



A Brief Introduction to Evolutionary Multiobjective Optimization

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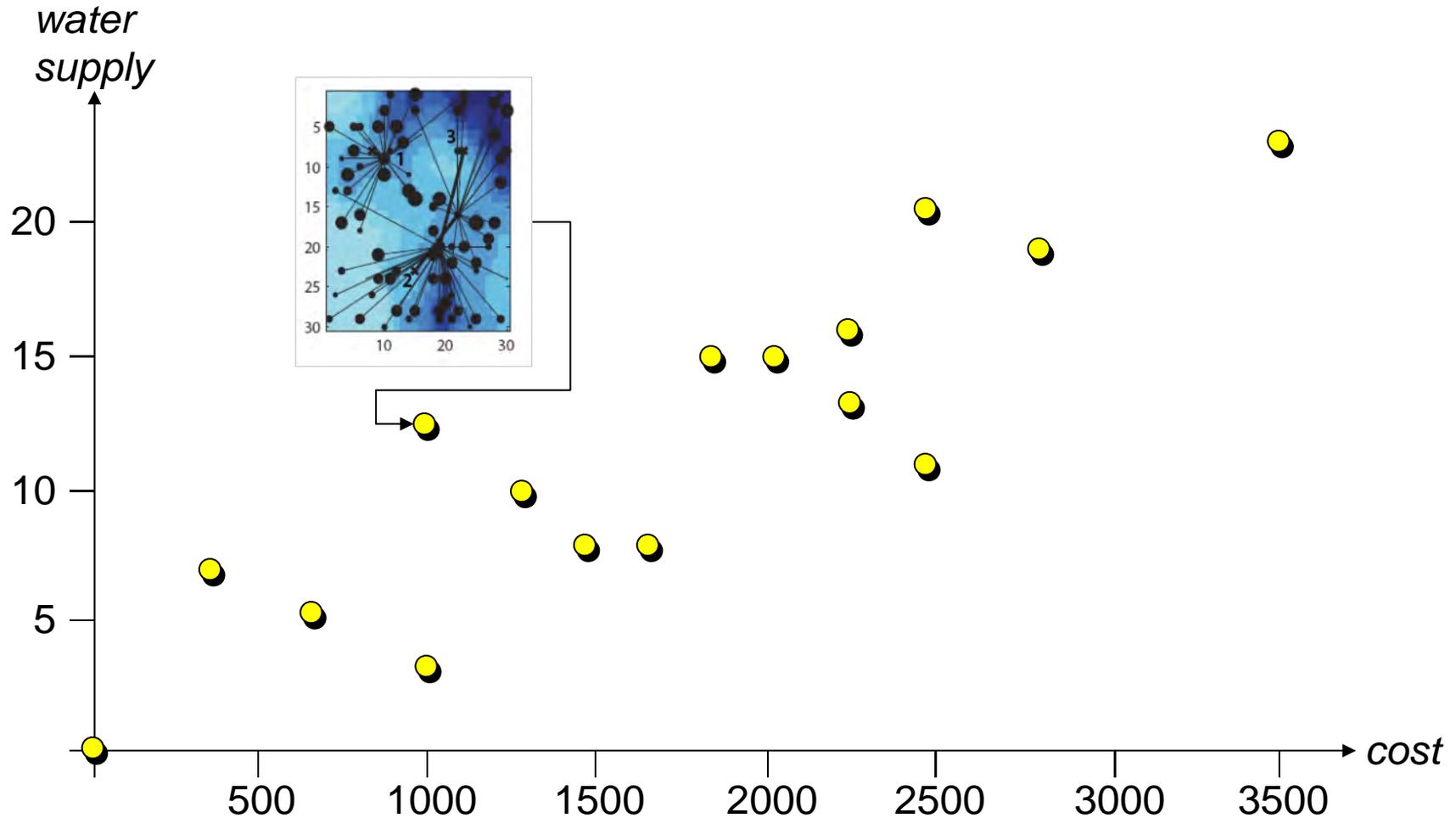


Microsoft
Research



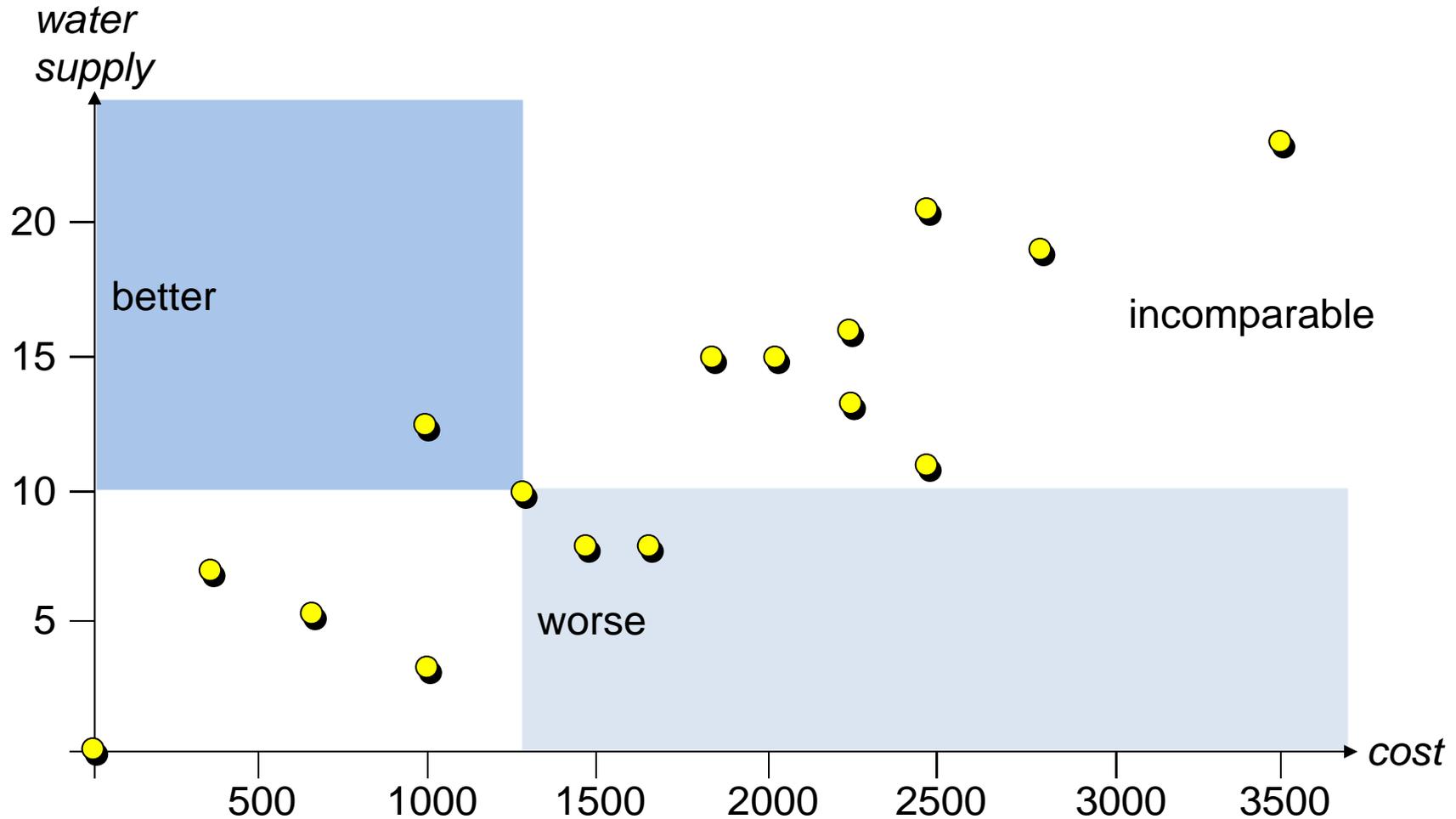
Principles of Multiple Criteria Decision Analysis

A hypothetical problem: all solutions plotted



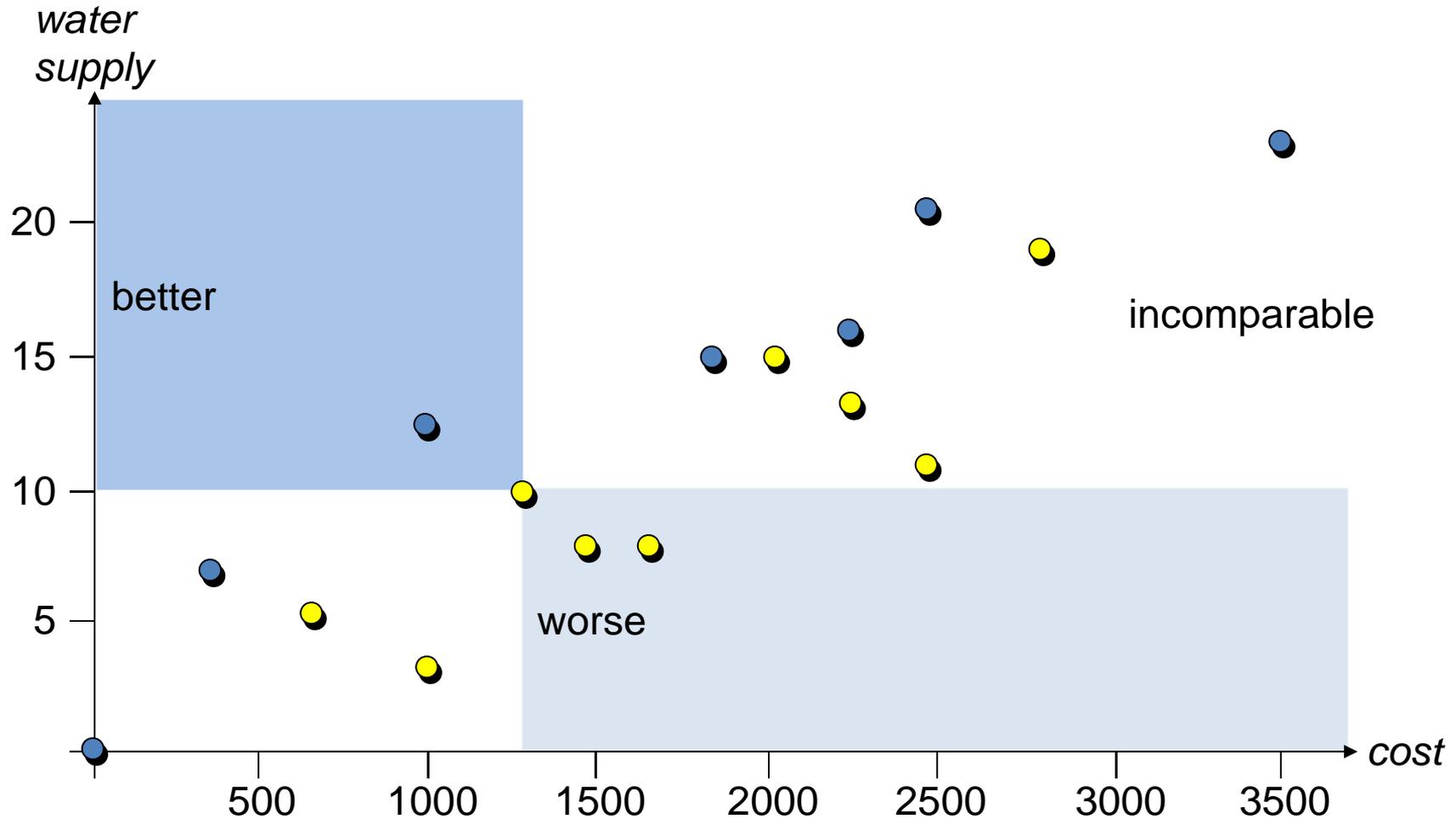
Principles of Multiple Criteria Decision Analysis

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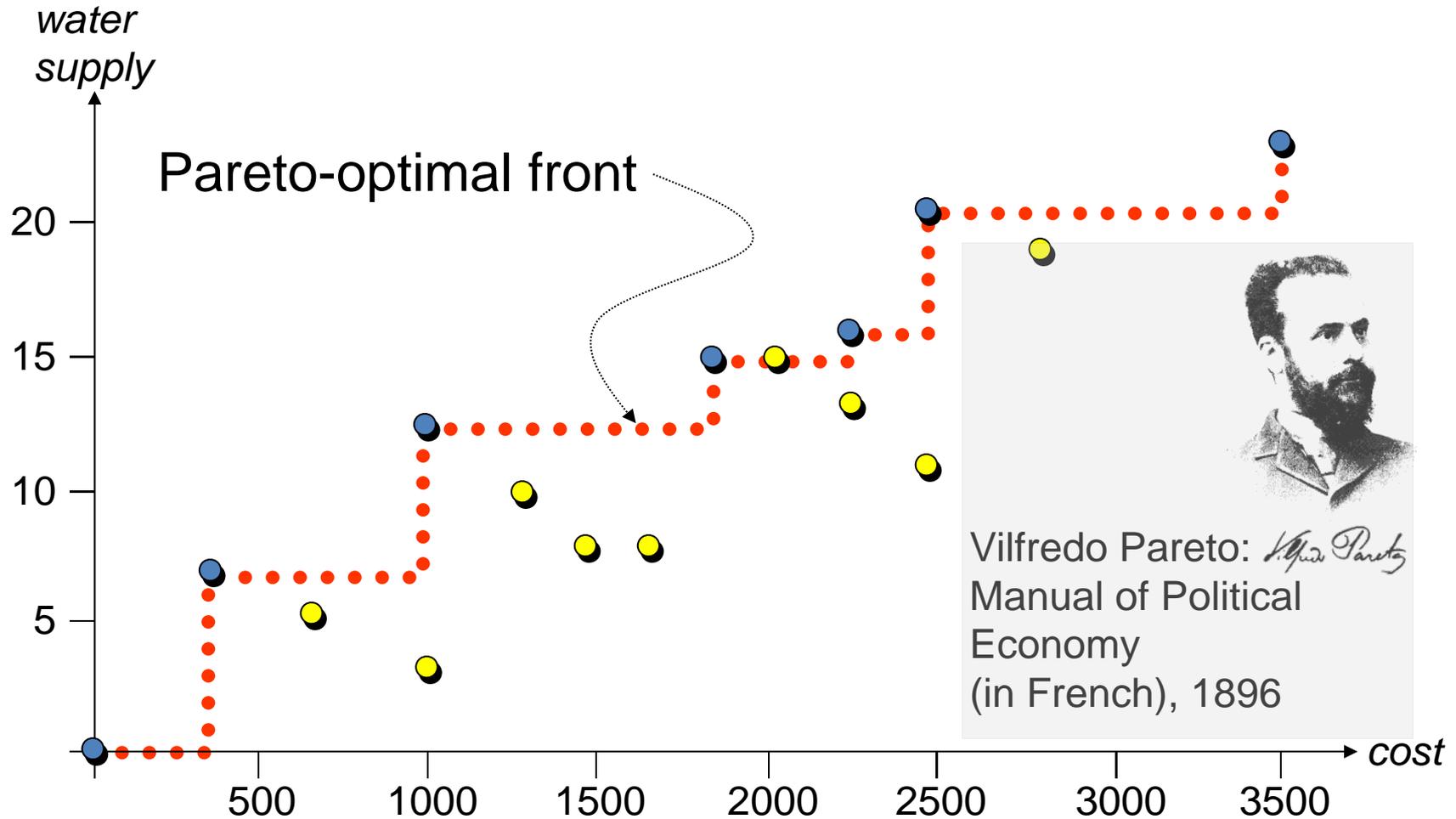
Principles of Multiple Criteria Decision Analysis

- Observations:**
- ❶ there is no single optimal solution, but
 - ❷ some solutions (●) are better than others (●)



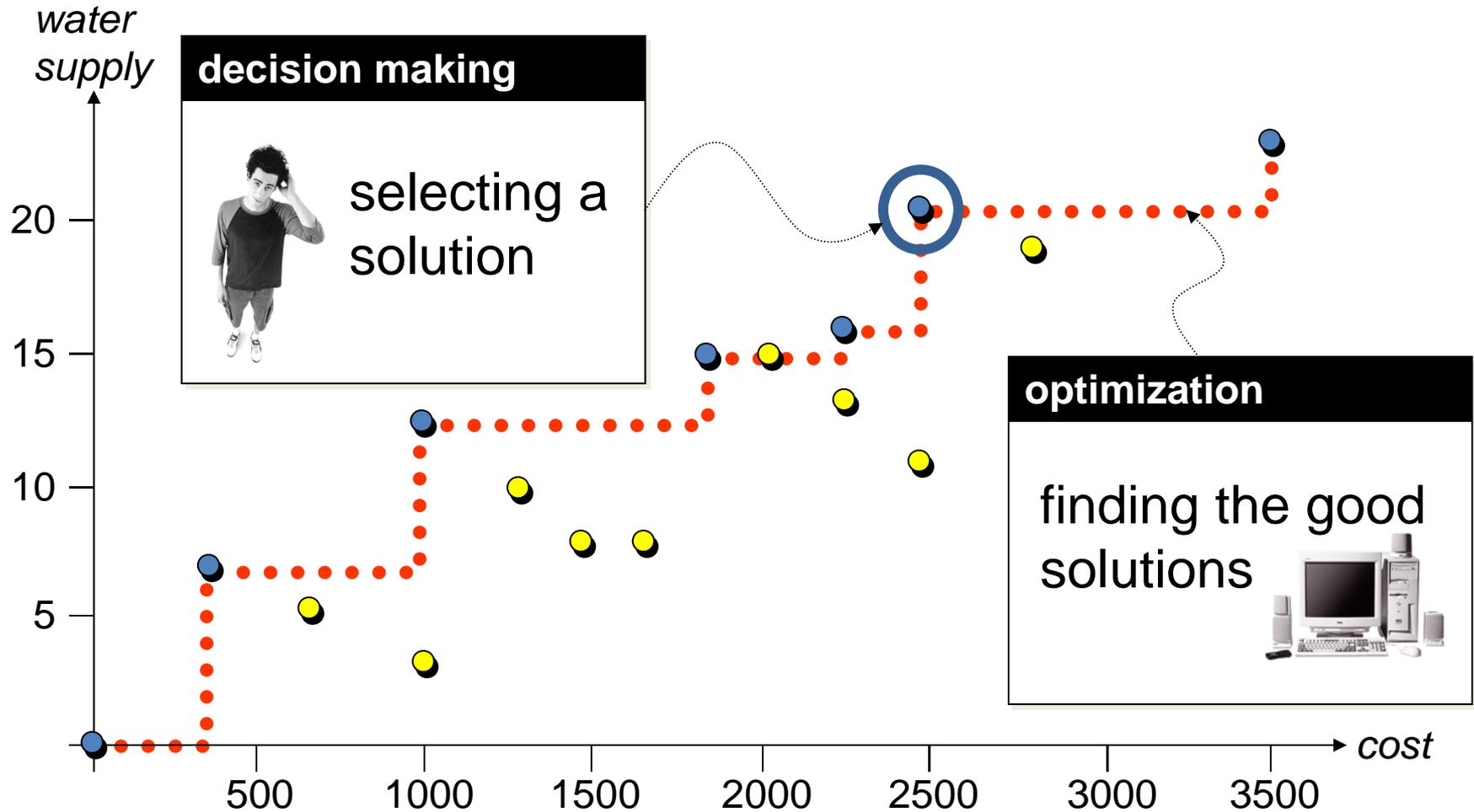
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- Observations:**
- 1 there is no single optimal solution, but
 - 2 some solutions (●) are better than others (●)



Principles of Multiple Criteria Decision Analysis

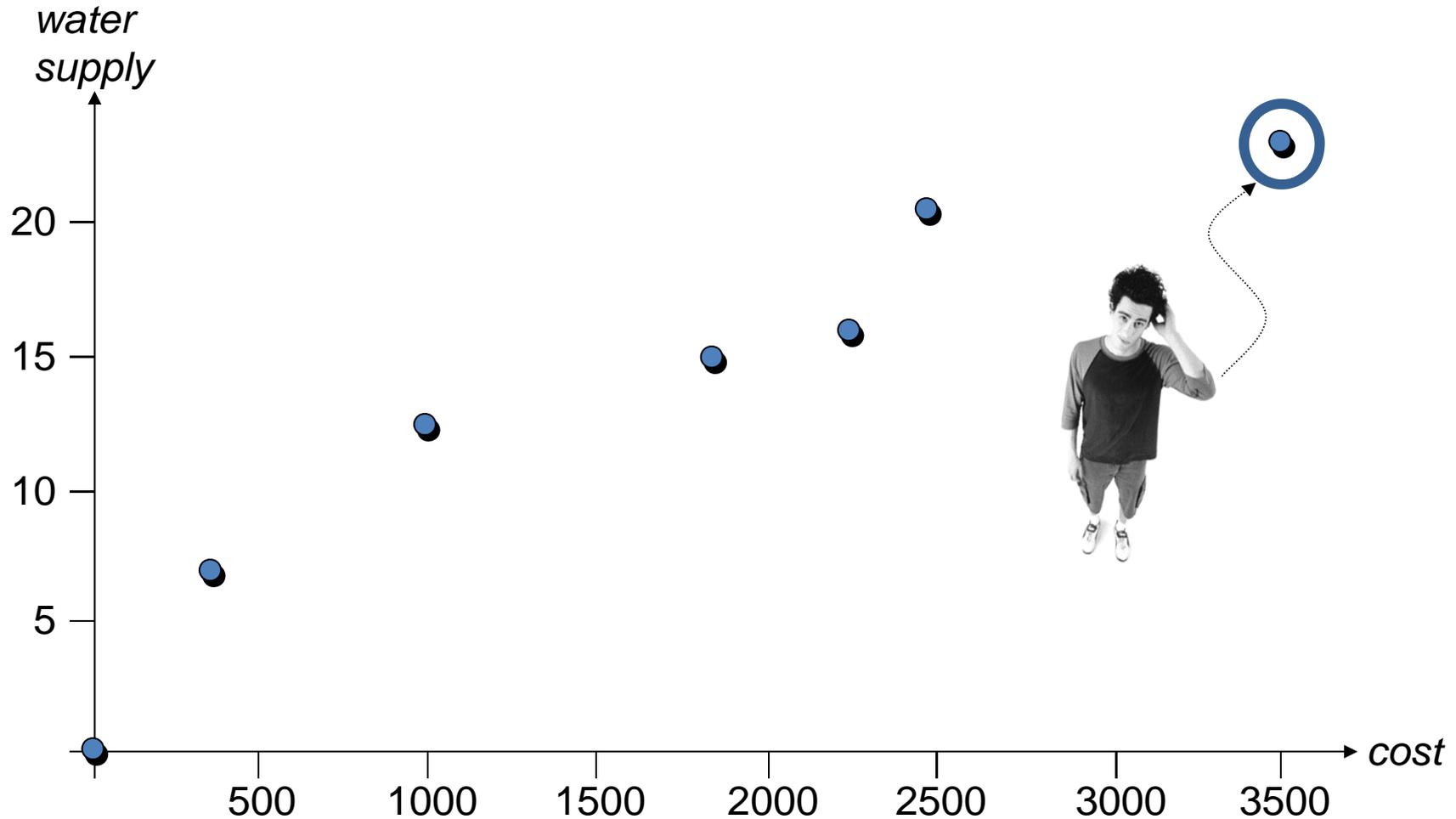
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- 1 there is no single optimal solution, but
 - 2 some solutions (●) are better than others (●)



Decision Making: Selecting a Solution

Possible Approach:

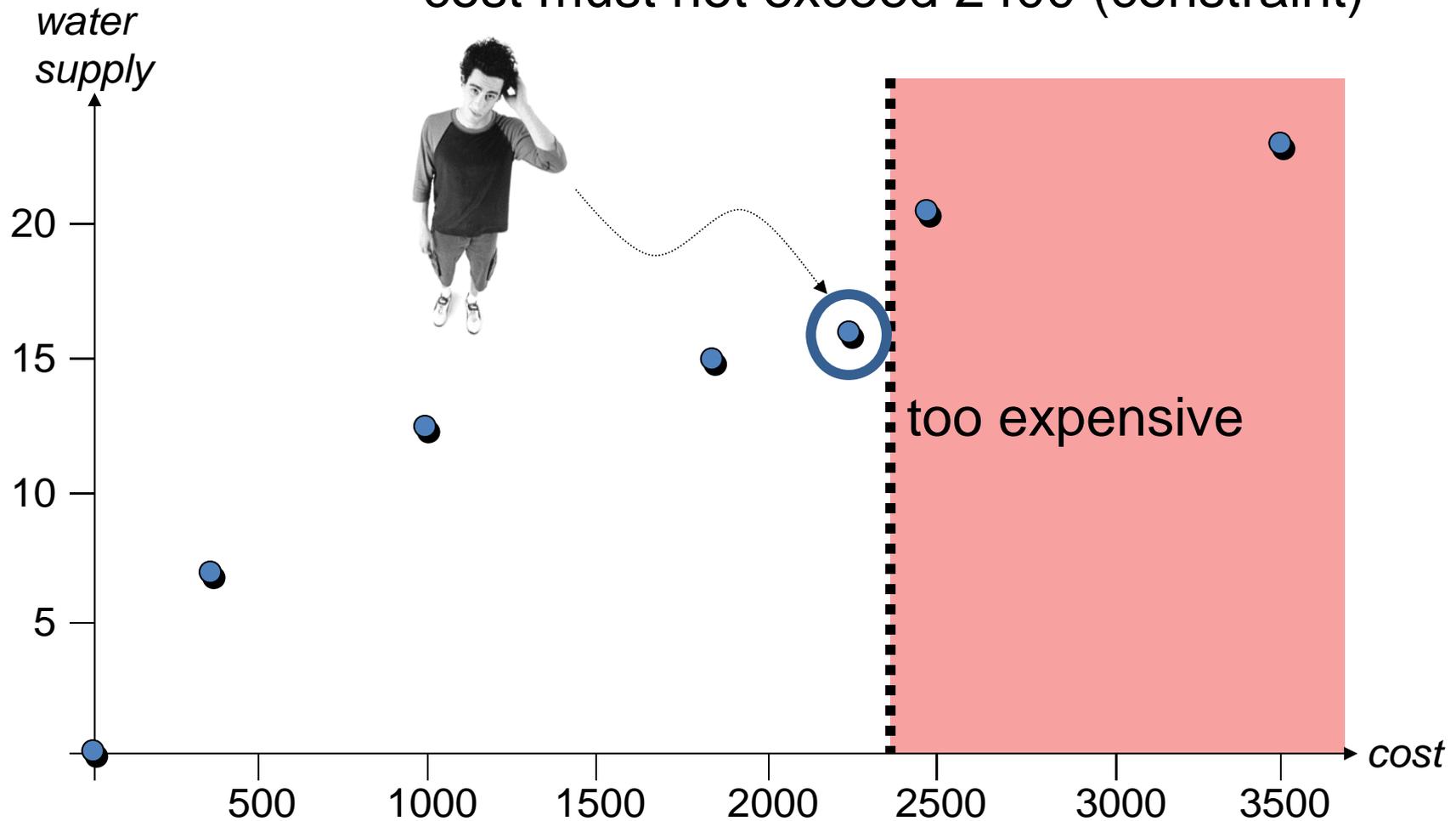
- supply more important than cost (ranking)



Decision Making: Selecting a Solution

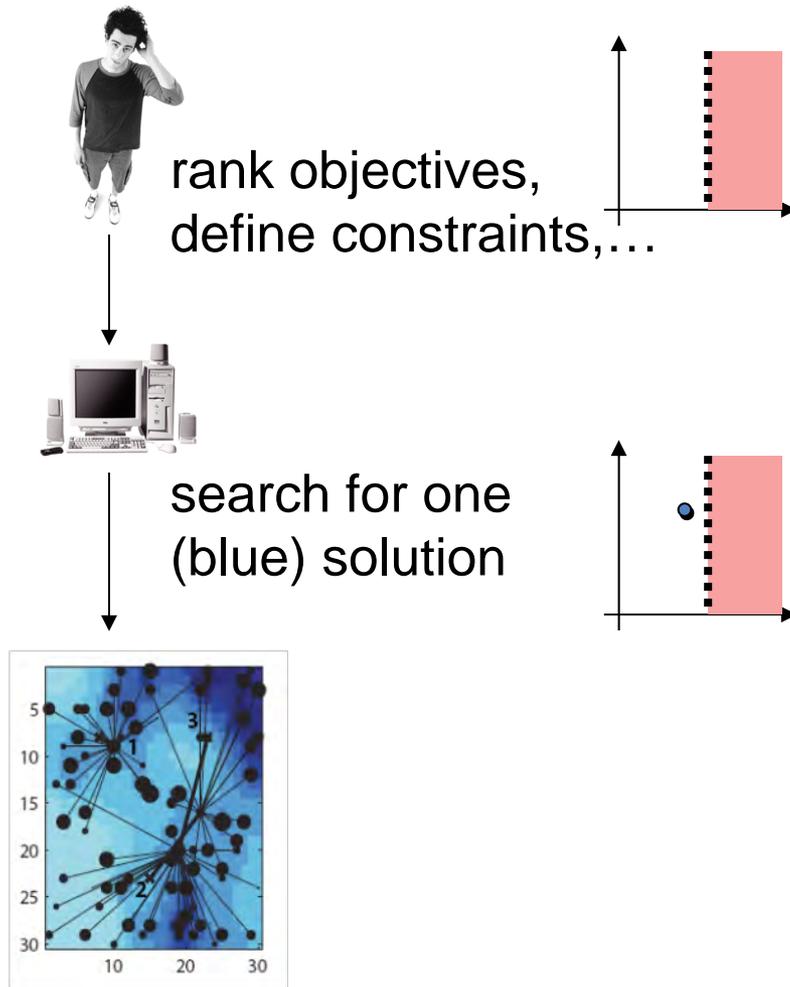
Possible Approach:

- supply more important than cost (ranking)
- cost must not exceed 2400 (constraint)



When to Make the Decision

Before Optimization:

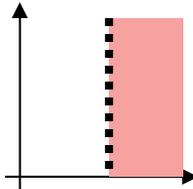


When to Make the Decision

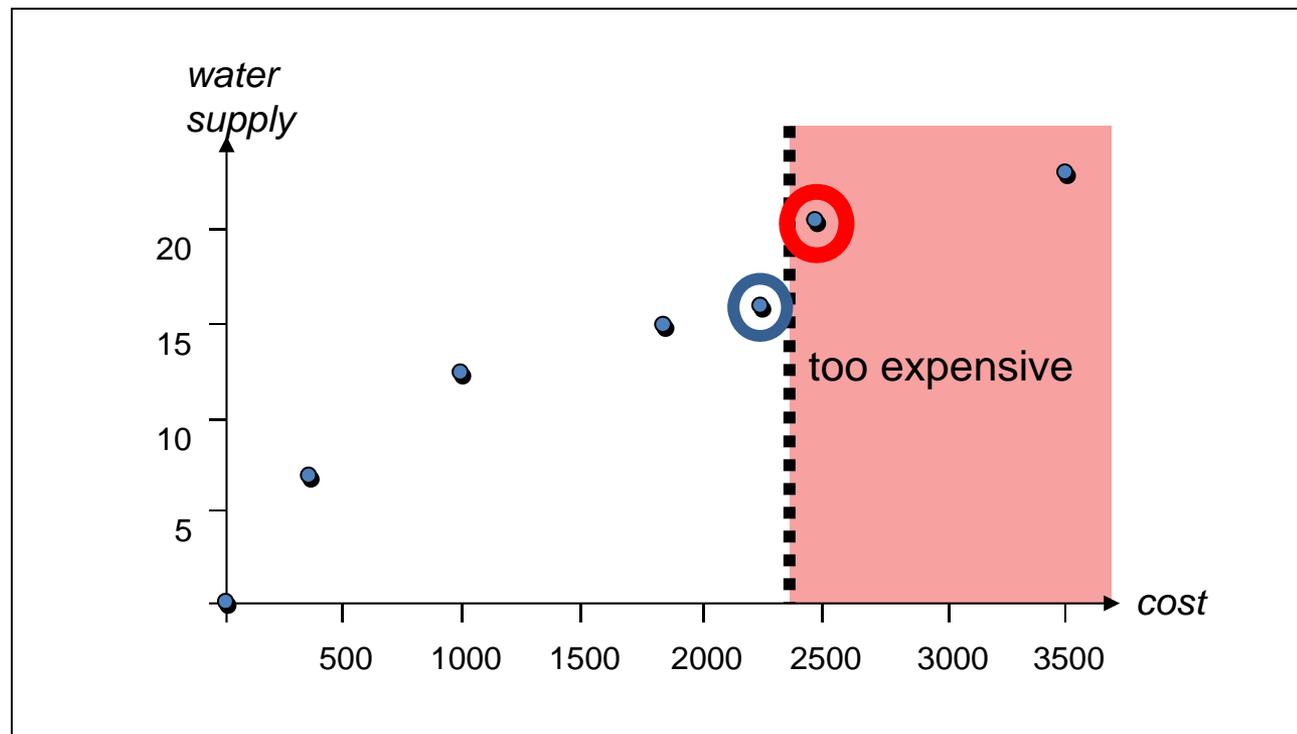
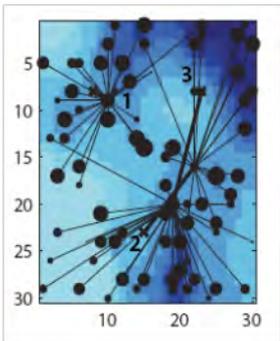
Before Optimization:



rank objectives,
define constraints,...

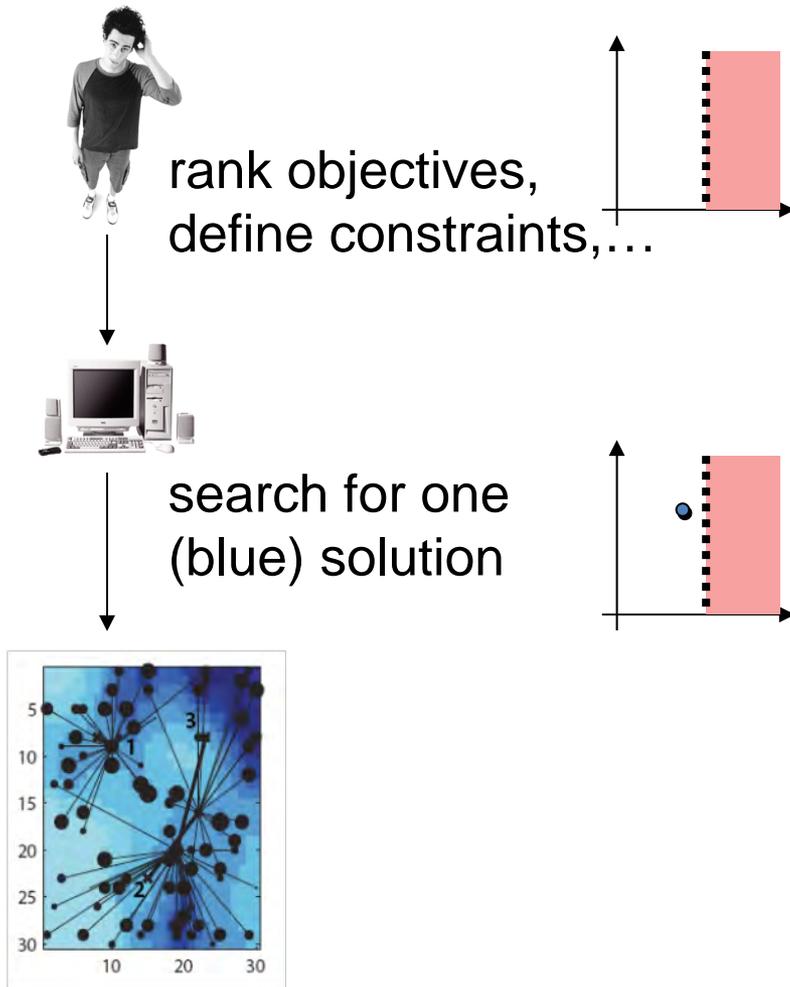


search for one
(blue) solution

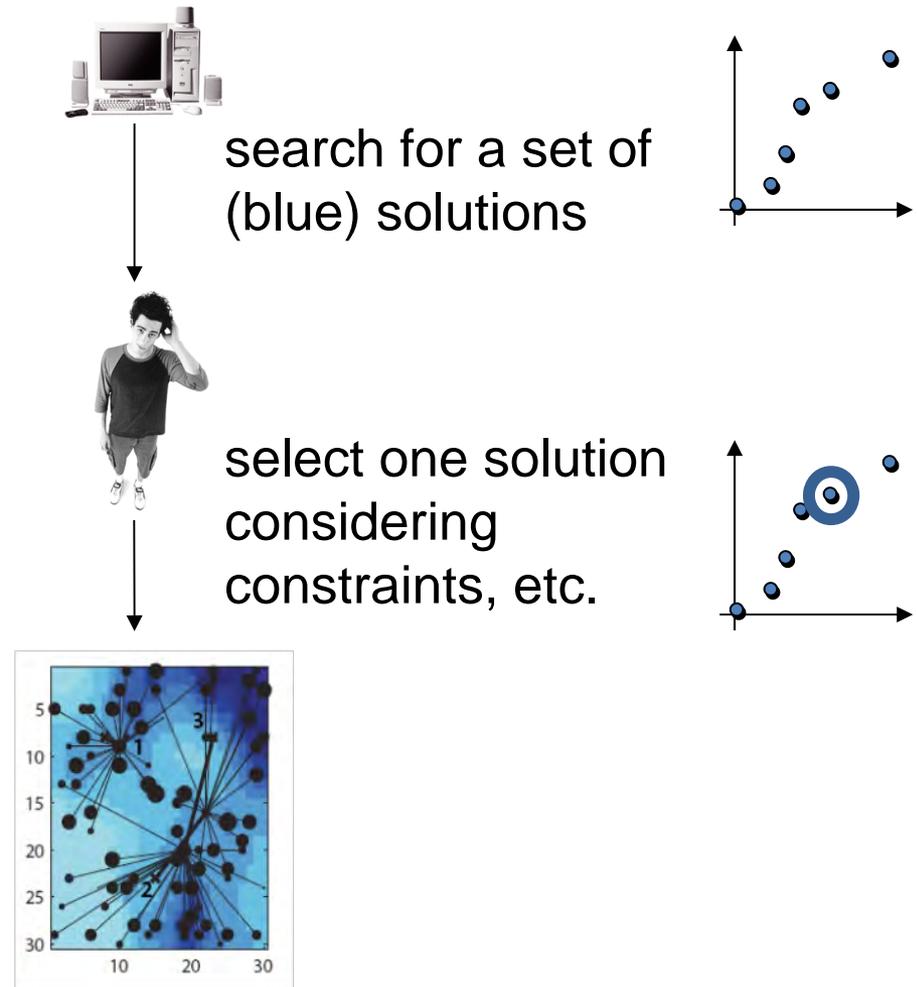


When to Make the Decision

Before Optimization:

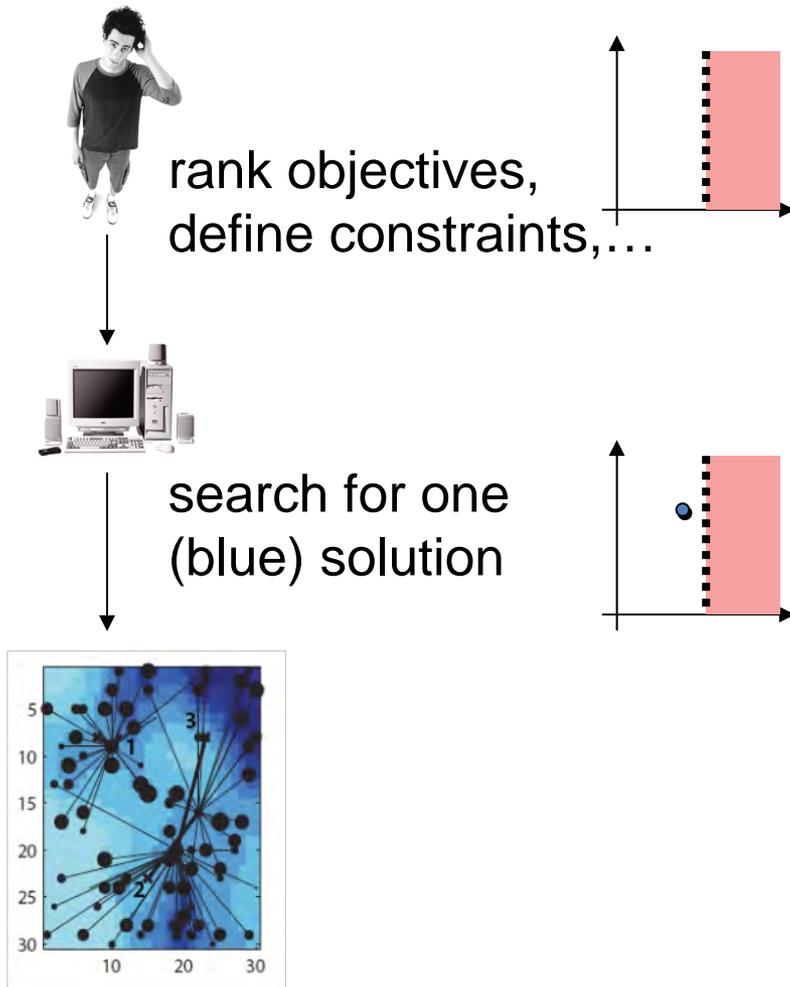


After Optimization:

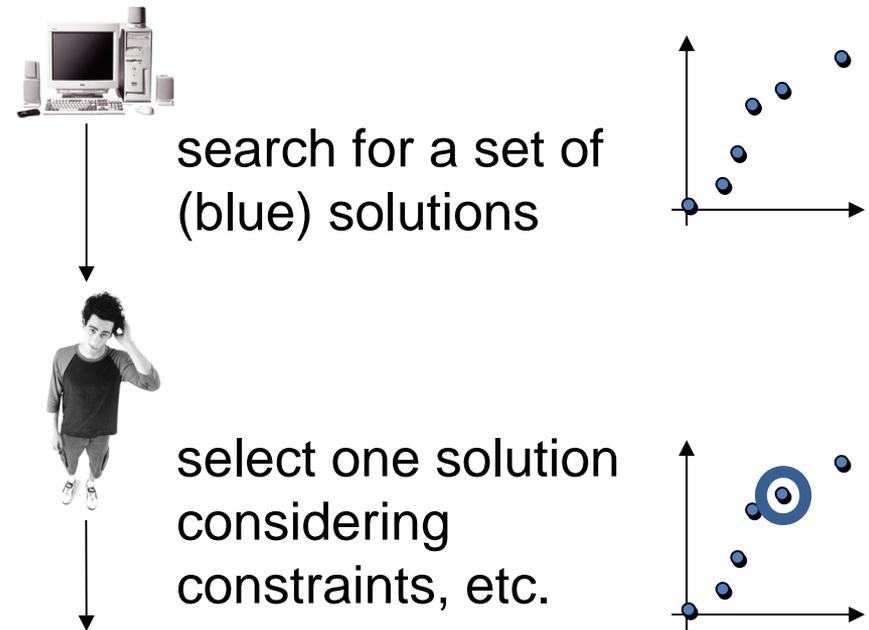


When to Make the Decision

Before Optimization:



After Optimization:



Focus: learning about a problem

- trade-off surface
- interactions among criteria
- structural information

Multiple Criteria Decision Making (MCDM)

Definition: MCDM

MCDM can be defined as the study of methods and procedures by which concerns about multiple conflicting criteria can be formally incorporated into the management planning process



International Society on
Multiple Criteria Decision Making

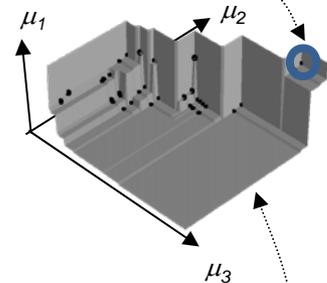


model

$$\begin{aligned} & \min_x [\mu_1(x), \mu_2(x), \dots, \mu_n(x)]^T \\ & \text{s.t.} \\ & g(x) \leq 0 \\ & h(x) = 0 \\ & x_l \leq x \leq x_u \end{aligned}$$

decision making
(exact) optimization

trade-off surface



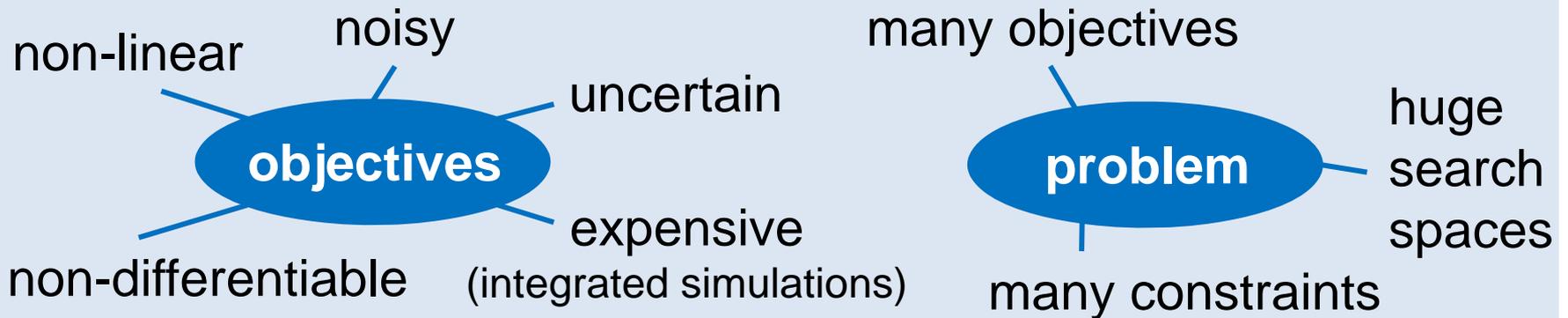
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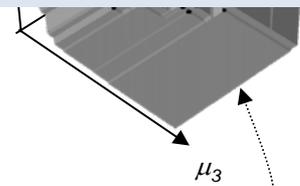


International Society on
Multiple Criteria Decision Making



$$\begin{aligned} g(x) &\leq 0 \\ h(x) &= 0 \\ x_l &\leq x \leq x_u \end{aligned}$$

(~~exact~~) optimization



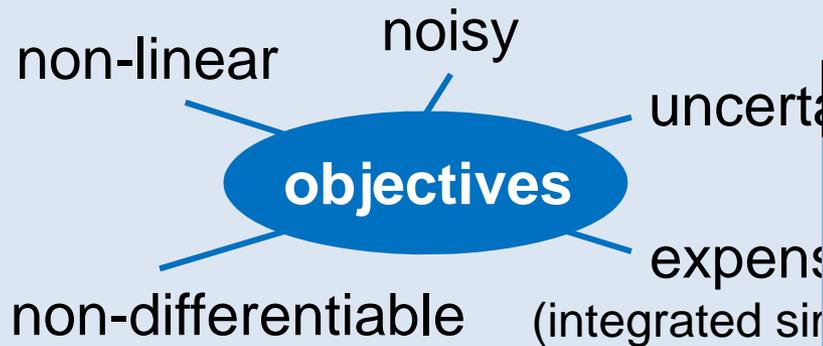
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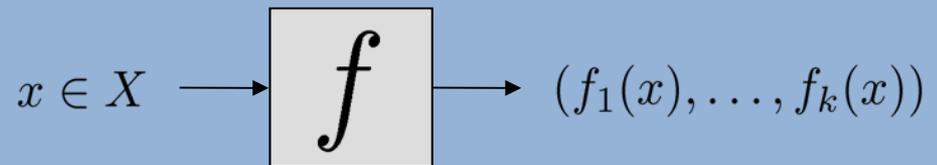


$$\begin{aligned} g(x) &\leq 0 \\ h(x) &= 0 \\ x_l &\leq x \leq x_u \end{aligned}$$

(~~exact~~) optimization

many objectives

Black box optimization



only mild assumptions

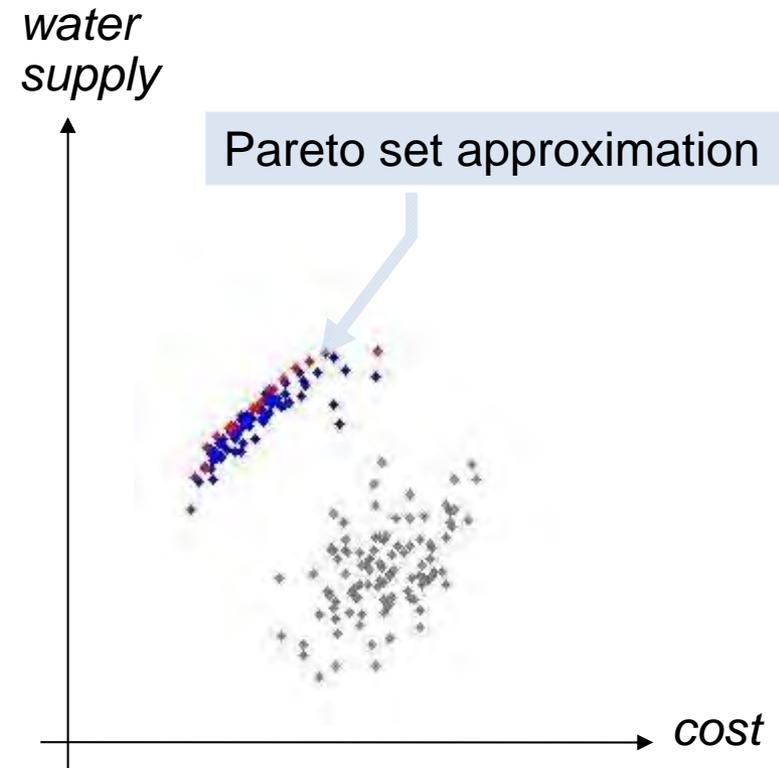
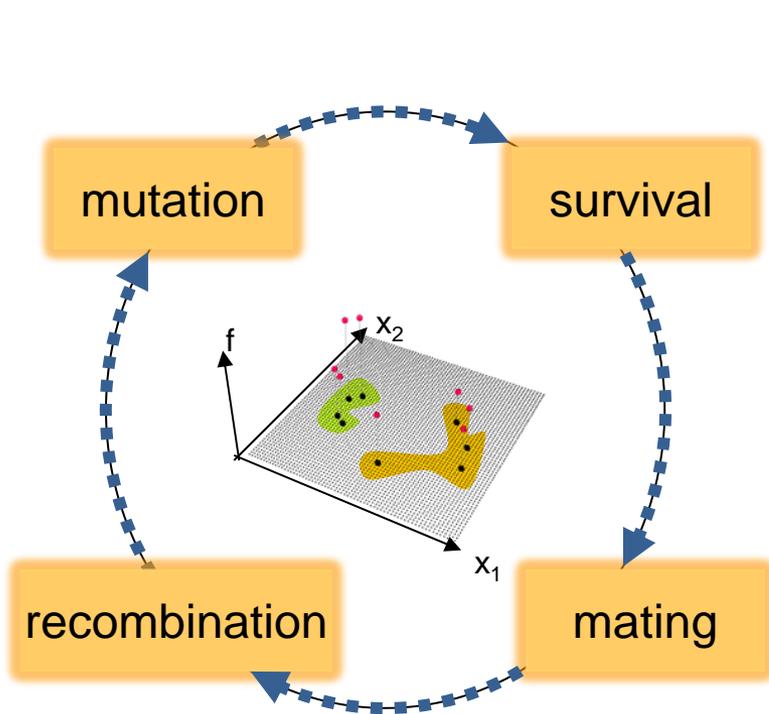


Evolutionary Multiobjective Optimization (EMO)

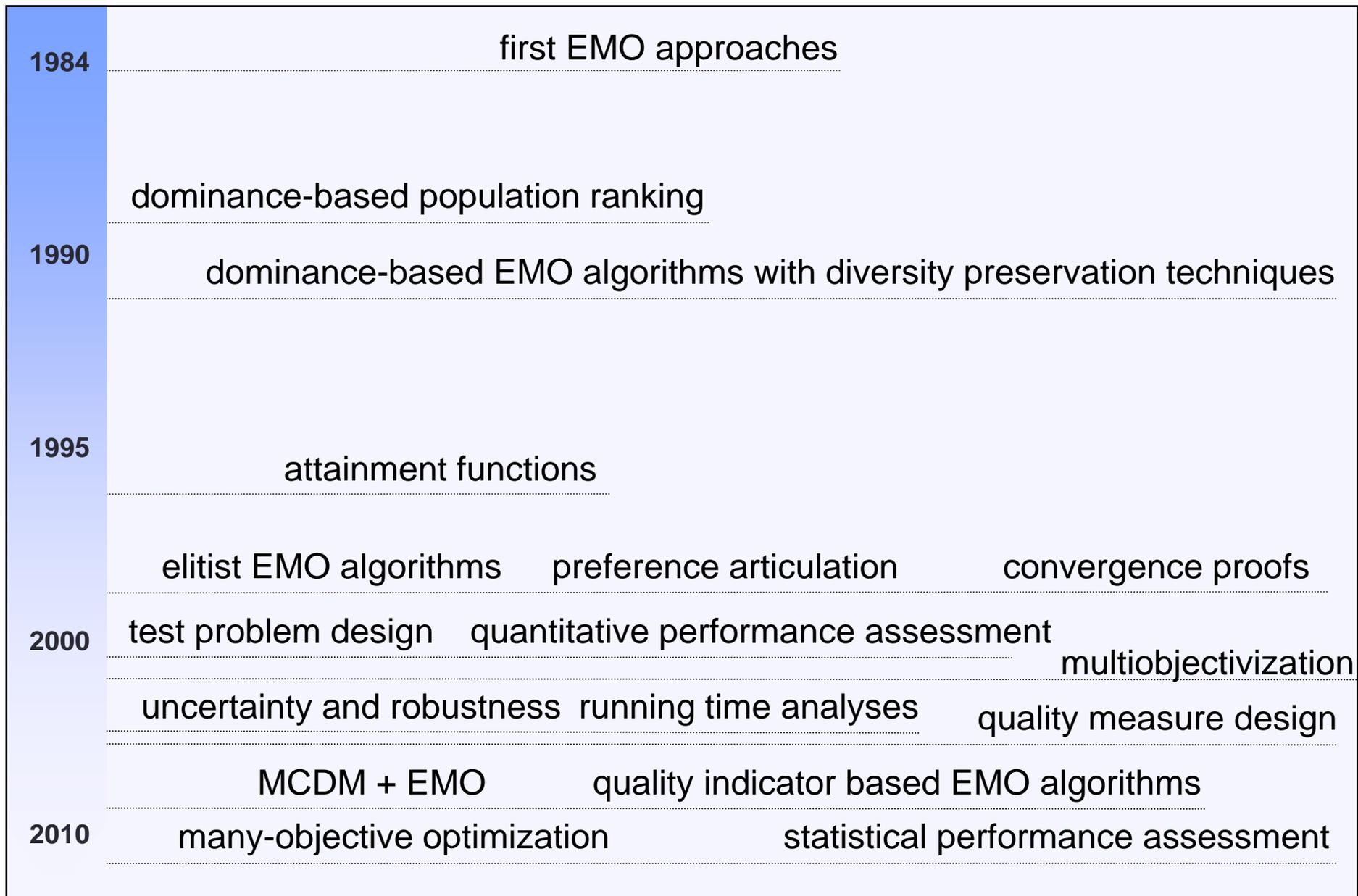
Definition: EMO

EMO = **evolutionary algorithms** / randomized search algorithms

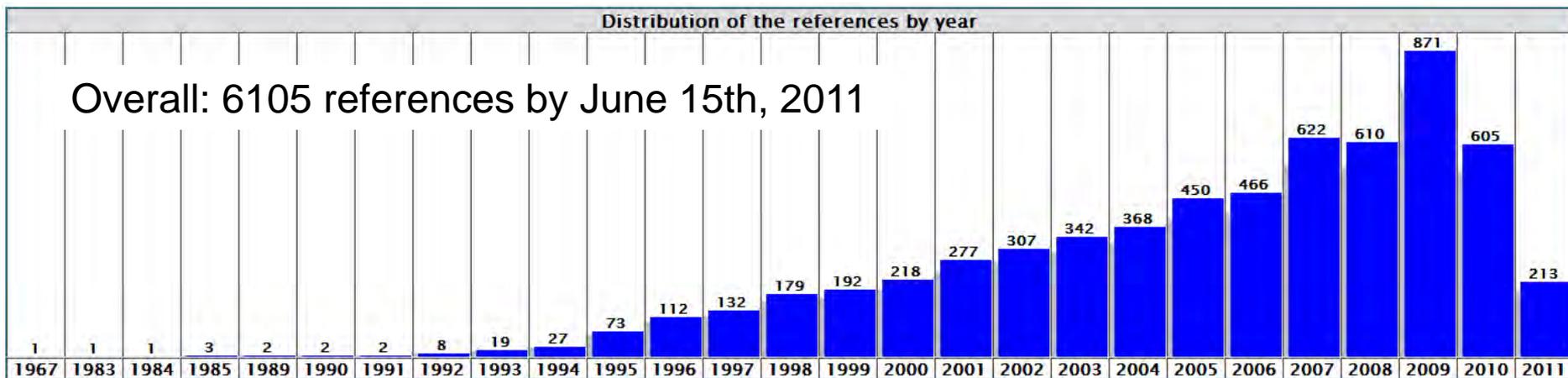
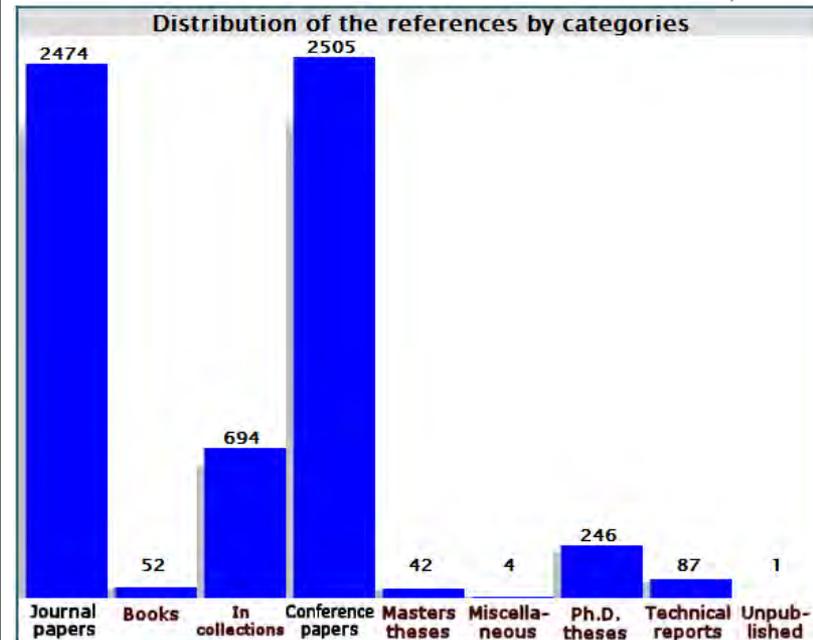
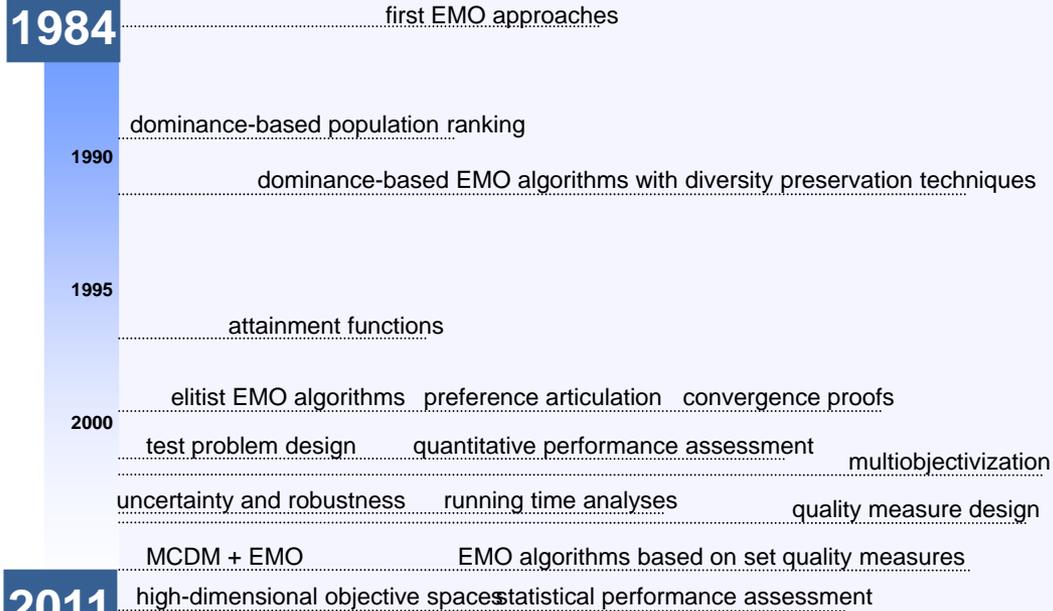
- applied to multiple criteria decision making (in general)
- used to approximate the Pareto-optimal set (mainly)



The History of EMO At A Glance



The History of EMO At A Glance



<http://delta.cs.cinvestav.mx/~ccoello/EMOO/EMOOstatistics.html>

The EMO Community

The EMO conference series:

EMO2001	EMO2003	EMO2005	EMO2007	EMO2009	EMO2011	EMO2013
Zurich	Faro	Guanajuato	Matsushima	Nantes	Ouro Preto	Sheffield
Switzerland	Portugal	Mexico	Japan	France	Brazil	UK



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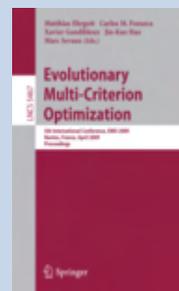
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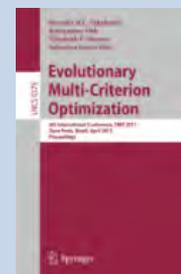
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39/72



42/83

?

Many further activities:

special sessions, special journal issues, workshops, tutorials, ...

A Brief Introduction to EMO

- basics: what is the difference between single- and multiobjective optimization?
- state-of-the-art algorithm design concepts
- performance assessment

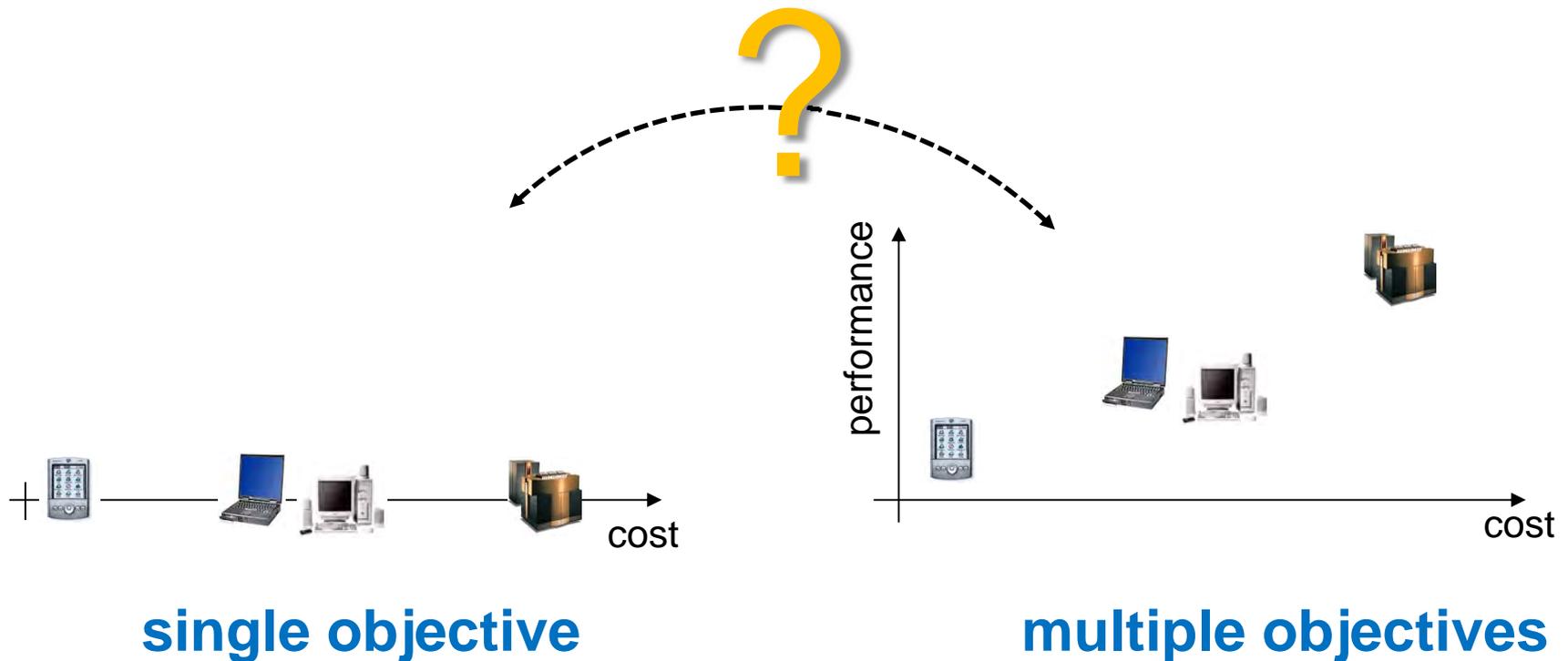
Advanced Concepts Useful in Practice

- objective reduction
- multiobjectivization
- innovization

Examples of Applications

Starting Point

What makes evolutionary multiobjective optimization different from single-objective optimization?



A General (Multiobjective) Optimization Problem

A *multiobjective optimization problem* is defined by a 5-tuple $(X, Z, \mathbf{f}, \mathbf{g}, \leq)$ where

- X is the decision space,
- $Z = \mathbb{R}^n$ is the objective space,
- $\mathbf{f} = (f_1, \dots, f_n)$ is a vector-valued function consisting of n objective functions $f_i : X \mapsto \mathbb{R}$,
- $\mathbf{g} = (g_1, \dots, g_m)$ is a vector-valued function consisting of m constraint functions $g_i : X \mapsto \mathbb{R}$, and
- $\leq \subseteq Z \times Z$ is a binary relation on the objective space.

The goal is to identify a decision vector $\mathbf{a} \in X$ such that (i) for all $1 \leq i \leq m$ holds $g_i(\mathbf{a}) \leq 0$ and (ii) for all $\mathbf{b} \in X$ holds $\mathbf{f}(\mathbf{b}) \leq \mathbf{f}(\mathbf{a}) \Rightarrow \mathbf{f}(\mathbf{a}) \leq \mathbf{f}(\mathbf{b})$.

Single-Objective Optimization As Special Case

decision space

objective space

objective function

$(X, Z, f: X \rightarrow Z, rel \subseteq Z \times Z)$

total order \leq on \mathbb{R}

Single-Objective Optimization As Special Case

decision space

objective space

objective function

$$(X, Z, f: X \rightarrow Z, \text{rel} \subseteq Z \times Z)$$

total order \leq on \mathbb{R}

$$(X, \text{prefrel})$$

total preorder where
 $a \text{ prefrel } b \Leftrightarrow f(a) \text{ rel } f(b)$

Preference Relations in the Multiobjective Case

decision space

objective space

objective functions

$$(X, Z, f: X \rightarrow Z, \text{rel} \subseteq Z \times Z)$$

partial order

$$(X, \text{prefrel})$$

preorder where
 $a \text{ prefrel } b : \Leftrightarrow f(a) \text{ rel } f(b)$

most of the time **not** total!

$$(X, \preceq_{par})$$

$$a \preceq_{par} b : \Leftrightarrow f(a) \leq_{par} f(b)$$

Example:

weak

Pareto dominance

Pareto Dominance

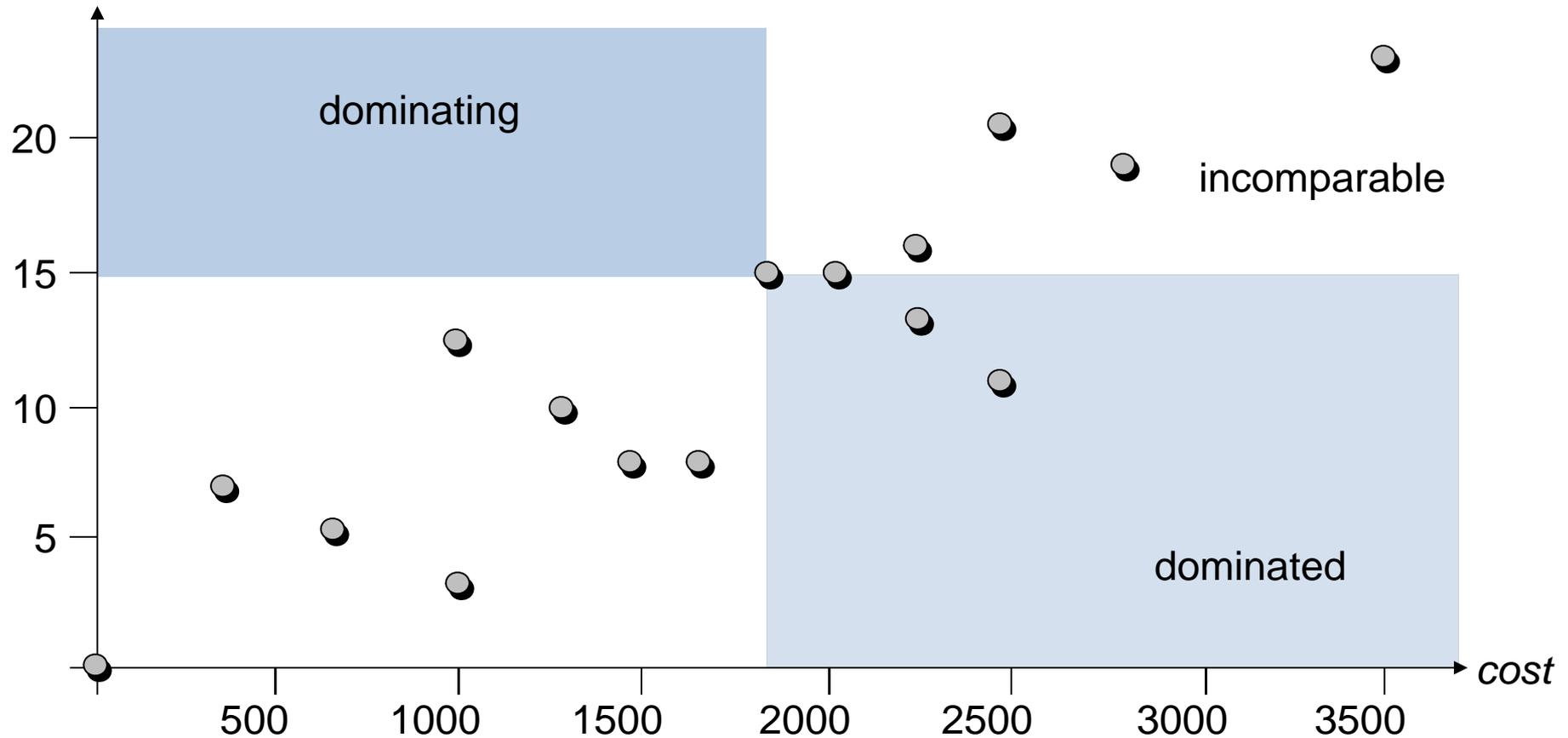
(u_1, \dots, u_n) weakly Pareto dominates (v_1, \dots, v_n) :

$$(u_1, \dots, u_n) \leq_{\text{par}} (v_1, \dots, v_n) :\Leftrightarrow \forall 1 \leq i \leq n : u_i \leq v_i$$

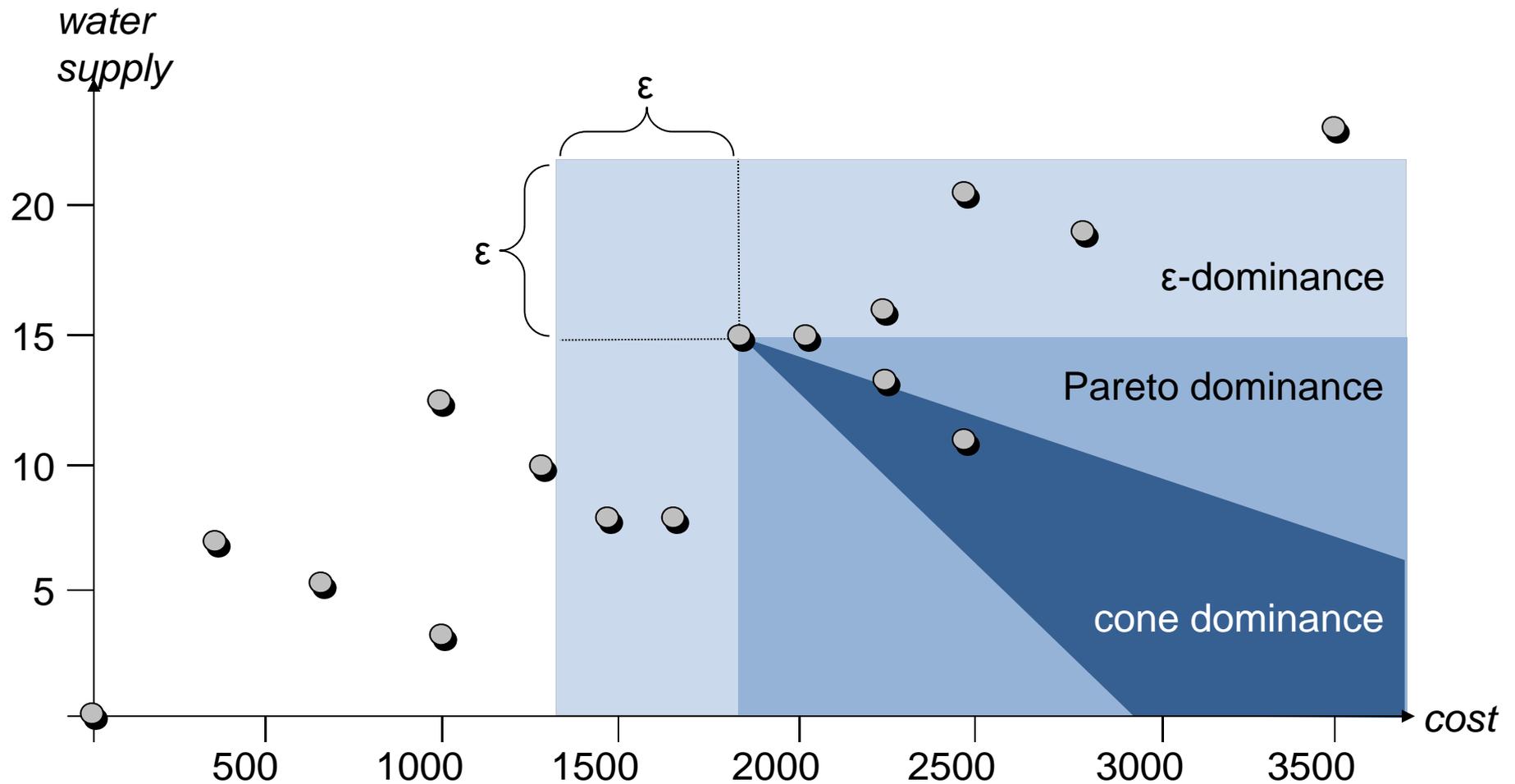
water
supply

(u_1, \dots, u_n) Pareto dominates (v_1, \dots, v_n) :

$$(u_1, \dots, u_n) \leq_{\text{par}} (v_1, \dots, v_n) \wedge (v_1, \dots, v_n) \not\leq_{\text{par}} (u_1, \dots, u_n)$$



Different Notions of Dominance



The Pareto-optimal Set

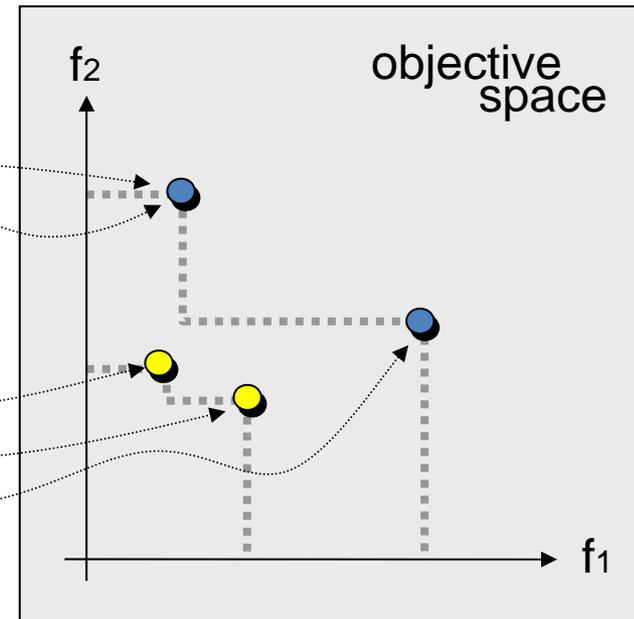
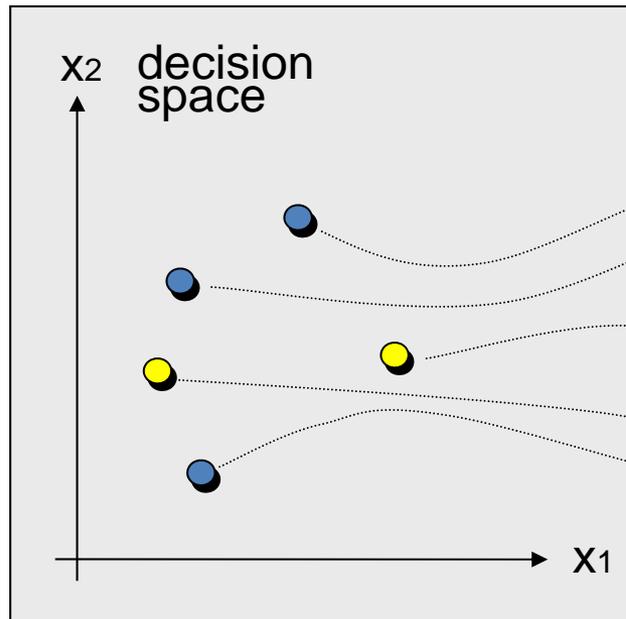
The *minimal set* of a preordered set (Y, \leq) is defined as

$$\text{Min}(Y, \leq) := \{a \in Y \mid \forall b \in Y : b \leq a \Rightarrow a \leq b\}$$

Pareto-optimal set $\text{Min}(X, \preceq_{par})$
non-optimal decision vector



Pareto-optimal front
non-optimal objective vector



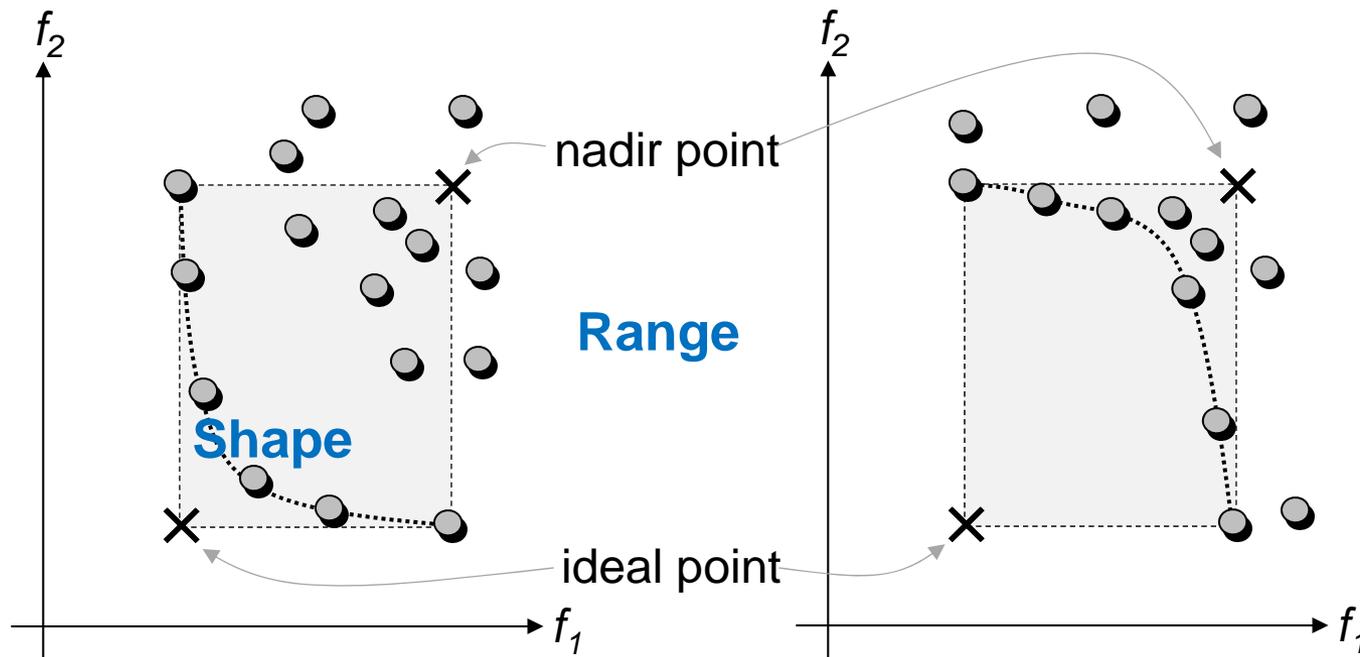
Remark: Properties of the Pareto Set

Computational complexity:

multiobjective variants can become NP- and #P-complete

Size:

Pareto set can be exponential in the input length
(e.g. shortest path [Serafini 1986], MST [Camerini et al. 1984])



Approaches To Multiobjective Optimization

A multiobjective problem is as such underspecified
...because not any Pareto-optimum is equally suited!

Additional preferences are needed to tackle the problem:

Solution-Oriented Problem Transformation:

Induce a total order on the decision space, e.g., by aggregation.

Set-Oriented Problem Transformation:

First transform problem into a set problem and then define an objective function on sets.

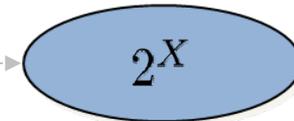
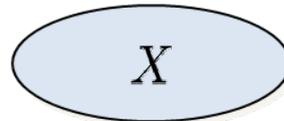
Preferences are needed in any case, but the latter are weaker!

Problem Transformations and Set Problems

single solution problem

set problem

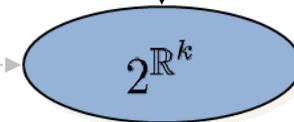
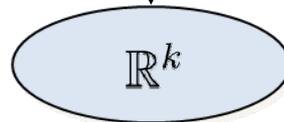
search space



$$f(x) = (f_1(x), f_2(x), \dots, f_k(x))$$

$$f^*(A) = \{f(x) \mid x \in A\}$$

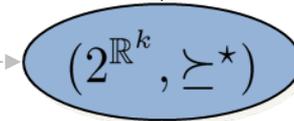
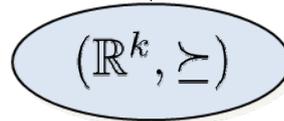
objective space



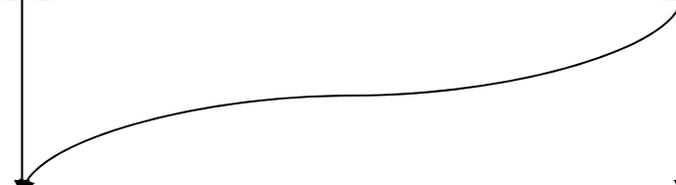
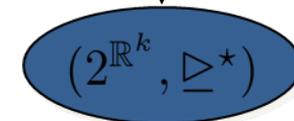
$$x \succeq y \Leftrightarrow \forall_i f_i(x) \geq f_i(y)$$

$$A \succeq^* B \Leftrightarrow \forall_{y \in B} \exists_{x \in A} x \succeq y$$

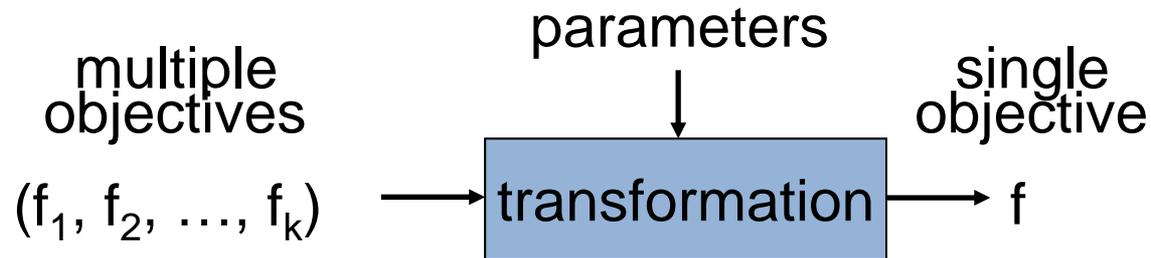
(partially) ordered set



(totally) ordered set

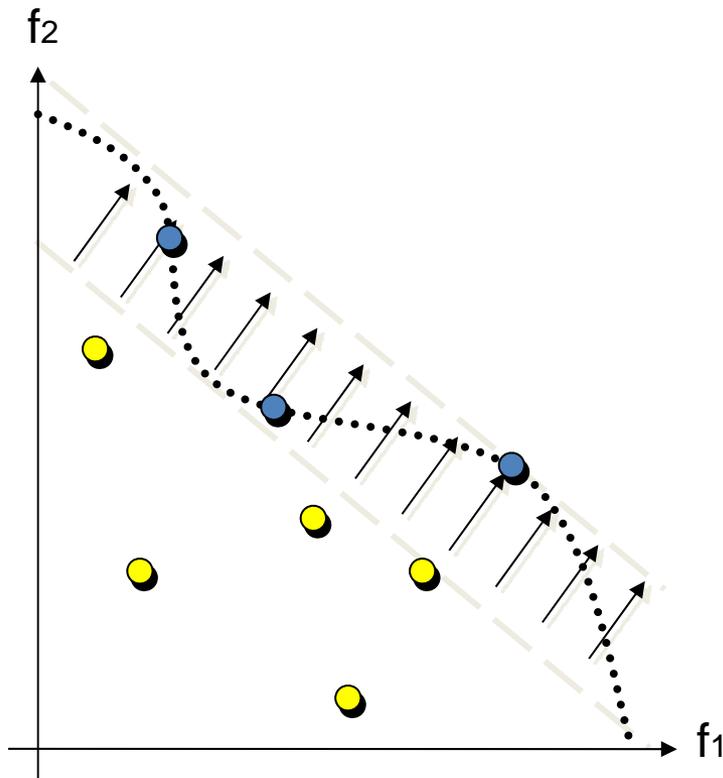
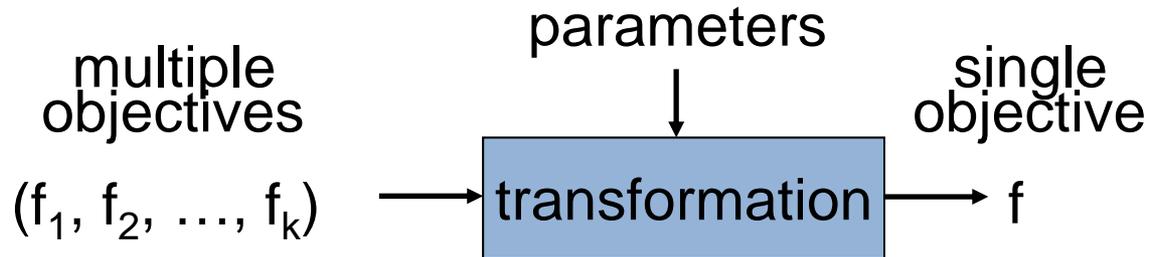


Solution-Oriented Problem Transformations

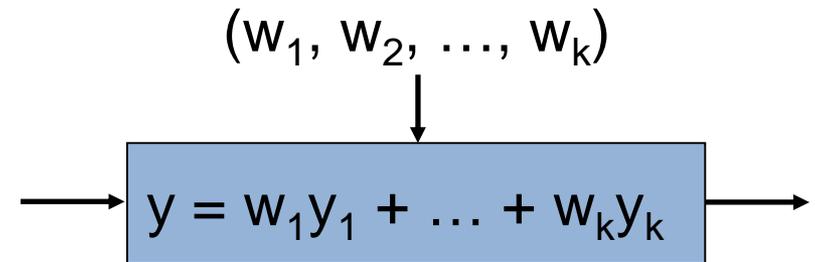


A *scalarizing function* s is a function $s : Z \mapsto \mathbb{R}$ that maps each objective vector $(u_1, \dots, u_n) \in Z$ to a real value $s(u_1, \dots, u_n) \in \mathbb{R}$.

Aggregation-Based Approaches



Example: weighting approach



Other example: Tchebycheff

$$y = \max w_i (u_i - z_i)$$

Set-Oriented Problem Transformations

For a multiobjective optimization problem $(X, Z, \mathbf{f}, \mathbf{g}, \leq)$, the associated *set problem* is given by $(\Psi, \Omega, F, \mathbf{G}, \preceq)$ where

- $\Psi = 2^X$ is the space of decision vector sets, i.e., the powerset of X ,
- $\Omega = 2^Z$ is the space of objective vector sets, i.e., the powerset of Z ,
- F is the extension of \mathbf{f} to sets, i.e.,
 $F(A) := \{\mathbf{f}(\mathbf{a}) : \mathbf{a} \in A\}$ for $A \in \Psi$,
- $\mathbf{G} = (G_1, \dots, G_m)$ is the extension of \mathbf{g} to sets, i.e., $G_i(A) := \max \{g_i(\mathbf{a}) : \mathbf{a} \in A\}$ for $1 \leq i \leq m$ and $A \in \Psi$,
- \preceq extends \leq to sets where
 $A \preceq B :\Leftrightarrow \forall \mathbf{b} \in B \exists \mathbf{a} \in A : \mathbf{a} \leq \mathbf{b}$.

Another approach:
define relation via
quality indicators

Quality of Pareto Set Approximations

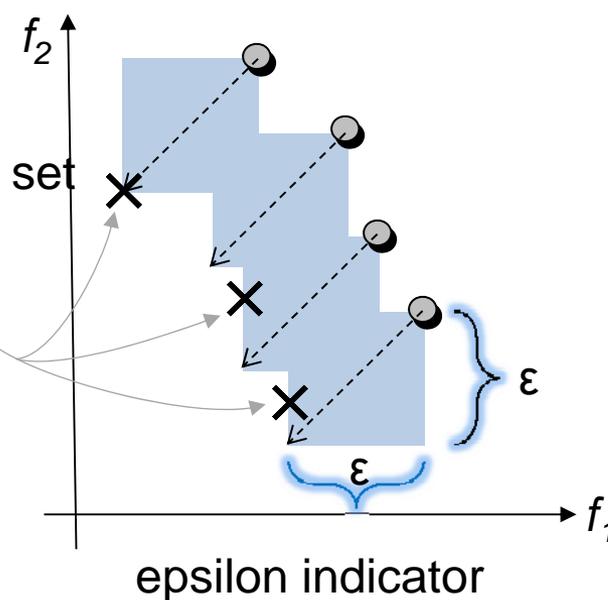
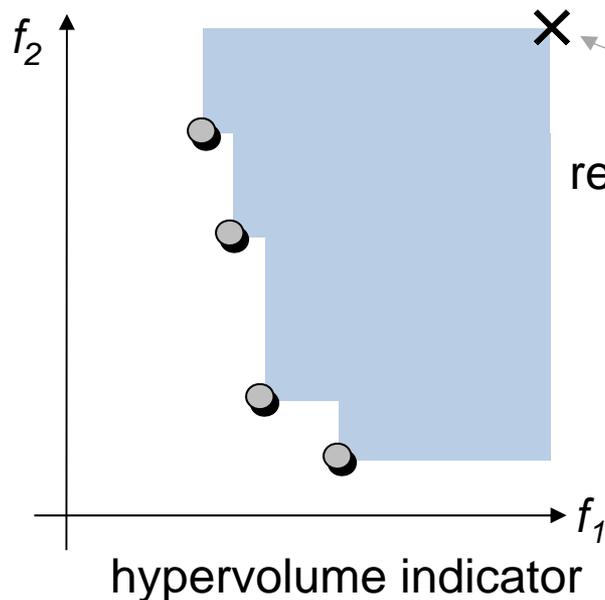
A (unary) *quality indicator* I is a function $I : \Psi \mapsto \mathbb{R}$ that assigns a Pareto set approximation a real value.

$$A \stackrel{\text{ref}}{\preceq} B :\Leftrightarrow I(A) \geq I(B)$$

$$A \stackrel{\text{ref}}{\preceq} B :\Leftrightarrow I(A, R) \leq I(B, R)$$

$I(A)$ = volume of weakly dominated area in objective space

$I(A, R)$ = how much needs A to be moved to weakly dominate R



Refinements

Not all preference relations are useful...

\succsim^{ref} **refines** the weak dominance relation \succsim iff

$$A \succsim B \wedge B \not\succeq A \Rightarrow A \succsim^{\text{ref}} B \wedge B \not\succeq^{\text{ref}} A \quad (\text{better} \Rightarrow \text{better})$$

...sought are total refinements

such as the hypervolume indicator

A Brief Introduction to EMO

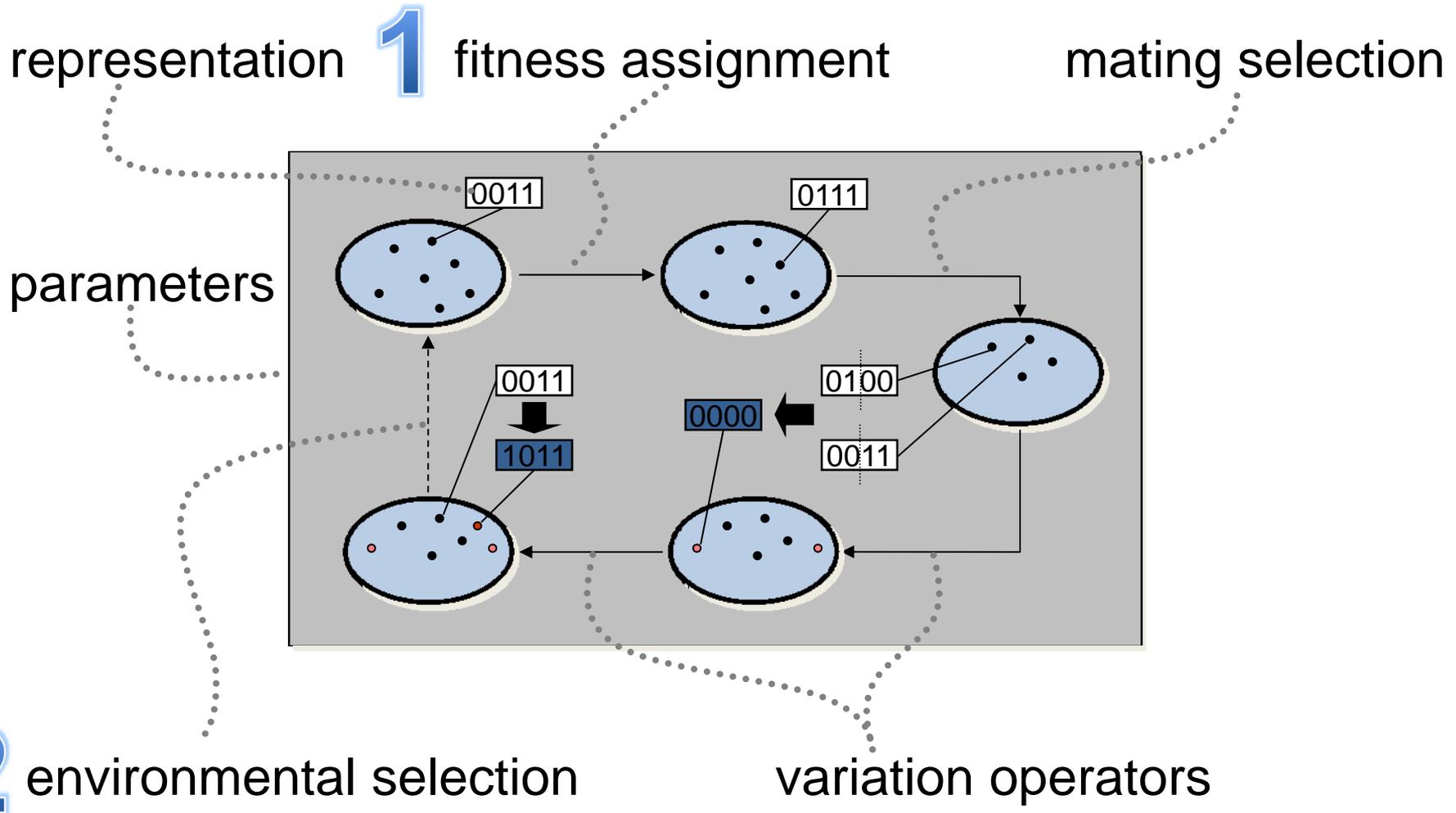
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Advanced Concepts Useful in Practice

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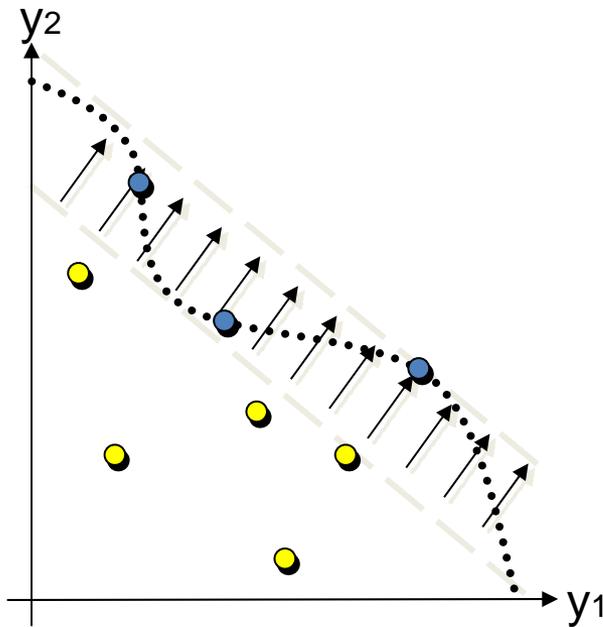
Examples of Applications

Algorithm Design: Particular Aspects

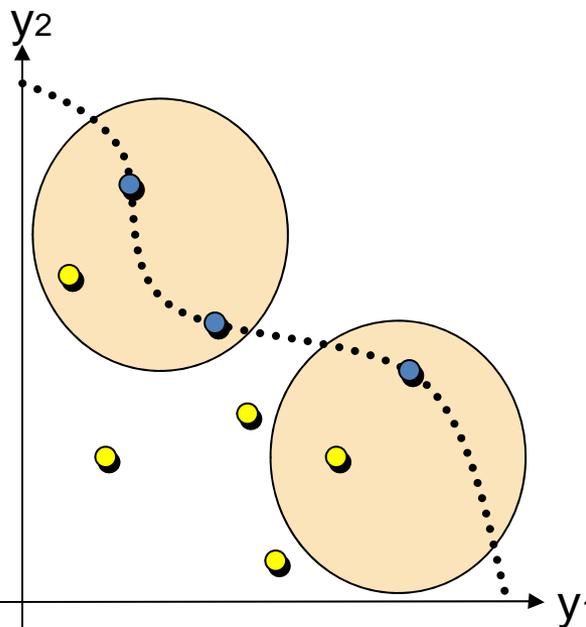


Fitness Assignment: Principal Approaches

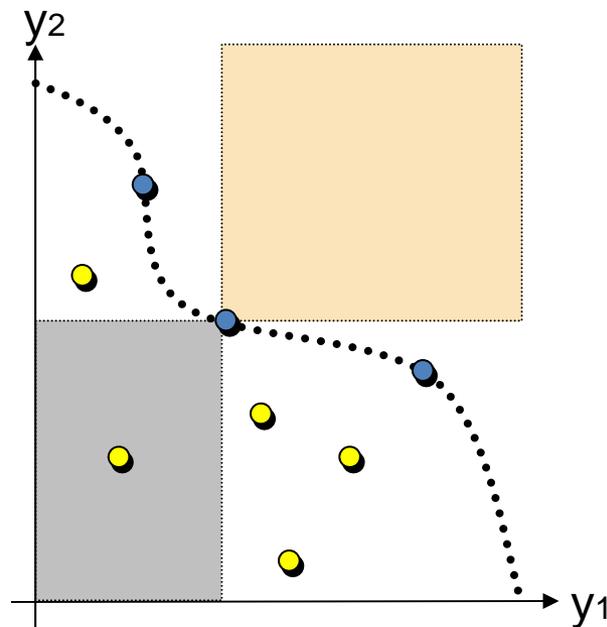
aggregation-based
weighted sum



criterion-based
VEGA



dominance-based
SPEA2



parameter-oriented
scaling-dependent



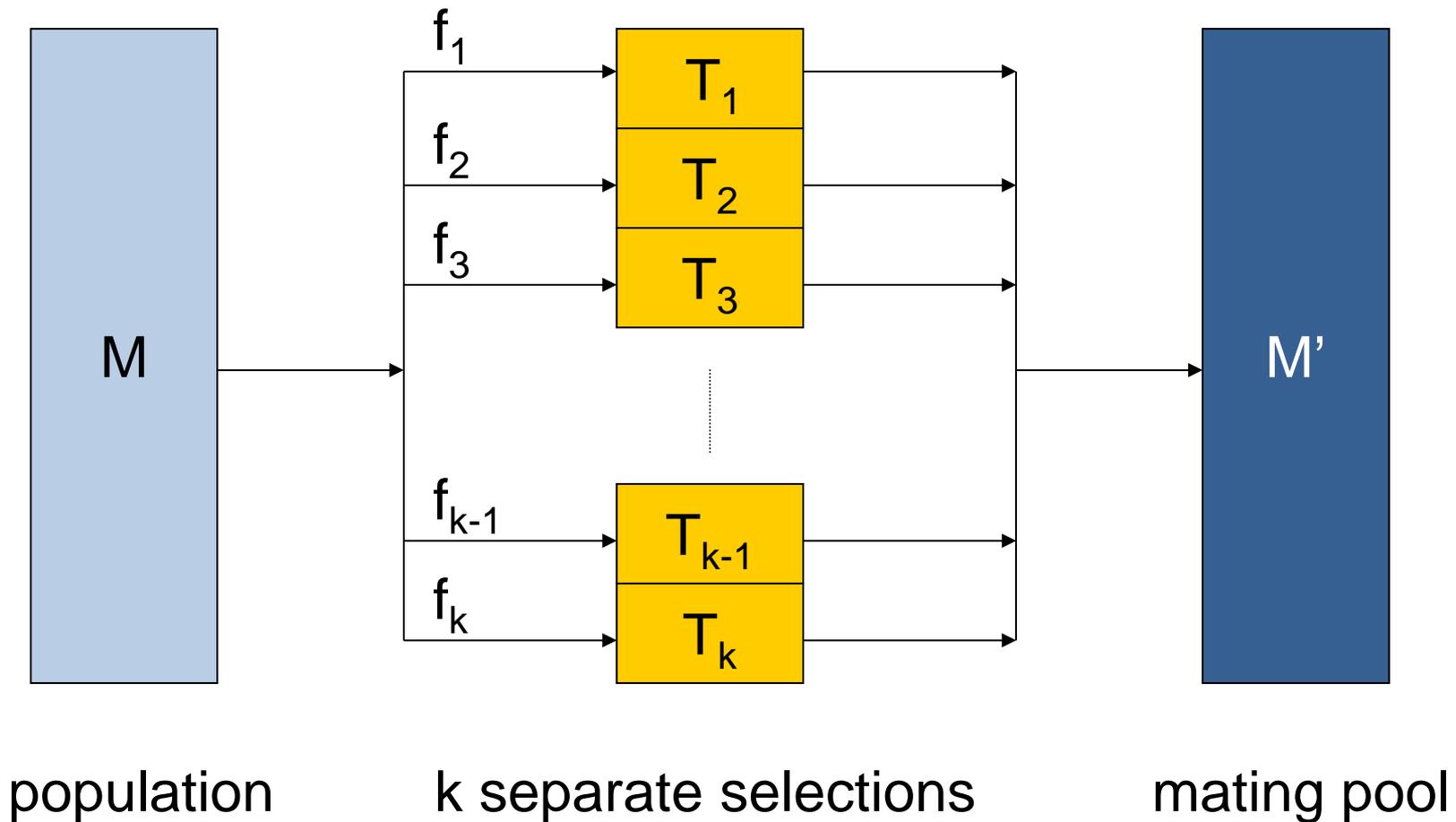
set-oriented
scaling-independent

Criterion-Based Selection: VEGA

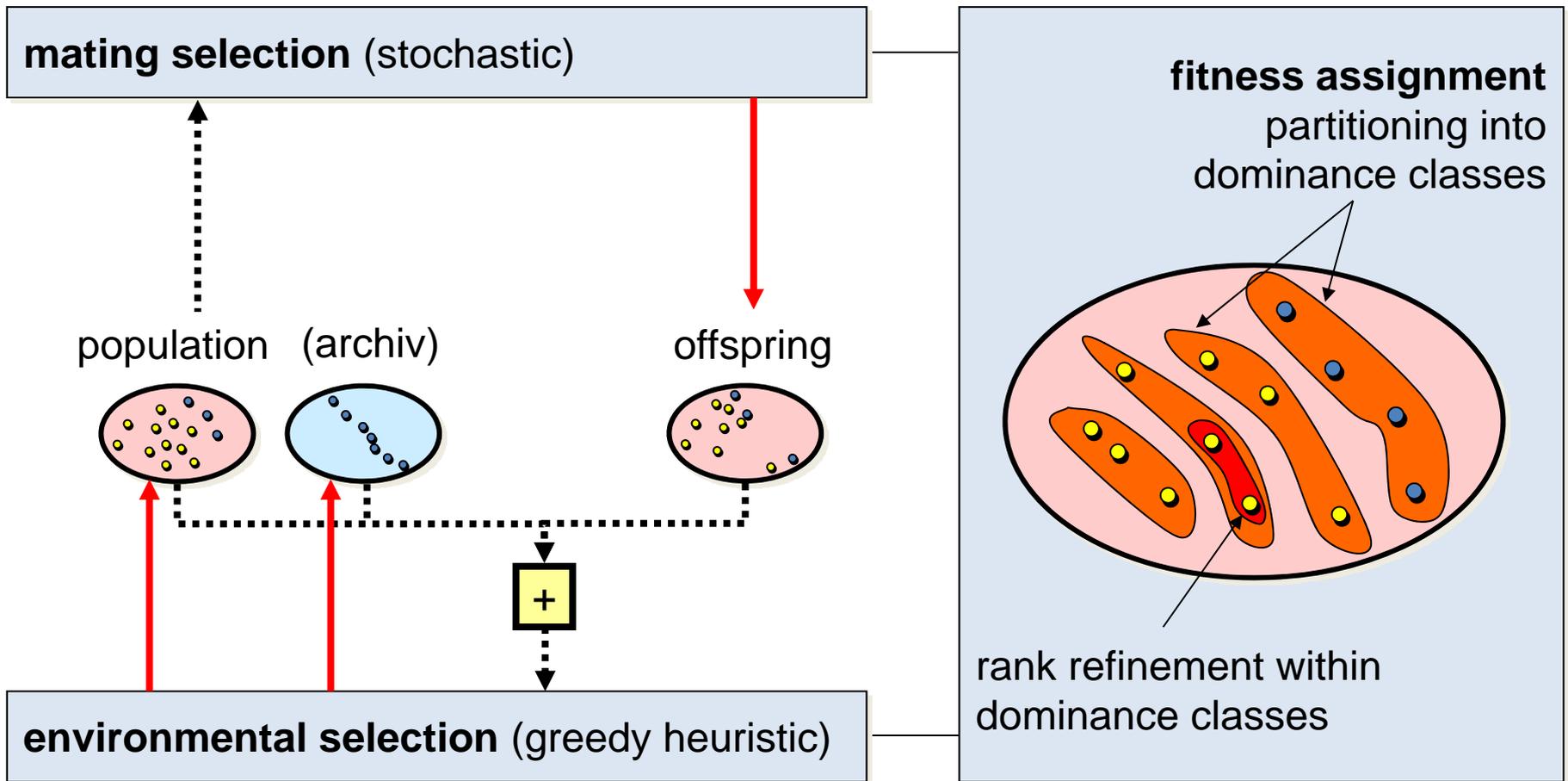
select
according to

shuffle

[Schaffer 1985]



General Scheme of Dominance-Based EMO



Ranking of the Population Using Dominance

... goes back to a proposal by David Goldberg in 1989.

... is based on pairwise comparisons of the individuals only.

- **dominance rank:** by how many individuals is an individual dominated?
MOGA, NPGA
- **dominance count:** how many individuals does an individual dominate?
SPEA, SPEA2
- **dominance depth:** at which front is an individual located?
NSGA, NSGA-II

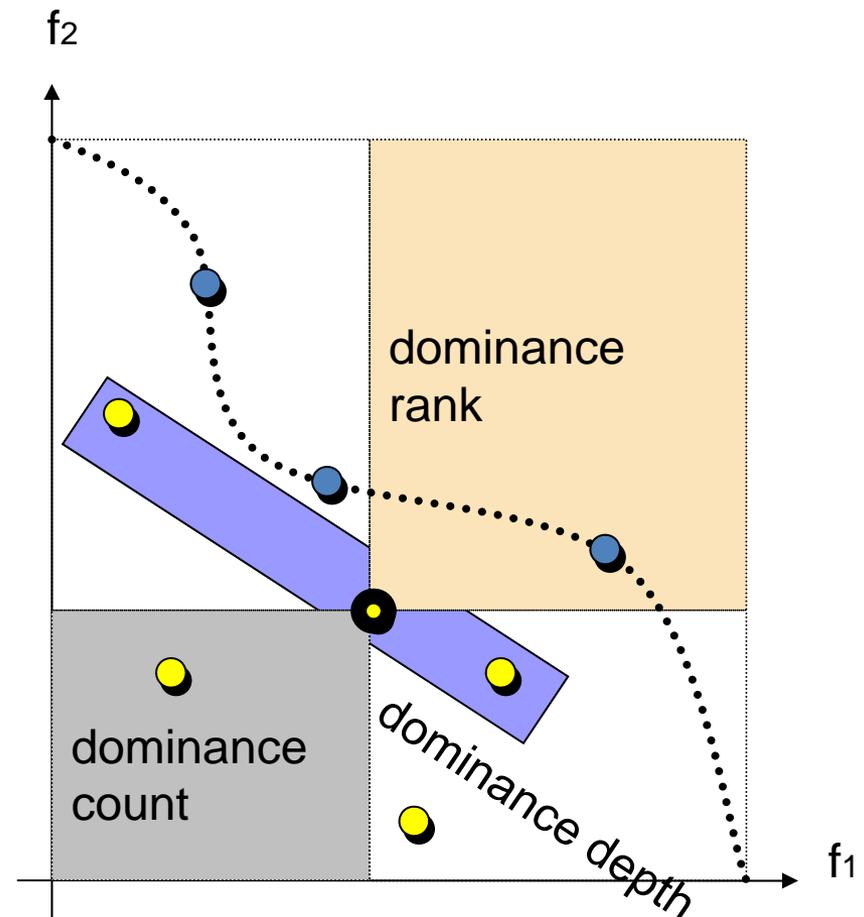
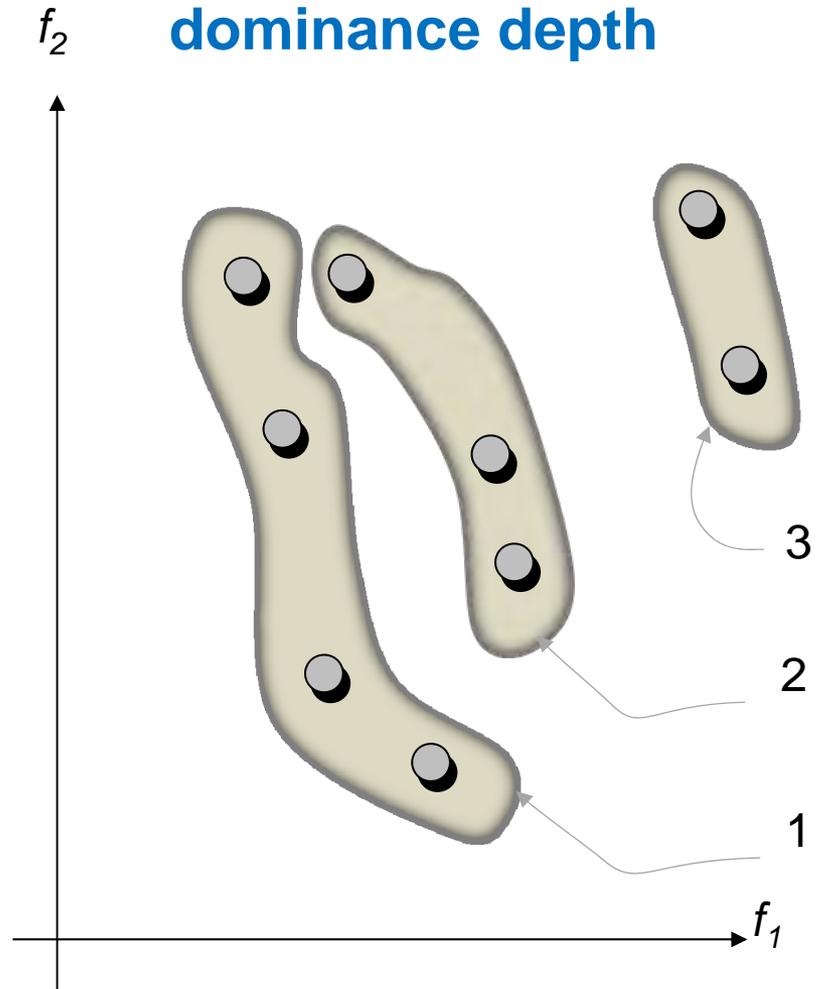
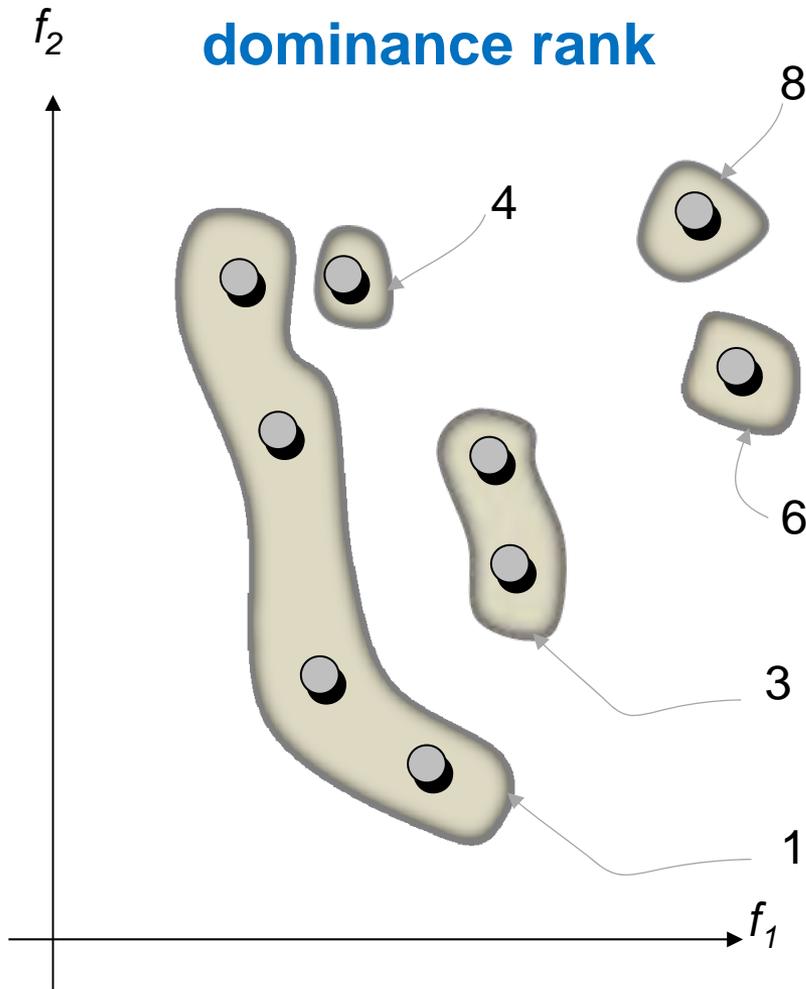


Illustration of Dominance-based Partitioning



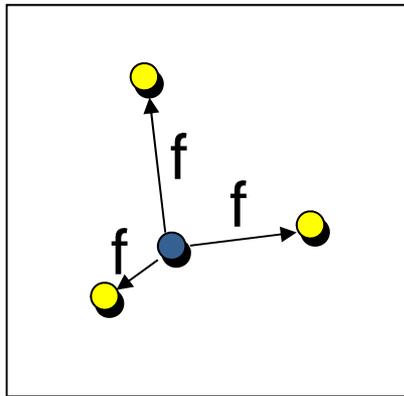
Refinement of Dominance Rankings

Goal: rank incomparable solutions within a dominance class

- ❶ Density information (good for search, but **usually no refinements**)

Kernel method

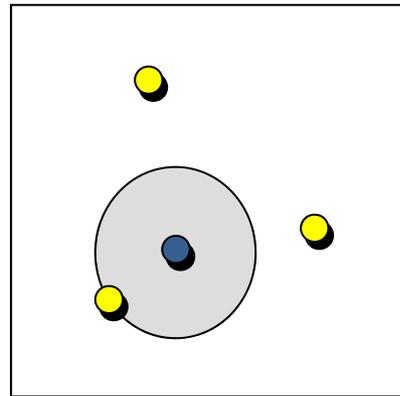
density =
function of the
distances



e.g. NSGA-II

k-th nearest neighbor

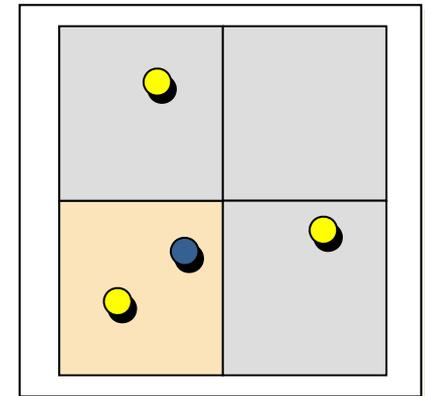
density =
function of distance
to k-th neighbor



e.g. SPEA2

Histogram method

density =
number of elements
within box



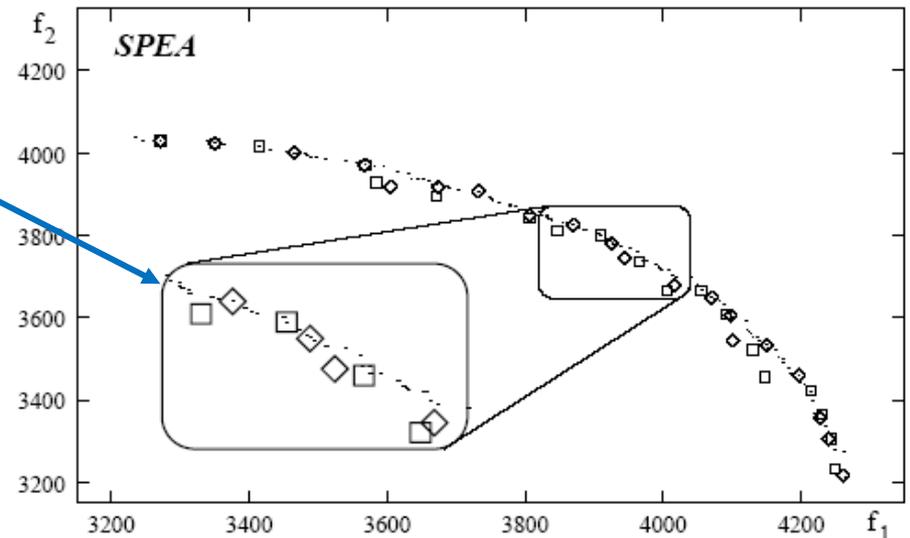
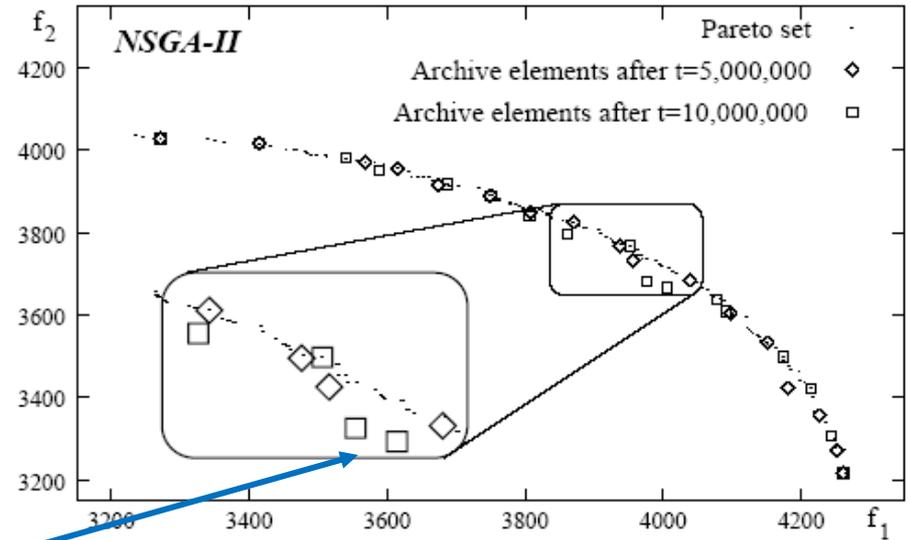
- ❷ Quality indicator (good for set quality): soon...

SPEA2 and NSGA-II: Cycles in Optimization

Selection in SPEA2 and NSGA-II can result in

deteriorative cycles

non-dominated
solutions already
found can be lost



Hypervolume-Based Selection

Latest Approach (e.g. SMS-EMOA [Beume et al. 2007], MO-CMA-ES [Igel et al. 2007])

use hypervolume indicator to guide the search: refinement!

Main idea

Delete solutions with the smallest hypervolume loss
 $d(s) = I_H(P) - I_H(P \setminus \{s\})$
iteratively

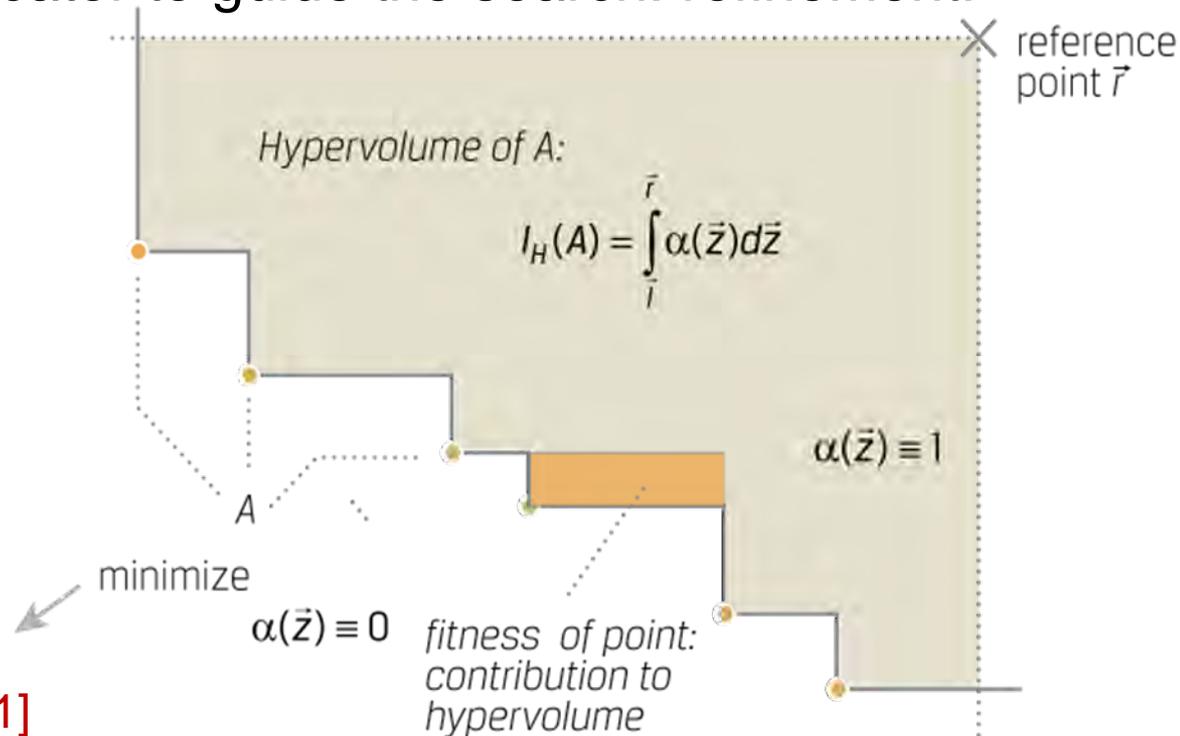
But: can also result

in cycles [Judt et al. 2011]

and is expensive [Bringmann and Friedrich 2009]

Therefore: HypE [Bader and Zitzler 2011]

Sampling + Contribution if more than 1 solution deleted



A Brief Introduction to EMO

- basics: what is the difference between single- and multiobjective optimization?
- state-of-the-art algorithm design concepts
- **performance assessment**

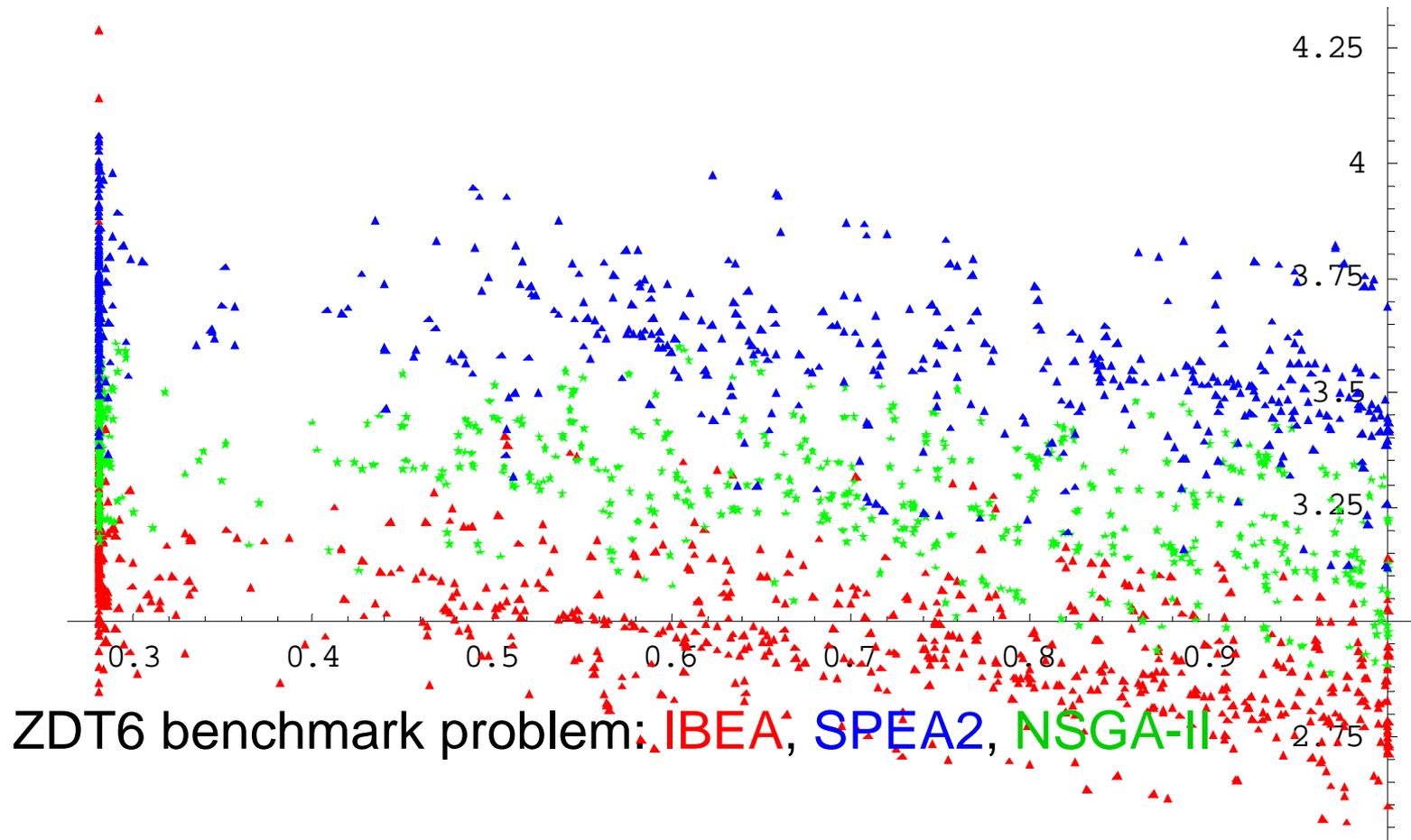
Advanced Concepts Useful in Practice

- objective reduction
- multiobjectivization
- innovization

Examples of Applications

Once Upon a Time...

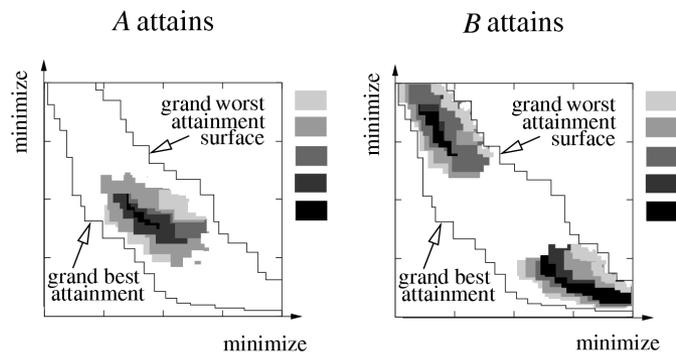
... multiobjective EAs were mainly compared visually:



Two Approaches for Empirical Studies

Attainment function approach:

- Applies statistical tests directly to the samples of approximation sets
- Gives detailed information about how and where performance differences occur



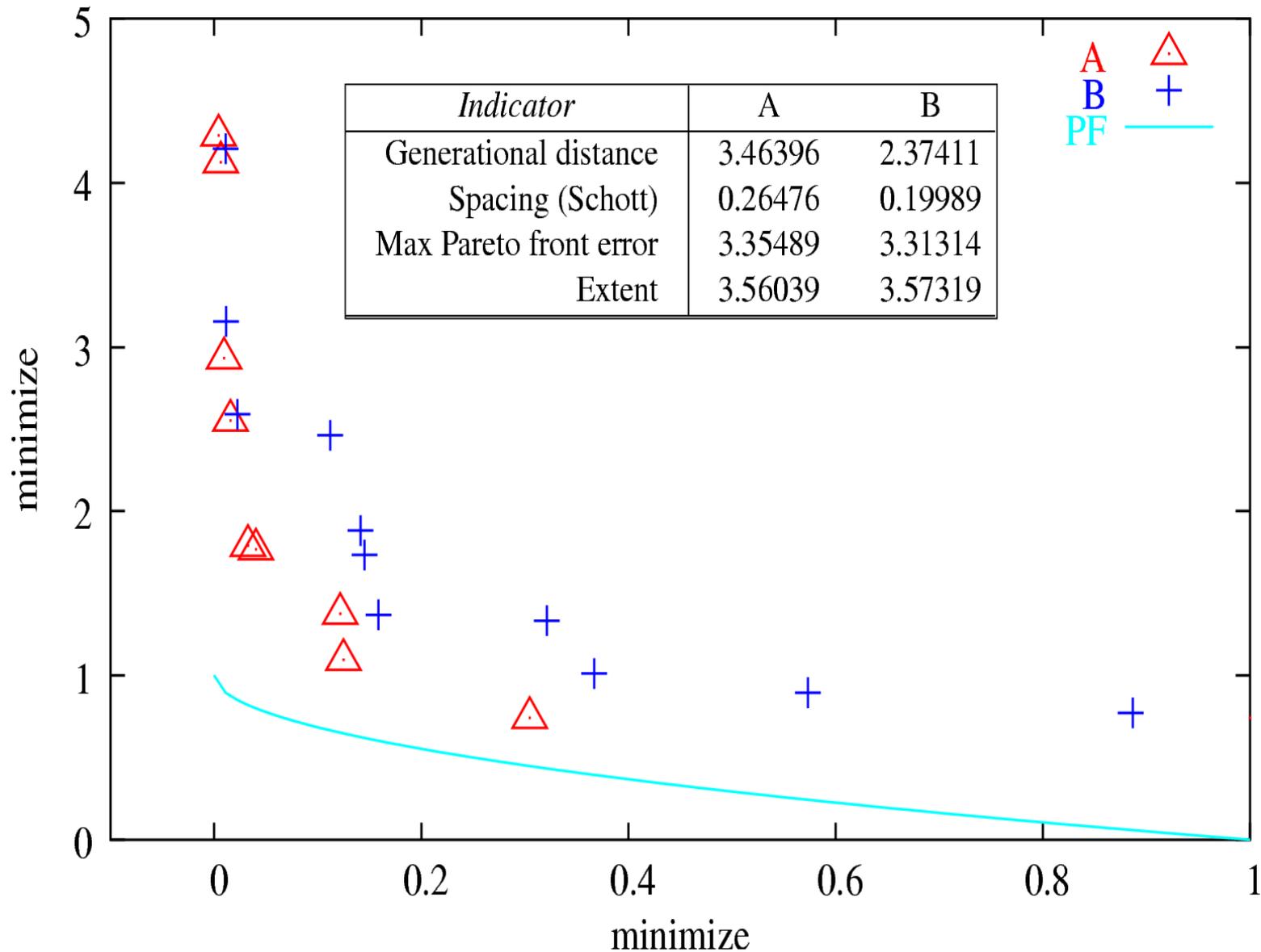
Quality indicator approach:

- First, reduces each approximation set to a single value of quality
- Applies statistical tests to the samples of quality values

<i>Indicator</i>	A	B
Hypervolume indicator	6.3431	7.1924
ϵ -indicator	1.2090	0.12722
R_2 indicator	0.2434	0.1643
R_3 indicator	0.6454	0.3475

see e.g. [Zitzler et al. 2003]

Problems With Non-Compliant Indicators



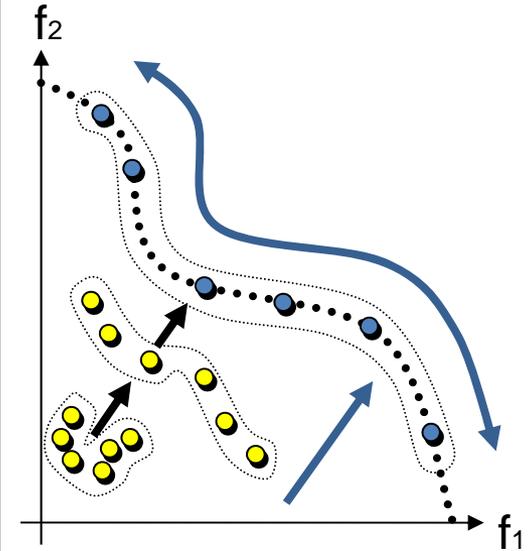
What Are Good Set Quality Measures?

There are **three aspects** [Zitzler et al. 2000]

Comparing different optimization techniques experimentally always involves the notion of performance. In the case of multiobjective optimization, the definition of quality is substantially more complex than for single-objective optimization problems, because the optimization goal itself consists of multiple objectives:

- The **distance** of the resulting nondominated set to the Pareto-optimal front should be minimized.
- A good (in most cases uniform) **distribution** of the solutions found is desirable. The assessment of this criterion might be based on a certain distance metric.
- The **extent** of the obtained nondominated front should be maximized, i.e., for each objective, a wide range of values should be covered by the nondominated solutions.

In the literature, some attempts can be found to formalize the above definition (or parts



Wrong! [Zitzler et al. 2003]

An infinite number of unary set measures is needed to detect in general whether A is better than B

But: total (weak) refinement nice \rightarrow hypervolume (or R2) indicator

A Brief Introduction to EMO

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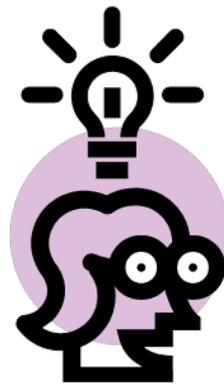
Examples of Applications

Motivation

multiobjective
problem

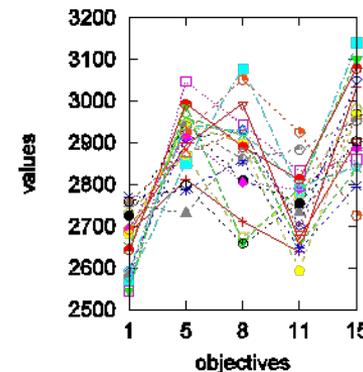
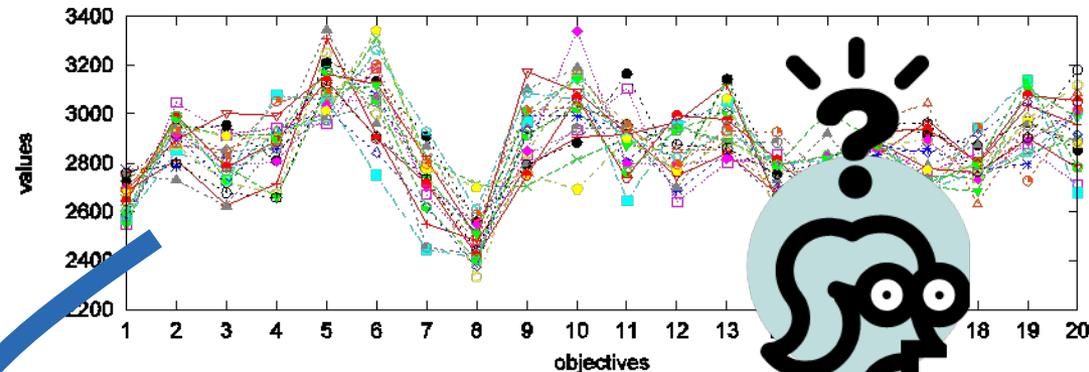
$$\begin{aligned} &\min. \{f_1(\mathbf{x}), \dots, f_k(\mathbf{x})\} \\ &\text{subject to } \mathbf{x} \in S \\ &\text{and } f_i : \mathbb{R}^n \rightarrow \mathbb{R} \end{aligned}$$

optimizer



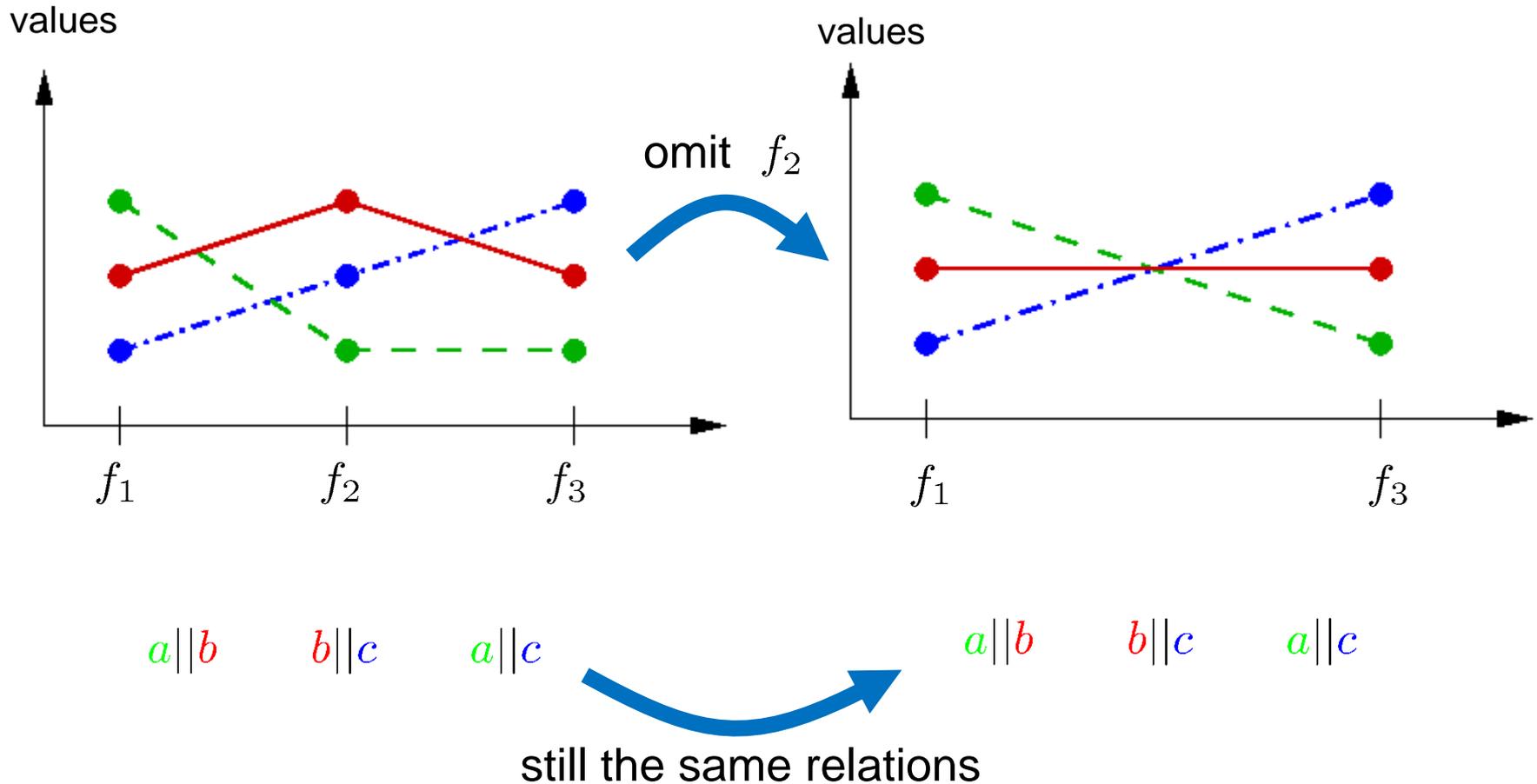
reduce number of objectives /
detect redundant objectives

(approximation of) Pareto front



⇒ assist the
decision maker
⇒ learn about the
problem

Underlying Concepts



Key questions

- Objective reduction possible without changing the problem?
- How to compute a minimum objective set?
- Applicable to real problems?

Objective Reduction Approaches

Omitting redundant objectives [Agrell 1997], [Gal and Leberling 1977]

- Not suitable for black-box optimization

PCA based objective reduction [Deb and Saxena 2005-2008]

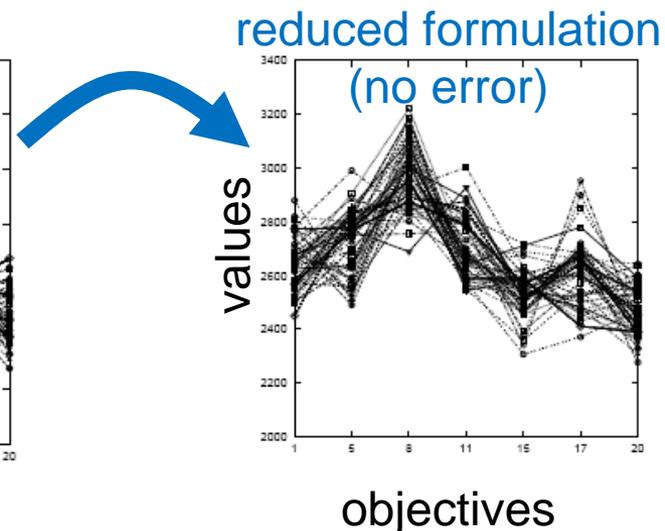
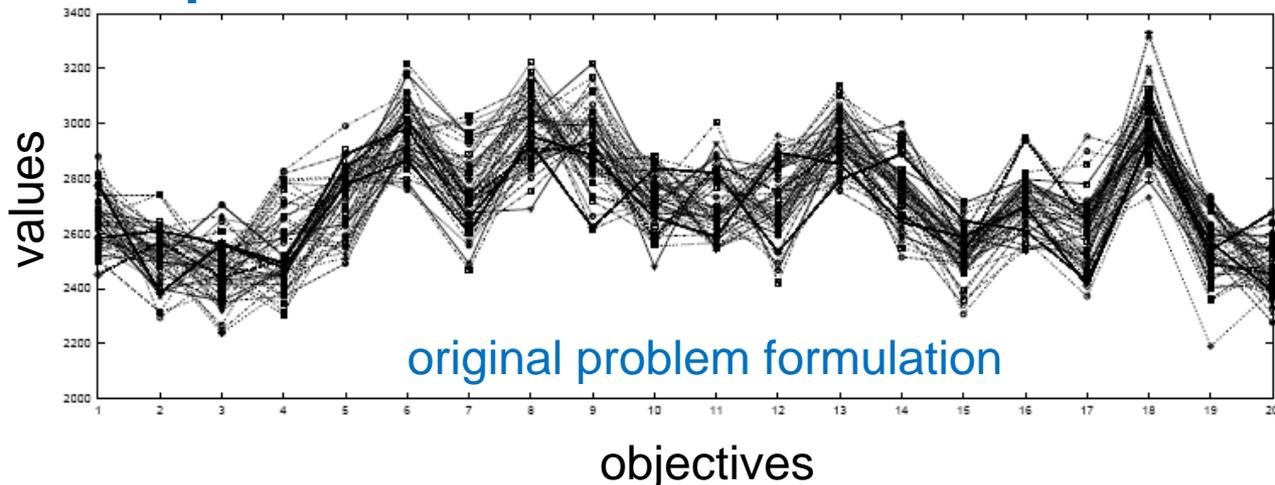
- Cannot guarantee preservation of dominance structure
- Works well in practice

Dominance Relation Preservation [Brockhoff and Zitzler 2006-2009] [López Jaimes et al. 2008, 2009]

- Goal: find minimal set of objectives that preserve dominance relation
- Efficient greedy algorithms available
[<http://www.tik.ee.ethz.ch/sop/download/supplementary/objectiveReduction/>]

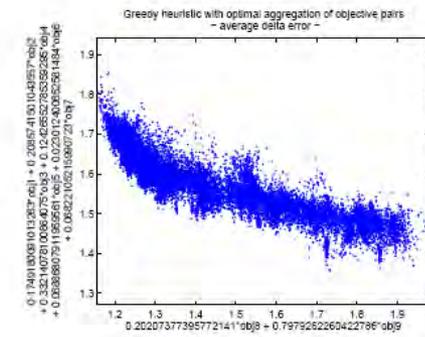
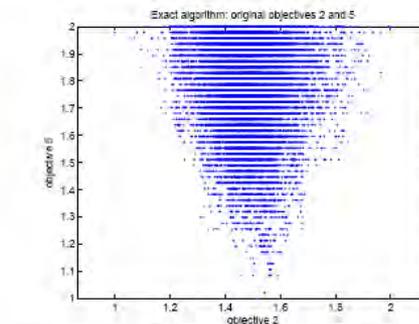
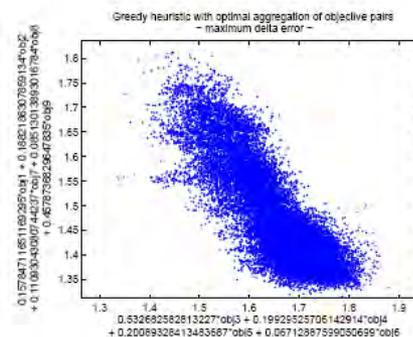
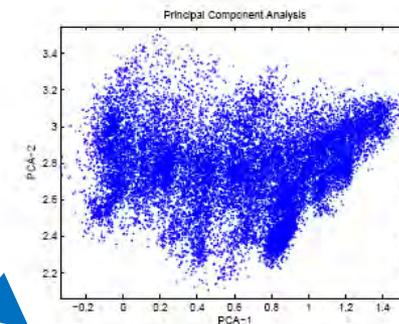
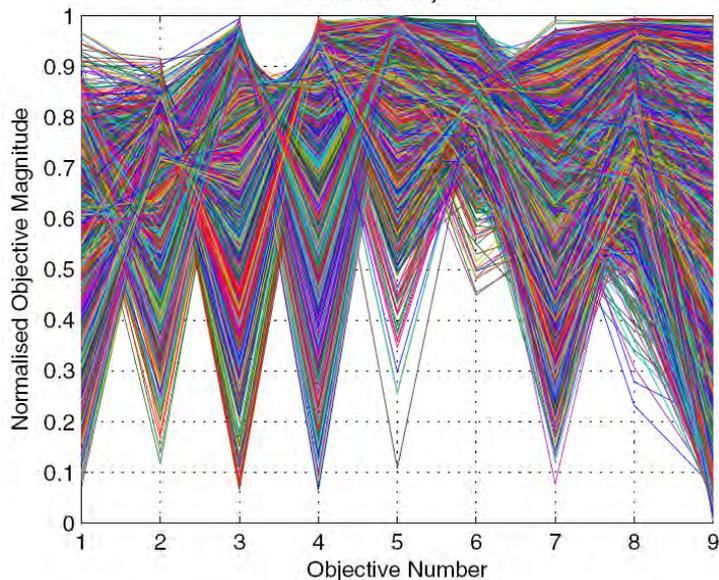
Objective Reduction: Examples

Knapsack Problem



Radar Waveform Problem

Normalised objectives

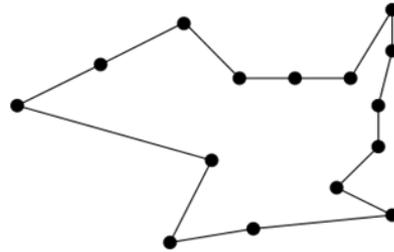


The Opposite: Multiobjectivization

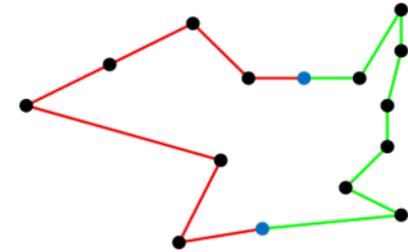
Some problems are easier to solve in a multiobjective scenario

example: TSP

[Knowles et al. 2001]



$$\pi \in S_n \rightarrow f(\pi)$$



$$\pi \in S_n \rightarrow (f_1(\pi, a, b), f_2(\pi, a, b))$$

Multiobjectivization

by **addition** of new “helper objectives” [Jensen 2004]

job-shop scheduling [Jensen 2004], frame structural design [Greiner et al. 2007], theoretical (runtime) analyses [Brockhoff et al. 2009]

by **decomposition** of the single objective

TSP [Knowles et al. 2001], minimum spanning trees [Neumann and Wegener 2006], protein structure prediction [Handl et al. 2008a], theoretical (runtime) analyses [Handl et al. 2008b]

Innovization

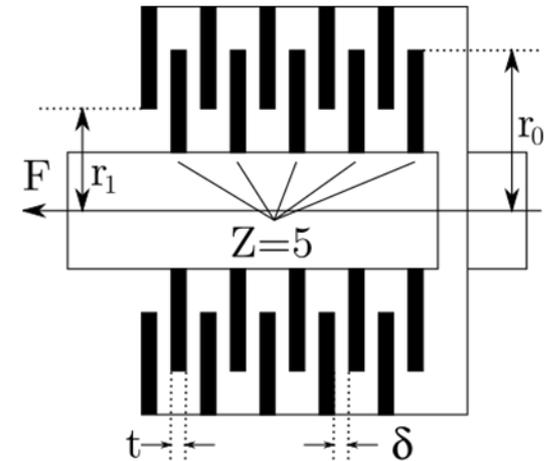
Often innovative design principles among solutions are found

example:

clutch brake design

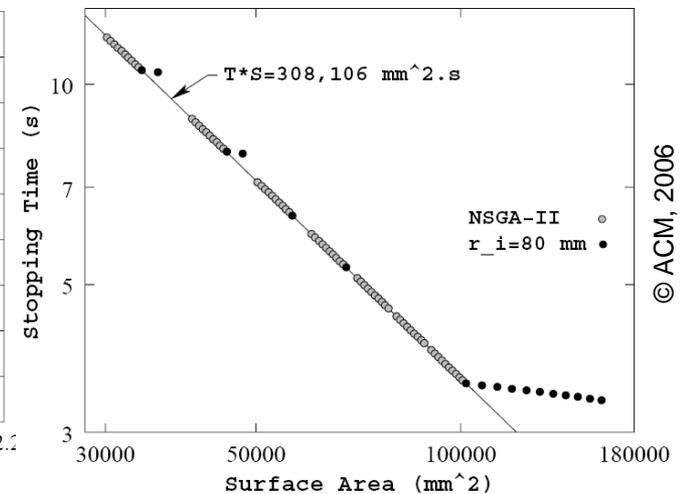
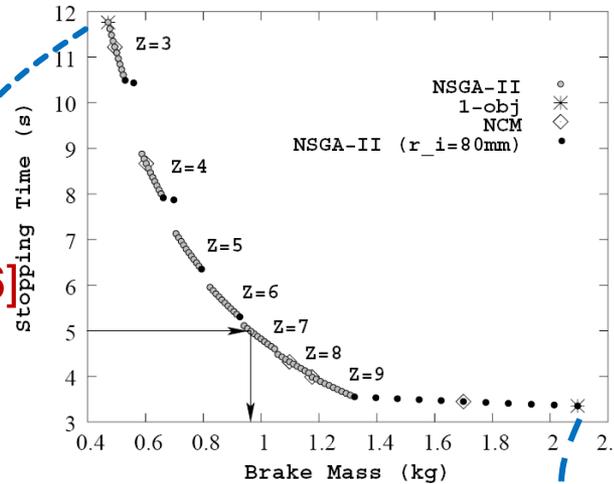
[Deb and Srinivasan 2006]

min. mass +
stopping time



Often innovative design principles among solutions are found

example:
clutch brake design
[Deb and Srinivasan 2006]



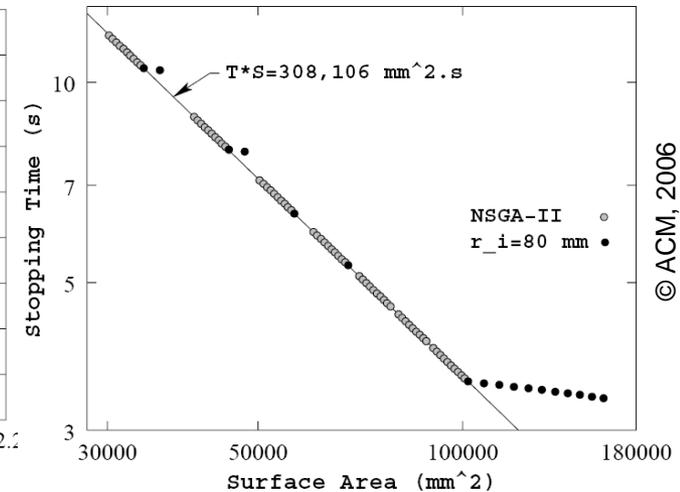
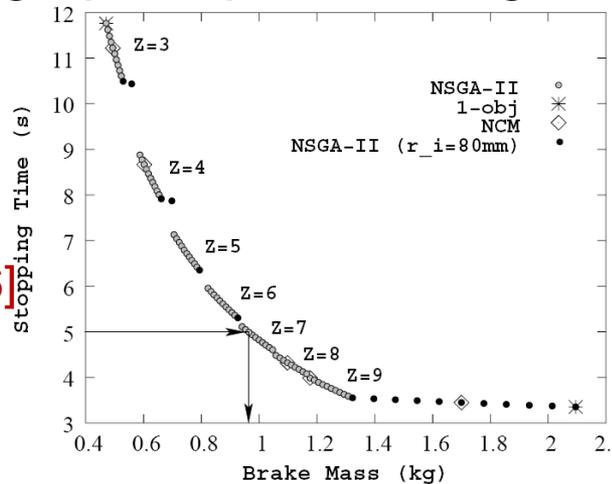
Solution	x_1	x_2	x_3	x_4	x_5	f_1	f_2
Min. f_1	70	90	1.5	1000	3	0.4704	11.7617
Min. f_2	80	110	1.5	1000	9	2.0948	3.3505

Often innovative design principles among solutions are found

example:

clutch brake design

[Deb and Srinivasan 2006]



Innovization [Deb and Srinivasan 2006]

- = using machine learning techniques to find new and innovative design principles among solution sets
- = learning about a multiobjective optimization problem

Other examples:

- SOM for supersonic wing design [Obayashi and Sasaki 2003]
- biclustering for processor design and KP [Ulrich et al. 2007]

A Brief Introduction to EMO

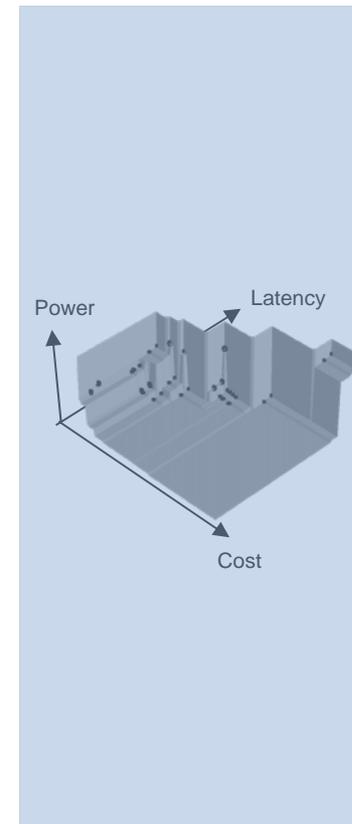
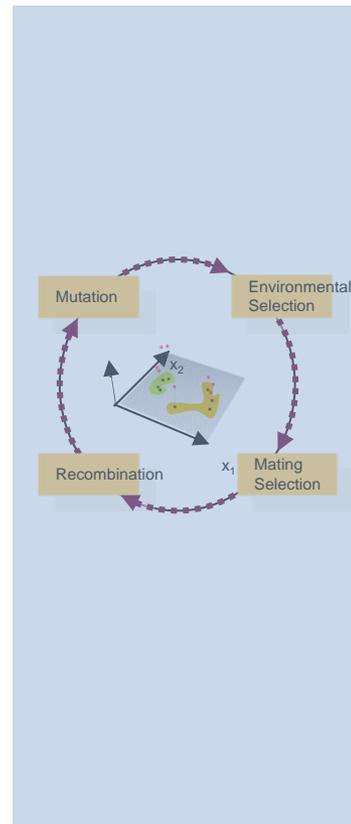
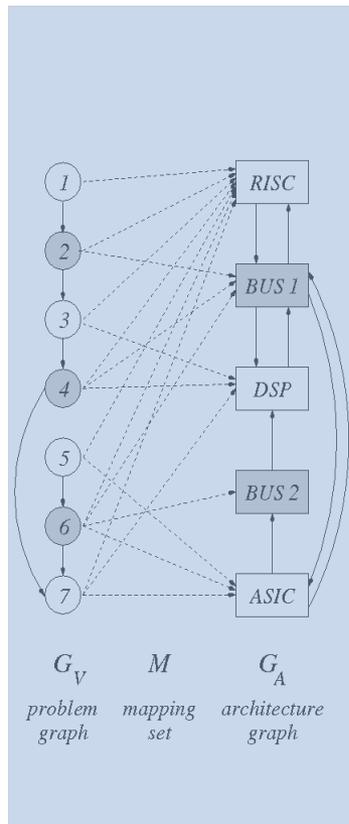
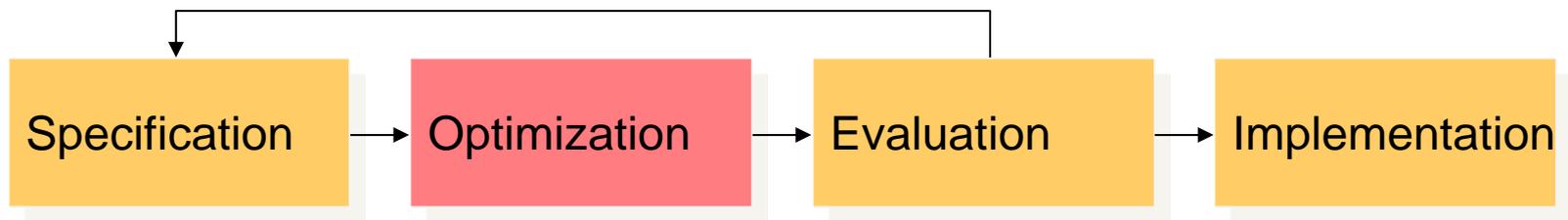
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Examples of Applications

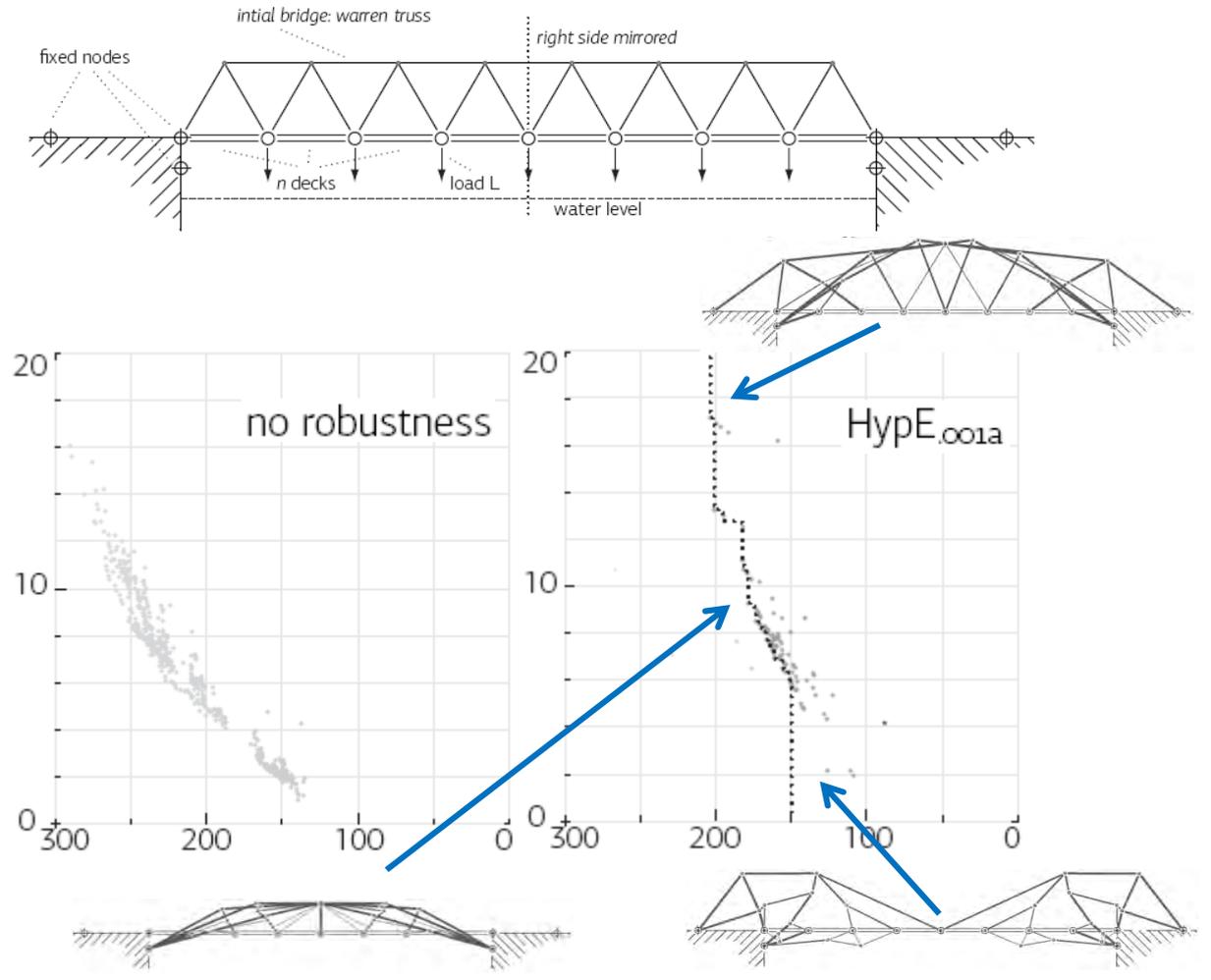
Application: Design Space Exploration



Application: Design Space Exploration

Truss Bridge Design

[Bader 2010]



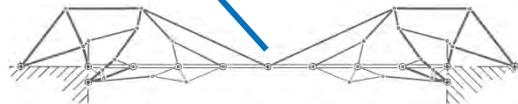
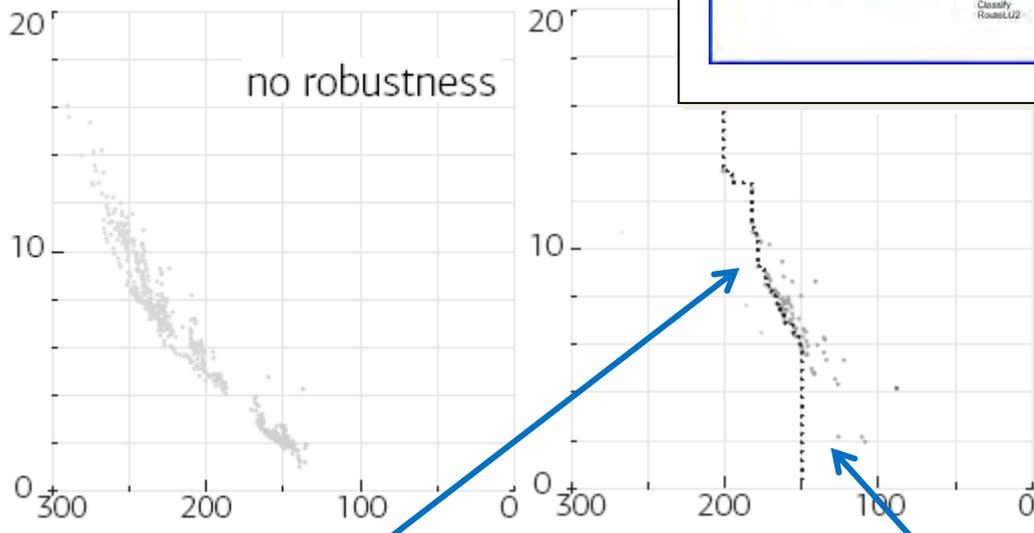
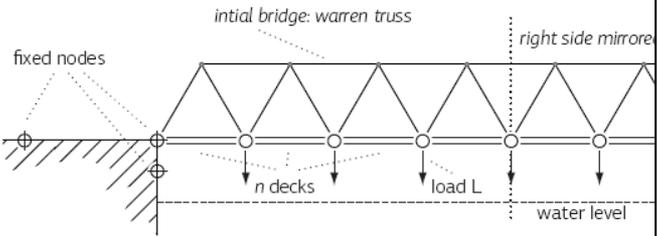
Implementation



Application: Design Space Exploration

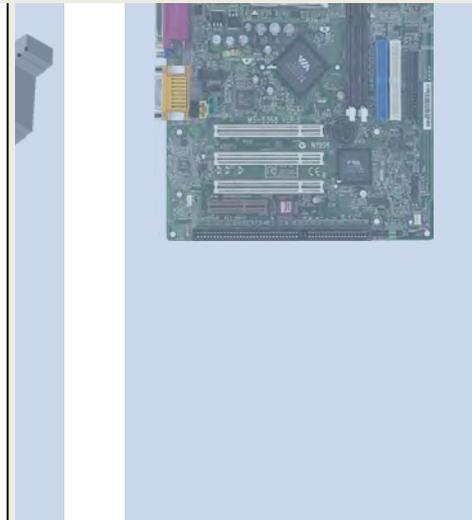
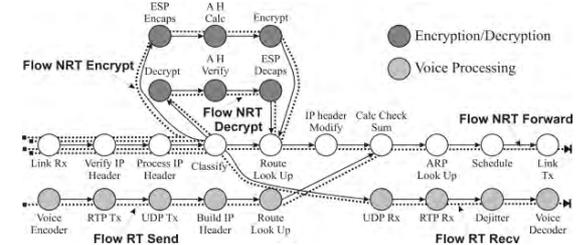
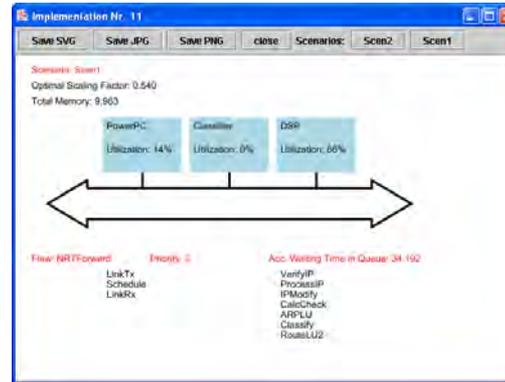
Truss Bridge Design

[Bader 2010]



Network Processor Design

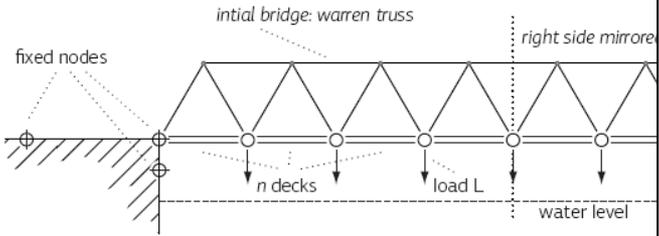
[Thiele et al. 2002]



Application: Design Space Exploration

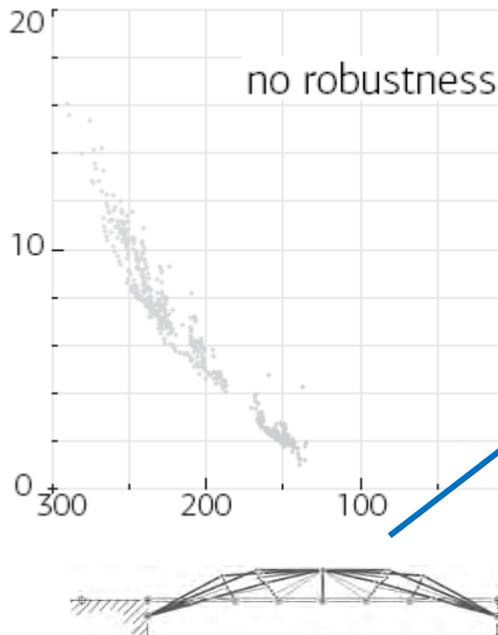
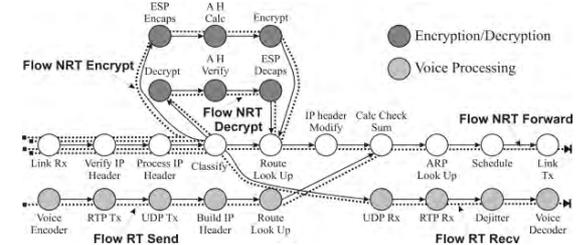
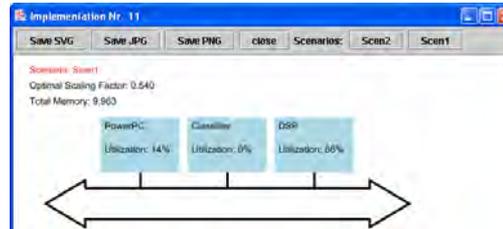
Truss Bridge Design

[Bader 2010]



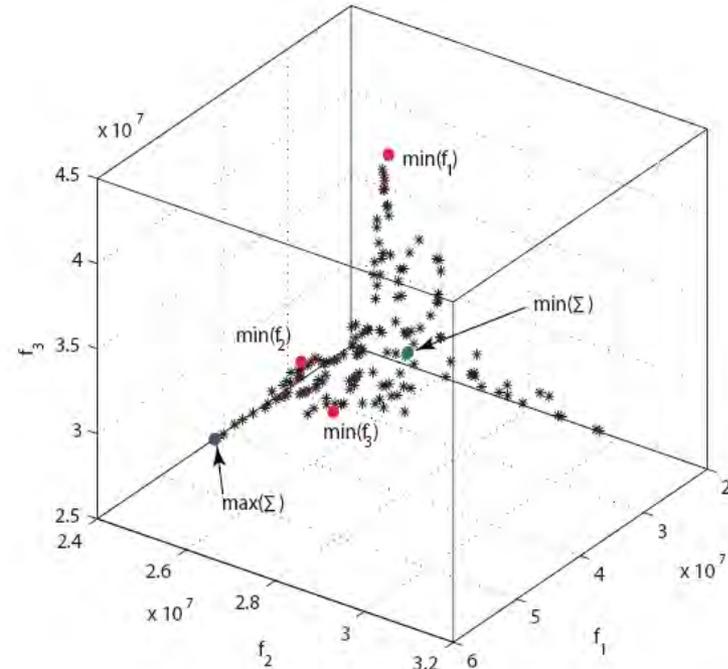
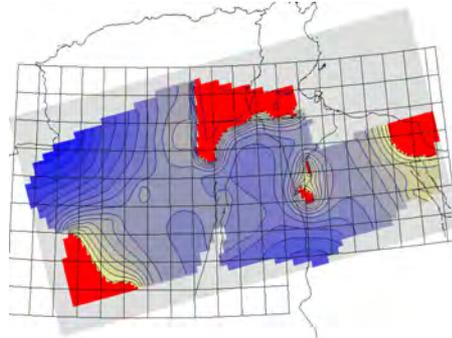
Network Processor Design

[Thiele et al. 2002]

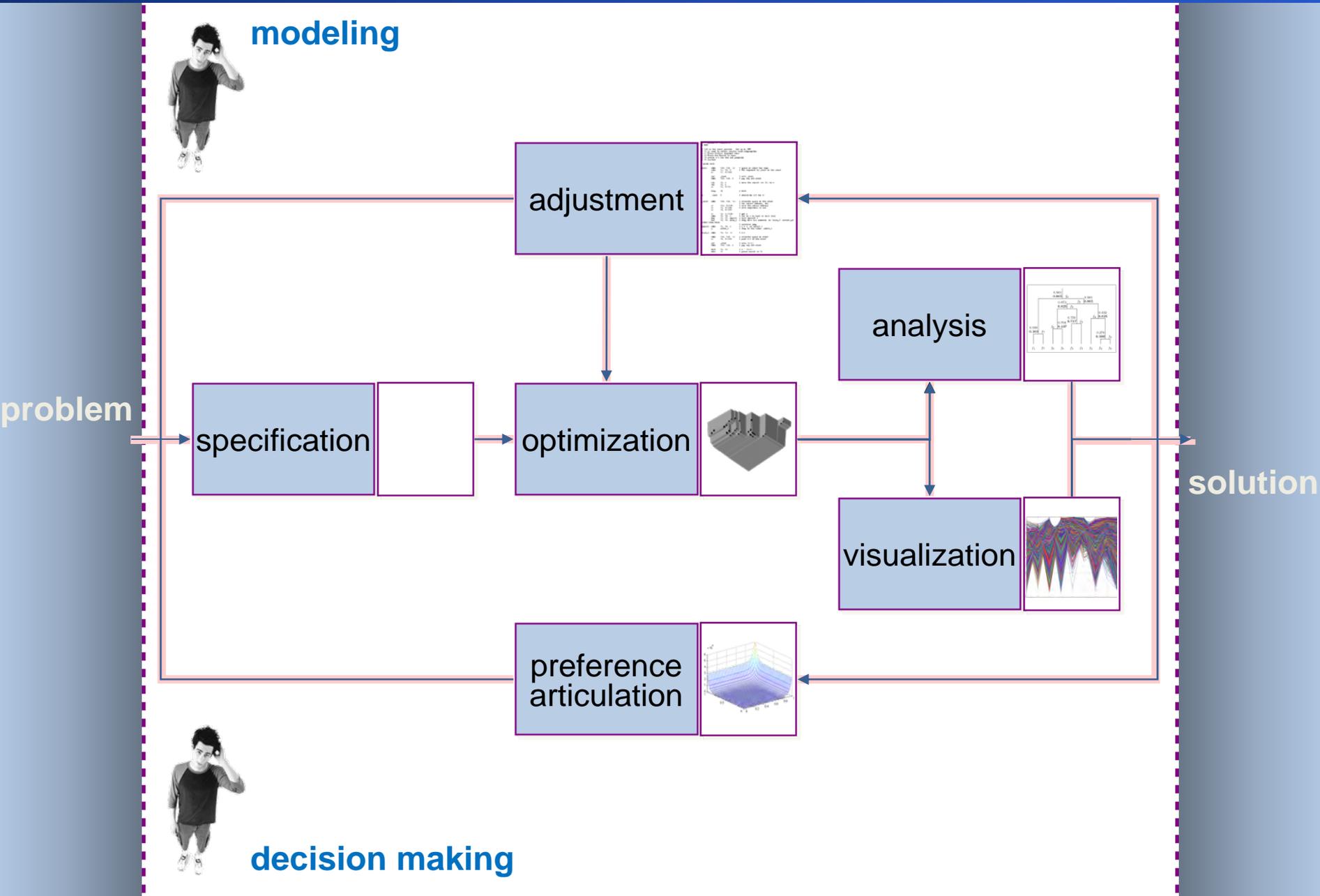


Water resource management

[Siegfried et al. 2009]



Conclusions: EMO as Interactive Decision Support



The EMO Community

Links:

- EMO mailing list: <http://w3.ualg.pt/lists/emo-list/>
- EMO bibliography: <http://www.lania.mx/~ccoello/EMOO/>
- EMO conference series: <http://www.mat.ufmg.br/emo2011/>

Books:

- ***Multi-Objective Optimization using Evolutionary Algorithms***
Kalyanmoy Deb, Wiley, 2001
- ***Evolutionary Algorithms for Solving Multi Evolutionary Algorithms for Solving Multi-Objective Problems Objective Problems***, Carlos A. Coello Coello, David A. Van Veldhuizen & Gary B. Lamont, Kluwer, 2nd Ed. 2007
- **Multiobjective Optimization—Interactive and Evolutionary Approaches**, J. Branke, K. Deb, K. Miettinen, and R. Slowinski, editors, volume 5252 of *LNCS*. Springer, 2008
- and more...

PISA

- Principles and Documentation
- PISA for Beginners
- Downloads
- Performance Assessment
- Write and Submit a Module
- Publications, Bugs, Contact & License

Download of Selectors, Variators and Performance Assessment

This page contains the currently available variators and selector (see also [Principles of PISA](#)) as well as performance assessment tools (see also [Performance Assessment](#)). The variators are mainly test and benchmark problems that can be used to assess the performance of different optimizers. EXPO is a complex application form the are of computer design that can be used as a benchmark problem too. The selectors are state-of-the-art evolutionary multi-objective optimization methods. If you want to write or submit a module, please look at [Write and Submit a Module](#). Links to documentation on the PISA specification can be found at [Documentation](#).

Jaroslav Hajek pointed out a severe bug in the [WFG selector](#), please redownload the module if your version is older than 2010/02/03.



Optimization Problems (variator)

- GWLAB - Multi-Objective Groundwater Management**
Package: in Matlab [more...](#)
- LOTZ - Demonstration Program**
Source: in C
Binaries: Solaris, Windows, Linux [more...](#)
- LOTZ2 - Leading Ones Trailing Zeros**
Source: in C
Binaries: Solaris, Windows, Linux [more...](#)
- LOTZ2 - Java Example Variator**
Source: in Java
Binaries: Windows, Linux [more...](#)
- Knapsack Problem**
Source: in C
Binaries: Solaris, Windows, Linux [more...](#)
- EXPO - Network Processor Design Problem**

Optimization Algorithms (selector)

- SPAM - Set Preference Algorithm for Multiobjective Optimization**
Source: in C
Binaries: Windows, Linux 32bit, Linux 64bit [more...](#)
- SHV - Sampling-based HyperVolume-oriented algorithm**
Source: in C
Binaries: Windows, Linux 32bit, Linux 64bit [more...](#)
- SIBEA - Simple Indicator Based Evolutionary Algorithm**
Source: in C
Binaries: Solaris, Windows, Linux [more...](#)
- HypE - Hypervolume Estimation Algorithm for Multiobjective Optimization**
Source: in C
Binaries: Windows, Linux 32bit, Linux 64bit [more...](#)
- SEMO - Demonstration Program**
Source: in C
Binaries: Solaris, Windows, Linux [more...](#)

Questions?

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