# Improved error bounds for quantization based numerical schemes

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(joint work with ABASS SAGNA)

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Conference in honour of Vlad Bally

Le Mans

9 Octobre 2015

#### Rough quantization

### What is Vector Quantization?

- Has its origin in the fields of signal processing in the late 1940's
- Describes the discretization of a random signal and analyses its recovery/reconstruction from the discretized one.



- Examples: Pulse-Code-Modulation (PCM), JPEG-Compression
- Extensive Survey about the IEEE-History: *IEEE on Inf. Theory*, 1982, [Gersho-Gray eds]
- Mathematical Foundation of Quantization Theory: S. Graf & H. Luschgy in *Foundation of quantization of probability measures*, LNM 2000.
- P. : Survey on Optimal Vector Quantization and its applications for numerics, *ESAIM Proc. & Surveys*, CEMRACS'13 course, 2015.

Rough quantization

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$$\widehat{X} = q(X)$$

is called a quantization of X. It aims at being a *discretization* of X  $\triangleright$  Example: if X is [0, 1]-valued, one may choose

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 $\triangleright$  *L*<sup>*p*</sup>-mean quantization error:

$$e_{p,N}(X;q) = \left\|X - q(X)\right\|_p$$

### What is it for? Quantization for Cubature

Let  $\Gamma = \{x_1, \ldots, x_N\}$ . Assume that we have access to the *elementary quantizers*  $x_i$  and the weights

$$w_i(q) := \mathbb{P}(\widehat{X} = x_i), \ i = 1, \dots, N.$$

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 $\implies$  The computation of  $\mathbb{E} F(\hat{X})$  for some a function  $F : \mathbb{R}^d \to \mathbb{R}$  becomes straightforward:

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 $\triangleright$  If F is Lipschitz continuous, a first error estimate reads

$$|\mathbb{E}F(X) - \mathbb{E}F(\widehat{X})| \leq [F]_{\mathsf{Lip}} \mathbb{E}||X - \widehat{X}||.$$

Quantization for Conditional expectation

 $\triangleright$  Applications in Numerical Probability = conditional expectation approximation.

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#### Quantization for Conditional expectation

▷ Applications in Numerical Probability = conditional expectation approximation.

$$\widehat{X} = q_X(X)$$
  $\widehat{Y} = q_Y(Y)$ 

Proposition (Pythagoras' Theorem for conditional expectation)

Let  $P(y, du) = \mathcal{L}(X | Y = y)$  be a regular version of the conditional distribution of X given Y, so that

$$\mathbb{E}(g(X) \mid Y) = Pg(Y) \text{ a.s.}$$

Then

$$\begin{split} \left\| \mathbb{E} \big( g(X) \mid Y \big) - \mathbb{E} \big( g(\widehat{X}) \mid \widehat{Y} \big) \right\|_{2}^{2} &\leq \quad \left[ g \right]_{\text{Lip}}^{2} \left\| X - \widehat{X} \right\|_{2}^{2} + \left\| Pg(Y) - Pg(\widehat{Y}) \right\|_{2}^{2} \\ &\leq \quad \left[ g \right]_{\text{Lip}}^{2} \left\| X - \widehat{X} \right\|_{2}^{2} + \left[ Pg \right]_{\text{Lip}}^{2} \left\| Y - \widehat{Y} \right\|_{2}^{2}. \end{split}$$

### If *P* propagates Lipschitz continuity:

$$[Pg]_{\mathrm{Lip}} \leq [P]_{\mathrm{Lip}}[g]_{\mathrm{Lip}}.$$

then quantization produces a control of the error.

Quantization for Conditional expectation

#### $\triangleright$ Sketch of proof As

$$Pg(Y) - \mathbb{E}(Pg(Y) | \widehat{Y}) \stackrel{L^{2}(\mathbb{P})}{\perp} \sigma(\widehat{Y})$$

so that by Pythagoras' theorem

$$\begin{split} \left\| \mathbb{E}(g(X) \mid Y) - \mathbb{E}(g(\widehat{X}) \mid \widehat{Y}) \right\|_{2}^{2} &= \left\| Pg(Y) - \mathbb{E}(Pg(Y) \mid \widehat{Y}) \right\|_{2}^{2} + \left\| \mathbb{E}(Pg(X) \mid \widehat{Y}) - \mathbb{E}(g(\widehat{X}) \mid \widehat{Y}) \right\|_{2}^{2} \\ &\leq \left\| Pg(Y) - Pg(\widehat{Y}) \right\|_{2}^{2} + \left\| g(X) - g(\widehat{X}) \right\|_{2}^{2} \\ &\leq \left[ Pg \right]_{\text{Lip}}^{2} \left\| Y - \widehat{Y} \right) \right\|_{2}^{2} + \left[ g \right]_{\text{Lip}}^{2} \left\| X - \widehat{X} \right\|_{2}^{2} . \end{split}$$

 $\triangleright$  If  $p \neq 2$ , a Minkowski like control is preserved

$$\begin{split} \left\| \mathbb{E} \big( g(X) \mid Y \big) - \mathbb{E} \big( g(\widehat{X}) \mid \widehat{Y} \big) \right\|_{p} &\leq [g]_{\mathrm{Lip}} \left\| X - \widehat{X} \right\|_{p} + \left\| Pg(Y) - Pg(\widehat{Y}) \right\|_{p} \\ &\leq [g]_{\mathrm{Lip}} \left\| X - \widehat{X} \right\|_{p} + [Pg]_{\mathrm{Lip}} \left\| Y - \widehat{Y} \right\|_{p}. \end{split}$$

### A typical result (BSDE)

▷ We consider a "standard" BSDE:

$$Y_t = h(X_T) + \int_t^T f(s, X_s, Y_s, Z_s) ds - \int_t^T Z_s dW_s, \quad t \in [0, T],$$

where the exogenous process  $(X_t)_{t \in [0,T]}$  is a diffusion

$$X_t = x + \int_0^t b(s, X_s) ds + \int_0^t \sigma(s, X_s) dW_s, \quad x \in \mathbb{R}^d.$$

with b,  $\sigma$ , h Lipschitz continuous in x, f Lipschitz in (x, y, z) uniformly in  $t \in [0, T]$ ...  $\triangleright$  which is the probabilistic representation of the partially non-linear PDE

 $\partial_t u(t,x) + Lu(t,x) + f(t,x,u(t,x),(\partial_x^* u\sigma)(t,x)) = 0 \text{ on } [0,T) \times \mathbb{R}^d, \quad u(T,.) = h$ with  $Lg = (\nabla b|g) + \frac{1}{2} \text{Tr}(\sigma^* D^2 g\sigma).$ 

 $\triangleright$  ... and its time discretization scheme with step  $\Delta_n = \frac{T}{n}$  recursively defined by

$$\begin{split} \bar{Y}_{t_{n}^{n}} &= h(\bar{X}_{t_{n}^{n}}), \\ \bar{Y}_{t_{k}^{n}} &= \mathbb{E}(\bar{Y}_{t_{k+1}^{n}}|\mathcal{F}_{t_{k}^{n}}) + \Delta_{n}f(t_{k}^{n},\bar{X}_{t_{k}^{n}},\mathbb{E}(\bar{Y}_{t_{k+1}^{n}}|\mathcal{F}_{t_{k}^{n}}),\bar{\zeta}_{t_{k}^{n}}), \\ \bar{\zeta}_{t_{k}^{n}} &= \frac{1}{\Delta_{n}}\mathbb{E}(\bar{Y}_{t_{k+1}^{n}}(W_{t_{k+1}^{n}}-W_{t_{k}^{n}})|\mathcal{F}_{t_{k}}) = \frac{1}{\Delta_{n}}\mathbb{E}((\bar{Y}_{t_{k+1}^{n}}-\bar{Y}_{t_{k}^{n}})(W_{t_{k+1}^{n}}-W_{t_{k}^{n}})|\mathcal{F}_{t_{k}}) \end{split}$$

where  $\bar{X}$  is the Euler scheme of X defined by

$$\bar{X}_{t_{k+1}^n} = \bar{X}_{t_k^n} + b({}_k^n, \bar{X}_{t_k^n})\Delta_n + \sigma({}_k^n, \bar{X}_{t_k^n})(W_{t_{k+1}^n} - W_{t_k^n}).$$

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#### Application to BSDE

▷ ... spatially discretized by quantization:

$$\begin{aligned} \widehat{Y}_n &= h(\widehat{X}_n) \\ \widehat{Y}_k &= \widehat{\mathbb{E}}_k(\widehat{Y}_{k+1}) + \Delta_n f_k(\widehat{X}_k, \widehat{\mathbb{E}}_k(\widehat{Y}_{k+1}), \widehat{\zeta}_k) \\ \text{with} & \widehat{\zeta}_k &= \frac{1}{\Delta_n} \widehat{\mathbb{E}}_k(\widehat{Y}_{k+1}(W_{t_{k+1}^n} - W_{t_k^n})) \end{aligned}$$

where  $\widehat{\mathbb{E}}_k = \mathbb{E}(\cdot | \widehat{X}_k)$ .

 $\triangleright$  A Quantization tree:  $N = N_0 + \cdots + N_n$ ,  $N_k$  = size of layer  $t_k^n$ .



#### Application to BSDE

- A quantization tree is not re-combining.
- But its size can designed a priori (and subject to possible optimization).

#### Theorem (A priori error estimates (Sagna-P., 2014), (P.,Wilbertz, 2012))

Suppose that all the "Lipschitz" assumptions on b,  $\sigma$ , f, h are fulfilled. (a) "Price": Then, for every k = 0, ..., n,

$$\left\|\bar{Y}_{t_k^n}-\widehat{Y}_k\right\|_2^2 \leq [f]_{\mathrm{Lip}}^2 \sum_{i=k}^n e^{(1+[f]_{\mathrm{Lip}})t_i^n} \mathcal{K}_i(b,\sigma,T,f,h) \left\|\bar{X}_{t_i^n}-\widehat{X}_{t_i^n}\right\|_2^2 = O\left(\frac{n}{N^{\frac{2}{d}}}\right),$$

(b) "Hedge":

$$\sum_{k=0}^{n-1} \Delta_n \left\| \bar{\zeta}_{t_k^n} - \widehat{\zeta}_k \right\|_2^2 \le \sum_{k=0}^{n-1} e^{(1 + [f]_{\mathrm{Lip}})t_k^n} \left\| Y_{t_{k+1}^n} - \widehat{Y}_{t_{k+1}^n} \right\|_2^2 + \mathcal{K}_k(b, \sigma, T, f, h) \left\| X_{t_k^n} - \widehat{X}_{t_k^n} \right\|_2^2$$

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(c) "RBSDE": The same error bounds hold with Reflected BSDE (so far without Z in f) by replacing h by  $h_k = h(t_k^n, .)$  where  $h(t, X_t)$  is the obstacle process in the resulting quantized scheme.

What is new (compared to Bally-P. 2003 for reflected BSDE)?

- +: Z in f for quantization error bounds.
- +: The square everywhere

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How to reduce the (quadratic) quantization error  $\|X - \widehat{X}\|_2$  ?

or to be more precise

Given a (finite) grid  $\Gamma = \{x_1, x_2, \dots, x_N\} \subset \mathbb{R}^d$ , how to solve

 $\inf_{q:\mathbb{R}^d\to \Gamma} \|X-q(X)\|_2 ?$ 

#### Voronoi Quantization

$$\label{eq:constraint} \begin{split} \triangleright \mbox{ Let } X : (\Omega, \mathcal{S}, \mathbb{P}) \to (\mathbb{R}^d, \mathcal{B}or(\mathbb{R}^d), |.|) \mbox{ be a random vector such that} \\ \mathbb{E}|X|^p < +\infty \qquad \mbox{ for some } p \in (0,\infty). \end{split}$$

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 $\vartriangleright \text{ Given a (finite) "grid" } \Gamma = \{x_1, x_2, \ldots, x_N\} \subset \mathbb{R}^d \text{ and } q: \mathbb{R}^d \to \Gamma$ 

$$\|X - \underbrace{q(X)}_{\in \Gamma}\|_{p} \ge \|\operatorname{dist}(X, \Gamma)\|_{p}.$$

This suggests to discretize of the random vector X using a Nearest Neighbor projection as a quantization function q.

• Let 
$$(C_i(\Gamma))_{1 \le i \le N}$$
 be a (Borel) Voronoi partition of  $\mathbb{R}^d$  generated by  $\Gamma$ , *i.e.* such that  
 $C_i(\Gamma) \subset \Big\{ z \in \mathbb{R}^d : \|z - x_i\| \le \min_{1 \le j \le N} \|z - x_j\| \Big\}.$ 

• Let  $q := \operatorname{Proj}_{\Gamma} : \mathbb{R}^d \to \Gamma$  be the induced Nearest Neighbor projection,

$$\xi\mapsto \sum_{i=1}^N x_i\mathbf{1}_{C_i(\Gamma)}(\xi).$$

Improved error bounds for quantization based numerica

so that

 $\triangleright$  We define the *Voronoi Quantization* of the random vector X as

$$\widehat{X}^{\Gamma} = \operatorname{Proj}_{\Gamma}(X) = \sum_{i=1}^{N} x_i \mathbf{1}_{C_i(\Gamma)}(X).$$

> This is a purely geometric optimization only depending on the norm.

▷ The *L<sup>p</sup>*-mean quantization error induced by a grid  $\Gamma$  ( $p \in (0, +\infty)$ ) induced by a grid  $\Gamma \subset \mathbb{R}^d$  with size  $|\Gamma| \leq N$ ,  $N \in \mathbb{N}$ 

Definition (L<sup>p</sup>-mean quantization error)

$$e_p(X;\Gamma) = \|X - \widehat{X}^{\Gamma}\|_p = \|\operatorname{dist}(X,\Gamma)\|_p = \|\min_{x\in\Gamma} |X - x|\|_p.$$









Optimal L<sup>p</sup>-mean quantization problem

Second idea to minimize the quantization error

Optimally fit the grid  $\Gamma$  to (the distribution of  $\mathbb{P}_{x}$ ) of X for a given "complexity".

▷ It amounts to solve the optimal  $L^p$ -mean quantization problem at level N,  $N \ge 1$ .

Definition (Optimal  $L^{p}$ -mean quantization error at level N)

We define the optimal  $L^{p}$ -mean quantization error at level N as

$$e_{p,N}(X) := \inf \left\{ \left\| \min_{x \in \Gamma} |X - x| \right\|_p : \Gamma \subset \mathbb{R}^d, |\Gamma| \leq N 
ight\}.$$

> One shows the more general optimality result

$$e_{p,N}(X) = \inf \{ \|X - \Xi\|_p : \Xi \in L^p(\mathbb{R}^d), \, |\Xi(\Omega)| \leq N \}.$$

i.e. no possible alternative than quantization

Theorem (Kieffer, Cuesta-Albertos, P., Graf-Luschgy, 1988  $\rightarrow$  2000)

(a) EXISTENCE AN OPTIMAL QUANTIZER: For every level  $N \ge 1$ , there exists (at least) one  $L^{p}$ -optimal quantization grid  $\Gamma^{N,p}$  at level N.

(b) If p = 2, stationarity property/self-consistency:  $\mathbb{E}(X | \widehat{X}^{\Gamma^{N,2}}) = \widehat{X}^{\Gamma^{N,2}}$ .

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One checks that

$$e_{p,N}(X)\downarrow 0$$
 as  $N\to +\infty$ .

Let  $(z_N)_{N>1}$  be an everywhere dense sequence in  $\mathbb{R}^d$ 

$$e_{p,N}(X) \leq e_pig(X,\{z_1,\ldots,z_N\}ig) \downarrow 0 \quad N 
ightarrow +\infty.$$

by the Lebesgue dominated convergence theorem.

 $\triangleright$  But...at which rate ?

### Rates of Optimal Quantization

#### Theorem (Zador's Theorem)

(a) SHARP ASYMPTOTIC (Zador, Kieffer, Bucklew & Wise, Graf & Luschgy (2000)):

Let 
$$X \in L^{p+}(\mathbb{R}^{d})$$
 with distribution  $\mathbb{P}_{X} = \varphi \cdot \lambda^{d} \stackrel{\perp}{+} \nu$ .  
Then  

$$\lim_{N \to \infty} N^{\frac{1}{d}} \cdot e_{p,N}(X) = Q_{p,\|\cdot\|} \cdot \left( \int_{\mathbb{R}^{d}} \|\varphi\|^{d/(d+p)} d\lambda_{d} \right)^{(d+p)/d}$$
where  $Q_{p,\|\cdot\|} = \inf_{N} N^{\frac{1}{d}} \cdot e_{p,N}(U([0,1]^{d}))$ .  
(b) NON-ASYMPTOTIC (Pierce, Luschgy-P. (2006)):  
Let  $p' > p$ . There exists  $C_{p,p',d} \in (0, +\infty)$  such that, for every  $\mathbb{R}^{d}$ -valued X r.v.

$$\forall N \geq 1, \quad e_{p,N}(X) \leq C_{p,p',d} \, \sigma_{p'}(X). \, N^{-\frac{1}{d}}.$$

**Remarks.** •  $\sigma_{p'}(X) := \inf_{a \in \mathbb{R}^d} \|X - a\|_{p'} \le +\infty$  is the  $L^{p'}$ -(pseudo-)standard deviation.

•  $N^{\frac{1}{d}}$  is known as the *curse of dimensionality*.

### Numerical computation of quantizers

 $\triangleright$  (Nearly) optimal grids can be computed by optimization algorithms :

- When d = 1 (or even d = 2): deterministic Newton-Raphson like methods
- In higher dimension (d ≥ 2 or 3), stochastic optimization methods based on a stochastic gradient approach:
  - Competitive Learning Vector Quantization algorithm (CLVQ),
  - (Fixed point) randomized Lloyd's I procedure.

both based on Monte Carlo simulations.

In fact, Optmial quantization appears as

Compressed Monte Carlo method

Optimal quantization Numerical computation of quantizers

On the numerical computation optimal quantizers (p = 2)

Computing optimal grids: the quadratic distorsion (p = 2)

$$D_N(x) := \mathbb{E} \min_{1 \leq i \leq N} \|X - x_i\|^2.$$

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$$\min_{x\in(\mathbb{R}^d)^N}D_N(x)\Longleftrightarrow\min_{|\Gamma|\leq N}e_2(X;\Gamma)$$

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 $\triangleright$  If  $\|\cdot\|$  is the canonical Euclidean norm on  $\mathbb{R}^d$  and x has distincts components

$$\nabla D_N(x) = \frac{1}{2} \left( \mathbb{E} \Big[ (x_i - X) \mathbf{1}_{\{X \in C_i(x)\}} \Big] \right)_{1 \le i \le N}$$

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$$D_N(x) := \mathbb{E} \min_{1 \leq i \leq N} ||X - x_i||^2.$$

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 $\triangleright \text{ The grid } \Gamma^{*,N} = \{x_1^*, \dots x_N^*\} \text{ is } L^2 \text{-optimal iff } x^{*,N} \in \operatorname{argmin} D_N.$ 

Hence

$$\Gamma^{*,N}$$
 is  $L^2$ -optimal  $\iff \nabla D_N \bigl( x^{*,N} \bigr) = 0.$ 

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▷ Connection critical point and stationarity:

$$\nabla D_N(x) = 0 \quad \Longleftrightarrow \quad x_i = \frac{\mathbb{E}\left(X\mathbf{1}_{\{X \in C_i(x)\}}\right)}{\mathbb{P}(X \in C_i(x))}, \ i = 1, \dots, N$$
$$\iff \quad \widehat{X}^x = \mathbb{E}(X \mid \widehat{X}^x)$$

$$\underbrace{d=1}_{k_{i}} \mu = \mathbb{P}_{x}, \ C_{i}(x_{1}, \dots, x_{N}) = [x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}], \ i = 1, \dots, N, .$$
$$x_{i} = \frac{\int_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}} \xi \mathbb{P}_{x}(d\xi)}{\mu([x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}])}, \ i = 1, \dots, N$$

 $\Rightarrow$  Evaluation of Voronoi cells, Gradient and Hessian is simple  $\rightsquigarrow$  Newton-Raphson

 $d \ge 2$ 

Stochastic Gradient Method: CLVQ

- Simulate  $\xi_1, \xi_2, \ldots$  independent copies of X
- Generate step sequence  $\gamma_1, \gamma_2, \dots$ Usually: step  $\gamma_n = \frac{A}{B+n} \searrow 0$  or  $\gamma_n = \eta \approx 0$

• Grid updating 
$$n \mapsto n+1$$
:

*Competition:* select winner index:  $i^* \in \operatorname{argmin}_i |x_i^n - \xi_n|$ 

Learning: 
$$\begin{cases} x_{i^*}^{n+1} := x_{i^*}^n + \gamma_n(x_{i^*}^n - \xi_n) \\ x_j^{n+1} := x_j^n, & \text{for } j \neq i^*. \end{cases}$$

$$\begin{array}{c|c} \underline{d=1} & \mu = \mathbb{P}_{x}, \ C_{i}(x_{1}, \dots, x_{N}) = [x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}], \ i = 1, \dots, N, \\ \\ & x_{i} = \frac{\int_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}} \xi \mathbb{P}_{x}(d\xi)}{\mu([x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}]}, \ i = 1, \dots, N \end{array}$$

 $\Rightarrow$  Evaluation of Voronoi cells, Gradient and Hessian is simple  $\rightsquigarrow$  Newton-Raphson

 $d \ge 2$ 

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LLOYD's algorithm as a randomized fixed-point procedure.

• Initial grid 
$$\Gamma^{(0)} = \{x_1^0, \dots, x_N^N\}$$
  
• Grid updating  $n \mapsto n + 1$ :  
(i)  $x_k^{(n+1)} = \mathbb{E}(X | \widehat{X}^{\Gamma^{(n)}} = x_k^{(n)})$   
(ii)  $\Gamma^{(n+1)} = \{x_k^{(n+1)}, k = 1 : N\}$  and  $\widehat{X}^{\Gamma^{(n+1)}} = \operatorname{Proj}_{\Gamma^{(n+1)}}(X)$ ,  
• so that  $\|X - \widehat{X}^{\Gamma^{(n+1)}}\|_2 \le \|X - \widehat{X}^{\Gamma^{(n)}}\|_2$ 

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Gilles F

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"Batch" approach [...]



Figure: Two *N*-quantizers related to  $\mathcal{N}(0; I_2)$  of size N = 500...

(with J. Printems)

Before...



Figure: A Quantizer for  $\mathcal{N}(0, l_2)$  of size N = 500 in  $(\mathbb{R}^2, \|\cdot\|_2)$ .

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Figure: An *N*-quantization of  $X \sim \mathcal{N}(0; I_2)$  with coloured weights:  $\mathbb{P}(X \in C_a(\Gamma))$ ,  $a \in \Gamma$ . (with J.Printems)  $\triangleright$  Weights:  $\mathbb{P}(X \in C_a(\Gamma)) \approx C^{st} \frac{f_X^{\frac{d}{d+2}}(a)}{N^{\frac{1}{d}}}$  (when *N* is large).  $\triangleright$  Local inertia:  $a \mapsto \mathbb{E}|X - a|^2 \mathbf{1}_{\{X \in C_a(\Gamma)\}} \approx \frac{e_n(\Gamma, X)}{N}$  (for fixed *N*).

#### As a result for Gaussian vectors...

 $\triangleright$  Instant search for the unique optimal quantizer using a Newton-Raphson descent on  $\mathbb{R}^N$  ... with an arbitrary accuracy.

 $\triangleright$  For  $\mathcal{N}(0;1)$  and  $N = 1, \dots, 500$ , tabulation within  $10^{-14}$  accuracy of optimal *N*-quantizers and textcolorbluecompanion parameters:

$$\boldsymbol{\alpha}^{(N)} = (\boldsymbol{\alpha}_1^{(N)}, \ldots, \boldsymbol{\alpha}_N^{(N)})$$

and

$$\mathbb{P}(X \in \mathit{C}_i(\boldsymbol{\alpha}^{(N)})), \; i = 1, \ldots N, \qquad \mathsf{and} \qquad \|X - \widehat{X}^{\boldsymbol{\alpha}^{(N)}}\|_2.$$

▷ For d = 1 up to 10? Also available for Gaussian  $\mathcal{N}(0, I_d)$   $(1 \le N \le 4000)$ .

Download at our WEBSITE :

www.quantize.maths-fi.com

#### Further Error Estimates

#### Proposition (First order)

If  $\Gamma^{N,*}$  is  $L^1\text{-optimal}$  at level  $N\geq 1$ 

$$e_{1,N}(X) = \mathbb{E} \| X - \widehat{X}^{\Gamma^{N,*}} \| = \sup_{[F]_{Lip} \leq 1} \| \mathbb{E}F(X) - \mathbb{E}F(\widehat{X}^{\Gamma^{N,*}})$$
$$\inf \Big\{ \sup_{[F]_{Lip} \leq 1} \| \mathbb{E}F(X) - \mathbb{E}F(Y) \|, \operatorname{card}(Y(\Omega)) \leq N \Big\}$$

=  $L^1$ -Wasserstein distance between  $\mathcal{L}(X)$  and the set  $\mathcal{P}_N$ .

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#### Proposition (Second order)

If  $F \in C^1_{Lip}$  and the grid  $\Gamma$  is stationary (e.g. because it is  $L^2$ -optimal), i.e.

$$\widehat{X}^{\mathsf{\Gamma}} = \mathbb{E}(X|\widehat{X}^{\mathsf{\Gamma}}),$$

then a Taylor expansion yields

$$\begin{aligned} |\mathbb{E} F(X) - \mathbb{E} F(\widehat{X}^{\Gamma})| &= |\mathbb{E} F(X) - \mathbb{E} F(\widehat{X}^{\Gamma}) - \mathbb{E} DF(\widehat{X}^{\Gamma}).(X - \widehat{X}^{\Gamma})| \\ &\leq [DF]_{Lip} \cdot \mathbb{E} ||X - \widehat{X}^{\Gamma}||^{2} = e_{2,N}(X)^{2}. \end{aligned}$$

 $\vartriangleright$  Furthermore, if F is convex, then Jensen's inequality implies for stationary  $\Gamma$ 

 $\mathbb{E} F(\widehat{X}^{\Gamma}) \leq \mathbb{E} F(X).$ 

### **Further Applications**

#### What are these applications using optimal quantization grids?

• Obstacle Problems: Valuation of Bermuda and American options, Reflected BSDE's [Bally-P.-Printems '01, '03 and '05, Illand '11].

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- Quadratic BSDE schemes by Markovian Quantization [Chassagneux-Richou'14].
- New error bounds for *BSDE* schemes by quadratic optimal quantization [P.-Sagna '15]

A new result : distortion mismatch /  $L^s$ -rate optimality, s > p

▷ Let  $\Gamma_N^{(p)}$ ,  $N \ge 1$ , be a sequence  $L^p$ -optimal grids.

What about  $e_s(X, \Gamma_N^p)$  ( $L^s$ -mean quantization error) when  $X \in L^s_{\mathbb{R}^d}(\mathbb{P})$  for s > p?

Theorem (L<sup>p</sup>-L<sup>s</sup>-distortion mismatch, Graf-Luschgy-P. 2005, Luschgy-P. 2015)

(a) Let  $X \in L^p_{\mathbb{R}^d}(\mathbb{P})$  and let  $(\Gamma_N^{(p)})_{N \ge 1}$  be an  $L^p$ -optimal sequence for grids. Let  $s \in (p, p + d)$ . If

$$X \in L^{rac{sd}{d+p-s}+\delta}(\mathbb{P}), \ \delta > 0,$$

(note that  $\frac{sd}{d+p-s} > s$  and  $\lim_{s \to p+d} \frac{sd}{d+p-s} = +\infty$ ), then

 $\overline{\lim_{N}} N^{\frac{1}{d}} e_{s}(\Gamma_{N}^{(p)}, X) < +\infty.$ 

(b) If  $\mathbb{P}_X = f(|x|) \cdot \lambda_d(d\xi)$  (radial density) then  $\delta = 0$  is admissible.

(c) If  $\mathbb{E} |X|^{\frac{sd}{d+p-s}} = +\infty$ , then  $\underline{\lim}_N N^{\frac{1}{d}} e_s(\Gamma_N^{(p)}, X) = +\infty$ .

 $\triangleright$  Possible perspectives: error bounds for quantization based numerical schemes for *BSDE* with a quadratic Z term ?

▷ So far, an application to quantized non-linear filtering.

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#### Applications Distortion mismatch

### Application to non-linear filtering

- Signal process  $(X_k)_{k\geq 0}$  is an  $\mathbb{R}^d$ -valued Markov chain.
- The observation process  $(Y_k)_{k\geq 0}$  is a sequence of  $\mathbb{R}^q$ -valued random vectors such that

 $(X_k, Y_k)_{k\geq 0}$  is a Markov chain.

• The conditional distribution

$$\mathcal{L}(Y_k | X_{k-1}, Y_{k-1}, X_k) = g_k(X_{k-1}, Y_{k-1}, X_k, y)\lambda_q(dy)$$

• Aim : compute

$$\Pi_{y_{0:n},n}(dx) = \mathbb{P}(X_k \in dx \mid Y_1 = y_1, \cdots, Y_n = y_n)$$

• Kallianpur-Streibel formula: set  $y = y_{0:n} = (y_0, \dots, y_n)$  a vector of observations

$$\Pi_{y,n}(dx) = \Pi_{y,n}f = \frac{\pi_{y,n}f}{\pi_{y,n}\mathbf{1}}$$

with the normalized filter  $\pi_{y_{0,n},n}$  defined by

$$\pi_{y_{0:n},n}f = \mathbb{E}(f(X_n)L_{y_{0:n},n})$$
 with  $L_{y_{0:n},n} = \prod_{k=1}^n g_k(X_{k-1}, y_{k-1}, X_k, y_k),$ 

solution to both a forward and a backward inductionsbased on the kernels

$$H_{y,k}h(x) = \mathbb{E}(h(X_k)g_k(x, y_{k-1}, X_k, y_k)|X_{k-1} = x), \quad H_{y,0}f(x) = \mathbb{E}(f(X_0)),$$

• Forward: Start from

$$\pi_{y,0} = H_{y,0}$$

and define by a forward induction

$$\pi_{y,k}f = \pi_{y,k-1}H_{y,k}f, \qquad k = 1,\ldots,n.$$

• Backward: We define by a backward induction

$$u_{y,n}(f)(x) = f(x), u_{y,k-1}(f) = H_{y,k}u_{y,k}(f), \quad k = 0, \dots, n.$$

so that

$$\pi_{y,n}f=u_{y,-1}(f)$$

This formulation is useful in order to establish the quantization error bound.

Quantized Kallianpur-Streibel formula (P.-Pham (2005))

• Quantization of the kernel:

$$H_{y_{0:n},k}f(x) \longrightarrow \widehat{H}_{y_{0:n},k}f(x) = \mathbb{E}(f(\widehat{X}_k)g_k(x, y_{k-1}, \widehat{X}_k, y_k)|\widehat{X}_{k-1} = x)$$

• Forward quantized dynamics (I):

$$\widehat{\pi}_{y,k}f = \widehat{\pi}_{y,k-1}\widehat{H}_{y,k}f, \qquad k = 1, \ldots, n.$$

• Forward quantized dynamics (II):

$$\widehat{\Pi}_{y}(dx) = \widehat{\Pi}_{y,n}f = \frac{\widehat{\pi}_{y,n}f}{\pi_{y_{0:n},n}\mathbf{1}}$$

(finitely supported unnormalized filter satisfies formally the same recursions)

• Weight computation: If  $\widehat{X}_n = \widehat{X}_n^{\Gamma_n}$ ,  $\Gamma_n = \{x_1^1, \dots, x_{N_n}^n\}$  then

$$\widehat{\Pi}_{y,n}(dx) = \sum_{i=1}^{N_n} \widehat{\Pi}_{y,n}^i \delta_{x_i^n} \quad \text{ with } \widehat{\Pi}_{y,n}^i = \widehat{\Pi}_{y,n} \big( \mathbf{1}_{C_i(\Gamma_n)} \big).$$

### From Lip to $\theta$ -Liploc assumptions

• Standard  $\mathcal{H}_{\text{Lip}}$  assumption for the conditional densities  $g_k(., y, ., y')$ : bounded by  $K_g$  and Lipschitz continuity.

$$|g_k(x,y,x',y') - g_k(\widehat{x},y,\widehat{x}',y')| \leq [g_k]_{\mathrm{Lip}}(y,y') (|x - \widehat{x}| + |x' - \widehat{x}'|).$$

• The kernels  $P_k(x, d\xi) = \mathbb{P}(X_k \in d\xi | X_{k-1} = x)$  propagate Lipschitz continuity with coefficient  $[P_k]_{\text{Lip}s}$  such that

$$\max_{k=1,\ldots,n} [P_k]_{\rm Lip} < +\infty$$

Aim: Switch to a  $\theta$ -local Lipschitz assumption ( $\theta : \mathbb{R}^d \to \mathbb{R}_+, \uparrow +\infty$  as  $|x| \uparrow +\infty$ ).

$$|h(x,x') - h(\hat{x},\hat{x}')| \leq [h]_{\text{loc}} \big(|x-\hat{x}| + |x'-\hat{x}'|\big) \big(1 + \theta(x) + \theta(x') + \theta(\hat{x}) + \theta(\hat{x}')\big)$$

• New  $(\mathcal{H}^{\theta}_{\text{Liploc}})$  assumption: the functions  $g_k$  are still bounded by  $K_g$  and  $\theta$ -local Lipschitz continuous

 $|g_k(x,y,x',y') - g_k(\widehat{x},y,\widehat{x}',y')| \leq [g_k]_{\mathrm{loc}}(y,y') \big(|x - \widehat{x}| + |x' - \widehat{x}'|\big) \big(1 + \theta(x) + \theta(x') + \theta(\widehat{x}) + \theta(\widehat{x}')\big)$ 

- The kernels P<sub>k</sub>(x, dξ) = P(X<sub>k</sub> ∈ dξ | X<sub>k-1</sub> = x) propagate θ-local Lipschitz continuity with coefficient [P<sub>k</sub>]<sub>loc</sub> < +∞.</li>
- The kernels  $P_k(x, d\xi)$  propagate  $\theta$ -control:  $\max_{0 \le k \le n-1} P_k(\theta)(x) \le C(1 + \theta(x))$ .

Typical example:  $X_k = \bar{X}_{t_k^n}^n$  (Euler scheme with step  $\Delta_n = \frac{\tau}{n}$ ),  $\theta(\xi) = |\xi|^{\alpha}$ ,  $\alpha > 0$ .

#### Theorem

Let  $s \in (1, 1 + \frac{d}{2})$  and  $\theta(x) = |x|^{\alpha}$ ,  $\alpha \in (0, \frac{1}{\frac{1}{s-1} - \frac{2}{d}})$ . Assume  $(X_k)$  and  $(g_k)$  satisfy  $(\mathcal{H}^{\theta}_{\text{Liploc}})$  (in particular  $(X_k)$  propagates  $\theta$ -Lipschitz continuity) and assume  $X_k \in L^{\frac{2ds}{d+2-2s}}$ ,  $k = 0, \ldots, n$ . Then

$$|\Pi_{y,n}f - \widehat{\Pi}_{y,n}f|^2 \leq \frac{2(K_g^n)^2}{\phi_n^2(y) \vee \widehat{\phi}_n^2(y)} \sum_{k=0}^n B_k^n(f,y) \times \underbrace{\|X_k - \widehat{X}_k\|_{2s}^2}_{\approx \|X_k - \widehat{X}_k\|_2^2 \leq c_k N_k^{-\frac{2}{d}} (Mismatch!!)}$$
(1)

with

$$\phi_n(y) = \pi_{y,n} \mathbf{1} \quad and \quad \widehat{\phi}_n(y) = \widehat{\pi}_{y,n} \mathbf{1},$$
$$B_k^n(f,y) := 2[P]_{\text{loc}}^{2(n-k)}[f]_{\text{loc}}^2 + 2\|f\|_{\infty}^2 R_{n,k} + \|f\|_{\infty} R_{n,k}^2,$$

where

$${\sf R}_{n,k} = rac{8^{rac{s}{s-1}}M_s^n}{{\cal K}_g^2} \Big[ [g_{k+1}]_{
m loc}^2 + [g_k]_{
m loc}^2 + \Big(\sum_{m=1}^{n-k} [P]_{
m loc}^{m-1} (1+[P]_{
m loc}) [g_{k+m}]_{
m loc} \Big)^2 \Big],$$

and

$$M_{s}^{n} := 2 \max_{k=0,\ldots,n} \left( \mathbb{E} \left( \theta(X_{k})^{\frac{2s}{s-1}} \right) + \mathbb{E} \left( \theta(\widehat{X}_{k})^{\frac{2s}{s-1}} \right) \right)$$

• Greedy quantization (Luschgy-P., JAT, 2014): sequence  $(a_N)_{N\geq 1}$  such that

 $\{a_1, \ldots, a_N\}, N \ge 1, \text{ is } L^p\text{-rate optimal}$ 

to spare RAM.

$$a_{N+1} = \operatorname{argmin}_{\xi \in \mathbb{R}^d} e_p(\{a_1, \ldots, a_N\} \cup \{\xi\}, X)$$

Numerical schemes can be successfully implemented with this quantization.

• Fast recursive quantization (in progress) in medium dimension (Sagna-P. , 2014)

#### Numerical illustrations

• Risk-neutral price under historical probability (B&S model, Euler scheme)

$$dY_t = \left(rY_t + \frac{\mu - r}{\sigma}Z\right)dt + Z_t dW_t$$

with

$$Y_{\tau}=h(X_{\tau})=(X_{\tau}-K)_+.$$

- $\triangleright$  Model parameters: r = 0.1; T = 0.1;  $\sigma = 0.25$ ;  $S_0 = K = 100$ .
- $\triangleright$  Quantization tree calibration: 7.5 10<sup>5</sup> *MC* and *NbLloyd* = 1.
- $\triangleright$  Reference call<sub>BS</sub>(K, T) = 3.66, Z<sub>0</sub> = 14.148. If  $\mu \in \{0.05, 0.1, 0.15, 0.2\}$ ,
  - n = 10 and  $N_k = \overline{N} = 20$ : Q-price = 3.65,  $\widehat{Z}_0 = 14.06$ .
  - n = 10 and  $N_k = \bar{N} = 40$ , Q-price = 3.66,  $\hat{Z}_0 = 14.08$ .
- ▷ Computation time :
- 5 seconds for one contract.
- Additional contracts for free (more than  $10^5/s$ ).

 $\triangleright$  Romberg extrapolation price = 2 \* Q-price(N<sub>2</sub>)-Q-price(N<sub>1</sub>) does improve the price (and the "hedge").

#### Numerical illustrations

• Bid-ask spreads on interest rates :

$$dY_t = \left(rY_t + \frac{\mu - r}{\sigma}Z_t + (R - r)\min\left(Y_t - \frac{Z_t}{\sigma}, 0\right)\right)dt + Z_t dW_t$$

with

$$Y_{\tau} = h(X_{\tau}) = (X_{\tau} - K_1)_+ - 2(X_{\tau} - K_2)_+, \quad K_1 = 95, \ K_2 = 105.$$
$$\mu = 0.05, r = 0.01, \ \sigma = 0.2, \ T = 0.25, \ R = 0.06$$

 $\triangleright$  Reference price = 2.978,  $\widehat{Z}_0 = 0.553$ .

 $\triangleright$  Quantized prices:

- n = 10 and  $N_k = \bar{N} = 20$ : *Q*-price = 2.96,  $\hat{Z}_0 = 0.515$ .
- n = 10 and  $N_k = \overline{N} = 40$ , Q-price = 2.97,  $\widehat{Z}_0 = 0.531$ .

▷ Romberg extrapolation price = 2 \* Q-price( $N_2$ )-Q-price( $N_1$ ) $\approx 2.98$ and Romberg  $\hat{Z}_0 \approx 0.547$ .

Comparable results though slightly less precise, due to the non linearity in Z compensated by the difference of convex functions....

 $\triangleright$  Due to J.-F. Chassagneux: W d-dimensional B.M.

 $dX_t = dW_t, \qquad -dY_t = f(t, Y_t, Z_t)dt - Z_t \cdot dW_t$ 

with  $f(t, y, z) = (z_1 + \ldots + z_d)(y - \frac{2+d}{2d})$ .  $\triangleright$  Solution :

$$Y_t = \frac{e_t}{1+e_t}, \qquad Z_t = \frac{e_t}{(1+e_t)^2} \text{ with } e_t = \exp(x_1 + \ldots + x_d + t).$$

We set t = 0.5, d = 2, 3, so that  $Y_0 = 0.5$  and  $Z_0^i = 0.24$ , for every i = 1, ..., d.



Figure: Convergence rate of the quantization error for the multidimensional example). Abscissa axis: the size N = 5, ..., 100 of the quantization. Ordinate axis: The error  $|Y_0 - \hat{Y}_0^N|$  and the graph  $N \mapsto \hat{a}/N + \hat{b}$ , where  $\hat{a}$  and  $\hat{b}$  are the regression coefficients. d = 3.

## Bon, Vlad on s'y remet quand?

# Faut profiter tant qu'on est jeunes !!