

# Invisibilité en champ lointain pour un problème de diffraction acoustique

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Fondation mathématique

**FMJH**

Jacques Hadamard

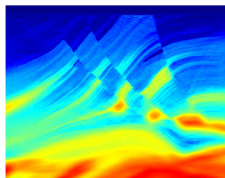


**CMAP**



# General setting

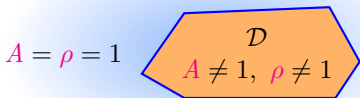
- ▶ We are interested in methods based on the **propagation of waves** to determine the shape, the physical properties of objects, in an **exact** or **qualitative** manner, from given measurements.
- ▶ GENERAL PRINCIPLE OF THE METHODS:
  - i) send waves in the medium;
  - ii) measure the scattered field;
  - iii) deduce information on the structure.



- Many **techniques**: Xray, ultrasound imaging, seismic tomography, ...
- Many **applications**: biomedical imaging, non destructive testing of materials, geophysics, ...

# Model problem

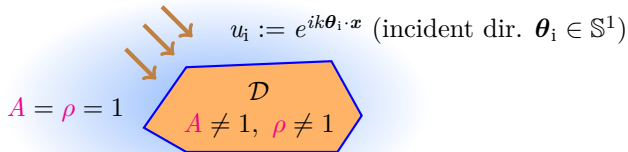
- Scattering in **time-harmonic** regime of an **incident plane wave** by a bounded penetrable **inclusion**  $\mathcal{D}$  (coefficients  $A, \rho$ ) in  $\mathbb{R}^2$ .



$$\left| \begin{array}{l} \text{Find } u \text{ such that} \\ -\operatorname{div}(A\nabla u) = k^2 \rho u \quad \text{in } \mathbb{R}^2, \\ u = u_i + u_s \quad \text{in } \mathbb{R}^2, \\ \lim_{r \rightarrow +\infty} \sqrt{r} \left( \frac{\partial u_s}{\partial r} - iku_s \right) = 0. \end{array} \right. \quad (1)$$

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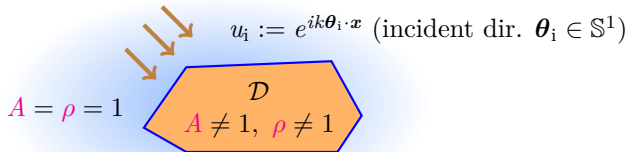
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DEFINITION:  $u_i =$  **incident** field (datum)  
 $u =$  **total** field (uniquely defined by (1))  
 $u_s =$  **scattered** field (uniquely defined by (1)).

# Illustration of the scattering of a plane wave

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► Below, the movies represent a **numerical approximation** of the solution of the previous problem.

Incident field

Total field

Scattered field

$$t \mapsto \Re e (e^{-i\omega t} u_i(\mathbf{x}))$$

$$t \mapsto \Re e (e^{-i\omega t} u(\mathbf{x}))$$

$$t \mapsto \Re e (e^{-i\omega t} u_s(\mathbf{x}))$$

► The **pulsation**  $\omega$  is defined by  $\omega = k/c$  where  $c = 1$  is the **celerity** of the waves in the homogeneous medium.



# Outline of the talk

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We are interested by defects that **cannot be detected** and by **invisibility**.

- For a given obstacle, is there an incident field that **does not scatter**?
- And when there is only a **finite number of emitters/receivers**?
- For a given obstacle and a finite number of emitters/receivers, how to build **invisible** obstacles?



- 1 Introduction
- 2 The Interior Transmission Eigenvalue Problem (ITEP)
- 3 A discrete interior transmission eigenvalue problem
- 4 Invisible inclusions for a finite number of incident/scattered directions
- 5 Conclusion

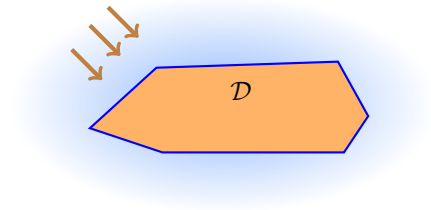
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# Presentation of the ITEP

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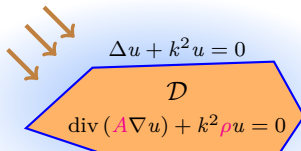
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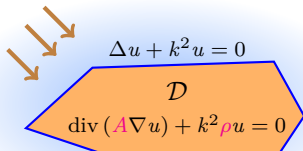
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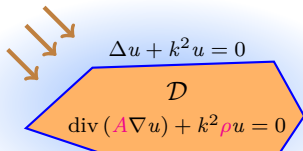
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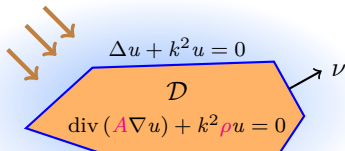
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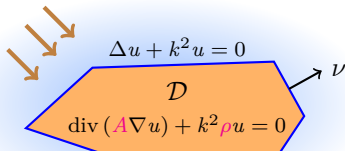
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$$u = w + \mathbf{0} \quad \text{in } \mathbb{R}^2 \setminus \mathcal{D}.$$

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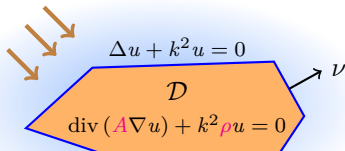
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TRANS. COND. ON  $\partial \mathcal{D}$

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# What framework for the ITEP?

---

- **Generalized combination** of incident plane waves:

$$w(\mathbf{x}) = \sum_{n=1}^N \alpha_n e^{ik\boldsymbol{\theta}_i^n \cdot \mathbf{x}} \quad \Rightarrow \quad w(\mathbf{x}) = \underbrace{\int_{\mathbb{S}^1} g(\boldsymbol{\theta}_i) e^{ik\boldsymbol{\theta}_i \cdot \mathbf{x}} d\boldsymbol{\theta}_i}_{\text{Herglotz wave function}}, \quad g \in L^2(\mathbb{S}^1).$$



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- Since **Herglotz wave functions** are **dense** in  $\{w \in H^1(\mathcal{D}) \mid \Delta w + k^2 w = 0\}$ , we consider the problem

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**DEFINITION.** Values of  $k \in \mathbb{C}$  for which this problem has a nontrivial solution  $(u, w)$  are called **transmission eigenvalues**.

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- For transmission eigenvalues, there are generalized combination of incident planes waves which produce **arbitrarily small scattered fields**.

# Variational formulation for the ITEP

---

- $k$  is a **transmission eigenvalue** if and only if there exists  $(u, w) \in X \setminus \{0\}$  such that, for all  $(u', w') \in X$ ,

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- ▶ Define on  $X \times X$  the sesquilinear form

$$a_k((u, w), (u', w')) = \int_{\mathcal{D}} A \nabla u \cdot \overline{\nabla u'} - \nabla w \cdot \overline{\nabla w'} - k^2 (\rho u \overline{u'} - w \overline{w'}) \, d\mathbf{x}.$$

- ▶ First, we consider the **source term problem**.
- ▶ Let **T** be an **isomorphism** of  $X$ . For  $\ell \in X'$ , we have

$$[ \quad (\mathcal{P}_V) \quad a_k((u, w), (u', w')) = \ell(u', w'), \quad \forall (u', w') \in X ]$$

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Goal: Find  $\mathbf{T}$  such that  $a_k(\cdot, \mathbf{T} \cdot)$  is coercive.

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$$\begin{aligned} a_k((u, w), \mathbf{T}(u, w)) &= \int_{\mathcal{D}} A |\nabla u|^2 + |\nabla w|^2 + |k|^2 (\rho |u|^2 + |w|^2) d\mathbf{x}, \\ &\quad - 2 \int_{\mathcal{D}} \nabla w \cdot \overline{\nabla u} + |k|^2 w \bar{u} d\mathbf{x}. \end{aligned}$$

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- This approach also works only assuming that  $A - 1$  and  $n - 1$  have a **constant sign** in a **neighbourhood of  $\partial\mathcal{D}$** .



- 3 For  $k \in \mathbb{R}i \setminus \{0\}$ , one finds

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Find  $(u, w) \in X$  such that:

$$\int_{\mathcal{D}} A \nabla u \cdot \overline{\nabla u'} - \nabla w \cdot \overline{\nabla w'} d\mathbf{x} = k^2 \int_{\mathcal{D}} (\rho u \bar{u}' - w \bar{w}') d\mathbf{x}, \quad \forall (u', w') \in X.$$

When  $A = 1$ , the **principal symbol vanishes**. It is necessary to **modify the functional framework** (also sometimes when  $A - 1$  changes sign on  $\partial\mathcal{D}$ ).

# Many other interesting questions

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- ▶ Recently, other topics have been considered:
  - **existence** of **real** and **complex** transmission eigenvalues;
  - **localization** of transmission eigenvalues in the complex plane;
  - **Weyl laws** for the transmission eigenvalues;
  - ...

but many questions remain open (see the **recent review** **F. Cakoni, H. Haddar, Transmission Eigenvalues in Inverse Scattering Theory, Inside Out II, 60, MSRI Publi., 527-578, 2012**).

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By the way, why such a detailed study 

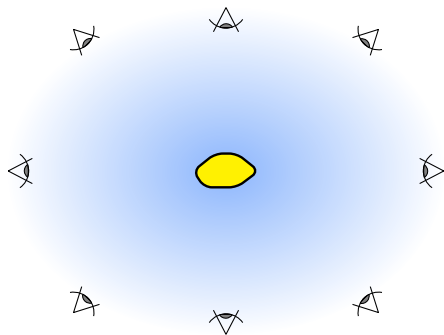
- ▶ Certain reconstruction methods need to avoid transmission eigenvalues.
- ▶ But transmission eigenvalues can also be **determined from measurements** and they carry information about the inclusion properties.  
⇒ *They can be used to find **qualitative properties** of the object.*

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# Problematic

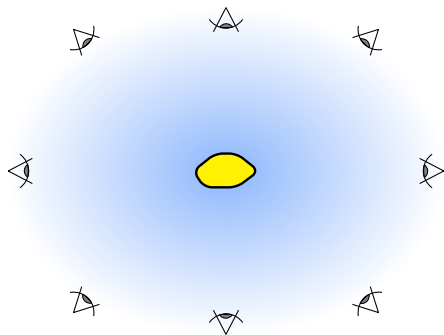
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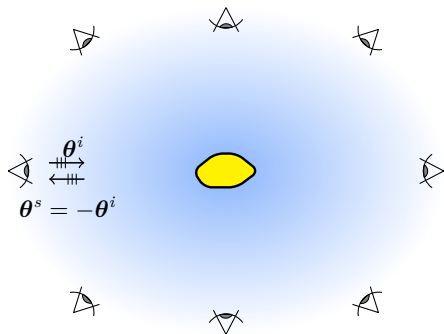
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We assume that we can send plane waves in the directions  $\theta_1, \dots, \theta_N$  of  $\mathbb{S}^1$  and measure the resulted scattered fields in the directions  $-\theta_1, \dots, -\theta_N$ .

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⇒ **Multistatic backscattering measurements**: emitters & receivers coincide.



# Far field pattern

---

- For a given incident direction  $\boldsymbol{\theta}_i$ , the **scattered field**  $u_s(\cdot, \boldsymbol{\theta}_i)$  admits the **asymptotic expansion**

$$u_s(\mathbf{x}, \boldsymbol{\theta}_i) = \frac{e^{ikr}}{\sqrt{r}} \left( u_s^\infty(\boldsymbol{\theta}_s, \boldsymbol{\theta}_i) + O(1/r) \right)$$

as  $r = |\mathbf{x}| \rightarrow +\infty$ , uniformly in  $\boldsymbol{\theta}_s \in \mathbb{S}^1$ .

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**DEFINITION:** The map  $u_s^\infty(\cdot, \cdot) : \mathbb{S}^1 \times \mathbb{S}^1 \rightarrow \mathbb{C}$  is called the **far field pattern**.

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The **far field pattern** is the quantity **one can measure** at infinity (the other terms are too small).

- ▶ **In practice**, the goal of imaging techniques is to find features of the inclusion from the knowledge of  $u_s^\infty(\cdot, \cdot)$  on a **finite subset** of  $\mathbb{S}^1 \times \mathbb{S}^1$ .

# Relative scattering matrix

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► Let  $\boldsymbol{\theta}_1, \dots, \boldsymbol{\theta}_N$  be given directions of  $\mathbb{S}^1$ . We introduce the **relative scattering matrix**  $\mathcal{S}(k) \in \mathbb{C}^{N \times N}$  defined via

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- Unlike in the continuous setting:
- these incident field can be **constructed exactly** (no density argument);
  - the scattered field **does not vanish identically** at infinity.



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- Unlike in the continuous setting, this problem **does not reduce** to a problem set on the (compact) **support of the inclusion**.
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## ► OPEN QUESTIONS:

- How to proceed to prove **discreteness** of transmission eigenvalues for situations other than **multistatic backscattering measurements**?
- Can we **relax** assumptions on  $A$  and  $\rho$ ?
- Can we prove **existence** of transmission eigenvalues in this setting?
- Do transmission eigenvalues in the discrete setting (if they exist) **converge** to the transmission eigenvalues of the continuous framework when the **number of directions tends to  $+\infty$** ?
- ...



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We explain how to construct non trivial inclusions such that  $\mathcal{S}(k) = 0$ . These inclusions cannot be detected from far field measurements.

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FORMULATION OF THE PROBLEM:

Find a real valued function  $\rho \neq 1$ , with  $\rho - 1$  supported in  $\mathcal{D}$ , such that the solution of the problem

$$\left| \begin{array}{l} \text{Find } u = u_s + e^{ik\theta_i \cdot x} \text{ such that} \\ -\Delta u = k^2 \rho u \quad \text{in } \mathbb{R}^2, \\ \lim_{r \rightarrow +\infty} \sqrt{r} \left( \frac{\partial u_s}{\partial r} - ik u_s \right) = 0 \end{array} \right.$$

verifies  $u_s^\infty(\theta_1) = \dots = u_s^\infty(\theta_N) = 0$ .

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## Origin of the method:

- The idea we will use has been introduced in Nazarov 11 to construct waveguides for which there are embedded eigenvalues in the continuous spectrum.
- It has been adapted in Bonnet-Ben Dhia & Nazarov 13 to build invisible perturbations of waveguides (see also Bonnet-Ben Dhia, Nazarov & Taskinen 14 for an application to a water-waves problem).

# General scheme: step 1



When there is **no inclusion**, there is **no scattered field**. Let us look for  $\rho$  as a **perturbation of the reference coefficient**:

$$\rho^\varepsilon = 1 + \varepsilon\mu, \quad \text{with } \mu \text{ compactly supported.}$$

► We denote  $u^\varepsilon$ ,  $u_s^\varepsilon$  the functions satisfying

$$\left| \begin{array}{l} \text{Find } u^\varepsilon = u_s^\varepsilon + e^{ik\theta_1 \cdot x} \text{ such that} \\ -\Delta u^\varepsilon = k^2 \rho^\varepsilon u^\varepsilon \quad \text{in } \mathbb{R}^2, \\ \lim_{r \rightarrow +\infty} \sqrt{r} \left( \frac{\partial u_s^\varepsilon}{\partial r} - ik u_s^\varepsilon \right) = 0 \end{array} \right.$$

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- As  $r \rightarrow +\infty$ , we have  $u_s^\varepsilon(\mathbf{x}) = \frac{e^{ikr}}{\sqrt{r}} \left( u_s^\varepsilon{}^\infty(\theta_s) + O(1/r) \right)$

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$$\text{with } u_s^\varepsilon{}^\infty(\theta_s) = c k^2 \int_{\mathcal{D}} (\rho^\varepsilon - 1) (u_i + u_s^\varepsilon) e^{-ik\theta_s \cdot \mathbf{x}} d\mathbf{x} \quad \left( c = \frac{e^{i\pi/4}}{\sqrt{8\pi k}} \right).$$



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- With this choice, we obtain the **expansion**, for **small**  $\varepsilon$

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## General scheme: step 2

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- In the expression  $\rho^\varepsilon = 1 + \varepsilon\mu$ , we redecompose  $\mu$  as

$$\mu = \mu_0 + \sum_{m=1}^N \tau_{1,m} \mu_{1,m} + \sum_{m=1}^N \tau_{2,m} \mu_{2,m}$$

where  $\tau_{1,m}, \tau_{2,m}$  are real parameters that we will tune  
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We introduce  $2N$  real parameters because we want to cancel  $N$  complex coefficients.

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Why this choice ?

...

## General scheme: step 3

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► ... because then we find

$$u_s^{\varepsilon \infty}(\boldsymbol{\theta}_n) = \varepsilon c k^2 (\tau_{1,n} + i\tau_{2,n}) + \varepsilon^2 c k^2 (F_{1,n}^\varepsilon(\vec{\tau}) + iF_{2,n}^\varepsilon(\vec{\tau})),$$

where  $F_{1,n}^\varepsilon, F_{2,n}^\varepsilon$  are **real-valued** functions depending (**non linearly**) on  $\varepsilon$ ,  
 $\vec{\tau} := (\tau_{1,1}, \dots, \tau_{1,N}, \tau_{2,1}, \dots, \tau_{2,N})^\top$ .

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Use the **term at order  $\varepsilon$**  whose dependence with respect to  $\rho$  is simple to **control** and **cancel** the whole expansion.

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- ▶ Now, we can impose  $u_s^{\varepsilon \infty}(\boldsymbol{\theta}_n) = 0$  solving the **fixed point problem**:

$$\text{Find } \vec{\tau} \in \mathbb{R}^{2N} \text{ such that } \vec{\tau} = F^\varepsilon(\vec{\tau}), \quad (2)$$

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- ▶ We can prove that the map  $F^\varepsilon : \mathbb{R}^{2N} \rightarrow \mathbb{R}^{2N}$  verifies the estimate  $|F^\varepsilon(\vec{\tau}) - F^\varepsilon(\vec{\tau}')| \leq C \varepsilon |\vec{\tau} - \vec{\tau}'|$ . Therefore  $F^\varepsilon$  is a **contraction** for  $\varepsilon$  small enough and (2) has a **unique solution**  $\vec{\tau}^{\text{sol}}$ .

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PROPOSITION: For  $\varepsilon$  small enough, define  $\rho^{\text{sol}} = 1 + \varepsilon\mu^{\text{sol}}$  with

$$\mu^{\text{sol}} = \mu_0 + \sum_{m=1}^N \tau_{1,m}^{\text{sol}} \mu_{1,m} + \sum_{m=1}^N \tau_{2,m}^{\text{sol}} \mu_{2,m}.$$

Then the solution of the scattering problem

$$\left| \begin{array}{l} \text{Find } u^\varepsilon = u_s^\varepsilon + e^{ik\theta_i \cdot x} \text{ such that} \\ -\Delta u = k^2 \rho^{\text{sol}} u \quad \text{in } \mathbb{R}^2, \\ \lim_{r \rightarrow +\infty} \sqrt{r} \left( \frac{\partial u_s}{\partial r} - ik u_s \right) = 0 \end{array} \right.$$

verifies  $u_s^\infty(\theta_1) = \dots = u_s^\infty(\theta_N) = 0$ .

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- $$e_n(\mathbf{x}) = \cos(k(\theta_i - \theta_n) \cdot \mathbf{x}) \quad \text{and} \quad e_{N+n}(\mathbf{x}) = \sin(k(\theta_i - \theta_n) \cdot \mathbf{x}).$$

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- On  $\mathcal{D}$ ,  $\{e_n\}_{n=1}^{2N}$  is linearly independent  $\Rightarrow$  the matrix  $\mathbb{B} \in \mathbb{R}^{2N \times 2N}$  s.t.

$$\mathbb{B}_{mn} = \int_{\mathcal{D}} e_m(\mathbf{x}) e_n(\mathbf{x}) d\mathbf{x}$$

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$$\mu_{1,m} = \sum_{n=1}^{2N} \mathbb{D}_{mn} e_n$$

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where  $\mu_0^\# \notin \text{span}\{\mu_{1,1}, \dots, \mu_{1,N}, \mu_{2,1}, \dots, \mu_{2,N}\}$ .

## Remarks

---

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- The inclusion **can be built** and does not involve singular materials ( $\neq$  cloaking techniques). Moreover,  $\mu^{\text{sol}}$  is just a small perturbation of  $\mu_0$ :

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- The method provides a **numerical algorithm**.
- It is a **proof of existence** of invisible inclusions. This may appear not so surprising since measurements belong to a space of **finite dimension** and  $\rho \in L^\infty(\mathcal{D})$ .

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## The case $\theta_i = \theta_s$

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- In the previous approach, we needed to assume  $\theta_i \neq \theta_n$ ,  $n = 1, \dots, N$ .

$$u_s^{\varepsilon \infty}(\theta_n) = 0 + \varepsilon c k^2 \int_{\mathcal{D}} \mu e^{ik(\theta_i - \theta_n) \cdot x} d\mathbf{x} + O(\varepsilon^2).$$



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- **No solution** if  $\mathcal{D}$  has corners and under certain assumptions on  $\rho$ .
  - Corners always scatter, E. Blåsten, L. Päiväranta, J. Sylvester, 2014
  - Corners and edges always scatter, J. Elschner, G. Hu, 2015
- And if  $\mathcal{D}$  is **smooth**?  $\Rightarrow$  The problem seems open.



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# Data and algorithm

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- ▶ We can solve the fixed point problem using an **iterative procedure**: we set  $\vec{\tau}^0 = (0, \dots, 0)^\top$  then define

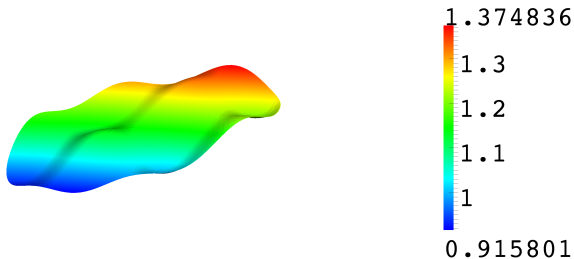
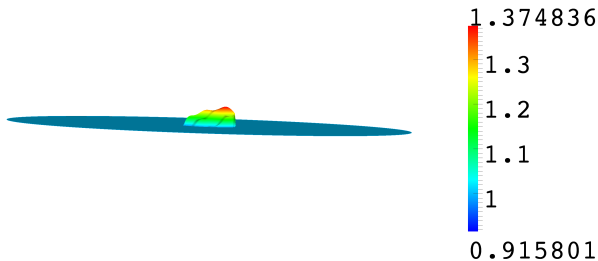
$$\vec{\tau}^{n+1} = F^\varepsilon(\vec{\tau}^n).$$

- ▶ At each step, we solve a scattering problem. We use a **P2 finite element method** set on the ball  $B_8$ . On  $\partial B_8$ , a truncated **Dirichlet-to-Neumann map** with 13 harmonics serves as a **transparent boundary condition**.
- ▶ For the numerical experiments, we take  $\mathcal{D} = B_1$ ,  $M = 3$  (3 directions of observation) and

$$\left| \begin{array}{ll} \theta_i = (\cos(\psi_i), \sin(\psi_i)), & \psi_i = 0^\circ \\ \theta_s^1 = (\cos(\psi_s^1), \sin(\psi_s^1)), & \psi_s^1 = 90^\circ \\ \theta_s^2 = (\cos(\psi_s^2), \sin(\psi_s^2)), & \psi_s^2 = 180^\circ \\ \theta_s^3 = (\cos(\psi_s^3), \sin(\psi_s^3)), & \psi_s^3 = 225^\circ \end{array} \right.$$

# Results: coefficient $\rho$ at the end of the process

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## Results: scattered field

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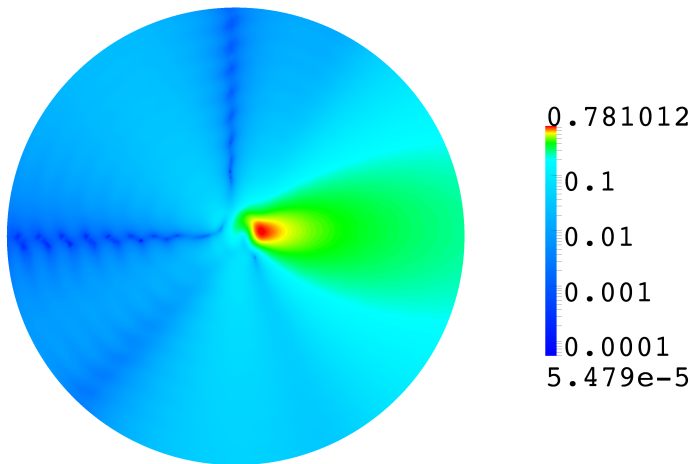


Figure:  $|u_s|$  at the end of the fixed point procedure in **logarithmic scale**. As desired, we see it is **very small** far from  $\mathcal{D}$  in the directions corresponding to the angles  $90^\circ$ ,  $180^\circ$  and  $225^\circ$ . The domain is equal to  $B_8$ .

# Results: far field pattern

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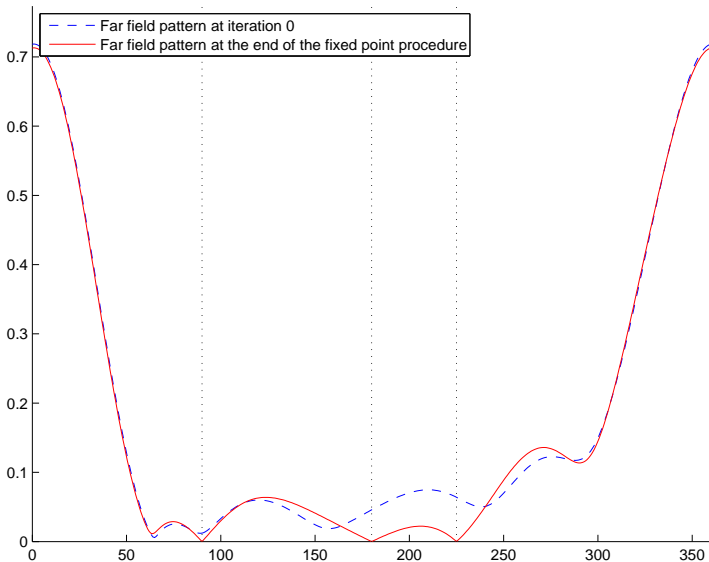


Figure: The dotted lines show the directions where we want  $u_s^\infty$  to vanish.

# Application to EIT

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► In Chesnel, Hyvönen & Staboulis 14, we adapted the approach to build **invisible conductivities** in Electrical Impedance Tomography.



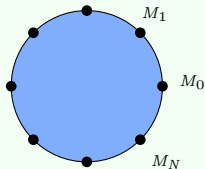
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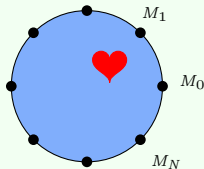
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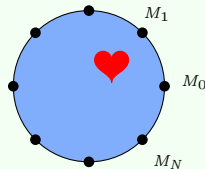
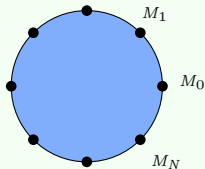
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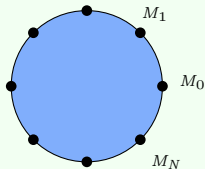
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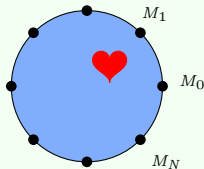
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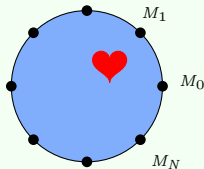
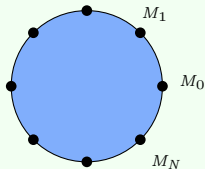


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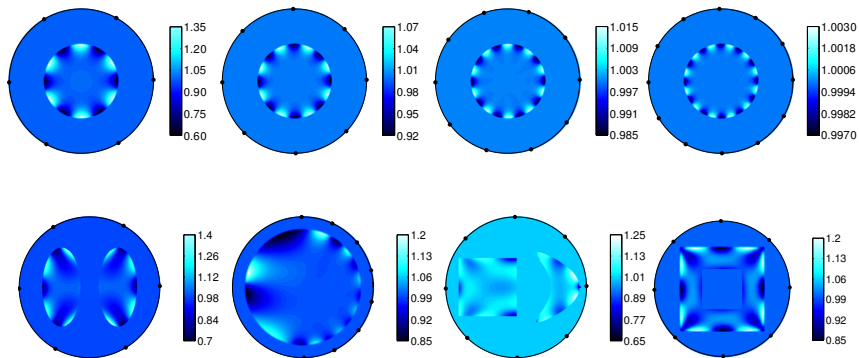
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- Open problem in 3D.

# Numerical results

Examples of conductivities which provide the same measurements as the reference conductivity  $\sigma = 1$ .



► The dots corresponds to the positions of the electrodes.

- 1 Introduction
- 2 The Interior Transmission Eigenvalue Problem (ITEP)
- 3 A discrete interior transmission eigenvalue problem
- 4 Invisible inclusions for a finite number of incident/scattered directions
- 5 Conclusion

## Conclusion

### Interior transmission eigenvalue problem

*For a given obstacle, is there an incident field that does not scatter?*

- ♠ Continuous setting: **non classical spectral problem**.  
⇒ Abundant literature but still many open questions.
- ♠ In practice, **finite number** of emitters/receivers.  
⇒ Many new questions in this context.

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### Invisibility

*For a given frequency, how to build an invisible obstacle?*

- ♠ Continuous setting: **impossible!** The knowledge of the far field operator on  $\mathbb{S}^1 \times \mathbb{S}^1$  **uniquely determine** the parameter of the inclusion (**Sylvester & Uhlmann 87, Bukhgeim 08**).
- ♠ **Finite number** of emitters/receivers: we presented a method.  
⇒ An important issue: can we **reiterate** the process to construct **larger defects** in the reference medium? *Work in progress...*

# Thank you for your attention.

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