

Advanced Optimization

Lectures/Exercises 3 and 4: (Evolutionary) Multiobjective Optimimmization

December 4, 2018 and December 11, 2018

Master AIC

Université Paris-Saclay, Orsay, France

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INRIA Saclay – Ile-de-France



Dimo Brockhoff
INRIA Saclay – Ile-de-France

Course Overview

	Date		Topic
1	Tue, 20.11.2018	Dimo	Randomized Algorithms for Discrete Problems
2	Tue, 27.11.2018	Dimo	Exercise: The Travelling Salesperson Problem
3	Tue, 4.12.2018	Dimo	Evolutionary Multiobjective Optimization I
4	Tue, 11.12.2018	Dimo	Evolutionary Multiobjective Optimization II
	vacation		
5	Tue, 8.1.2019	Dimo	Looking at Data
6	Tue, 15.1.2019	Anne	Continuous Optimization I
7	Tue, 29.1.2019	Anne	Continuous Optimization II
	Tue, 12.2.2019		oral presentations (individual time slots)

all lectures from 14h00 till 17h15

here in E107 in Nov/Dec and in E105 in January

Organization Oral Exams

Tuesday, Feb 12, 2019		
9:30am	Martin	
10am	Robin	
10:30am	Hao	
11am	Malik	
11:30am	Jiaxin	
12am	Samuel	
12:30pm	Nouredine	
1:30pm	Mirwaisse	
2:00pm		
2:30pm	Alexandre	
3pm	Luc	
3:30pm		
4pm		

to be assigned: Antoine, David, Cedric, Luca

Overview of the Next Two Lectures

Introduction to multiobjective optimization

(a bit more detailed than in the introductory lecture)

- difference to single-objective optimization, the basics
- algorithms and their design principles
- performance assessment and benchmarking
- integration of preferences
- a few aspects of visualization

Exercise around COCO

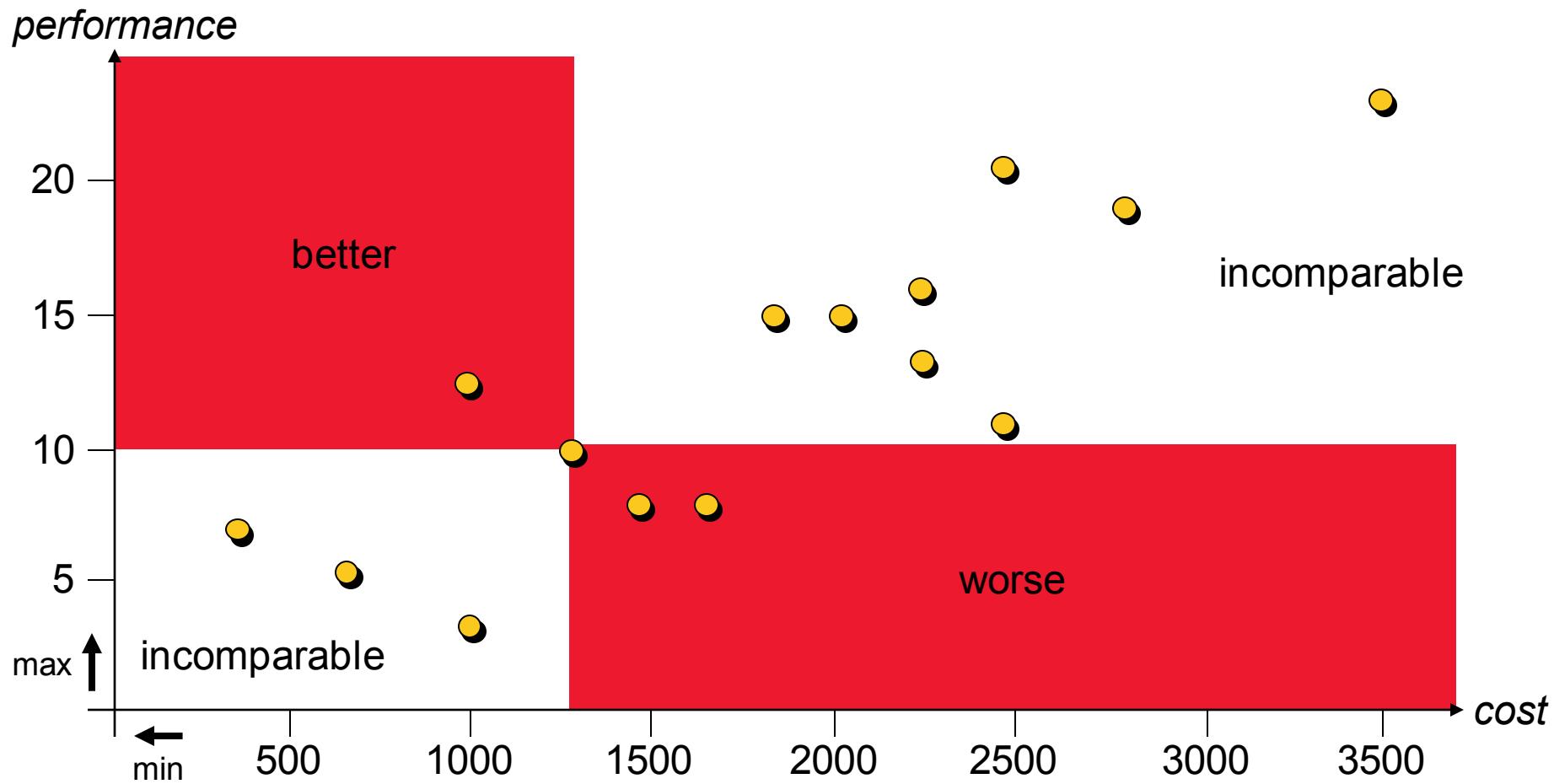
- implement basic algorithm(s)
- benchmark on COCO
 - two goals: testing our software and producing data for the upcoming BBOB-2019 workshop

Multiobjective Optimization

A Brief Introduction to Multiobjective Optimization

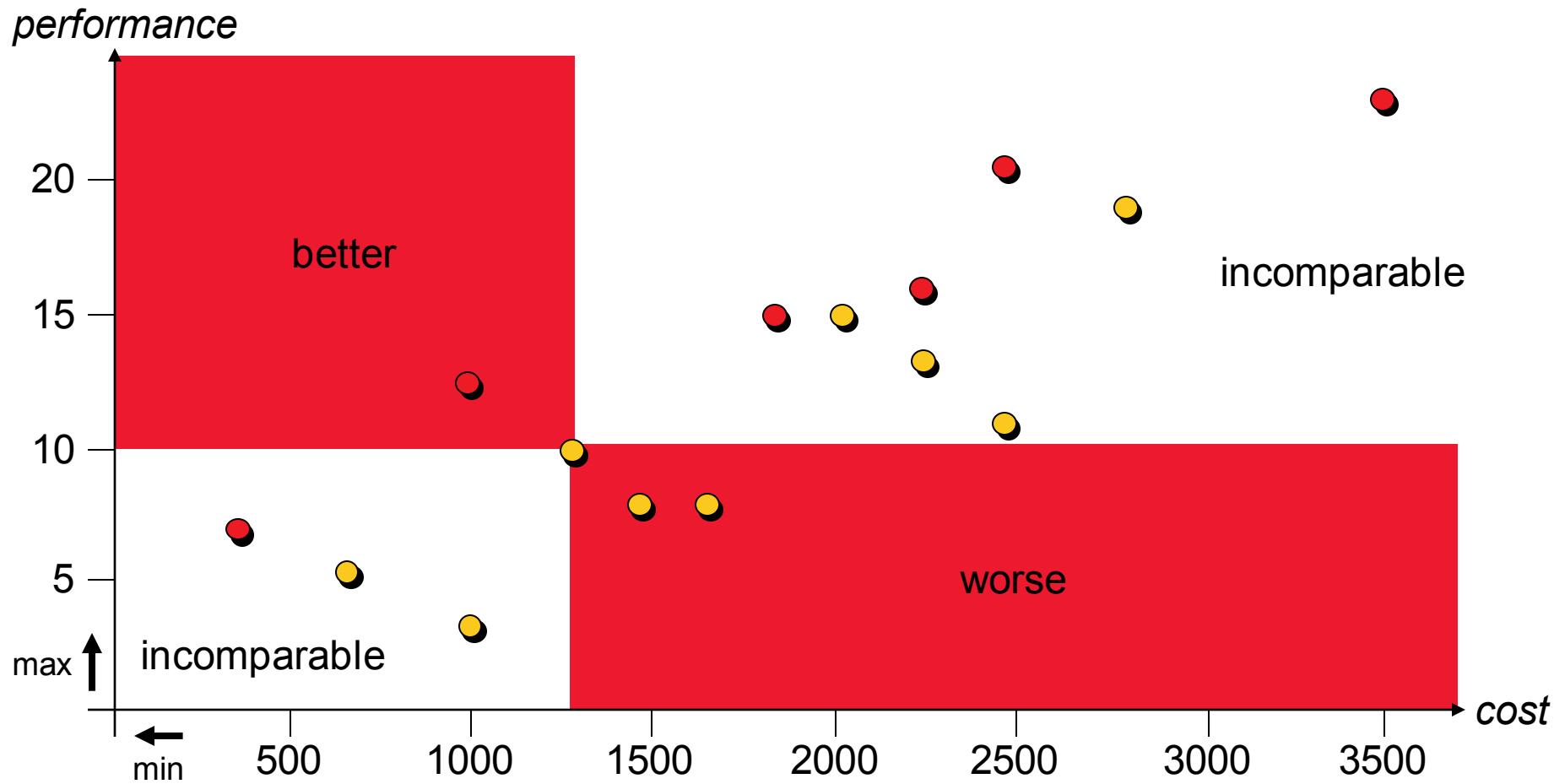
Multiobjective Optimization

Multiple objectives that have to be optimized simultaneously



A Brief Introduction to Multiobjective Optimization

Observations: ① there is no single optimal solution, but
② some solutions (●) are better than others (○)

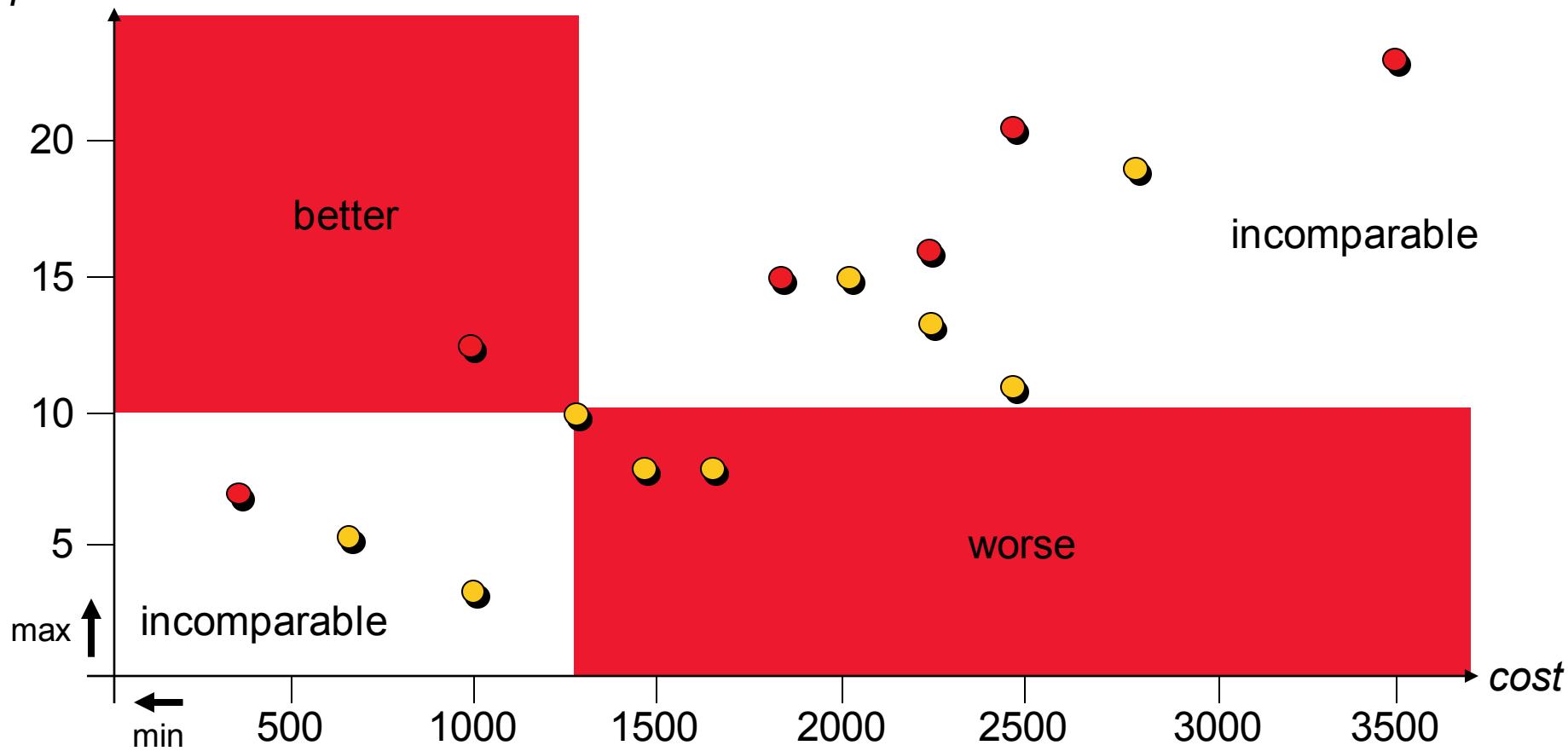


A Brief Introduction to Multiobjective Optimization

u weakly Pareto dominates v ($u \leqslant_{par} v$): $\forall 1 \leq i \leq k : f_i(u) \leq f_i(v)$

u Pareto dominates v ($u <_{par} v$): $u \leqslant_{par} v \wedge v \not\leqslant_{par} u$

performance

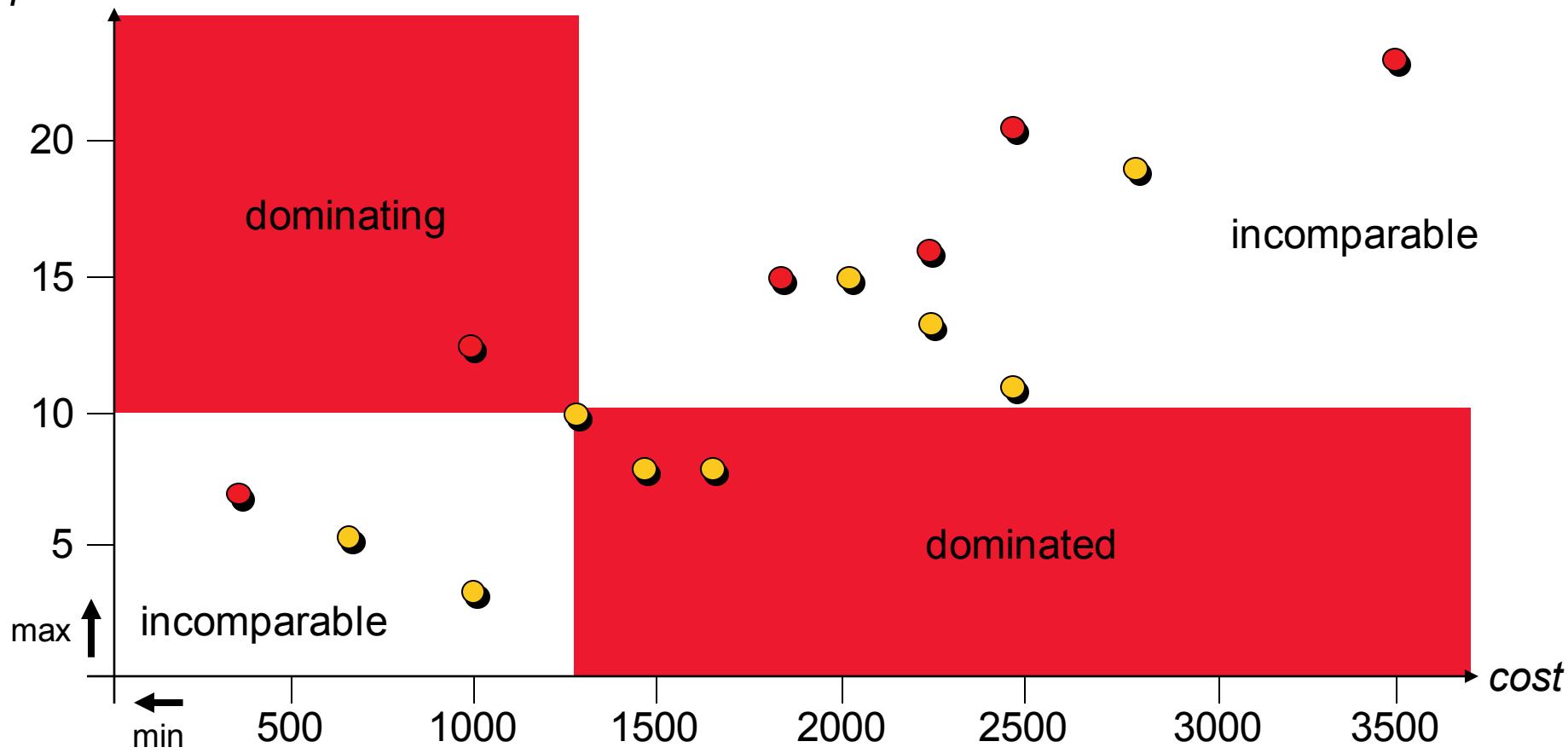


A Brief Introduction to Multiobjective Optimization

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u Pareto dominates v ($u <_{par} v$): $u \leqslant_{par} v \wedge v \not\leqslant_{par} u$

performance



Exercise 1

Show the equivalence between

$$u <_{par} v : \quad u \leq_{par} v \wedge v \not\leq_{par} u$$

and

$$\forall 1 \leq i \leq k: f_i(u) \leq f_i(v) \text{ and } \exists 1 \leq j \leq k: f_j(u) < f_j(v)$$

Exercise 1: Solution

Proof:

$$\begin{aligned} u <_{par} v &: \quad u \leq_{par} v \wedge v \not\leq_{par} u \\ \Leftrightarrow \forall 1 \leq i \leq k: f_i(u) &\leq f_i(v) \text{ and not } (\forall 1 \leq i \leq k: f_i(v) \leq f_i(u)) \\ \Leftrightarrow \forall 1 \leq i \leq k: f_i(u) &\leq f_i(v) \text{ and not } (\forall 1 \leq i \leq k: f_i(u) \geq f_i(v)) \\ \forall 1 \leq i \leq k: f_i(u) &\leq f_i(v) \text{ and } \exists 1 \leq j \leq k: f_j(u) < f_j(v) \end{aligned}$$

Exercise 2: Understanding Pareto Dominance

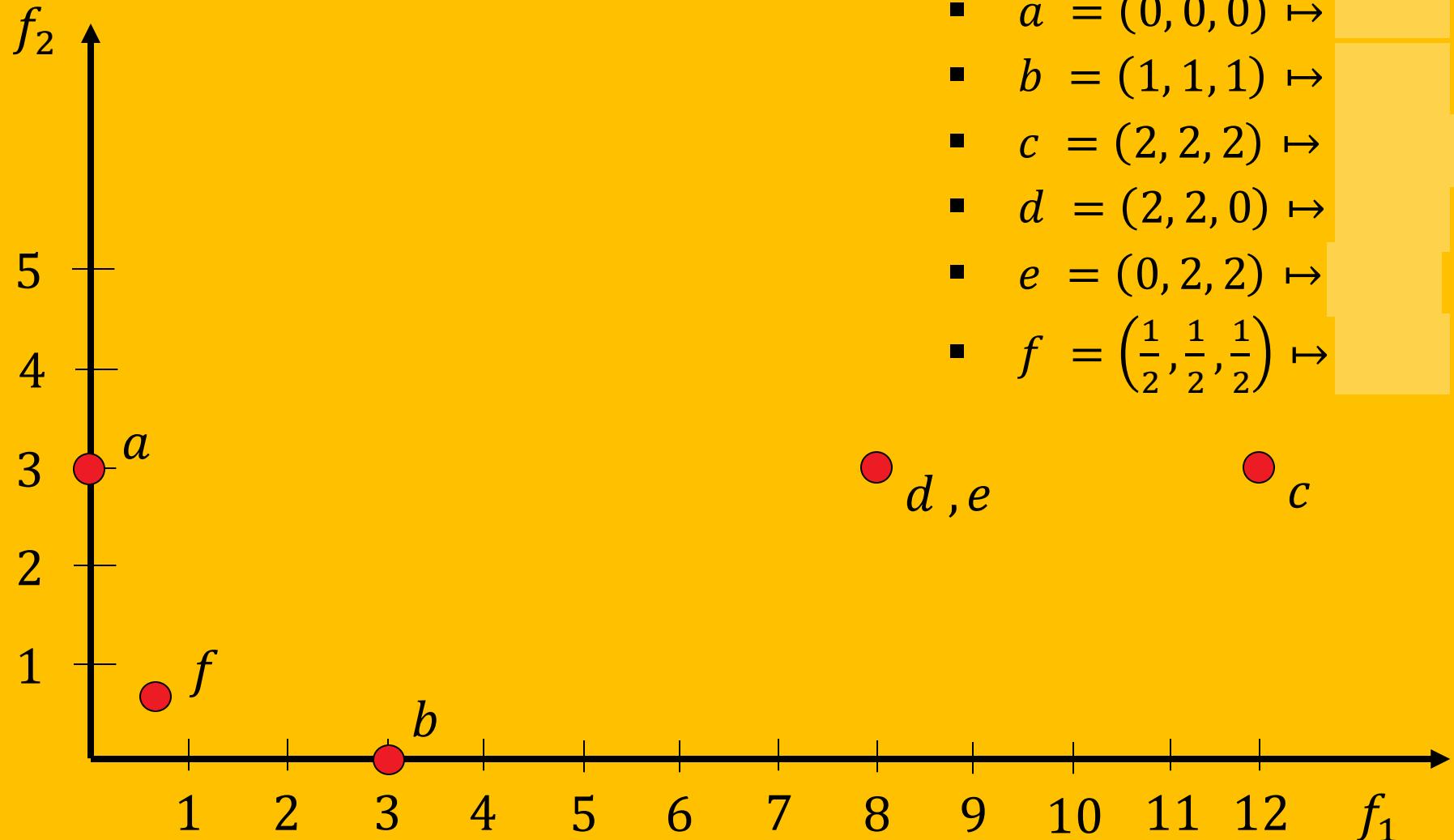
Given the following solutions, tell which ones dominate each other and which don't for the double sphere (minimization) problem

$$f_{\text{doublesphere}}: x \mapsto (\sum_{i=1}^n x_i^2, \sum_{i=1}^n (x_i - 1)^2).$$

- $a = (0, 0, 0)$
- $b = (1, 1, 1)$
- $c = (2, 2, 2)$
- $d = (2, 2, 0)$
- $e = (0, 2, 2)$
- $f = \left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right)$

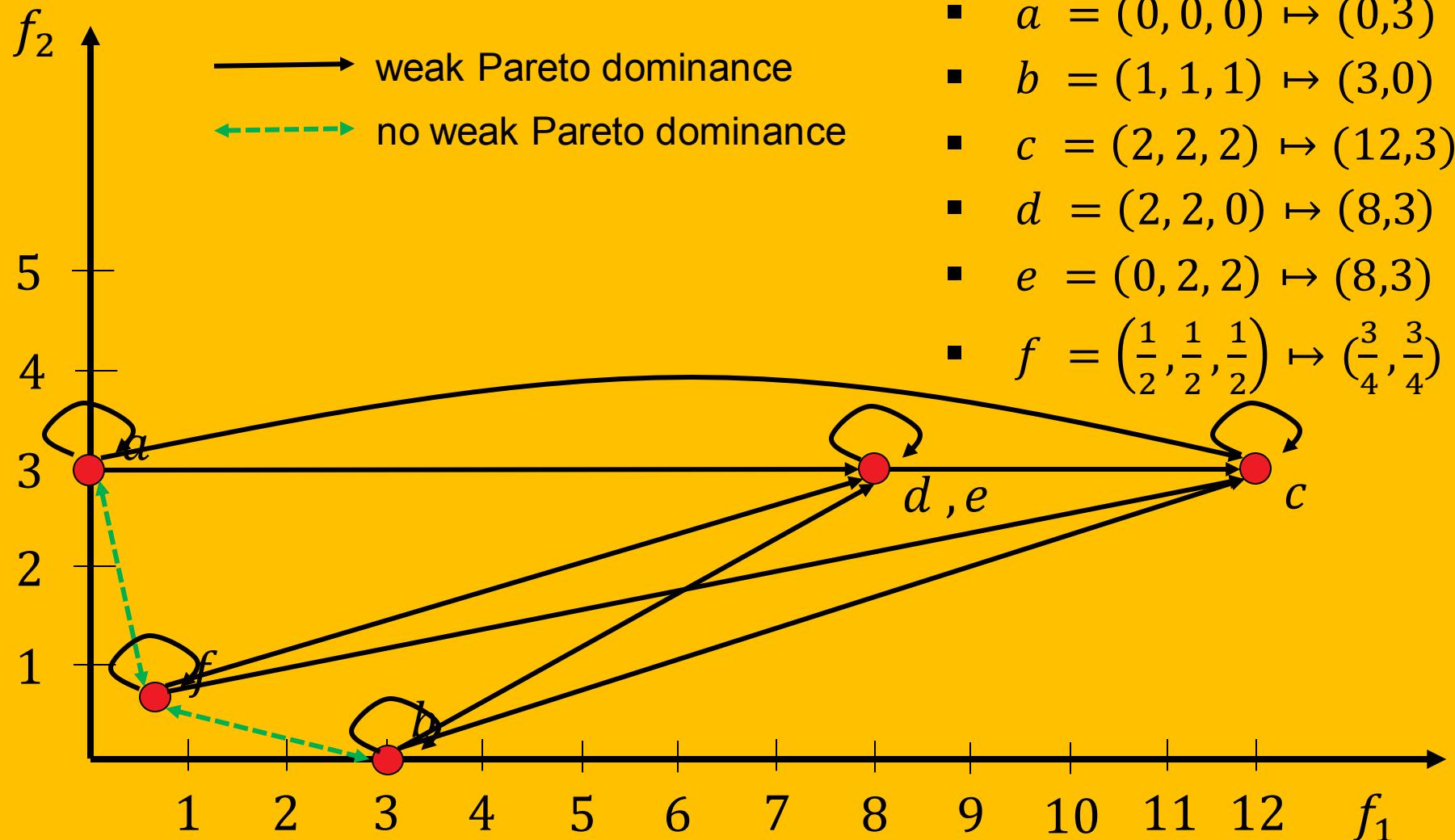
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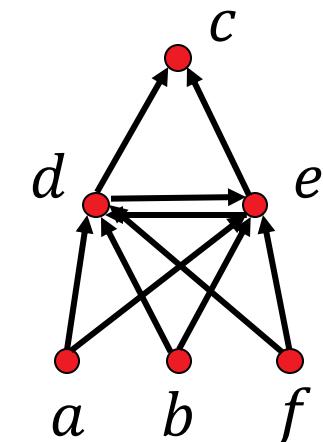
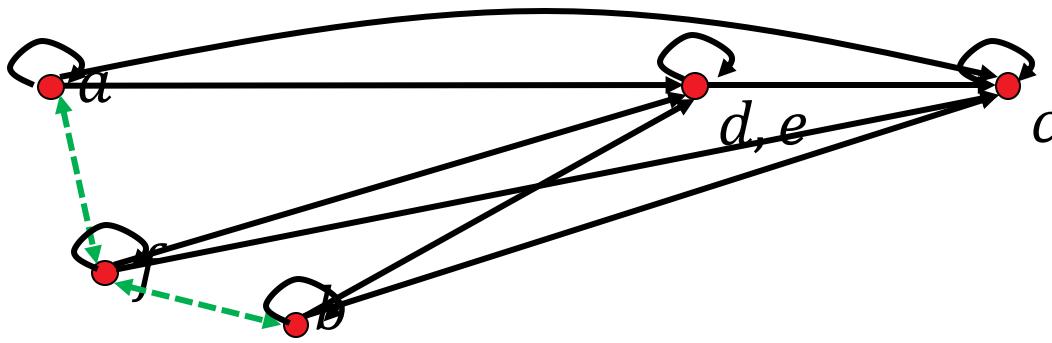
Exercise 2: Understanding Pareto Dominance

$f_{\text{doublesphere}}: x \mapsto (\sum_{i=1}^n x_i^2, \sum_{i=1}^n (x_i - 1)^2)$.



Visualizing Dominance Relations as Graphs

We can simplify the visualization of the (weak) Pareto dominance relation by *transitive reduction*:



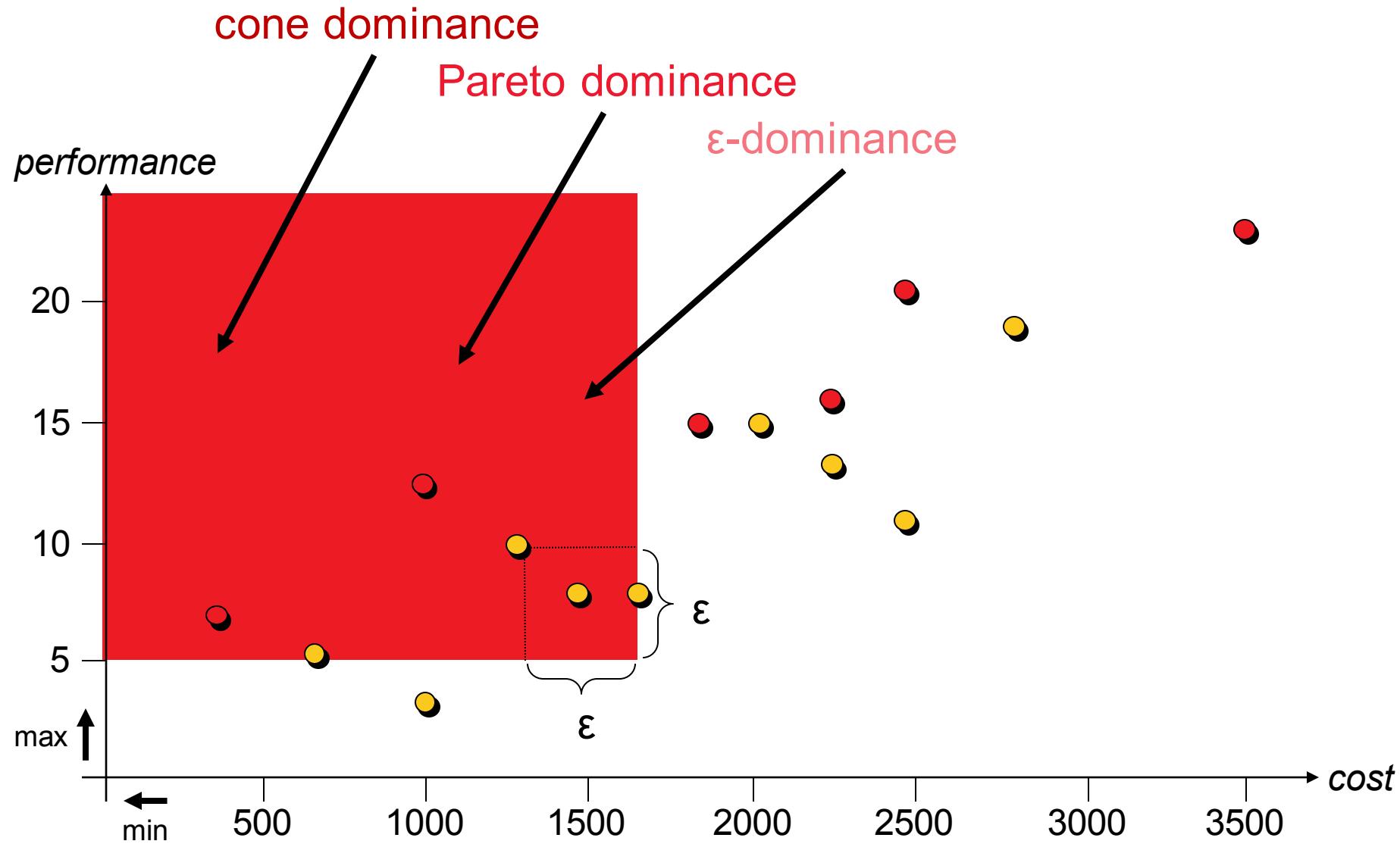
The **weak Pareto dominance is a preorder**, i.e. a relation that is

- reflexive and transitive
- minimal elements = Pareto-optimal solutions

If no *indifferent* solutions $x \neq y$ with $f(x) = f(y)$ exist, we have antisymmetry and a partial order ("poset")---visualizable as Hasse diagram.

! The Pareto dominance itself is not reflexive and thus, never a poset!

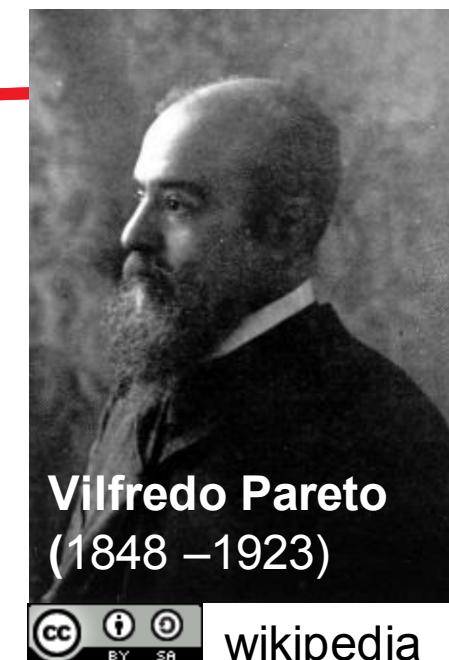
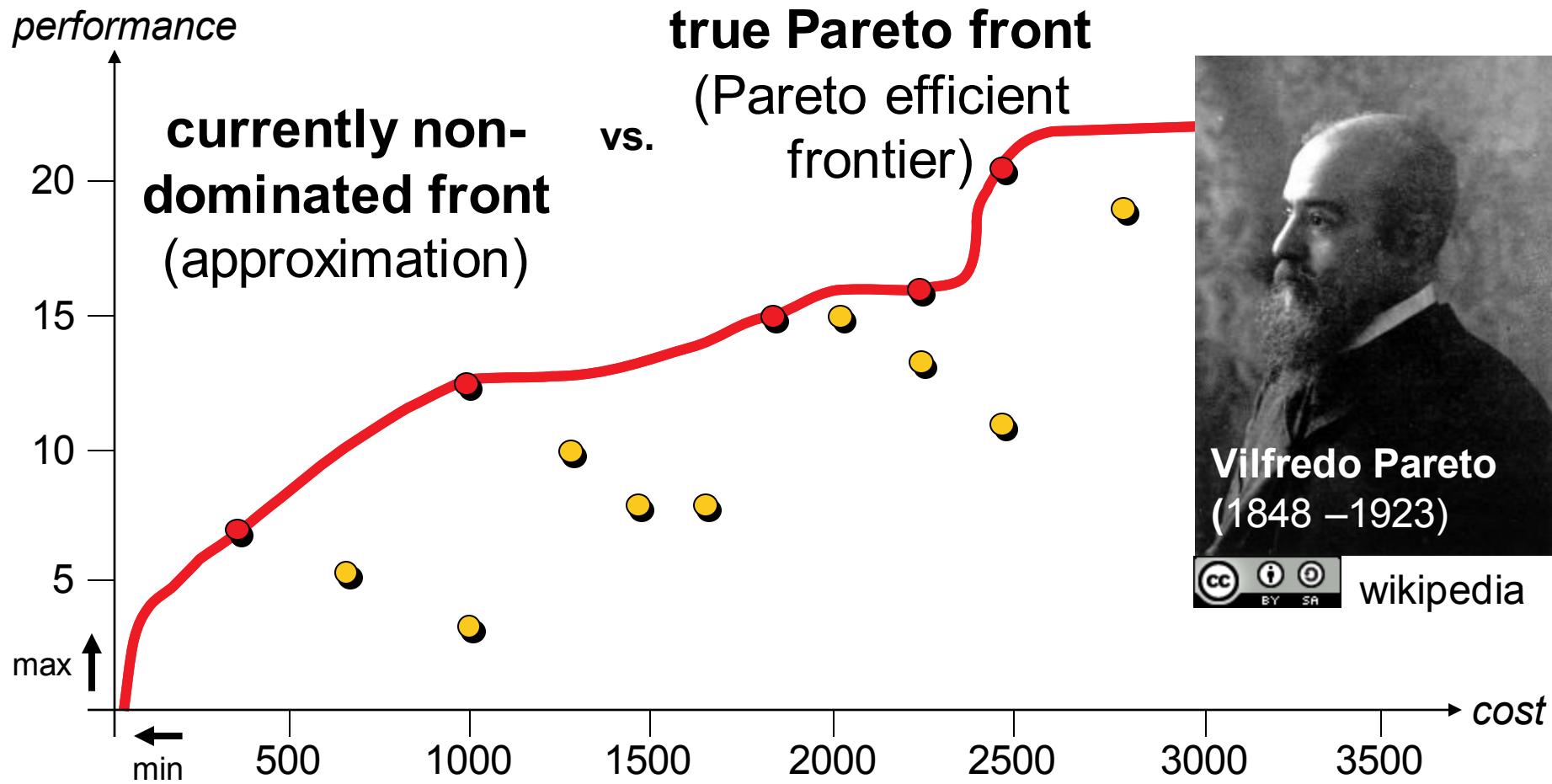
A Brief Introduction to Multiobjective Optimization



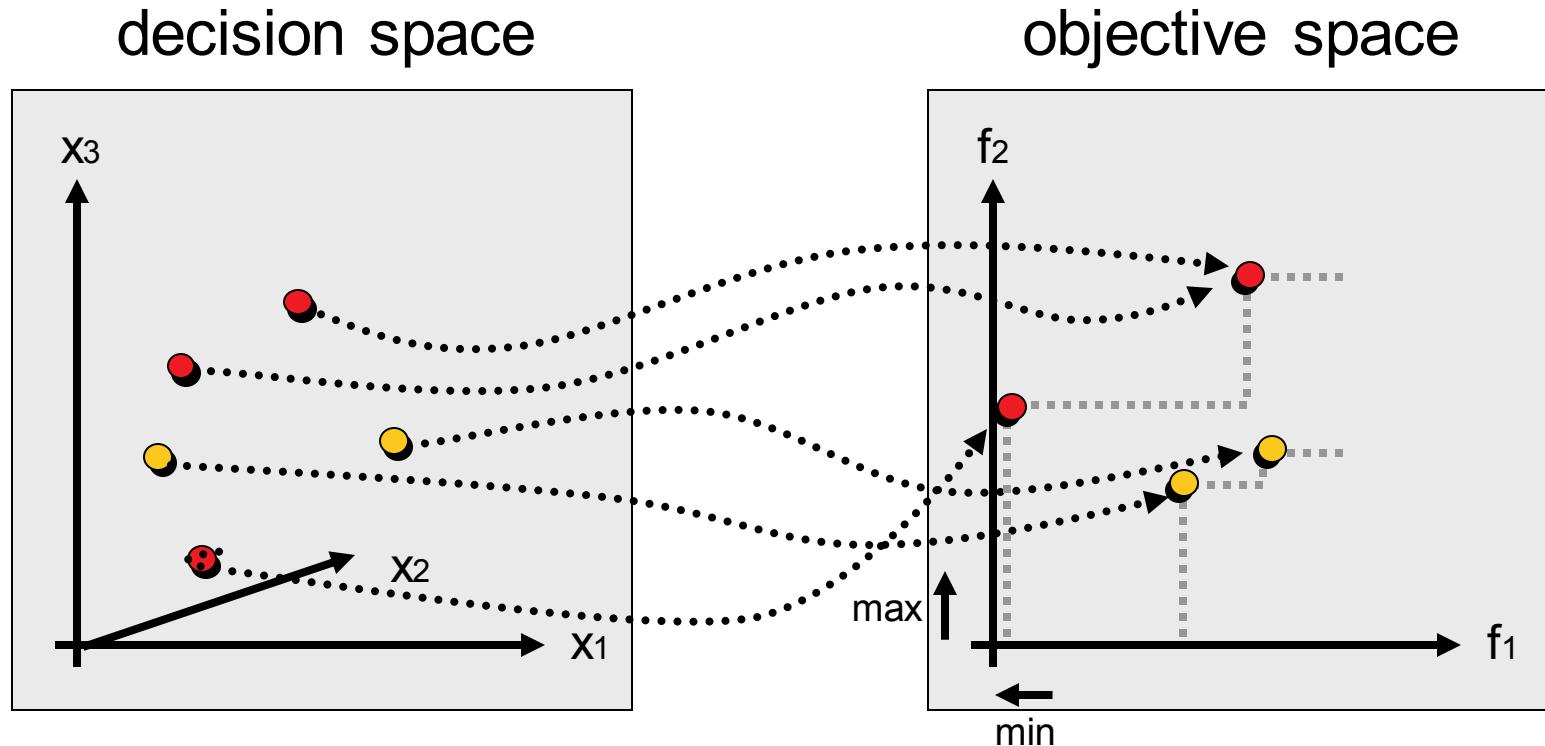
A Brief Introduction to Multiobjective Optimization

Pareto set: set of all non-dominated solutions (decision space)

Pareto front: its image in the objective space



A Brief Introduction to Multiobjective Optimization



solution of Pareto-optimal set
non-optimal **decision vector**

- vector of Pareto-optimal front
- non-optimal **objective vector**

Exercise 3: Pareto Front of Double Sphere

What is the Pareto set/front of the double sphere problem

$$f_{\text{doublesphere}}: x \mapsto (\sum_{i=1}^n x_i^2, \sum_{i=1}^n (x_i - 1)^2)$$

- a) what is the Pareto set?
- b) what is the associated Pareto front?

Tips for a)

- display some solutions in the search space (let's say in 2-D)
- investigate where dominating solutions lie
- investigate where dominated solutions lie
- finally, show graphically that what you think is the Pareto set is actually the Pareto set (take a point anywhere within your guessed set and show in which direction you can improve and where you cannot improve anymore)

A Necessary Condition On the Pareto Set

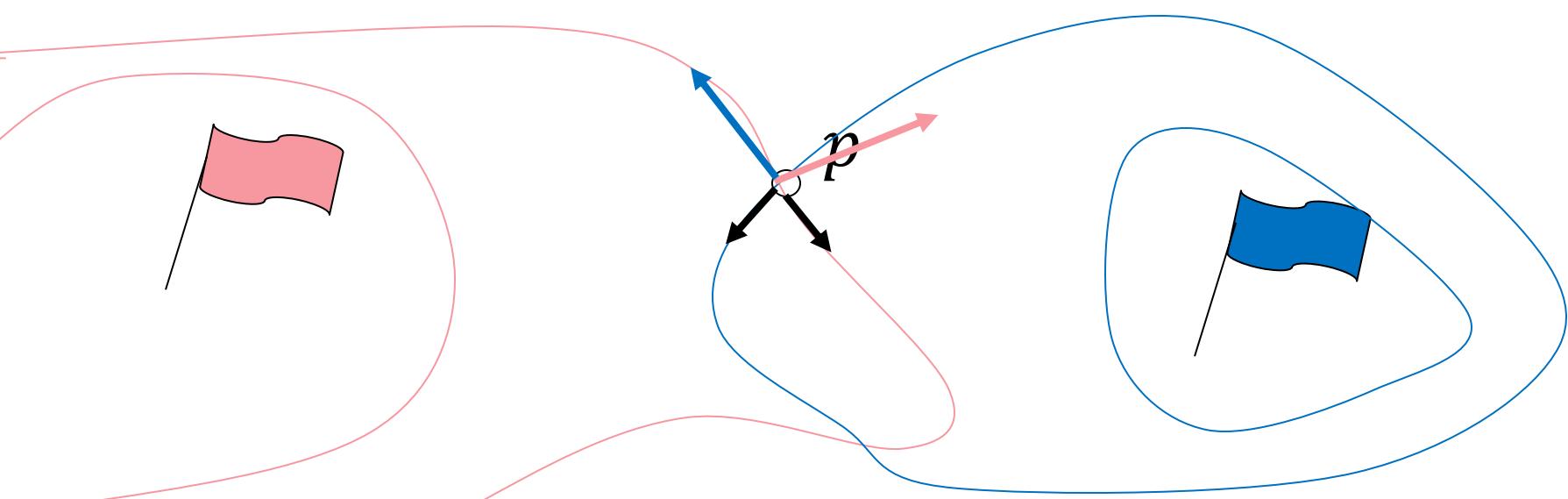
Necessary Condition:

For a Pareto-optimal solution p , the gradients of all objective functions in p must be collinear.

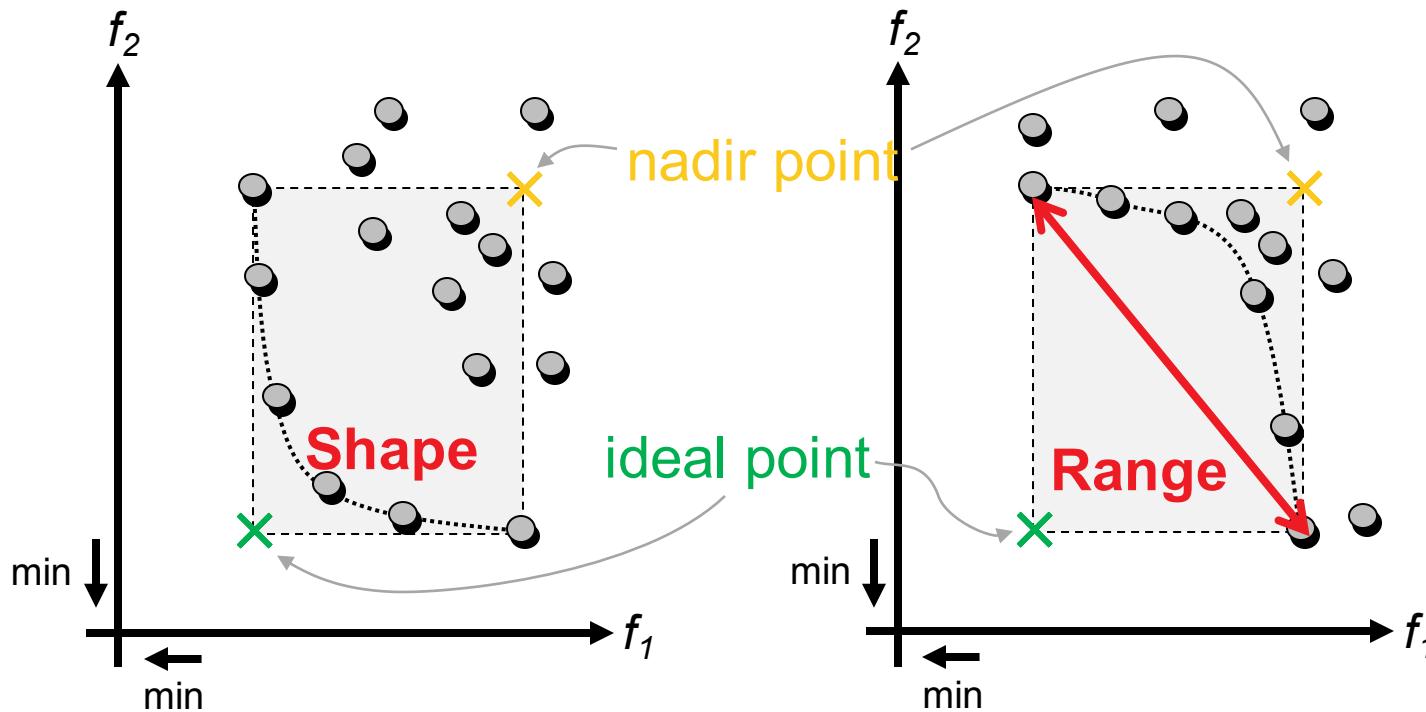
(Visual) Reasoning:

If this is not the case, we can move along one level set and improve on the other objective.

[remember the KKT conditions for constrained optimization]



Ideal and Nadir Point



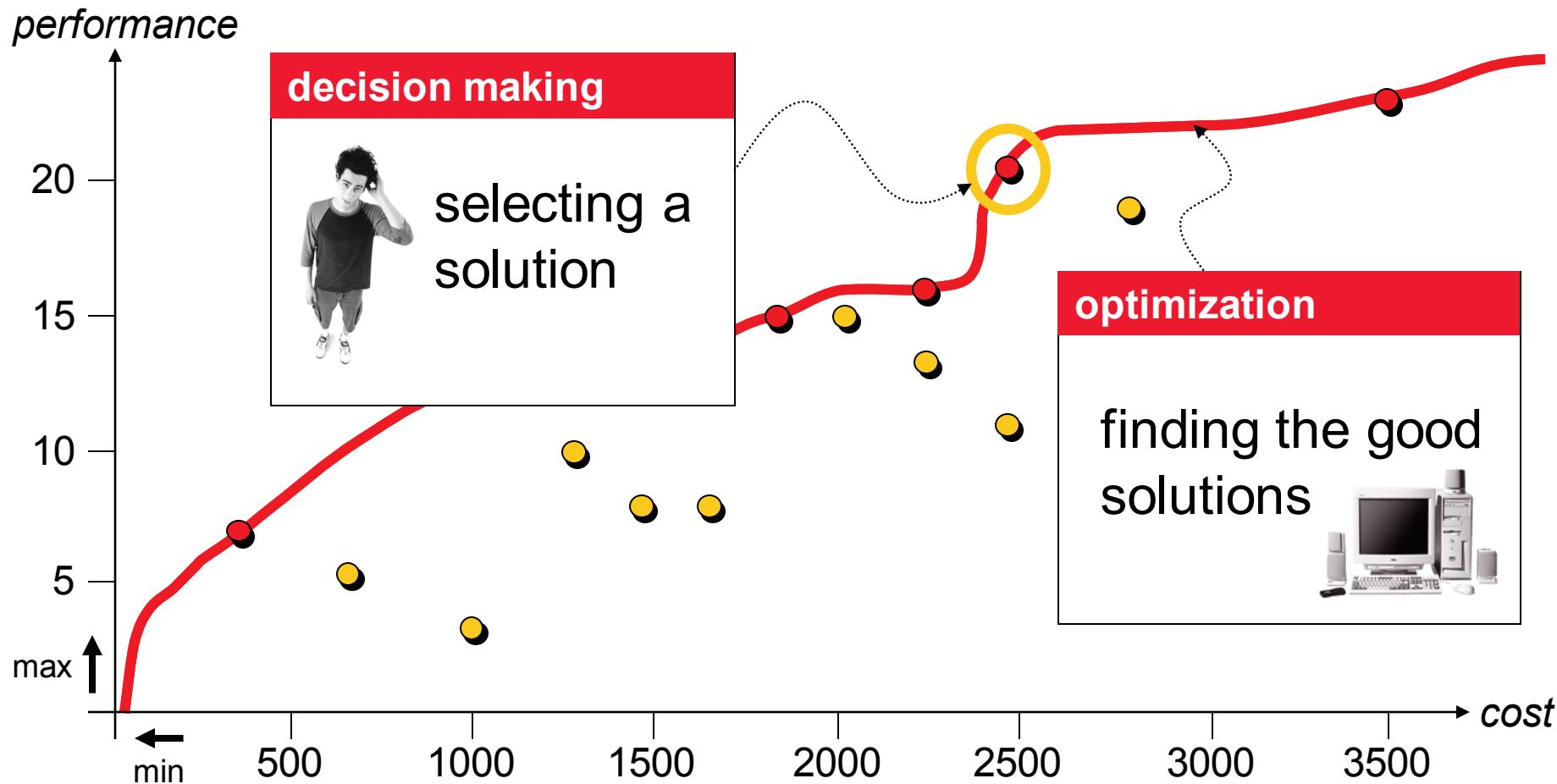
ideal point: best values
nadir point: worst values

} obtained for *Pareto-optimal* points

Optimization vs. Decision Making

Multiobjective Optimization

combination of optimization of a set and a decision for a solution

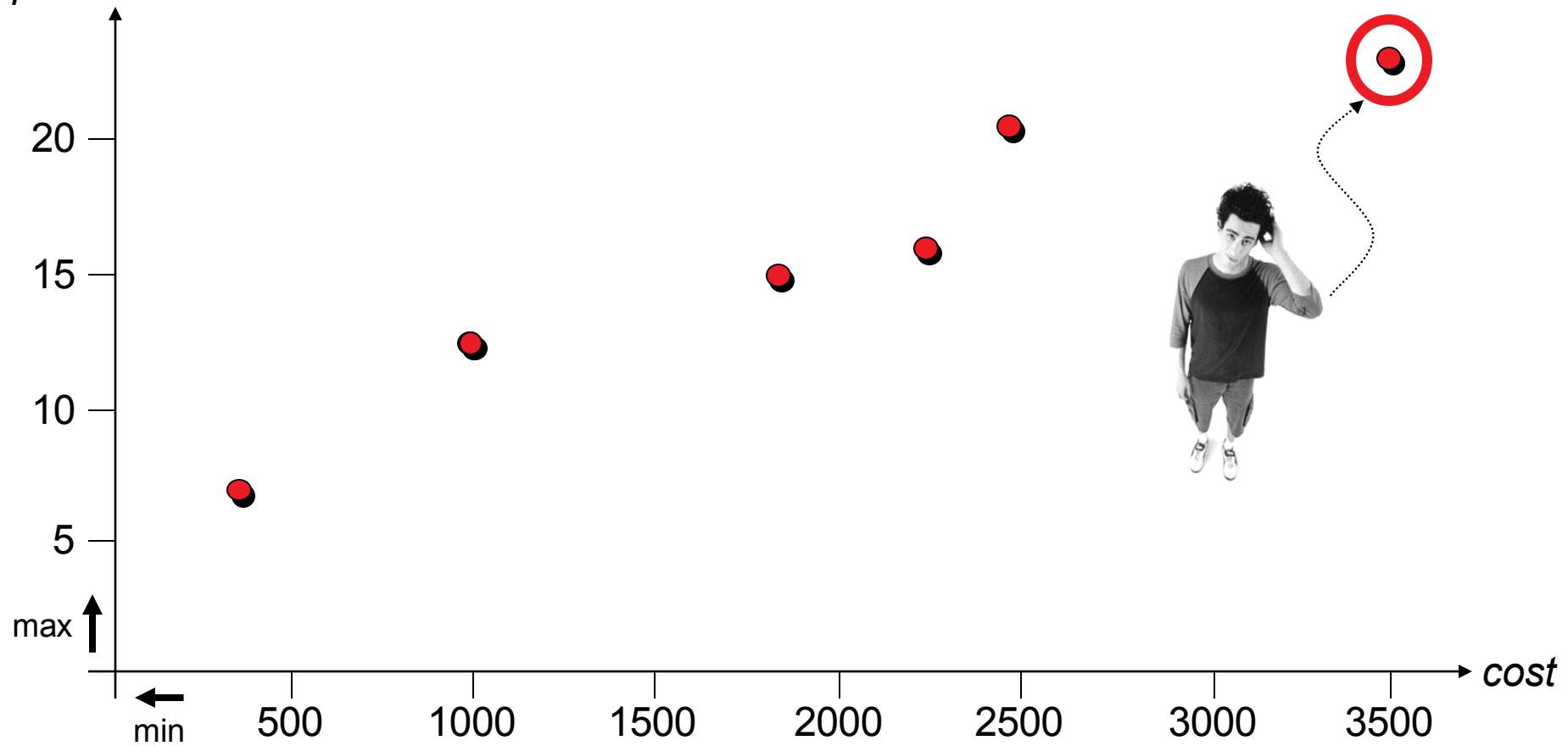


Selecting a Solution: Examples

Possible Approaches:

① ranking: performance more important than cost

performance

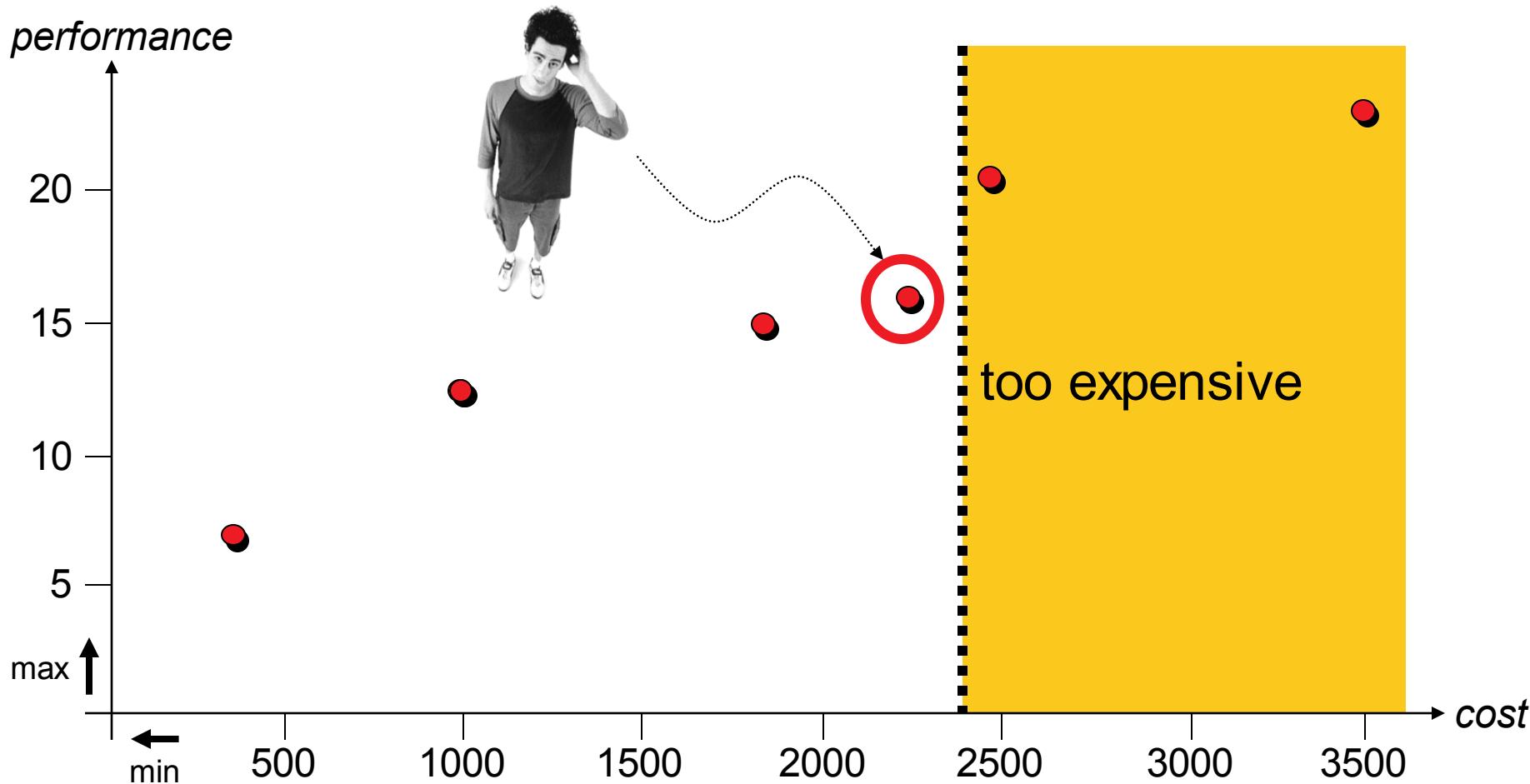


Selecting a Solution: Examples

Possible

① ranking: performance more important than cost

Approaches: ② constraints: cost must not exceed 2400

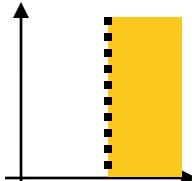


When to Make the Decision

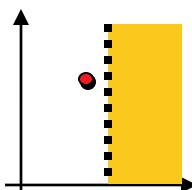
Before Optimization:



rank objectives,
define constraints,...



search for one
(good) solution



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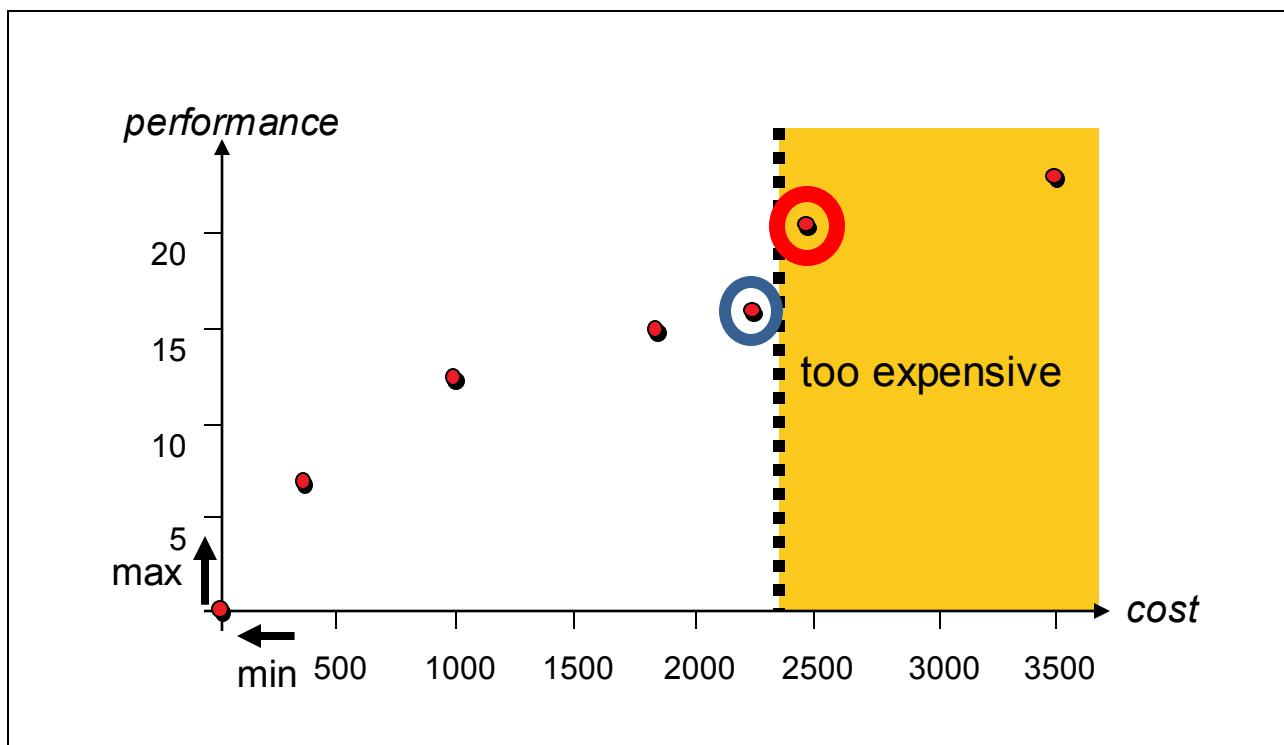
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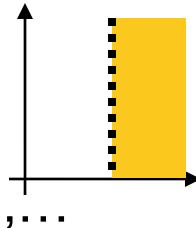


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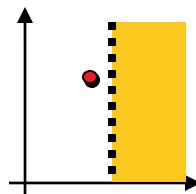
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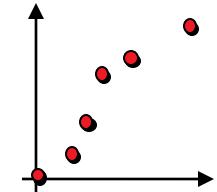
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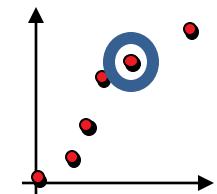
After Optimization:



search for a **set** of
(good) solutions



select one solution
considering
constraints, etc.

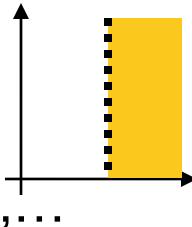


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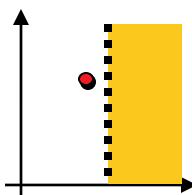
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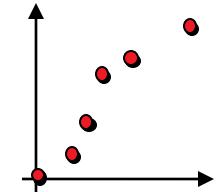
search for one
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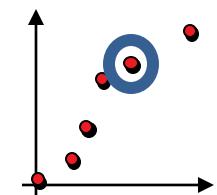
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Focus: learning about a problem

- trade-off surface
- interactions among criteria
- structural information
- also: interactive optimization

Two Communities...



International Society on
Multiple Criteria Decision Making



- established field
(beginning in 1950s/1960s)
- bi-annual conferences since
1975
- background in economics,
math, management and
social sciences
- focus on optimization and
decision making
- quite young field
(first papers in mid 1980s)
- bi-annual conference since
2001
- background in computer
science, applied math and
engineering
- focus on optimization
algorithms

...Slowly Merge Into One



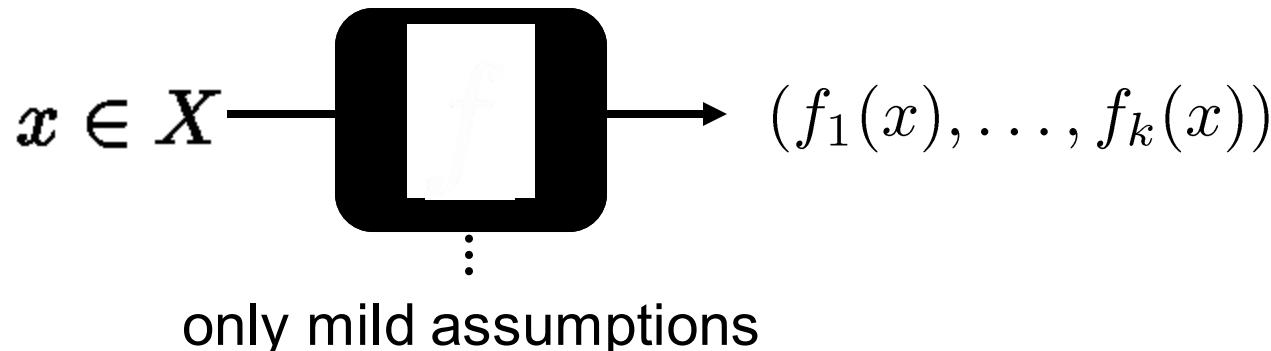
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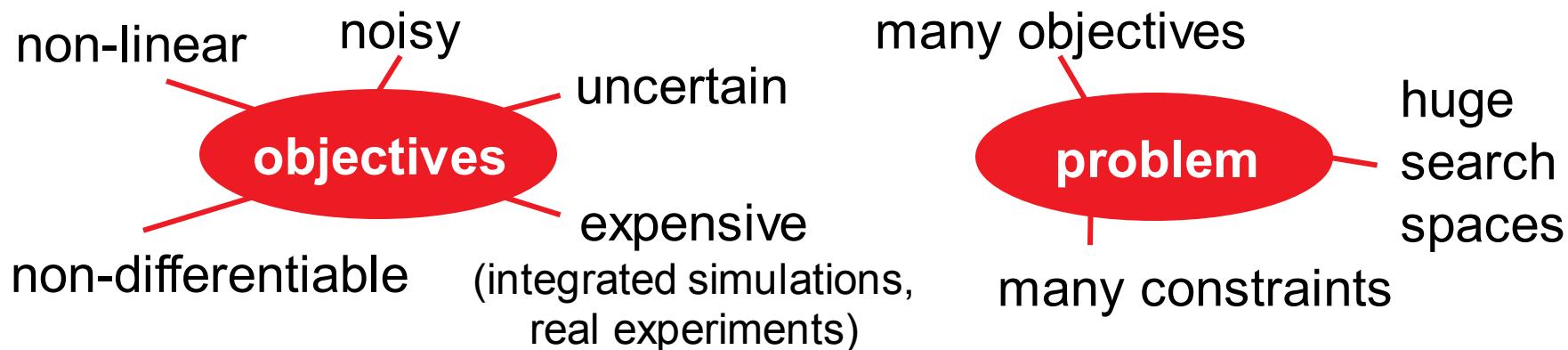
- MCDM track at EMO conference since 2009
- special sessions on EMO at the MCDM conference since 2008
- joint Dagstuhl seminars since 2004

One of the Main Differences

Blackbox optimization



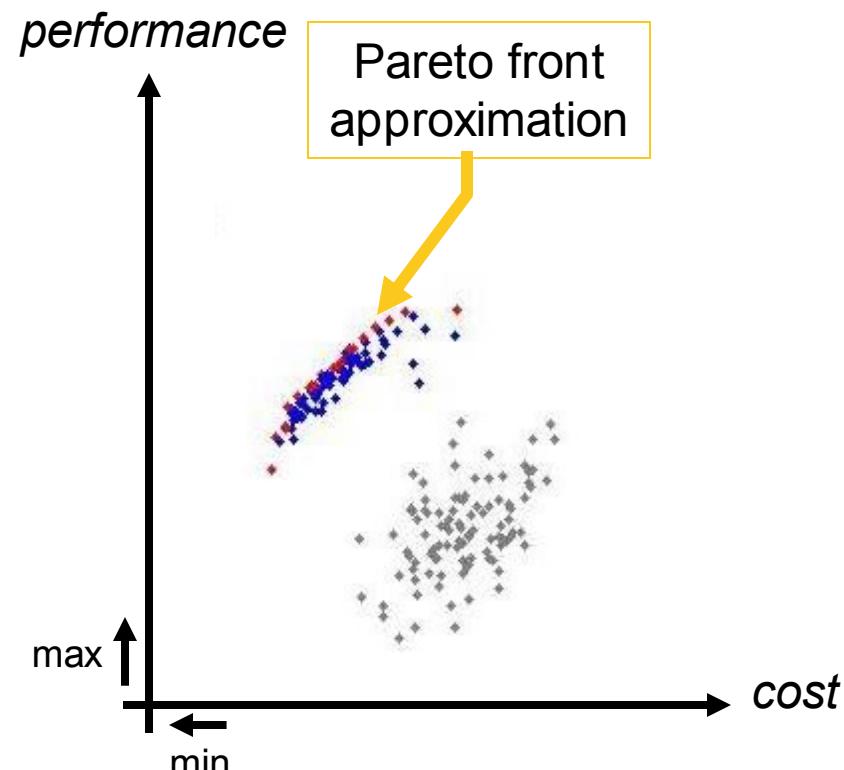
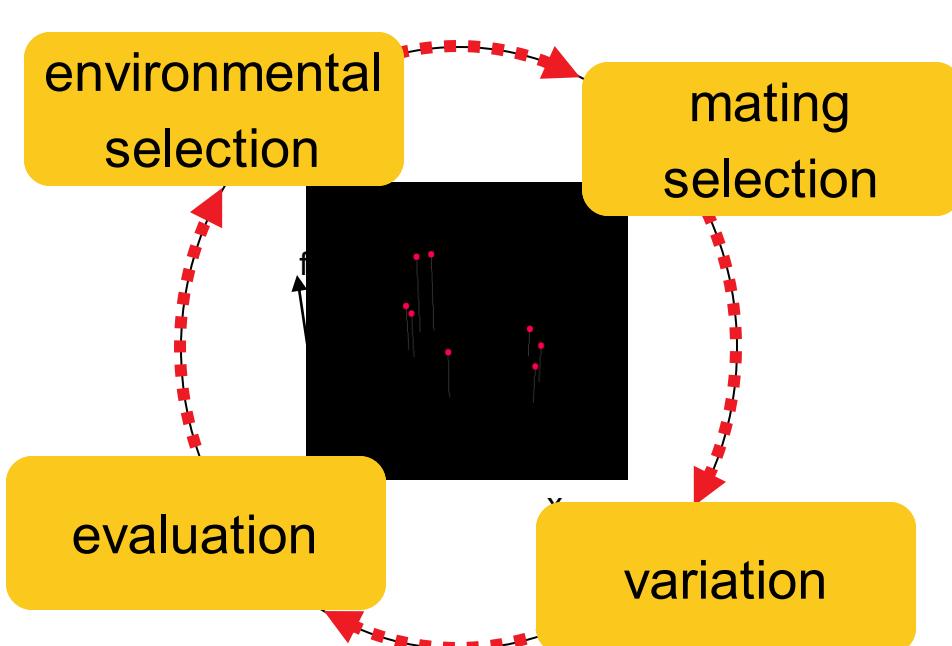
→ EMO therefore well-suited for real-world engineering problems



The Other Main Difference

Evolutionary Multiobjective Optimization

- set-based algorithms
- therefore possible to approximate the Pareto front in one run

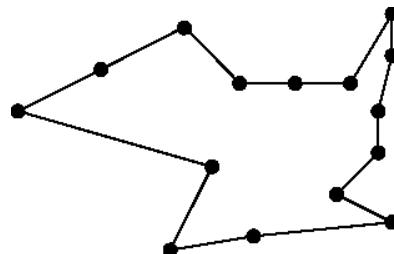


Multiobjectivization

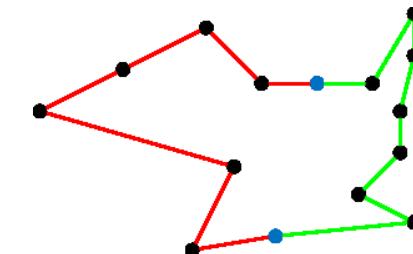
Some problems are easier to solve in a multiobjective scenario

example: TSP

[Knowles et al. 2001]



$$\pi \in S_n \rightarrow f(\pi)$$



$$\pi \in S_n \rightarrow (f_1(\pi, a, b), f_2(\pi, a, b))$$

Multiobjectivization

by **addition** of new “helper objectives” [Jensen 2004]

job-shop scheduling [Jensen 2004], frame structural design
[Greiner et al. 2007], VRP [Watanabe and Sakakibara 2007], ...

by **decomposition** of the single objective

TSP [Knowles et al. 2001], minimum spanning trees [Neumann and Wegener 2006], protein structure prediction [Handl et al. 2008a], ...

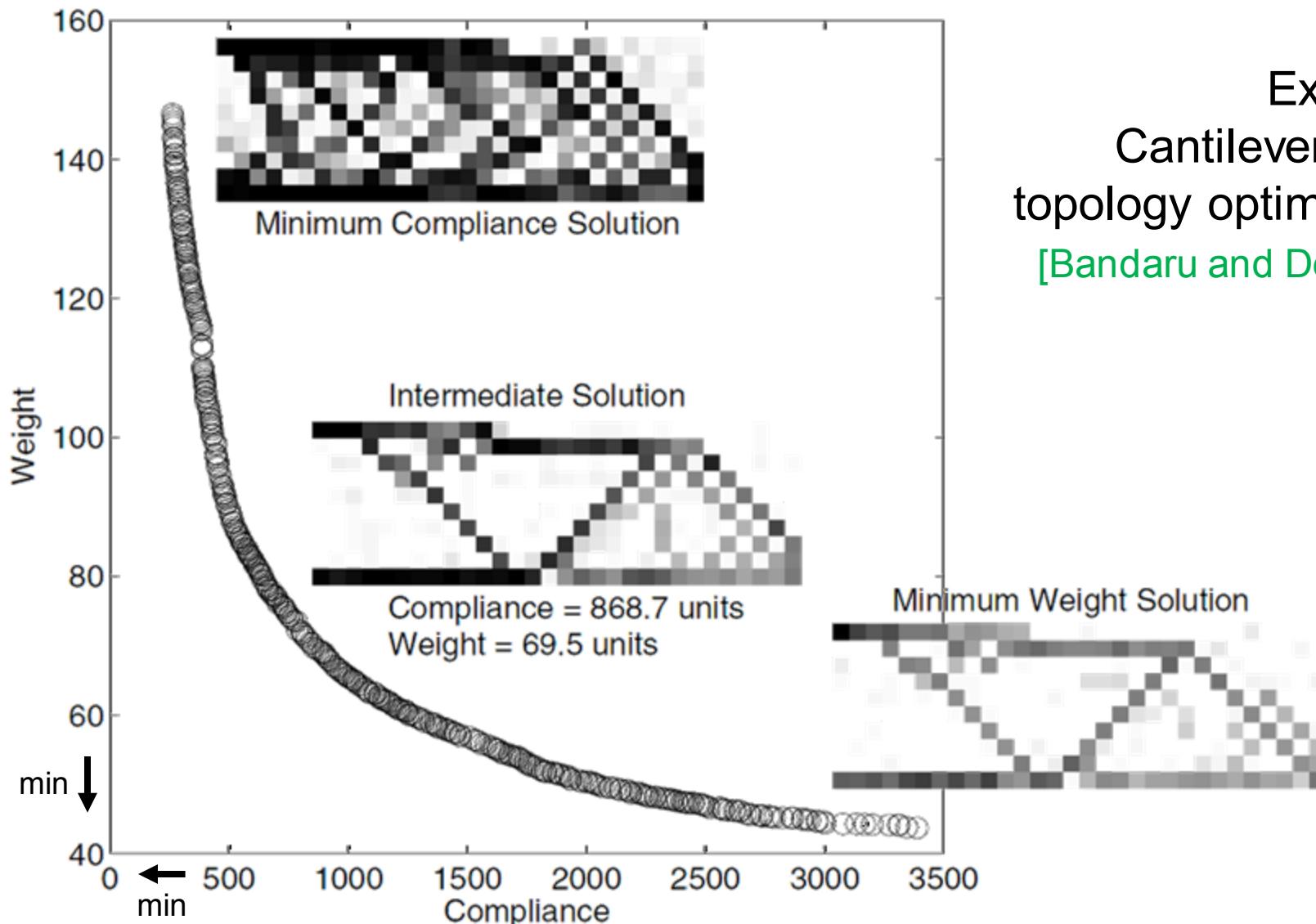
also backed up by theory e.g. [Brockhoff et al. 2009, Handl et al. 2008b]

related to *constrained* and *multimodal* single-objective optimization

see also this recent overview: [Segura et al. 2013]

Innovization

Often innovative design principles among solutions are found



Example:
Cantilever beam
topology optimization
[Bandaru and Deb 2015]

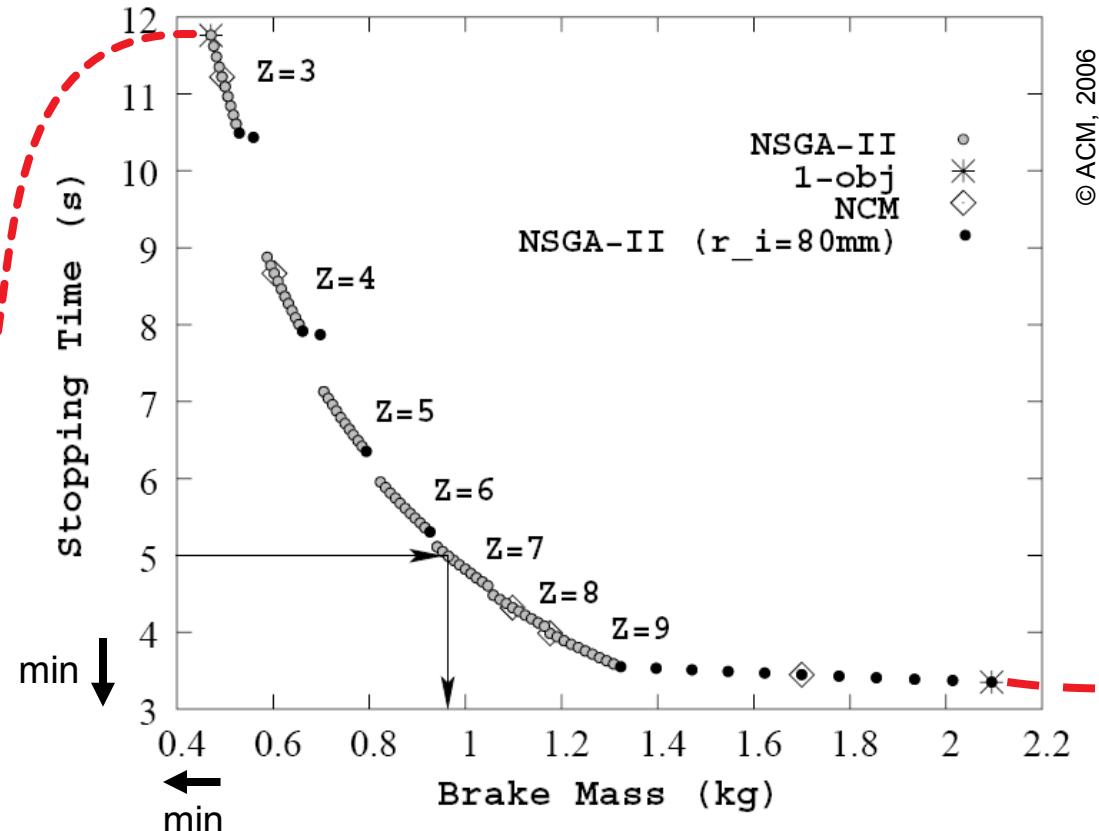
Innovation

Often innovative design principles among solutions are found

Example:

Clutch brake design

[Deb and Srinivasan 2006]



Solution	x_1	x_2	x_3	x_4	x_5	f_1	f_2
Min. f_1	70	90	1.5	1000	3	0.4704	11.7617
Min. f_2	80	110	1.5	1000	9	2.0948	3.3505

Innovation

Often innovative design principles among solutions are found

Innovation [Deb and Srinivasan 2006]

- = using machine learning techniques to find new and innovative design principles among solution sets
- = learning from/about a multiobjective optimization problem

Other examples:

- Self-Organizing Maps for supersonic wing design [Obayashi and Sasaki 2003]
- Biclustering for processor design and knapsack [Ulrich et al. 2007]
- Successful case studies in engineering
(noise barrier design, polymer extrusion, friction stir welding)
[Deb et al. 2014]

The Big Picture

Basic Principles of Multiobjective Optimization

- algorithm design principles and concepts
- performance assessment

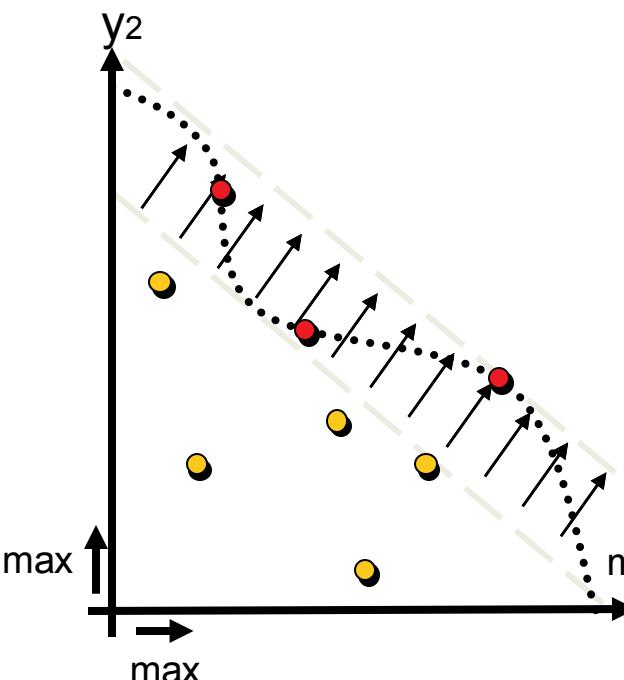
Selected Advanced Concepts

- preference articulation
- visualization aspects

Approaches to Multiobjective Optimization

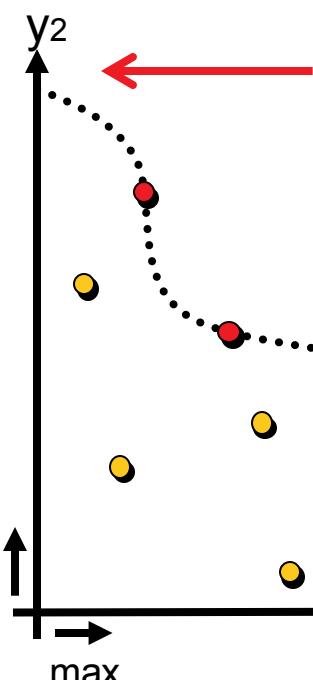
aggregation-based

*problem decomposition
(multiple single-objective
optimization problems)*



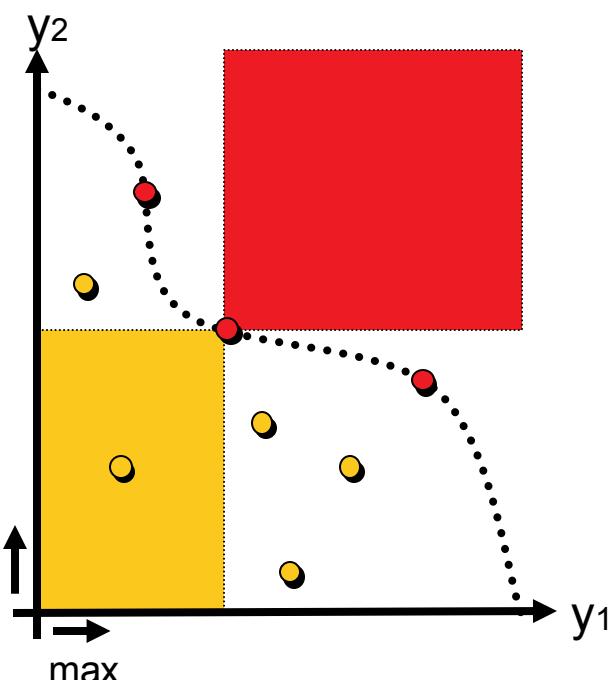
criterion-based

VEGA



dominance-based

SPEA2, NSGA-II
“modern” EMOA

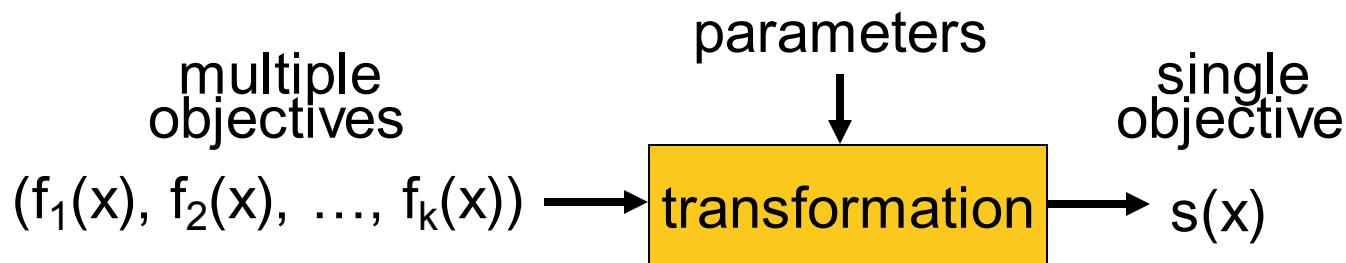


solution-oriented
scaling-dependent



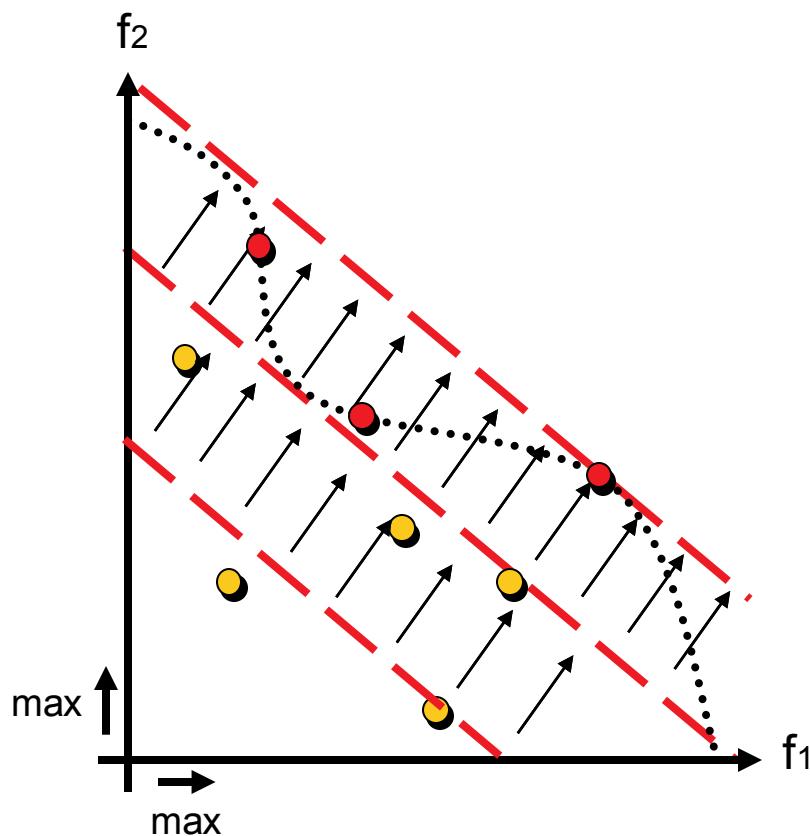
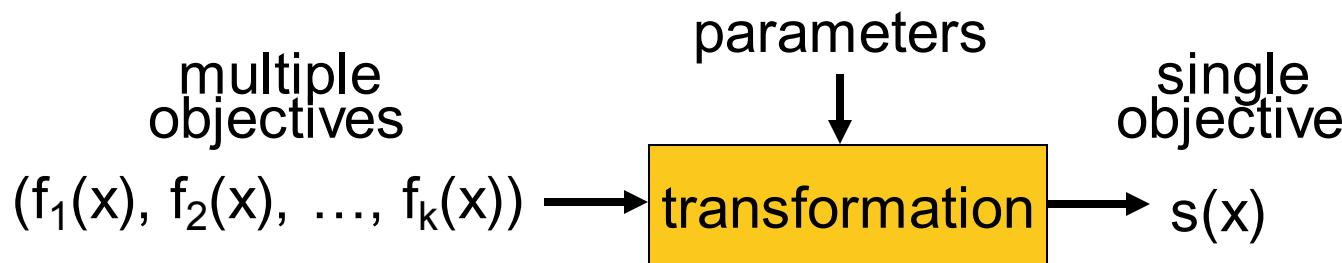
set-oriented
less scaling-independent

Solution-Oriented Problem Transformations



A scalarizing function s is a function $s: Z \rightarrow \mathbb{R}$ that maps each objective vector $u = (u_1, \dots, u_n) \in Z$ to a real value $s(u) \in \mathbb{R}$

Solution-Oriented Problem Transformations



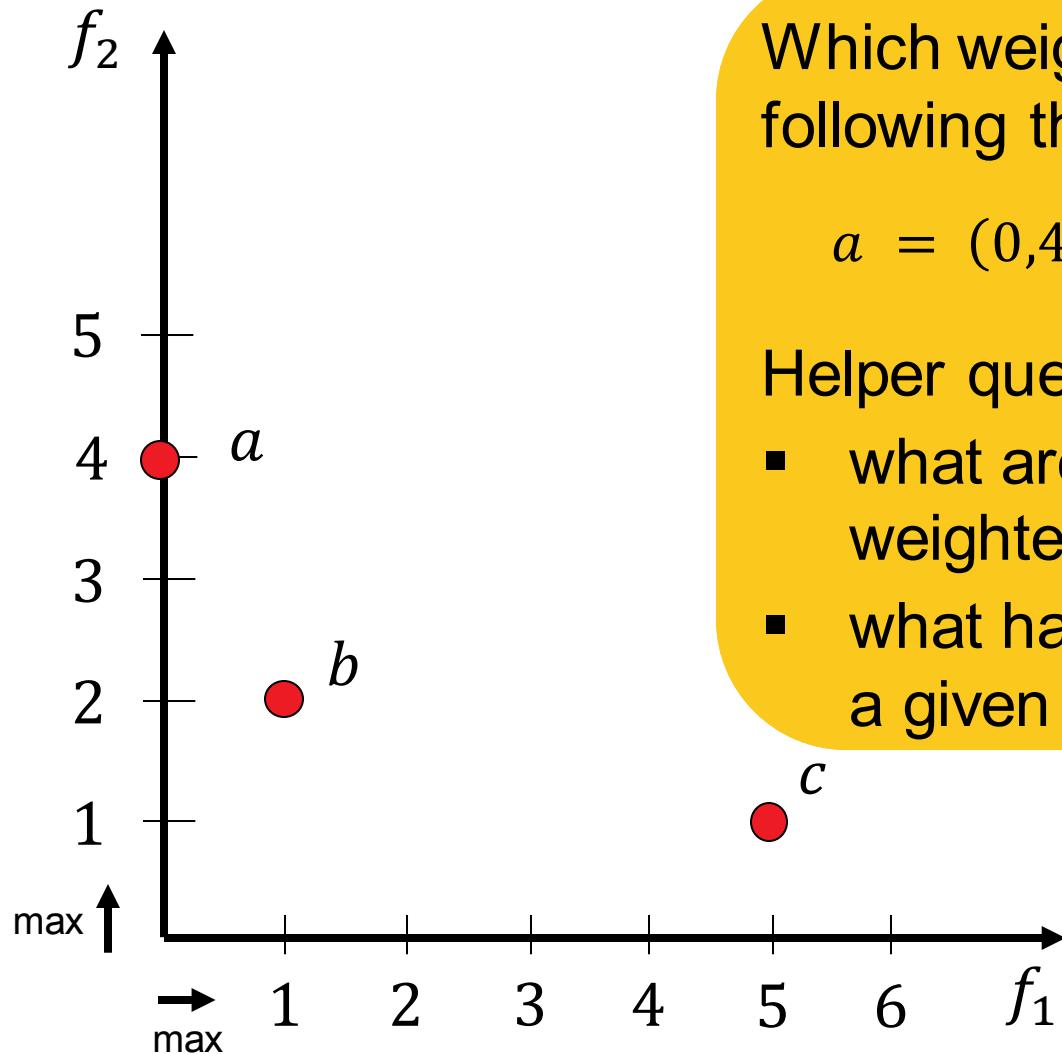
Example 1: weighted sum approach

(w_1, w_2, \dots, w_k) ↓

→ $y = w_1y_1 + \dots + w_ky_k$ →

```
graph TD; A["(w1, w2, ..., wk)"] --> B["y = w1y1 + ... + wkyk"]; B --> C["→"];
```

Exercise 4: Weighted Sum



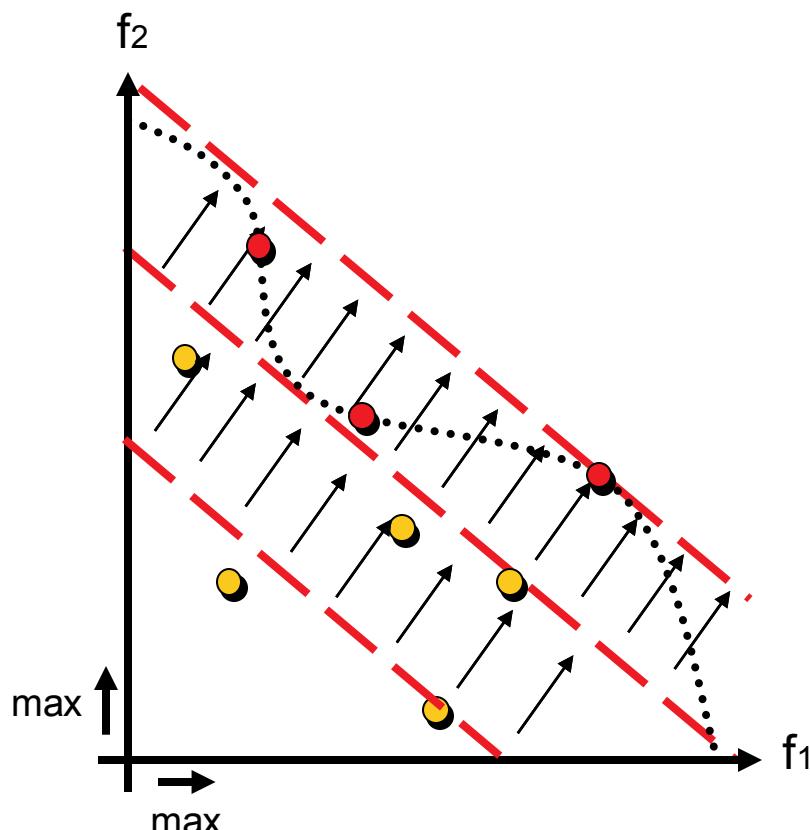
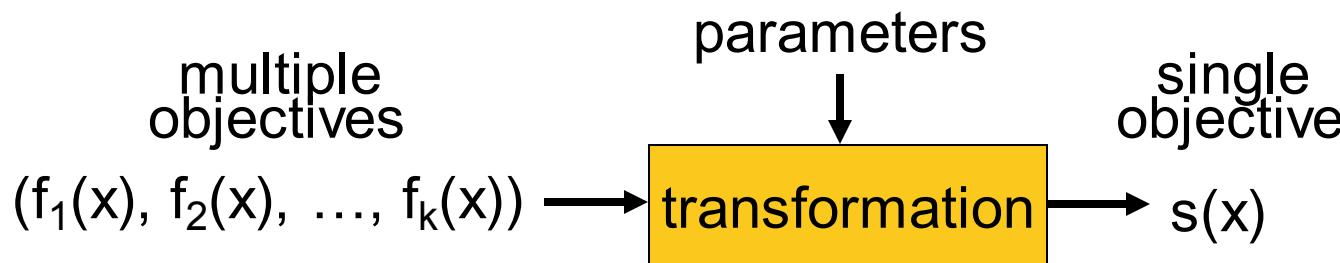
Which weights are optimal for the following three points?

$$a = (0,4) \quad b = (1,2) \quad c = (5,1)$$

Helper questions:

- what are the lines of equal weighted sum for a given weight?
- what happens if you optimize wrt. a given weighted sum?

Solution-Oriented Problem Transformations

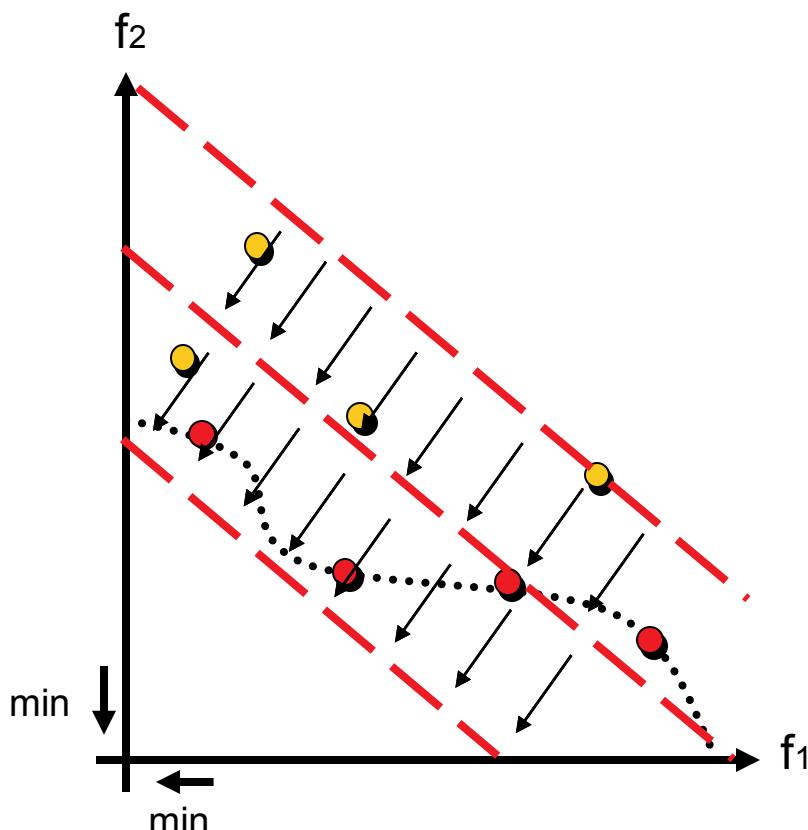
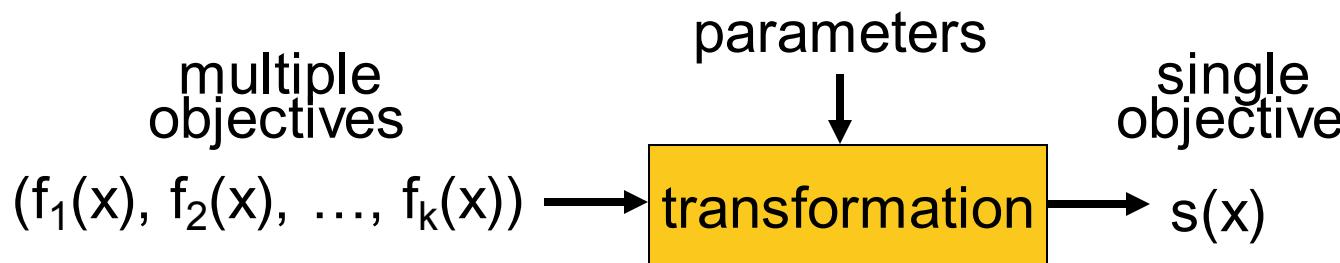


Example 1: weighted sum approach

$$(w_1, w_2, \dots, w_k) \rightarrow y = w_1y_1 + \dots + w_ky_k$$

Disadvantage: not all Pareto-optimal solutions can be found if the front is not concave (for maximization)

Solution-Oriented Problem Transformations

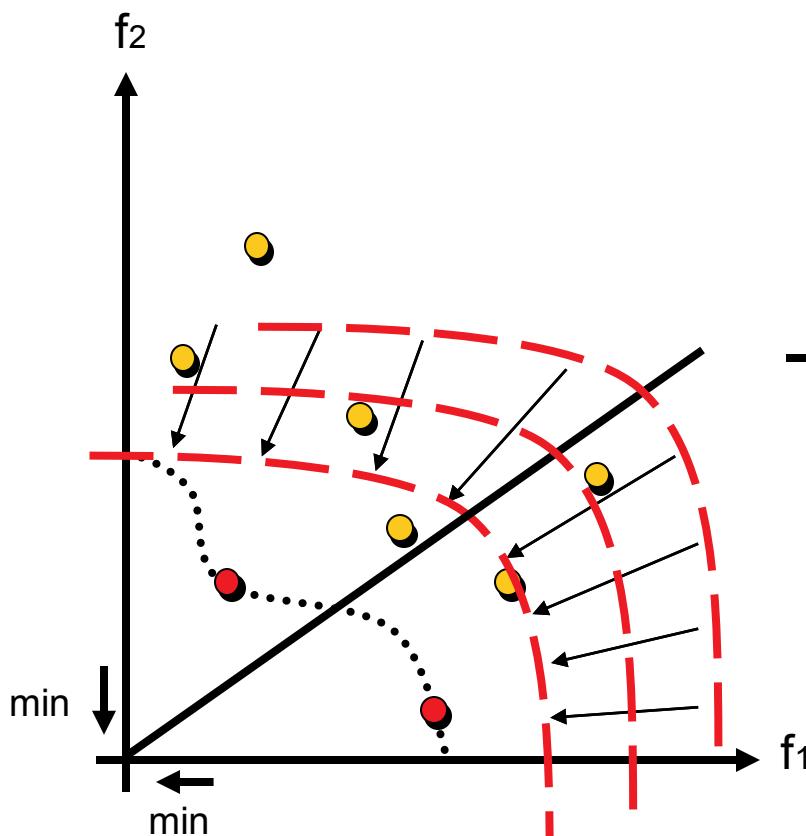
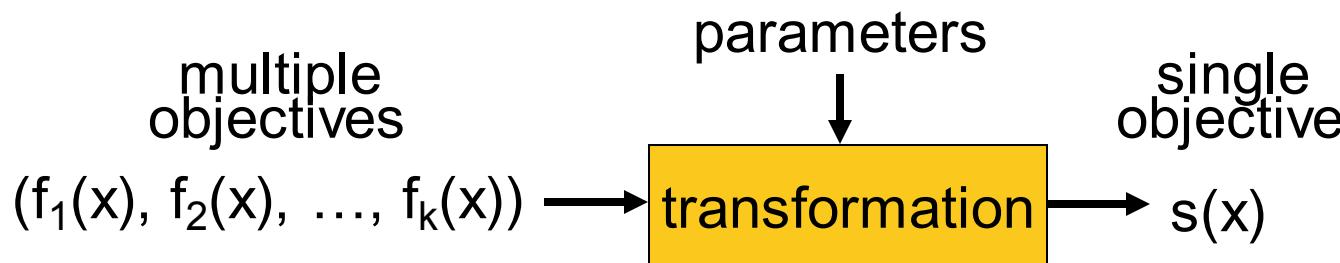


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Solution-Oriented Problem Transformations



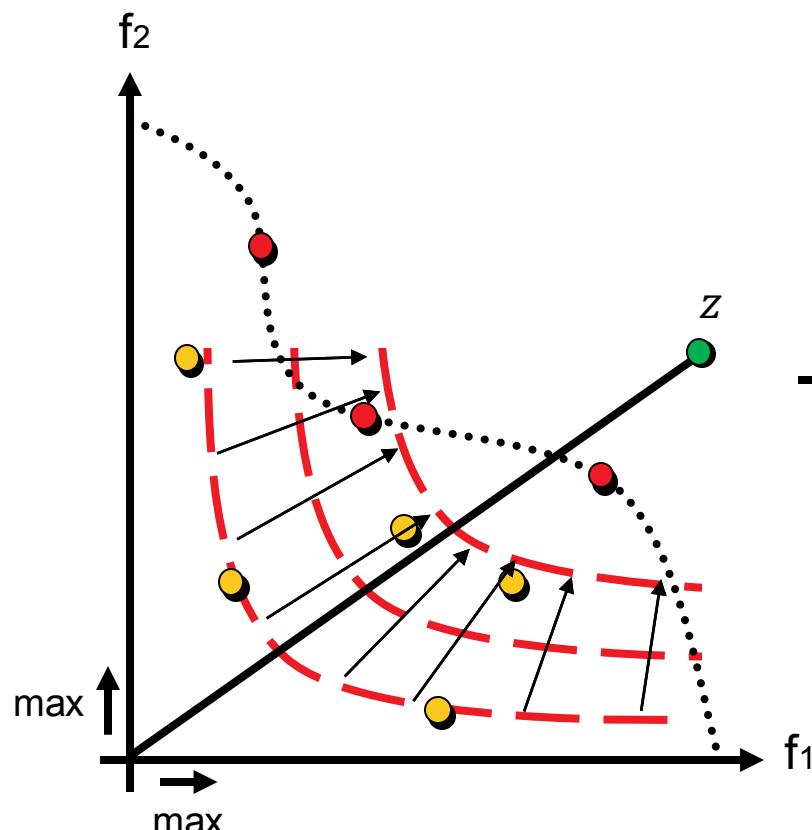
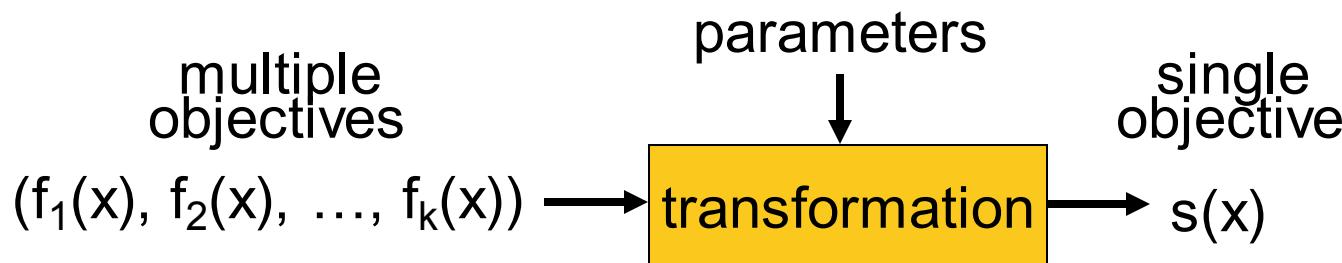
Example 2: weighted p-norm

$$(w_1, w_2, \dots, w_k) \rightarrow y = \sqrt[p]{(w_1 y_1)^p + \dots + (w_k y_k)^p}$$

$p = 1$: weighted sum

$p = \infty$: weighted Tchebycheff

Solution-Oriented Problem Transformations



Example 2: weighted p-norm

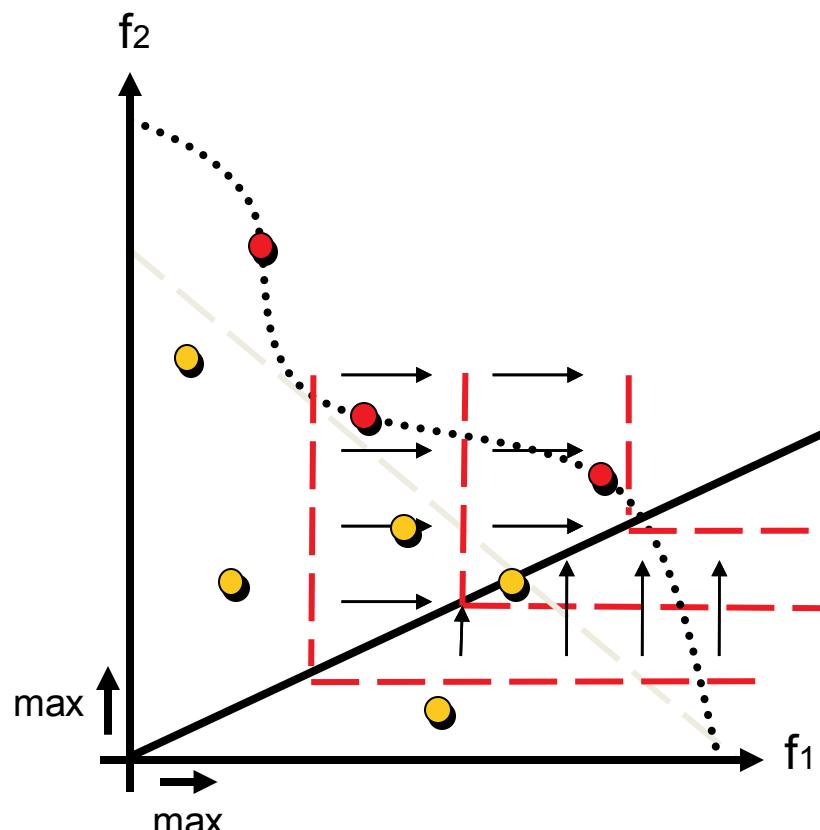
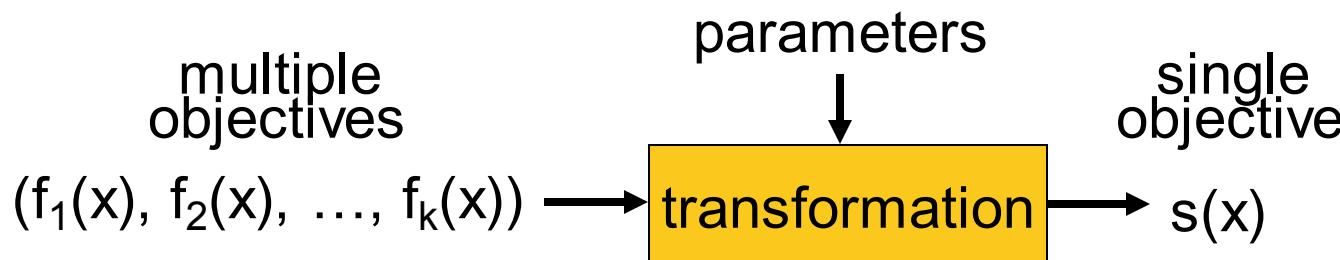
(w_1, w_2, \dots, w_k)

$$y = \sqrt[p]{\sum_{i=1}^k (|w_i(y_i - z_i)|)^p}$$

$p = 1$: weighted sum

$p = \infty$: weighted Tchebycheff

Solution-Oriented Problem Transformations



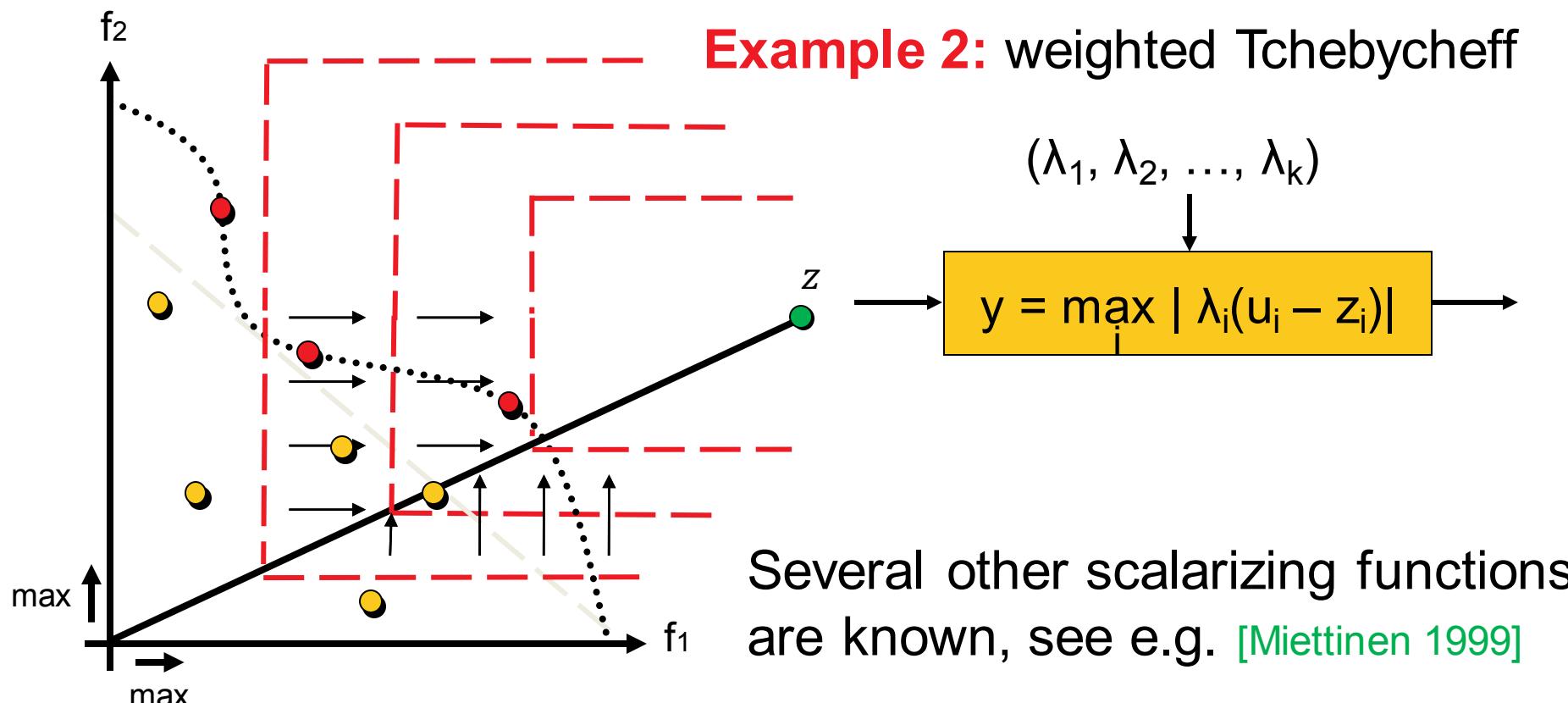
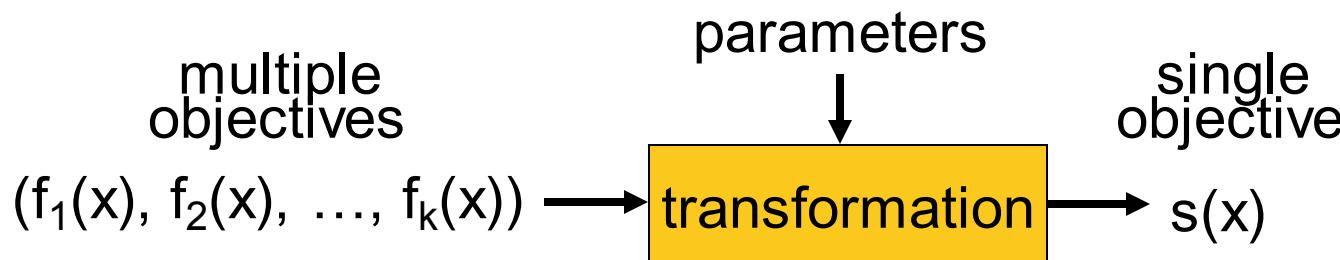
Example 2: weighted Tchebycheff

$(\lambda_1, \lambda_2, \dots, \lambda_k)$

$$y = \max_i |\lambda_i(u_i - z_i)|$$

Several other scalarizing functions are known, see e.g. [Miettinen 1999]

Solution-Oriented Problem Transformations



Exercise: Benchmarking a Weighted Sum Approach on COCO

Exercise

Goal: Implement a Simple Weighted Sum Approach:

- N scalarizing functions, optimized with CMA-ES
- Python: use CMA-ES after `pip install cma` (more details here: <https://pypi.python.org/pypi/cma>)
- use ask and tell interface (next slide)
- CMA-ES parameters as default (with $\sigma_{init} = 3$ and initialized in [-5,5])
- no details given about:
 - how to normalize the objectives and estimate z
 - the order in which the N scalarizing functions are optimized
 - how to do restarts and how to distribute the budget

2nd Goal:

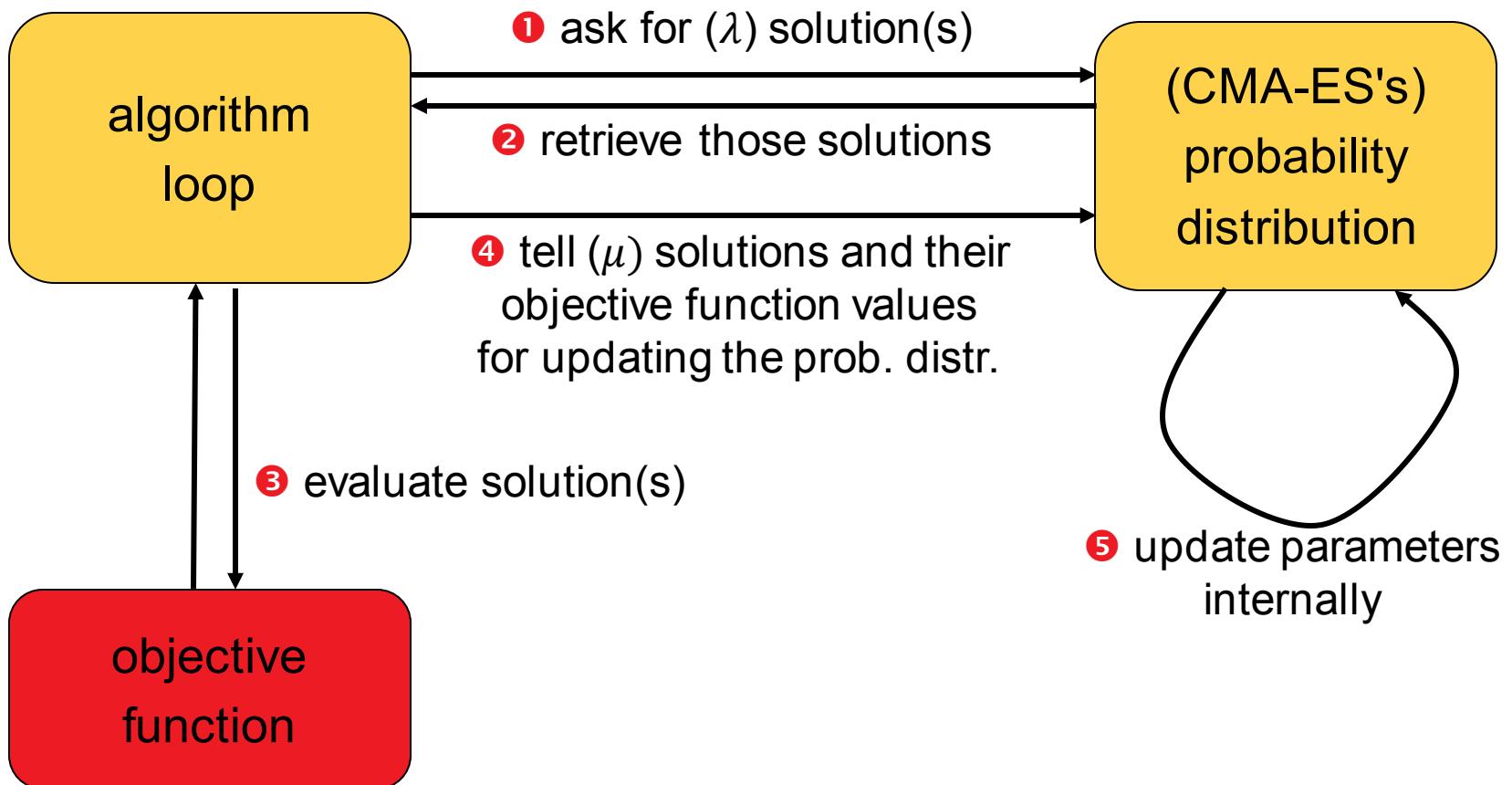
- produce data for the new **bbob-biobj-ext** suite
- hence, interested in your evaluations

The Idea of the Ask&Tell Interface to Optimization

example from the CMA-ES web page:

```
>>> import cma
>>> es = cma.CMAEvolutionStrategy(12 * [0], 0.5)
>>> while not es.stop():
...     solutions = es.ask()
...     es.tell(solutions,
...             [cma.ff.rosen(x) for x in solutions])
...     es.logger.add() # write data to disc
...                   to be plotted
...     es.disp()
<output omitted>
>>> es.result_pretty()
<output omitted>
>>> cma.plot() # shortcut for es.logger.plot()
```

Ask&Tell with CMA-ES (Visually)



Exercise: concrete

- a) download COCO (release 2.2.1) from
<https://github.com/numbbo/coco/>
- b) install and test it via `python do.py run-python`
- c) run the previous example code of CMA-ES (e.g. in ipython shell)
to get an idea how it works
- d) start your implementation of a weighted sum optimizer from
http://www.cmap.polytechnique.fr/~dimo.brockhoff/advancedOptSaclay/2018/exercises/example_experiment_WS.py within the function `def weighted_sum(fun, budget)`
tip: start simple and extend!
- e) run the experiments by typing
`python example_experiment_WS.py bbo-biobj-ext BUDGET`
with `BUDGET` any integer (start small and then increase) and send all data to me by email ☺

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