Transport equation on a network of circles with a persistently excited damping

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• We consider:

$$\dot{x} = Ax + \alpha(t)Bu.$$

- $x \in \mathbb{R}^d$ : state;  $u \in \mathbb{R}^m$ : control;  $\alpha \in \mathcal{G} \subset L^{\infty}(\mathbb{R}_+; [0, 1])$ .
- Linear time-invariant control system:  $\dot{x} = Ax + Bu$ .
- $\alpha(t)$ : activity of the control u(t) at time t.
- If  $\alpha(t) \in \{0,1\}$ : switched system between

$$\dot{x} = Ax$$
 and  $\dot{x} = Ax + Bu$ .

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### Introduction PE systems in finite dimension

$$\dot{x} = Ax + \alpha(t)Bu, \qquad \alpha \in \mathcal{G}$$

- If  $\alpha(t) \equiv 0$ , there is no action of the control on the system.
- The class G should ensure a sufficient amount of action of the control on the system.
- Persistently exciting (PE) signals: for  $T \ge \mu > 0$ , we say that  $\alpha \in \mathcal{G}(T, \mu)$  if  $\alpha \in L^{\infty}(\mathbb{R}_+; [0, 1])$  and

$$\forall t \in \mathbb{R}_+, \quad \int_t^{t+T} \alpha(s) ds \ge \mu.$$

• Persistently excited (PE) system: system with  $\alpha \in \mathfrak{G}(\mathcal{T}, \mu)$ .

### Theorem (A. Chaillet, Y. Chitour, A. Loría, M. Sigalotti, 2008)

Suppose that the pair (A, B) is controllable and that the matrix A is skew-symmetric. Then, for every  $T \ge \mu > 0$ , there exists constants  $C \ge 1$ ,  $\gamma > 0$  such that, for every  $x_0 \in \mathbb{R}^d$  and every  $\alpha \in \mathfrak{G}(T, \mu)$ , the corresponding solution of

$$\dot{x} = (A - \alpha(t)BB^{\mathsf{T}})x$$

satisfies

$$\|x(t)\| \leq C e^{-\gamma t} \|x_0\|.$$

- $u = -B^{\mathsf{T}}x$  is a feedback that stabilizes the system.
- More information on switched systems, PE systems and their stability: course by Yacine Chitour on Saturday and Sunday.

$$\dot{z} = Az + \alpha(t)Bu, \qquad z \in X, \ u \in U, \ \alpha \in \mathfrak{G}(T, \mu).$$

#### X, U Banach spaces.

$$\begin{cases} \partial_{tt}^{2} u(t,x) = \partial_{xx}^{2} u(t,x) - \alpha(t)\chi(x)\partial_{t}u(t,x), & x \in [0,L], \\ u(t,x) = 0, & x \in \{0,L\}. \end{cases}$$

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- Few results are known concerning the stability and the stabilizability of PE systems in infinite dimension.
- [F. Hante, M. Sigalotti, M. Tucsnak, 2012]: generalized observability inequality and unique continuation principle for stability analysis.
- It would be useful to have a "toy model" to understand the effects of PE signals in infinite dimensional systems.

Transport equation on a network of circles

Discussion 00

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## Transport equation on a network of circles The model

$$\begin{cases} \partial_t u_i(t,x) + \partial_x u_i(t,x) \\ + \alpha_i(t)\chi_i(x)u_i(t,x) = 0, & t \in \mathbb{R}_+, \ x \in [0, L_i], \ i \in [\![1, N_d]\!], \\ \partial_t u_i(t,x) + \partial_x u_i(t,x) = 0, & t \in \mathbb{R}_+, \ x \in [0, L_i], \ i \in [\![N_d + 1, N]\!], \\ u_i(t,0) = \sum_{j=1}^N m_{ij}u_j(t, L_j), & t \in \mathbb{R}_+, \ i \in [\![1, N]\!], \\ u_i(0,x) = u_{i,0}(x), & x \in [0, L_i], \ i \in [\![1, N]\!]. \end{cases}$$

- $\alpha_i \in \mathfrak{G}(\mathcal{T},\mu)$  for  $i \in \llbracket 1, N_d \rrbracket$ .
- $\chi_i$ : characteristic function of an interval  $[a_i, b_i] \subset [0, L_i]$ .
- $M = (m_{ij})_{1 \le i,j \le N}$ : transmission matrix.

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# Transport equation on a network of circles Motivation

- Understand the effects of PE signals in infinite dimensional systems.
- Inspired by the wave equation on a star-shaped network.
- PDEs on networks:
  - [S. Nicaise, 1987],
  - [G. Lumer, 1980],
  - [R. Dáger, E. Zuazua, 2006],
  - [J. Valein, E. Zuazua, 2009]...
- Stability with intermittent signals: [M. Gugat, M. Sigalotti, 2010].



## Transport equation on a network of circles Hypotheses

If  $\frac{L_i}{L_j} \in \mathbb{Q}$  for every i, j and the damping intervals are small enough, one may find periodic solutions (depending on M).

### Hypothesis

There exist  $i, j \in \llbracket 1, N \rrbracket$  such that  $\frac{L_i}{L_i} \notin \mathbb{Q}$ .

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There exist  $i, j \in \llbracket 1, N \rrbracket$  such that  $\frac{L_i}{L_i} \notin \mathbb{Q}$ .

The total mass  $\sum_{i=1}^{N} \int_{0}^{L_{i}} u_{i}(t, x) dx$  is preserved and non-negative initial conditions imply non-negative solutions  $\iff M$  is left stochastic.

### Hypothesis

**1** 
$$|M|_{\ell^1} \leq 1$$

2 For every  $i, j \in [[1, N]]$ , we have  $m_{ij} \neq 0$ .

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### Transport equation on a network of circles Main result

### Theorem (Y. Chitour, G. M., M. Sigalotti)

For every  $T \ge \mu > 0$ , there exist  $C \ge 1$  and  $\gamma > 0$  such that, for every  $p \in [1, +\infty]$ , every initial condition  $u_{i,0} \in L^p(0, L_i)$ ,  $i \in [\![1, N]\!]$ , and every choice of signals  $\alpha_i \in \mathcal{G}(T, \mu)$ ,  $i \in [\![1, N_d]\!]$ , the corresponding solution satisfies

$$\sum_{i=1}^{N} \|u_i(t)\|_{L^p(0,L_i)} \leq C e^{-\gamma t} \sum_{i=1}^{N} \|u_{i,0}\|_{L^p(0,L_i)}, \qquad \forall t \geq 0.$$

# Transport equation on a network of circles Main result

- Our proof relies on the explicit formula for the solutions.
- The main difficulty comes from the fact that the  $\alpha_i$  are PE and may be zero on several time intervals, switching off the damping.
- It is also important to take into account the fact that L<sub>i</sub> ∉ Q for certain i, j and combine it with the persistence of excitation of the α<sub>i</sub>.

We can give an explicit formula for the solutions of this system. To simplify: N = 2, no damping,  $L_1 < L_2$ .

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$$u_1(t,0) = m_{11}u_1(t-s, L_1-s) + m_{12}u_2(t-s, L_2-s)$$
  
 $0 \le s \le \min\{t, L_1, L_2\}$ 

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## Transport equation on a network of circles Explicit solution

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 $u_1(t,0) = m_{11} [m_{11}u_1(t-s, L_1 - (s - L_1)) + m_{12}u_2(t-s, L_2 - (s - L_1))]$  $+ m_{12}u_2(t-s, L_2 - s)$  $L_1 \le s \le \min\{t, 2L_1, L_2\}$ 

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## Transport equation on a network of circles Explicit solution



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### Transport equation on a network of circles Explicit solution

$$u_{1}(t,0) = \sum_{n=0}^{\left\lfloor \frac{t}{L_{2}} \right\rfloor} \beta_{1,n,t} u_{1,0}(L_{1} - \{t - nL_{2}\}_{L_{1}}) + \sum_{m=0}^{\left\lfloor \frac{t}{L_{1}} \right\rfloor} \beta_{2,m,t} u_{2,0}(L_{2} - \{t - mL_{1}\}_{L_{2}})$$

• Notation: 
$$\{x\}_y = x - \lfloor \frac{x}{y} \rfloor y$$
.

• 
$$\beta_{j,n,t}$$
 can be computed from  $M$ .

• This formula can be generalized to larger *N* and to take the damping into account.

### Theorem

### The solution satisfies

$$u_{i}(t,0) = \sum_{j=1}^{N} \sum_{\substack{\mathfrak{n}\in\mathfrak{N}_{j}\\\mathcal{L}(\mathfrak{n})\leq t}} \vartheta^{(i)}_{j,\mathfrak{n}+\left\lfloor\frac{t-L(\mathfrak{n})}{L_{j}}\right\rfloor} \mathbf{1}_{j,L_{j}-\{t-L(\mathfrak{n})\}_{L_{j}},t} u_{j,\mathfrak{0}}\left(L_{j}-\{t-L(\mathfrak{n})\}_{L_{j}}\right)$$

#### Lemma

Let 
$$T \ge \mu > 0$$
. If  $\exists C_0 \ge 1, \ \gamma_0 > 0 \ s.t.$ 

$$\left|\vartheta_{j,\mathfrak{n},x,t}^{(i)}
ight|\leq C_{0}e^{-\gamma_{0}|\mathfrak{n}|_{\ell^{1}}}$$

for every choice of PE signals  $\alpha_k \in \mathcal{G}(T, \mu)$ , then  $\exists C \ge 1, \gamma > 0$  s.t., for every  $p \in [1, +\infty]$ , every solution satisfies

$$\sum_{i=1}^{N} \|u_i(t)\|_{L^p(0,L_i)} \leq C e^{-\gamma t} \sum_{i=1}^{N} \|u_{i,0}\|_{L^p(0,L_i)}, \qquad \forall t \geq 0$$

It suffices to study the coefficients  $\vartheta_{j,n,x,t}^{(i)}$ .

### Theorem

The coefficients  $\vartheta_{j,\mathfrak{n},\mathsf{x},t}^{(i)}$  satisfy

$$\vartheta_{j,\mathbf{0},L_{j,t}}^{(i)} = m_{ij},$$
  
$$\vartheta_{j,\mathbf{n},L_{j,t}}^{(i)} = \sum_{\substack{k=1\\n_k \ge 1}}^{N} m_{kj} \ \vartheta_{k,\mathbf{n}-\mathbf{1}_k,L_k,t}^{(i)} \ e^{-\int_{t-L(\mathbf{n})+a_k}^{t-L(\mathbf{n})+b_k} \alpha_k(s)ds}.$$

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Transport equation on a network of circles Exponential convergence of the coefficients

Decomposition of the set  $\mathbb{N}^N$ .



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### Transport equation on a network of circles Exponential convergence of the coefficients

In  $\mathfrak{N}_b(\rho)$ :

#### Lemma

 $\exists \mu \in (0, 1) \text{ s.t., } \forall i, j, n, x, t \text{ and } \forall k \in \llbracket 1, N \rrbracket$ , we have

$$\left|\vartheta_{j,\mathfrak{n},x,t}^{(i)}\right| \leq \binom{|\mathfrak{n}|_{\ell^1}}{n_k} \mu^{|\mathfrak{n}|_{\ell^1}}.$$

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### Transport equation on a network of circles Exponential convergence of the coefficients

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### Corollary

 $\exists \rho > 0, \ C \ge 1, \ \gamma > 0 \ s.t., \ \forall i, j, x, t \ and \ \forall \mathfrak{n} \in \mathfrak{N}_b(\rho), \ we \ have \\ \left| \vartheta_{j,\mathfrak{n},x,t}^{(i)} \right| \le C e^{-\gamma |\mathfrak{n}|_{\ell^1}}.$ 

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#### Lemma

Let  $T \ge \mu > 0$ .  $\exists \eta \in (0, 1)$  and  $K \in \mathbb{N}$  s.t., for every pair of circles  $k_1 \in \llbracket 1, N \rrbracket$  and  $k_2 \in \llbracket 1, N_d \rrbracket \setminus \{k_1\}$  with  $\frac{L_{k_1}}{L_{k_2}} \notin \mathbb{Q}$ , every  $\alpha_{k_2} \in \mathfrak{G}(T, \mu)$  and every suitable  $\mathfrak{n}$ , t, there exists  $\mathfrak{r} \in \mathfrak{N}$  with  $n_j \le r_j \le K + n_j$ ,  $j \in \{k_1, k_2\}$ , and  $r_j = n_j$  for  $j \in \llbracket 1, N \rrbracket \setminus \{k_1, k_2\}$ , such that

$$e^{-\int_{t-L(\mathfrak{r})+a_{k_2}}^{t-L(\mathfrak{r})+b_{k_2}}\alpha_{k_2}(s)ds} \leq \eta$$

Key hypotheses:  $\frac{L_{k_1}}{L_{k_2}} \notin \mathbb{Q}$  and  $\alpha_{k_2} \in \mathfrak{G}(\mathcal{T}, \mu)$ .

Since the decay  $e^{-\int_{t-L(n)+a_k}^{t-L(n)+b_k} \alpha_{k_2}(s)ds}$  is "active enough" "often enough", we can obtain the following result.

#### Lemma

Let  $T \ge \mu > 0$  and  $\sigma \in (0, 1)$ .  $\exists \gamma > 0$ ,  $\Lambda_0 \in \mathbb{N}^*$  s.t.,  $\forall i, j, x, t$  and  $\forall \mathfrak{n} \in \mathfrak{N}_c(\sigma)$  with  $|\mathfrak{n}|_{\ell^1} \ge \Lambda_0$ , we have

$$\left|artheta_{j,\mathfrak{n},x,t}^{(i)}
ight|\leq e^{-\gamma|\mathfrak{n}|_{\ell^{1}}}$$

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$$\left|\vartheta_{j,\mathfrak{n},x,t}^{(i)}\right| \leq e^{-\gamma \left|\mathfrak{n}\right|_{\ell^{1}}}.$$

This proves that the coefficients decrease exponentially with  $|\mathfrak{n}|_{\ell^1}$ , and so our theorem is proved.

# Discussion on the result Remarks

- If the damping terms are always active (α<sub>i</sub>(t) ≡ 1 for every i), one can also show the exponential convergence of the solutions to zero without the hypothesis L<sub>i</sub> ∉ Q for certain i, j.
- With the PE damping, exponential convergence cannot be true in general without this hypothesis.
- If the damping terms are always active, one can replace the hypothesis  $|M|_{\ell^1} \leq 1$  by  $|M|_{\ell^p} \leq 1$  for a certain  $p \in [1, +\infty]$  when  $N_d \geq N 1$ .
- We do not know if this still holds true for the PE damping.

# Discussion on the result Open problems

- To which classes of matrices can we generalize this result?  $|M|_{\ell^p} \leq 1$  for a certain  $p \in [1, +\infty]$ ? Orthogonal matrices?
- What about coefficients  $m_{ij} = 0$ ? Can we have some of them? Under which hypotheses?
- Can these ideas be used to study waves on a star-shaped network of strings with a persistently excited damping?