

Evolutionary Computation: A Unified Approach

Kenneth De Jong

Computer Science Department
George Mason University
kdejong@gmu.edu
www.cs.gmu.edu/~eclab

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1

Historical roots:

- **Evolution Strategies (ESs):**

- developed by Rechenberg, Schwefel, etc. in 1960s.
- focus: real-valued parameter optimization
- individual: vector of real-valued parameters
- reproduction: Gaussian “mutation” of parameters
- M parents, $K \gg M$ offspring

2

Historical roots:

- **Evolutionary Programming (EP):**

- Developed by Fogel in 1960s
- Goal: evolve intelligent behavior
- Individuals: finite state machines
- Offspring via mutation of FSMs
- M parents, M offspring

3

Historical roots:

- **Genetic Algorithms (GAs):**

- developed by Holland in 1960s
- goal: robust, adaptive systems
- used an internal “genetic” encoding of points
- reproduction via mutation and recombination of the genetic code.
- M parents, M offspring

4

Present Status:

- wide variety of evolutionary algorithms (EAs)
- wide variety of applications
 - optimization
 - search
 - learning, adaptation
- well-developed analysis
 - theoretical
 - experimental

5

Interesting dilemma:

- A bewildering variety of algorithms and approaches:
 - GAs, ESs, EP, GP, Genitor, CHC, messy GAs, ...
- Hard to see relationships, assess strengths & weaknesses, make choices, ...

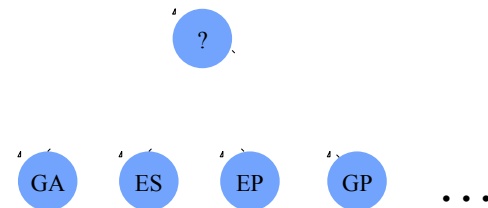
6

A Personal Interest:

- Develop a general framework that:
 - Helps one compare and contrast approaches.
 - Encourages crossbreeding.
 - Facilitates intelligent design choices.

7

Viewpoint:



8

Starting point:

- Common features
- Basic definitions and terminology

9

Common Features:

- Use of Darwinian-like evolutionary processes to solve difficult computational problems.
- Hence, the name:

Evolutionary Computation

10

Key Element: An Evolutionary Algorithm

- Based on a Darwinian notion of an evolutionary system.
- Basic elements:
 - a population of “individuals”
 - a notion of “fitness”
 - a birth/death cycle biased by fitness
 - a notion of “inheritance”

11

An EA template:

1. Randomly generate an initial population.

2. Do until some stopping criteria is met:

Select individuals to be parents (biased by fitness).
Produce offspring.
Select individuals to die (biased by fitness).

End Do.

3. Return a result.

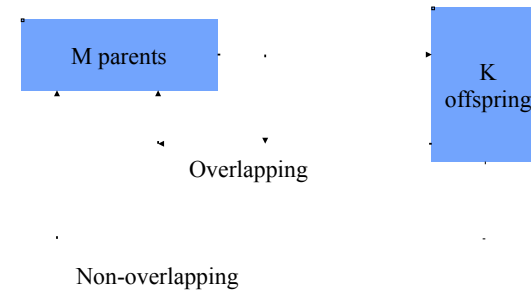
12

Instantiate by specifying:

- Population dynamics:
 - Population size
 - Parent selection
 - Reproduction and inheritance
 - Survival competition
- Representation:
 - Internal to external mapping
- Fitness

13

EA Population Dynamics:



14

Population sizing:

- Parent population size M :
 - degree of parallelism
- Offspring population size K :
 - amount of activity w/o feedback

15

Population sizing:

- Examples:
 - $M=1$, K small: early ESs
 - M small, K large: typical ESs
 - M moderate, $K=M$: traditional GAs and EP
 - M large, K small: steady state GAs
 - $M = K$ large: traditional GP

16

Selection pressure:

- Overlapping generations:
 - more pressure than non-overlapping
- Selection strategies (decreasing pressure):
 - truncation
 - tournament and ranking
 - fitness proportional
 - uniform
- Stochastic vs. deterministic

17

Reproduction:

- Preserve useful features
- Introduce variety and novelty
- Strategies:
 - single parent: cloning + mutation
 - multi-parent: recombination + mutation
 - ...
- Price's theorem:
 - fitness covariance

18

Exploitation/Exploration Balance:

- Selection pressure: exploitation
 - reduce scope of search
- Reproduction: exploration
 - expand scope of search
- Key issue: appropriate balance
 - e.g., strong selection + high mutation rates
 - e.g., weak selection + low mutation rates

19

Representation:

- How to represent the space to be searched?
 - **Genotypic** representations:
 - universal encodings
 - portability
 - minimal domain knowledge

20

Representation:

- How to represent the space to be searched?

– **Phenotypic** representations:

- problem-specific encodings
- leverage domain knowledge
- lack of portability

21

Fitness landscapes:

- Continuous/discrete
- Number of local/global peaks
- Ruggedness
- Constraints
- Static/dynamic

22

The Art of EC:

- Choosing problems that make sense.
- Choosing an appropriate EA:
 - reuse an existing one
 - hand-craft a new one

23

EC: Using EAs to Solve Problems

- What kinds of problems?
- What kinds of EAs?

24

Intuitive view:

- parallel, adaptive search procedure.
- useful global search heuristic.
- a paradigm that can be instantiated in a variety of ways.
- can be very general or problem specific.
- strong sense of fitness “optimization”.

25

Evolutionary Optimization:

- **fitness:** function to be optimized
- **individuals:** points in the space
- **reproduction:** generating new sample points from existing ones.

26

Useful Optimization Properties:

- applicable to continuous, discrete, mixed optimization problems.
- no *a priori* assumptions about convexity, continuity, differentiability, etc.
- relatively insensitive to noise
- easy to parallelize

27

Real-valued Param. Optimization:

- high dimensional problems
- highly multi-modal problems
- problems with non-linear constraints

28

Discrete Optimization:

- TSP problems
- Boolean satisfiability problems
- Frequency assignment problems
- Job shop scheduling problems

29

Multi-objective Optimization:

- Pareto optimality problems
- a variety of industrial problems

30

Properties of standard EAs:

- **GAs:**
 - universality encourages new applications
 - well-balanced for global search
 - requires mapping to internal representation

31

Properties of standard EAs:

- **ESs:**
 - well-suited for real-valued optimization.
 - built-in self-adaptation.
 - requires significant redesign for other application areas.

32

Properties of standard EAs:

- **EP:**
 - well-suited for phenotypic representations.
 - encourages domain-specific representation and operators.
 - requires significant design for each application area.

33

Other EAs:

- **GENITOR: (Whitley)**
 - “steady state” population dynamics
 - K=1 offspring
 - overlapping generations
 - parent selection: ranking
 - survival selection: ranking
 - large population sizes
 - high mutation rates

34

Other EAs:

- **GP: (Koza)**
 - standard GA population dynamics
 - individuals: parse trees of Lisp code
 - large population sizes
 - specialized crossover
 - minimal mutation

35

Other EAs:

- **Messy GAs: (Goldberg)**
 - Standard GA population dynamics
 - Adaptive binary representation
 - genes are position-independent

36

Other EAs:

- GENOCOP: (Michalewicz)
 - Standard GA population dynamics
 - Specialized representation & operators for real valued constrained optimization problems.

37

Designing an EA:

- Choose an appropriate representation
 - effective building blocks
 - semantically meaningful subassemblies
- Choose effective reproductive operators
 - fitness covariance

38

Designing an EA:

- Choose appropriate selection pressure
 - local vs. global search
- Choosing a useful fitness function
 - exploitable information

39

Industrial Example: Evolving NLP Tagging Rules

- Existing tagging engine
- Existing rule syntax
- Existing rule semantics
- Goal: improve
 - development time for new domains
 - tagging accuracy

40

Evolving NLP Tagging Rules

- Representation: (first thoughts)
 - variable length list of GP-like trees



- Difficulty: effective operators

41

Evolving NLP Tagging Rules

- Representation: (second thoughts)
 - variable length list of pointers to rules



- Operators:
 - mutation: permute, delete rules
 - recombination: exchange rule subsets
 - Lamarckian: add a new rule

42

Evolving NLP Tagging Rules

- Population dynamics:
 - multi-modal: $M > \text{small}$
 - typical: 30-50
 - high operator variance: $K/M > 1$
 - typical: 3-5 : 1
 - parent selection: uniform
 - survival selection: binary tournament

43

Evolving NLP Tagging Rules

- So, what is this thing?
 - A GA, ES, EP, ...
- My answer:
 - a thoughtfully designed EA

44

Analysis tools:

- Schema analysis
- Convergence analysis
- Markov models
- Statistical Mechanics
- Visualization

45

New developments and directions:

- Exploiting parallelism:
 - coarsely grained network models
 - isolated islands with occasional migrations
 - finely grained diffusion models
 - continuous interaction in local neighborhoods

46

New developments and directions:

- Co-evolutionary models:
 - competitive co-evolution
 - improve performance via “arms race”
 - cooperative co-evolution
 - evolve subcomponents in parallel

47

New developments and directions:

- Exploiting Morphogenesis:
 - sophisticated genotype --> phenotype mappings
 - evolve plans for building complex objects rather than the objects themselves.

48

New developments and directions:

- Self-adaptive EAs:

- dynamically adapt to problem characteristics:
 - varying population size
 - varying selection pressure
 - varying representation
 - varying reproductive operators
- goal: robust “black box” optimizer

49

New developments and directions:

- Hybrid Systems:

- combine EAs with other techniques:
 - EAs and gradient methods
 - EAs and TABU search
 - EAs and ANNs
 - EAs and symbolic machine learning

50

New developments and directions:

- Time-varying environments:

- fitness landscape changes during evolution
- goal: adaptation, tracking
- standard optimization-oriented EAs not well-suited for this.

51

New developments and directions:

- Agent-oriented problems:

- individuals more autonomous, active
- fitness a function of other agents and environment-altering actions
- standard optimization-oriented EAs not well-suited for this.

52

EA Generalizations:

- **Meta-heuristics:**
 - Heuristic for designing heuristics
 - E.g., hill climbing, greedy, ...
 - Adopt no-free lunch view
 - Instantiate EA template in a problem-specific manner

53

EA Generalizations:

- **Nature-Inspired Computation:**
 - Early example: simulated annealing
 - Today: evolutionary algorithms
 - Others: particle swarm, ant colony, ...

54

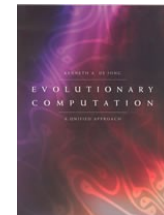
Conclusions:

- **Powerful tool for your toolbox.**
- **Complements other techniques.**
- **Best viewed as a paradigm to be instantiated, guided by theory and practice.**
- **Success a function of particular instantiation.**

55

More information:

- **Journals:**
 - Evolutionary Computation (MIT Press)
 - Trans. on Evolutionary Computation (IEEE)
 - Genetic Programming & Evolvable Hardware
- **Conferences:**
 - GECCO, CEC, PPSN, FOGA, ...
- **Internet:**
 - www.cs.gmu.edu/~eclab
- **My book:**
 - Evolutionary Computation: A Unified Approach
 - MIT Press, 2006



56