasmons Polaritons** that propagate at the interface between a metal and a dielectric can help reducing the size of **computer chips**.



- ▶ The **negative refraction** at the interface metamaterial/dielectric could allow the realization of **perfect lenses** (Pendry, 00), **photonic traps** ...

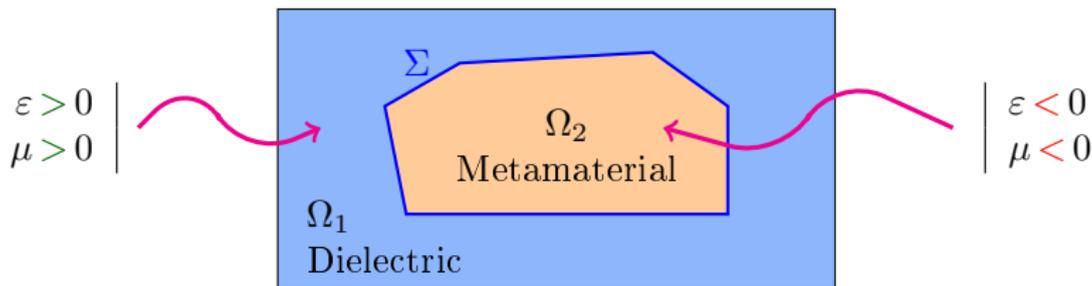
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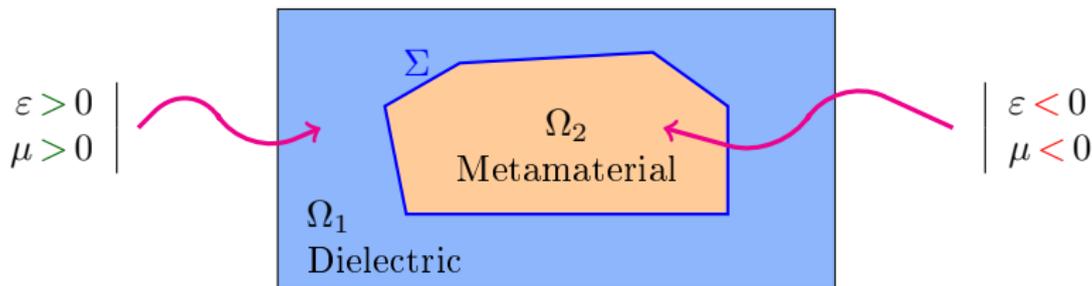
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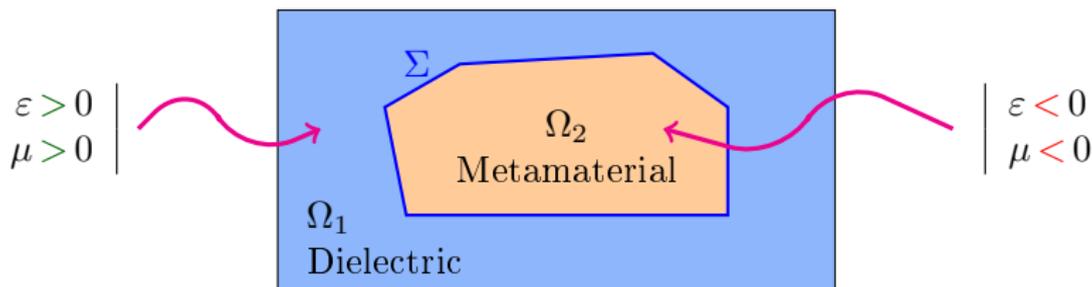


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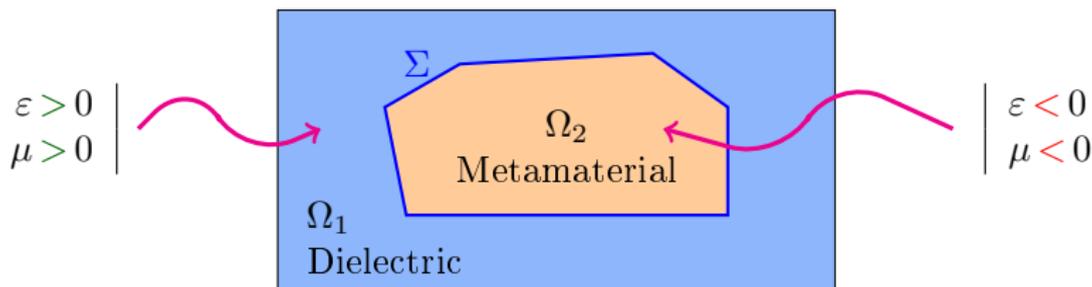


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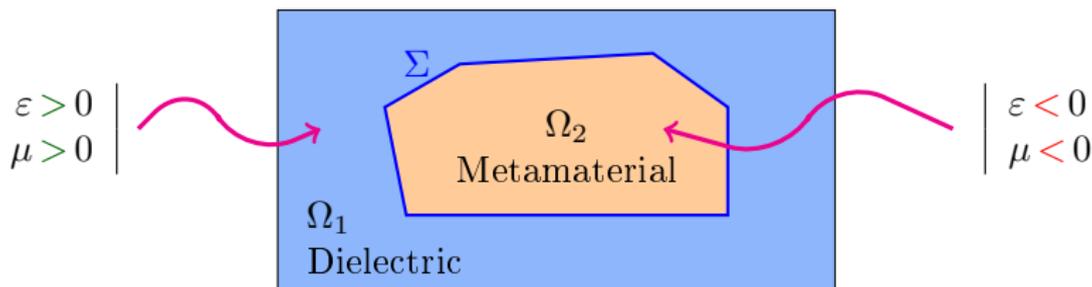


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Does well-posedness still hold ? What is the appropriate functional framework ? What about the convergence of approximation methods ? ...

Classical results for positive materials

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What happens in presence of **sign-changing** ε and μ ?

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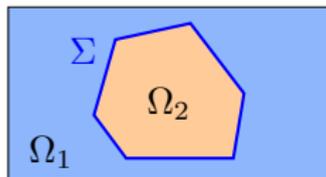
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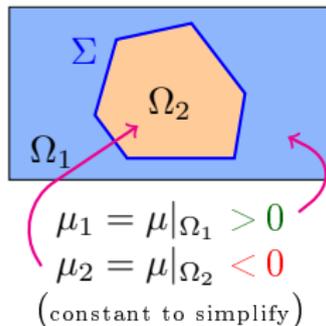


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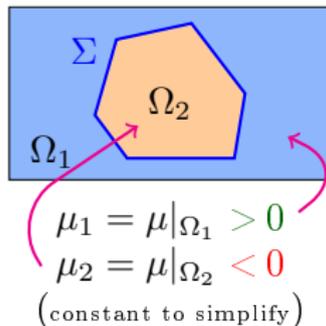
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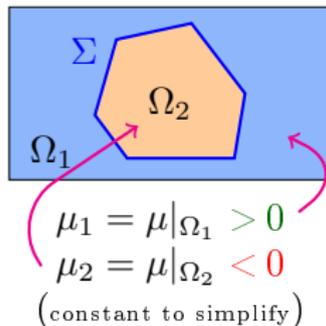
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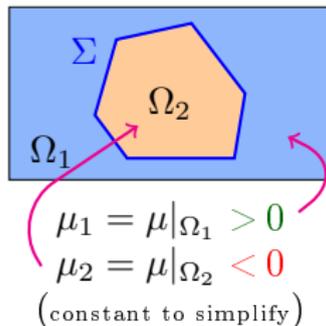
$$\text{with } a(u, v) = \int_{\Omega} \mu^{-1} \nabla u \cdot \nabla v \quad \text{and} \quad l(v) = \langle f, v \rangle_{\Omega}.$$

A scalar model problem

Problem for E_z in 2D in case of an invariance with respect to z :

$$\left| \begin{array}{l} \text{Find } E_z \in H_0^1(\Omega) \text{ such that:} \\ \operatorname{div}(\mu^{-1} \nabla E_z) + \omega^2 \varepsilon E_z = -f \quad \text{in } \Omega. \end{array} \right.$$

- $H_0^1(\Omega) = \{v \in L^2(\Omega) \mid \nabla v \in L^2(\Omega); v|_{\partial\Omega} = 0\}$
- f is the source term in $H^{-1}(\Omega)$



Since $H_0^1(\Omega) \subset\subset L^2(\Omega)$, we focus on the principal part.

$$(\mathcal{P}) \quad \left| \begin{array}{l} \text{Find } u \in H_0^1(\Omega) \text{ s.t.:} \\ \operatorname{div}(\mu^{-1} \nabla u) = -f \text{ in } \Omega. \end{array} \right.$$

\Leftrightarrow

$$(\mathcal{P}_V) \quad \left| \begin{array}{l} \text{Find } u \in H_0^1(\Omega) \text{ s.t.:} \\ a(u, v) = l(v), \forall v \in H_0^1(\Omega). \end{array} \right.$$

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DEFINITION. We will say that the problem (\mathcal{P}) is **well-posed** if the operator $A = \operatorname{div}(\mu^{-1} \nabla \cdot)$ is an **isomorphism** from $H_0^1(\Omega)$ to $H^{-1}(\Omega)$.

Mathematical difficulty

- Classical case $\mu > 0$ everywhere :

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- ▶ For a **symmetric domain** (w.r.t. Σ) with $\mu_2 = -\mu_1$, we can build a kernel of **infinite dimension**.

Idea of the T-coercivity 1/2

Let \mathbf{T} be an **isomorphism** of $\mathbf{H}_0^1(\Omega)$.

$$(\mathcal{P}) \Leftrightarrow (\mathcal{P}_V) \left| \begin{array}{l} \text{Find } u \in \mathbf{H}_0^1(\Omega) \text{ such that:} \\ a(u, v) = l(v), \forall v \in \mathbf{H}_0^1(\Omega). \end{array} \right.$$

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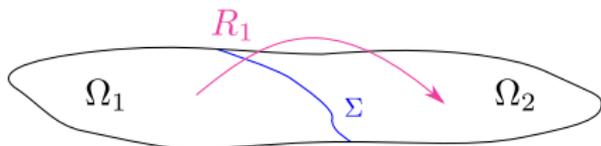
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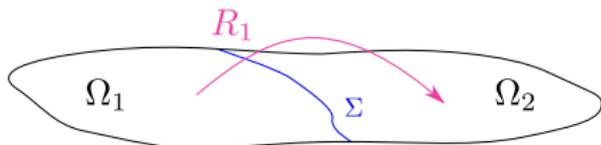
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$$\begin{aligned} R_1 u_1 &= u_1 & \text{on } \Sigma \\ R_1 u_1 &= 0 & \text{on } \partial\Omega_2 \setminus \Sigma \end{aligned}$$

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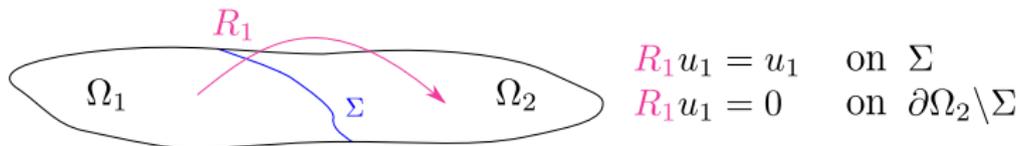
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2 $\mathbf{T}_1 \circ \mathbf{T}_1 = Id$ so \mathbf{T}_1 is an **isomorphism** of $H_0^1(\Omega)$

Idea of the T-coercivity 2/2

3 One has $a(u, \mathbb{T}_1 u) = \int_{\Omega} |\mu|^{-1} |\nabla u|^2 - 2 \int_{\Omega_2} \mu_2^{-1} \nabla u \cdot \nabla (R_1 u_1)$

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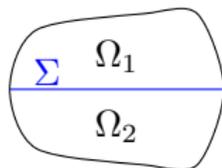
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5 Conclusion:

THEOREM. If the **contrast** $\kappa_{\mu} = \mu_2/\mu_1 \notin [-\|R_1\|^2; -1/\|R_2\|^2]$ (**critical interval**) then $\operatorname{div}(\mu^{-1} \nabla \cdot)$ is an **isomorphism** from $H_0^1(\Omega)$ to $H^{-1}(\Omega)$.

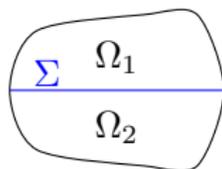
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- ▶ A simple case: symmetric domain



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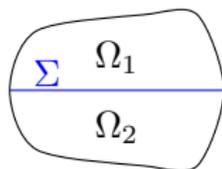


$$R_1 = R_2 = S_\Sigma$$

so that $\|R_1\| = \|R_2\| = 1$
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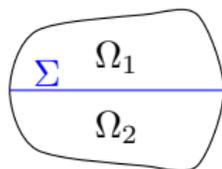
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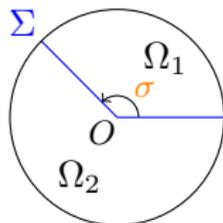
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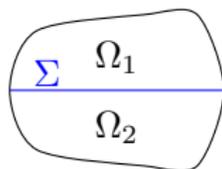
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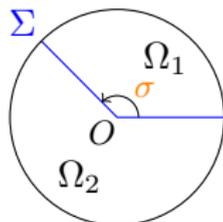
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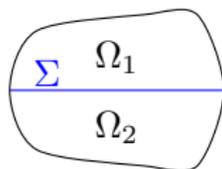
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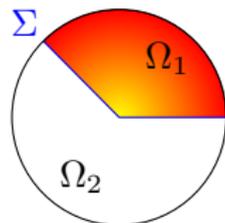
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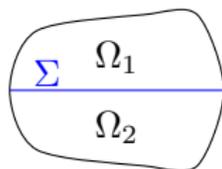
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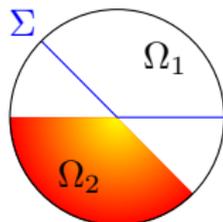
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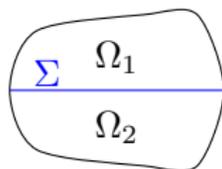


Action of R_1 : symmetry

w.r.t θ

Choice of R_1, R_2 ?

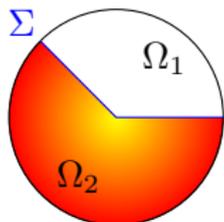
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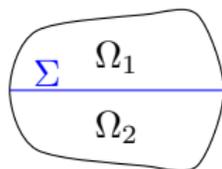
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Action of R_1 : symmetry + dilatation w.r.t θ

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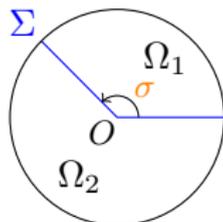
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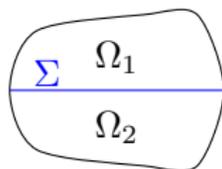


Action of R_1 : symmetry + dilatation w.r.t θ

$$\|R_1\|^2 = \mathcal{R}_\sigma = (2\pi - \sigma)/\sigma$$

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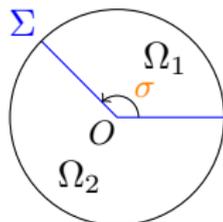
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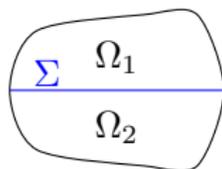
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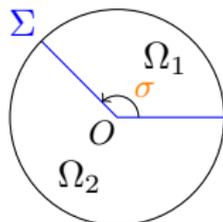
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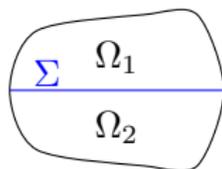
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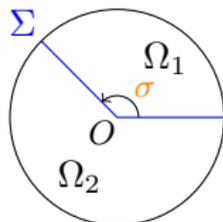
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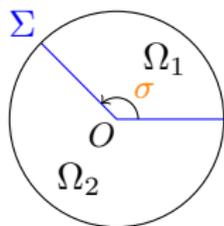
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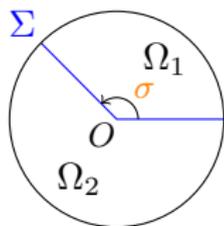
PROPOSITION. The problem (\mathcal{P}) is well-posed in the Fredholm sense for a **polygonal interface** if $\kappa_\mu \notin [-\mathcal{R}_\sigma; -1/\mathcal{R}_\sigma]$ where σ is the smallest angle.

The case of an interface with corners



What happens when $\kappa_\mu \in [-\mathcal{R}_\sigma; -1/\mathcal{R}_\sigma]$?

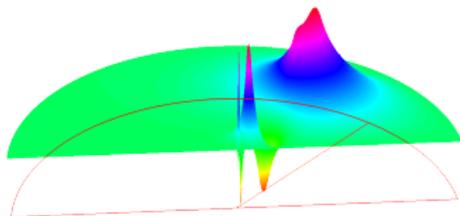
The case of an interface with corners



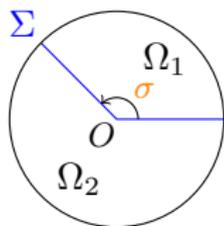
What happens when $\kappa_\mu \in [-\mathcal{R}_\sigma; -1/\mathcal{R}_\sigma]$?

For $\kappa_\mu \in [-\mathcal{R}_\sigma; -1/\mathcal{R}_\sigma]$, $\kappa_\mu \neq -1$:

- There exists a **propagative singularity** $\varphi(\theta)r^{\pm i\eta} = \varphi(\theta)e^{\pm i\eta \ln r}$ with $\eta \in \mathbb{R}^*$ which belongs to $H^{1-\delta}(\Omega)$ but not to $H^1(\Omega)$.



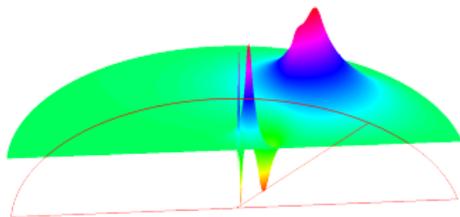
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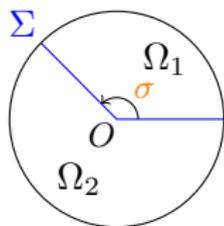
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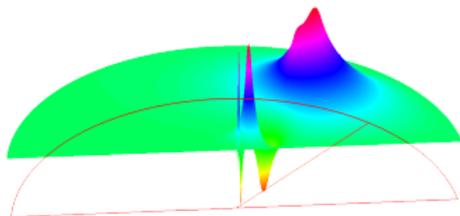
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- Due to this singularity, **the problem is not Fredholm** in $H^1(\Omega)$.
- We have justified a **new functional framework** in which Fredholm property is recovered, by selecting the outgoing singularity.
Bonnet-Ben Dhia, Chesnel and Claeys (submitted)

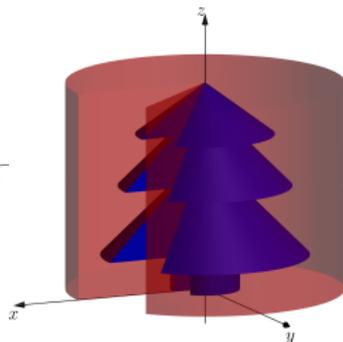
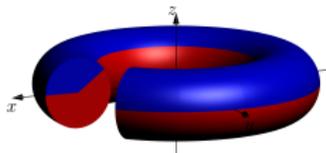
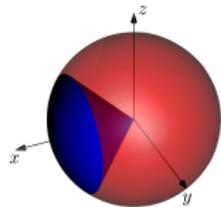
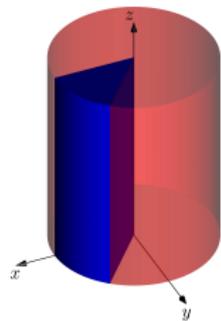


Extensions for the scalar case

- ▶ The T-coercivity approach can be used to deal with the **Neumann** problem.

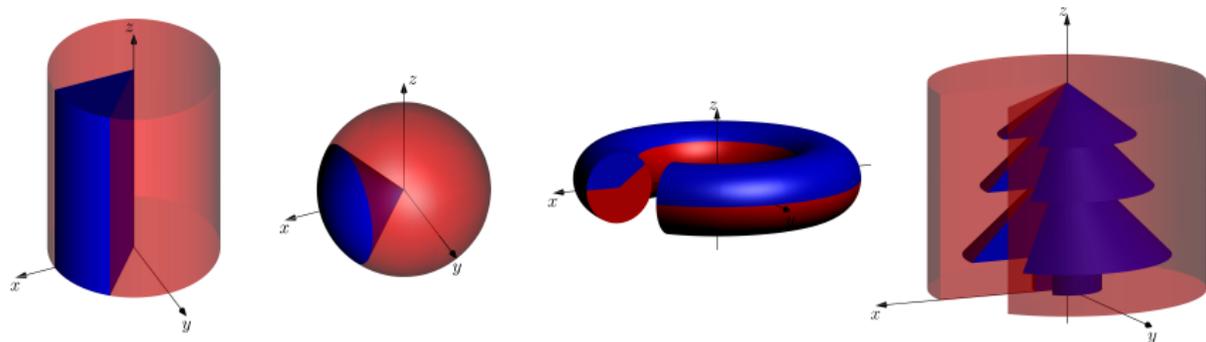
Extensions for the scalar case

- ▶ The T-coercivity approach can be used to deal with the **Neumann** problem.
- ▶ **3D geometries** can be handled in the same way.

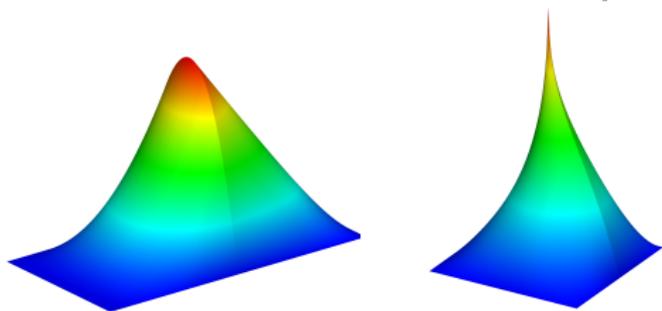


Extensions for the scalar case

- ▶ The T-coercivity approach can be used to deal with the **Neumann** problem.
- ▶ **3D geometries** can be handled in the same way.



- ▶ The T-coercivity technique allows to justify convergence of standard **finite element** method for simple meshes (*joint work with P. Ciarlet Jr.*).



- 1 Introduction
- 2 The coerciveness issue for the scalar cases
- 3 The coerciveness and compactness issues for the vectorial cases**
- 4 Conclusion

T-coercivity in the vector case 1/3

Let us consider the problem for the **magnetic** field \mathbf{H} :

$$\left| \begin{array}{l} \text{Find } \mathbf{H} \in \mathbf{V}_T(\mu; \Omega) \text{ such that for all } \mathbf{H}' \in \mathbf{V}_T(\mu; \Omega) : \\ \underbrace{\int_{\Omega} \varepsilon^{-1} \mathbf{curl} \mathbf{H} \cdot \mathbf{curl} \mathbf{H}'}_{a(\mathbf{H}, \mathbf{H}')} - \omega^2 \underbrace{\int_{\Omega} \mu \mathbf{H} \cdot \mathbf{H}'}_{c(\mathbf{H}, \mathbf{H}')} = \underbrace{\int_{\Omega} \mathbf{F} \cdot \mathbf{H}'}_{l(\mathbf{H}')}, \end{array} \right.$$

with $\mathbf{V}_T(\mu; \Omega) := \{\mathbf{u} \in \mathbf{H}(\mathbf{curl}; \Omega) \mid \operatorname{div}(\mu \mathbf{u}) = 0, \mu \mathbf{u} \cdot \mathbf{n} = 0 \text{ on } \partial\Omega\}$.

\mathbb{T} -coercivity in the vector case 1/3

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First attempt

$$\text{Let us try } \mathbb{T}\mathbf{H} = \begin{cases} \mathbf{H}_1 & \text{in } \Omega_1 \\ -\mathbf{H}_2 + 2R_1\mathbf{H}_1 & \text{in } \Omega_2 \end{cases},$$

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$$\begin{cases} (\mathbf{R}_1\mathbf{H}_1) \times \mathbf{n} & = \mathbf{H}_2 \times \mathbf{n} & \text{on } \Sigma \\ \mu_1(\mathbf{R}_1\mathbf{H}_1) \cdot \mathbf{n} & = \mu_2\mathbf{H}_2 \cdot \mathbf{n} & \text{on } \Sigma \end{cases}$$

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Not possible!

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♠ Impossible because $\operatorname{div}(\varepsilon \mathbf{curl} \mathbf{H}) \neq 0$. *The solution: add a gradient...*

T-coercivity in the vector case 3/3

Third attempt

Consider $\mathbf{H} \in \mathbf{V}_T(\mu; \Omega)$.

T-coercivity in the vector case 3/3

Third attempt

Consider $\mathbf{H} \in \mathbf{V}_T(\mu; \Omega)$.

- 1 Introduce $\varphi \in H_0^1(\Omega)$ such that $\operatorname{div}(\varepsilon(\mathbf{curl} \mathbf{H} - \nabla \varphi)) = 0$.

T-coercivity in the vector case 3/3

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Ok

if $(\varphi, \varphi') \mapsto \int_{\Omega} \varepsilon \nabla \varphi \cdot \nabla \varphi'$ is **T-coercive** on $H_0^1(\Omega)$. $(\mathcal{A}_\varepsilon)$

T-coercivity in the vector case 3/3

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2 Introduce $\mathbf{u} \in \mathbf{V}_T(1; \Omega)$ the function satisfying

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T-coercivity in the vector case 3/3

Third attempt

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\mathbb{T} -coercivity in the vector case 3/3

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👉 Use the results of the previous section to check $(\mathcal{A}_{\varepsilon})$ and (\mathcal{A}_{μ}) .

\mathbb{T} -coercivity in the vector case 3/3

Third attempt

Consider $\mathbf{H} \in \mathbf{V}_T(\mu; \Omega)$.

LEMMA. Suppose

$$(\varphi, \varphi') \mapsto \int_{\Omega} \varepsilon \nabla \varphi \cdot \nabla \varphi' \text{ is } \mathbf{T}\text{-coercive on } H_0^1(\Omega); \quad (\mathcal{A}_{\varepsilon})$$

$$(\varphi, \varphi') \mapsto \int_{\Omega} \mu \nabla \varphi \cdot \nabla \varphi' \text{ is } \mathbf{T}\text{-coercive on } H^1(\Omega)/\mathbb{R}. \quad (\mathcal{A}_{\mu})$$

Then, there exists $\mathbb{T} \in \mathcal{L}(\mathbf{V}_T(\mu; \Omega))$ such that, for all \mathbf{H}, \mathbf{H}'

$$a(\mathbf{H}, \mathbb{T}\mathbf{H}') = a(\mathbb{T}\mathbf{H}, \mathbf{H}') = \int_{\Omega} \mathbf{curl} \mathbf{H} \cdot \mathbf{curl} \mathbf{H}'.$$

$$a(\mathbf{H}, \mathbb{T}\mathbf{H}) = \int_{\Omega} \varepsilon^{-1} \mathbf{curl} \mathbf{H} \cdot \mathbf{curl} \mathbf{u} = \int_{\Omega} |\mathbf{curl} \mathbf{H}|^2.$$

Use the results of the previous section to check $(\mathcal{A}_{\varepsilon})$ and (\mathcal{A}_{μ}) .

A result of compact embedding

- ▶ Using the analogue of the previous result in $\mathbf{V}_N(1; \Omega)$, we can prove the

THEOREM. Suppose

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Then, the embedding of

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- ▶ Since for all \mathbf{H}, \mathbf{H}'

$$a(\mathbf{H}, \mathbf{T}\mathbf{H}') = a(\mathbf{T}\mathbf{H}, \mathbf{H}') = \int_{\Omega} \mathbf{curl} \mathbf{H} \cdot \mathbf{curl} \mathbf{H}',$$

we deduce *a posteriori* that \mathbf{T} is an isomorphism of $\mathbf{V}_T(\mu; \Omega)$.

The result for the magnetic field

Consider $\mathbf{F} \in \mathbf{L}^2(\Omega)$ such that $\operatorname{div} \mathbf{F} \in \mathbf{L}^2(\Omega)$.

THEOREM. Suppose

$$(\varphi, \varphi') \mapsto \int_{\Omega} \varepsilon \nabla \varphi \cdot \nabla \varphi' \text{ is } \mathbf{T}\text{-coercive} \text{ on } H_0^1(\Omega); \quad (\mathcal{A}_\varepsilon)$$

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Then, the problem for the **magnetic field**

$$\left| \begin{array}{l} \text{Find } \mathbf{H} \in \mathbf{H}(\mathbf{curl}; \Omega) \text{ such that:} \\ \mathbf{curl} \varepsilon^{-1} \mathbf{curl} \mathbf{H} - \omega^2 \mu \mathbf{H} = \mathbf{F} \quad \text{in } \Omega \\ \mu \mathbf{H} \cdot \mathbf{n} = 0 \quad \text{on } \partial\Omega. \end{array} \right.$$

is **well-posed** for all $\omega \in \mathbb{C} \setminus \mathcal{S}$ where \mathcal{S} is a discrete (or empty) set of \mathbb{C} .

... and the result for the electric field

Consider $\mathbf{F} \in \mathbf{L}^2(\Omega)$ such that $\operatorname{div} \mathbf{F} \in \mathbf{L}^2(\Omega)$.

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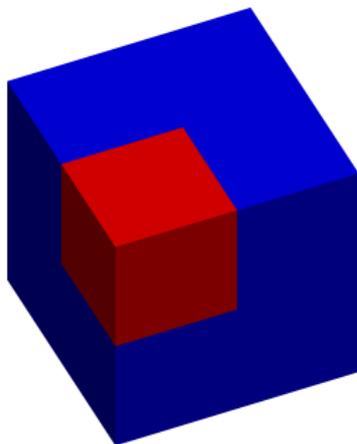
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Then, the problem for the **electric field**

$$\left| \begin{array}{l} \text{Find } \mathbf{E} \in \mathbf{H}(\mathbf{curl}; \Omega) \text{ such that:} \\ \mathbf{curl} \mu^{-1} \mathbf{curl} \mathbf{E} - \omega^2 \varepsilon \mathbf{E} = \mathbf{F} \quad \text{in } \Omega \\ \mathbf{E} \times \mathbf{n} = 0 \quad \text{on } \partial\Omega. \end{array} \right.$$

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Application to the Fichera's corner



PROPOSITION. Suppose

$$\kappa_\varepsilon \notin \left[-7; -\frac{1}{7}\right] \quad \text{and} \quad \kappa_\mu \notin \left[-7; -\frac{1}{7}\right]. \quad *$$

Then, the problems for the **electric** and **magnetic** fields are **well-posed** for all $\omega \in \mathbb{C} \setminus \mathcal{S}$ where \mathcal{S} is a discrete (or empty) set of \mathbb{C} .

* Note that 7 is the ratio of the **blue volume** over the **red volume**...

- 1 Introduction
- 2 The coerciveness issue for the scalar cases
- 3 The coerciveness and compactness issues for the vectorial cases
- 4 Conclusion

Conclusions for the bounded domain

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For the continuous problem

- ✓ We have studied the scalar problem with a **geometric T-coercivity**.
- ✓ We have proved that the **Maxwell's problems** for \mathbf{E} and \mathbf{H} are **well-posed** as soon as the two **scalar** problems are well-posed.

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For the numerical methods

- ✓ In the scalar case: in practice, usual methods converge. Partial proofs are available **Bonnet-Ben Dhia *et al.*, 10, Nicaise-Venel, 11, Chesnel-Ciarlet, submitted.**
- ♠ In the vector case: convergence of an **edge elements** method has to be studied.

Conclusions for the bounded domain

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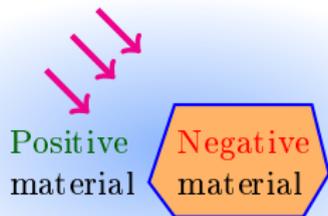
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Inside the critical interval

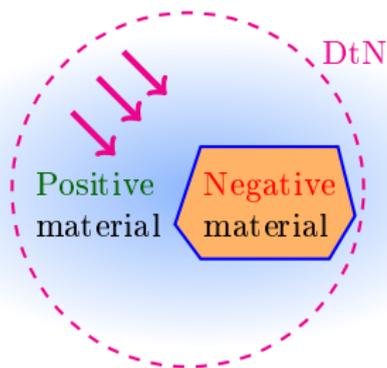
- ✓ In the scalar case, we have developed a functional framework to take into account the **propagative singularity** **Bonnet-Ben Dhia *et al.*, submitted.**
- ♠ In the vector case: a theoretical study is in progress.
- ♠ Our new model raises **a lot of questions**, related to the physics of **plasmonics** and **metamaterials**.

Perspectives for the scattering problem



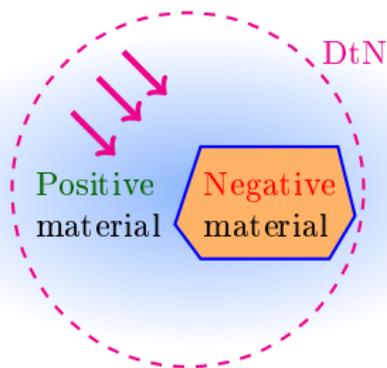
- ✓ We hope to be able to deal with the scattering problem for a bounded negative obstacle using a D_{tn} operator and the results presented in this talk.

Perspectives for the scattering problem

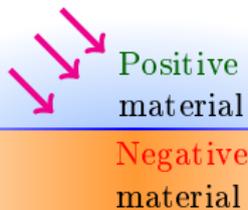


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Perspectives for the scattering problem

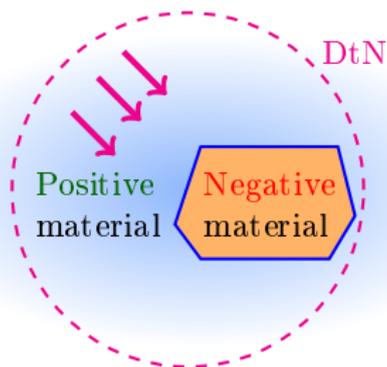


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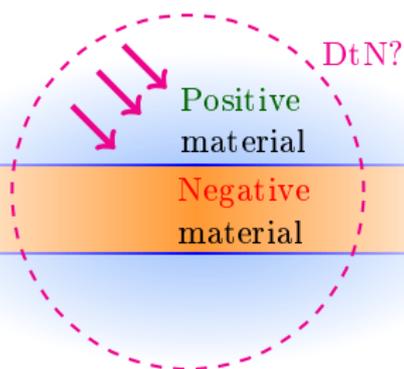


- ♠ For an **unbounded** negative obstacle, the problem looks more complicated. **The exterior problem is not standard.**

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Thank you for your attention.



A.-S. Bonnet-Ben Dhia, L. Chesnel, P. Ciarlet Jr., *T-coercivity for scalar interface problems between dielectrics and metamaterials*, M2AN, to appear, 2012.



A.-S. Bonnet-Ben Dhia, L. Chesnel, P. Ciarlet Jr., *T-coercivity for the Maxwell transmission problem between a dielectric and a negative material*, on going work.



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