

# HIGH ORDER A-STABLE METHODS FOR THE NUMERICAL SOLUTION OF SYSTEMS OF D.E.'S

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## Abstract.

The following note shows how one can obtain one step methods of arbitrarily high order which satisfy Dahlquist's requirements of  $A$ -stability. Although most of these methods appear at the moment to be largely of theoretical interest the author is working on several practical applications.

## 1. Introduction.

In [3] Dahlquist defines  $A$ -stability as follows:

**DEFINITION.** *A  $k$ -step method is called  $A$ -stable, if all of its solutions tend to zero, as  $n \rightarrow \infty$ , when the method is applied with fixed positive  $h$  to any differential equation of the form*

$$(1) \quad \frac{dy}{dx} = qy$$

where  $q$  is a complex constant with negative real part.

He then establishes that the trapezoid rule is the most accurate linear multi-step method satisfying his  $A$ -stability requirement and also points out that the classical 4th order Runge–Kutta process is not  $A$ -stable. The same can be said for all other explicit R. K. processes.

## 2. $A$ -Stable Runge-Kutta Methods.

Butcher [2] has shown that for any positive integer  $n$ , there exists an  $n$  stage implicit R. K. process of order  $2n$ , of the form:

$$K_i = f \left( y_0 + h \sum_{j=1}^n \beta_{ij} K_j \right) \quad (i = 1, 2, \dots, n)$$

$$y_1 = y_0 + h \sum_{i=1}^n b_i K_i.$$

It is not difficult to show that when Butcher's  $n$  stage method is applied to (1) we obtain simply the  $n$ th diagonal Padé approximation  $P_{nn}(x)$

of  $\exp(x)$  for  $x=qh$  [7]. This follows from the fact that Butcher's stage method applied to (1) reduces to the quotient of two polynomials of degree  $n$  in  $qh$  and since this rational function must be an approximation of order  $2n$  of the exponential function it follows that it is the diagonal Padé approximation  $P_{nn}(qh)$  of  $\exp(qh)$  [7]. For example, Butcher's 2 stage method has

$$\begin{aligned}\beta_{11} &= \frac{1}{4} & \beta_{12} &= \frac{1}{4} - \frac{\sqrt{3}}{6} \\ \beta_{21} &= \frac{1}{4} + \frac{\sqrt{3}}{6} & \beta_{22} &= \frac{1}{4} \\ b_1 &= \frac{1}{2} & b_2 &= \frac{1}{2}\end{aligned}$$

and hence for (1) we would have

$$\begin{aligned}K_1 &= q \left( y_0 + \frac{h}{4} K_1 + \left( \frac{1}{4} - \frac{\sqrt{3}}{6} \right) h K_2 \right), \\ K_2 &= q \left( y_0 + \left( \frac{1}{4} + \frac{\sqrt{3}}{6} \right) h K_1 + \frac{h}{4} K_2 \right).\end{aligned}$$

Hence, solving for  $K_1$  and  $K_2$  using Cramer's rule gives

$$\begin{aligned}K_1 &= qy_0 \left( 1 - \frac{qh\sqrt{3}}{6} \right) / \Delta, \\ K_2 &= qy_0 \left( 1 + \frac{qh\sqrt{3}}{6} \right) / \Delta,\end{aligned}$$

where

$$\Delta = 1 - \frac{1}{2}(qh) + \frac{(qh)^2}{12}.$$

Finally,

$$\begin{aligned}y_1 &= y_0 + h(b_1 K_1 + b_2 K_2) \\ &= \left( \frac{1 + \frac{1}{2}qh + \frac{(qh)^2}{12}}{1 - \frac{1}{2}(qh) + \frac{(qh)^2}{12}} \right) y_0 \\ &= P_{22}(qh)y_0.\end{aligned}$$

Now Birkhoff & Varga [1] have noted that the diagonal Padé approximations  $P_{nn}(z)$  have the property that  $|P_{nn}(z)| \leq 1$  for  $R(z) \leq 0$  for

$n = 0, 1, 2, \dots$  and hence Butcher's  $n$ -stage implicit  $RK$  processes of order  $2n$  are  $A$ -stable for  $n = 1, 2, 3, \dots$ .

### 3. Additional $A$ -Stable one step methods.

If one is willing to allow the introduction of second and higher derivatives into the equations being used then a generalized class of linear one step methods first given by Obrechhoff [5] of the form

$$(2) \quad y_{n+1} = y_n + \sum_{i=1}^j \alpha_{ij} h^i ((-1)^{i+1} y_{n+1}^{(i)} + y_n^{(i)}) \quad (j = 1, 2, 3, \dots)$$

also exist which are of order  $2j$  when  $\alpha_{ij}$  is the  $i$ th coefficient in the numerator of the  $j$ th diagonal Padé approximation  $P_{jj}(x)$  of  $e^x$ . Thus for (1), (2) reduces to  $y_{n+1} = P_{jj}(qh)y_n$  and (2) is  $A$ -stable for all  $j$ . Note that for  $j=1$  in (2) we have simply Dahlquist's result and for  $j=2$  we have Milne's method [4, page 76, equation 35.1] which Ralston [6] observed was unconditionally stable. Milne [4, page 78] has also considered (2) for the case  $j=3$  but no discussion of stability appears to have been previously made for the cases  $j \geq 3$ .

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