

Instruc

Instructor/Presenter

- Ken Stanley's connections to Generative and Developmental Systems (GDS):
 - Co-author of 2003 GDS review paper, A Taxonomy for Artificial Embryogeny
 - Co-founder of GECCO GDS Track in 2007 and Co-chair of track from 2007-2009 (now integrated into "Complex Systems" track)
 - Co-inventor of NEAT, CPPN indirect encoding, and the HyperNEAT GDS algorithm

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- At least 20 GDS-related publications

K. O. Stanley and R. Miikkulainen. <u>A taxonomy for artificial embryogeny</u>. Artificial Life, 9(2):93–130, 2003.

Course Agenda

- Part 1: Intro to GDS
 - Motivation
 - Classical Encodings
 - Dimensions of Development
- Break
- Part 2: Exploring Abstraction
 - CPPNs
 - HyperNEAT
 - Representations and theoretical issues

Objectives of the Tutorial

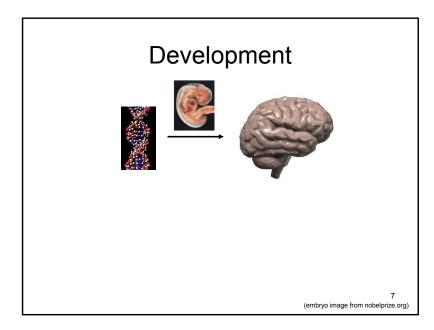
- At the end, you will know:
 - What GDS is about
 - Motivation for GDS
 - Historical precedent
 - Popular approaches
 - Biological analogies
 - Recent approaches
 - Representational properties
 - Theoretical issues
 - Goals for the field

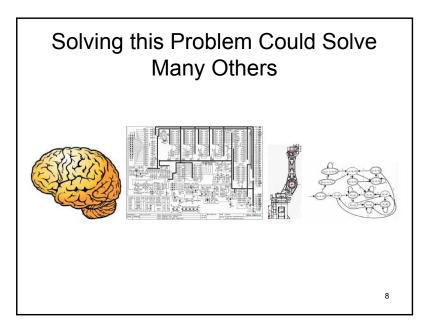
Inspiration vs. Simulation

- Often confused in GDS
 - Simulation: Model biology to learn about biology
 - Inspiration: Abstract biology to create new algorithms
- This tutorial's perspective: Looking for *inspiration*
 - What from biology is *essential* to achieve what we want?
 - What can be ignored?
 - What should we add that is biologically implausible yet works better for our purposes?

Goal: Evolve Systems of Biological Complexity Image: Image: Image: Open state of the systems of Biological Complexity Image: Imag

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Historical Precedent

- Turing (1952) was interested in morphogenesis
 - Experimented with reaction-diffusion equations in pattern generation
- Lindenmayer (1968) investigated plant growth
 - Developed L-systems, a grammatical rewrite system that abstracts how plants develop

Lindenmayer, A. (1968). <u>Mathematical models for cellular interaction in development: Parts I and II</u>. Journal of Theoretical Biology, 18, 280–299, 300–315. Turing, A. (1952). <u>The chemical basis of morphogenesis</u>. *Philosophical Transactions of the Royal Society B*, 237, 37–72.

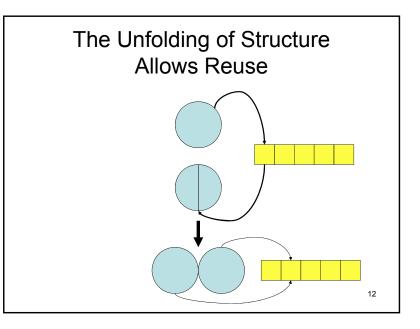
A Field with Many Names

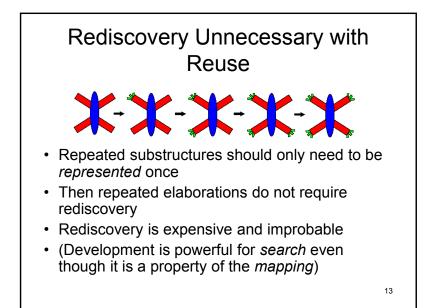
- Generative and Developmental Systems (GECCO track)
- Artificial Embryogeny
- Artificial Ontogeny
- Computational Embryogeny
- Computational Embryology
- Developmental Encoding
- Indirect Encoding
- Generative Encoding
- Generative Mapping
- ...

Development is Powerful Because of Reuse

- Genetic information is reused during embryo development
- Many structures share information
- Allows enormous complexity to be encoded compactly

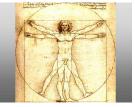






Indirect encoding: Genes do not map directly to units of structure in phenotype
Phenotype develops from embryo into mature form
Genetic material can be reused
Many existing developmental encoding systems

Therefore, GDS





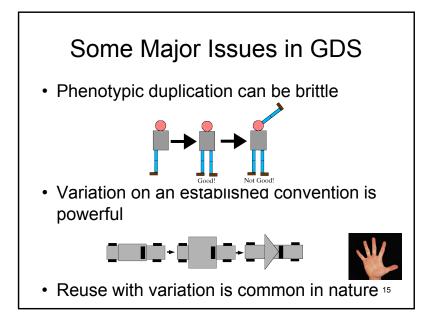


Symmetry

Repetition

Repetition with variation

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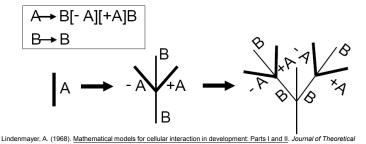


Classic Developmental Encodings

- Grammatical (Generative)
 - Utilize properties of grammars and computer languages
 - Subroutines and hierarchy
- Cell chemistry (Development)
 - Simulate low-level chemical and biological properties
 - Diffusion, reaction, growth, signaling, etc.

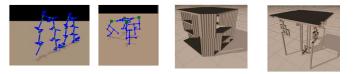
Grammatical Example 1

• L-systems: Good for fractal-like structures, plants, highly regular structures



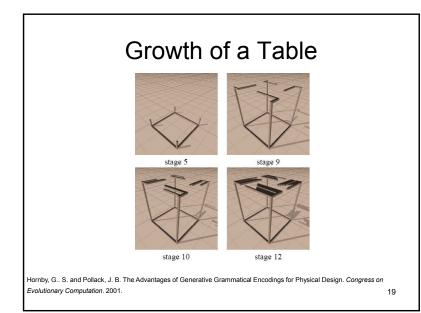
Biology, 18, 280–299, 300–315. Lindenmayer, A. (1974). Adding continuous components to L-systems. In G. Rozenberg & A. Salomaa (Eds.), L systems: 17 Lecture notes in computer science 15 (pp. 53–68). Heidelberg, Germany: Springer-Verlag.

L-System Evolution Successes



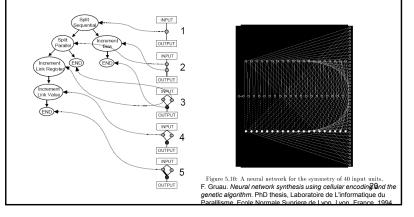
- Greg Hornby's Ph.D. dissertation topic (http://ic.arc.nasa.gov/people/hornby)
- · Clear advantage over direct encodings

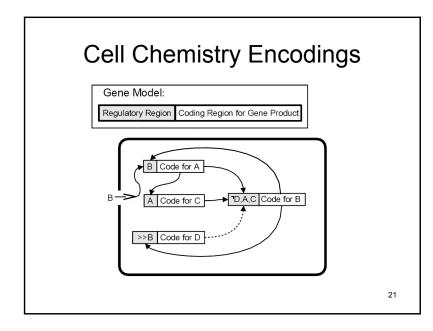


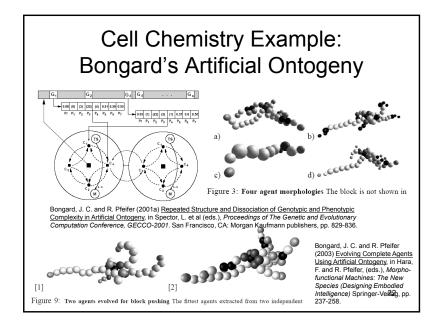


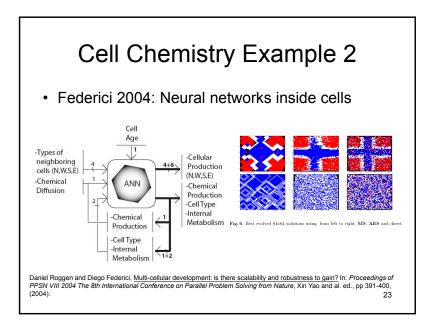
Grammatical Example 2

• Cellular Encoding (CE; Gruau 1993, 1996)



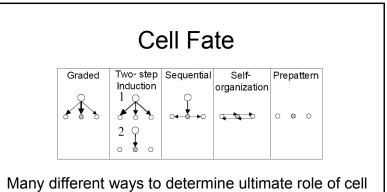




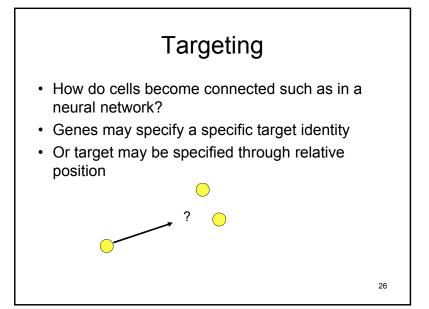


Differences in GDS Implementations

- Encoding: Grammatical vs. Cell-chemistry vs. Other (coming later)
- Cell Fate: Final role determined in several ways
- · Targeting: Special or relative target specification
- Canalization: Robustness to small disturbances
- Complexification: From fixed-length genomes to expanding genomes

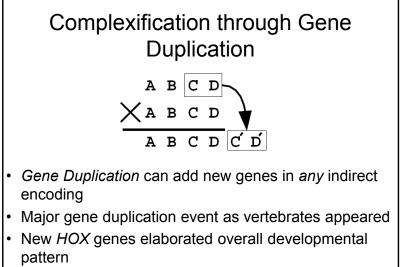


 Cell positioning mechanism can also differ from nature

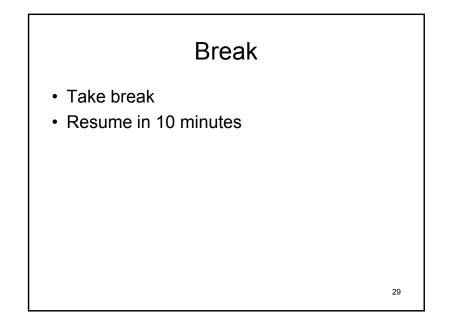


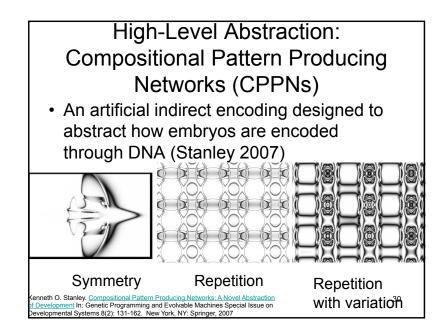


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• Initially redundant regulatory roles are partitioned ²⁸

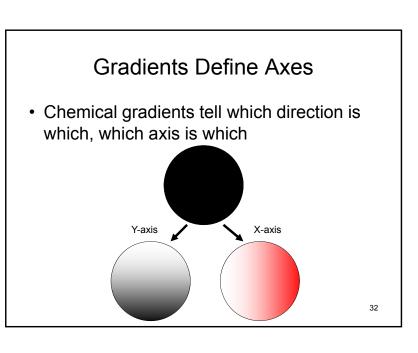




What is Development Really Doing?

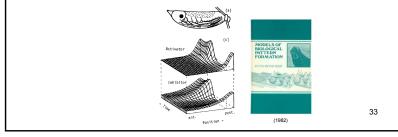
- A plan upon a plan upon a plan
- Each layer lays a groundwork for the next
- A structure is built in a coordinate frame
 - First the axes must be defined
 - Then the core structure is situated
 - Then further axes are defined

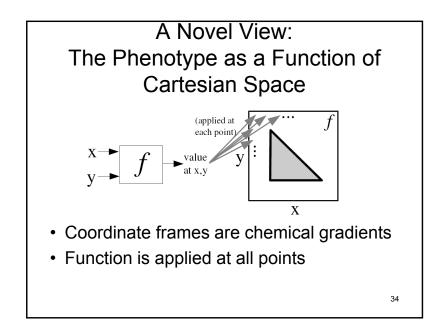
 $-\operatorname{And}$ so on

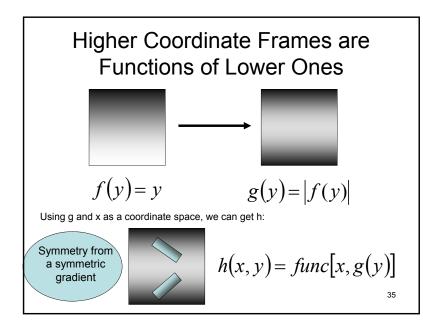


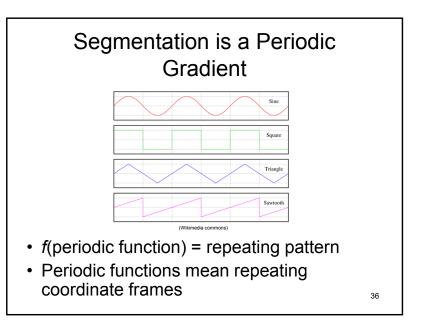
Cells Know Where They Are Through Gradients

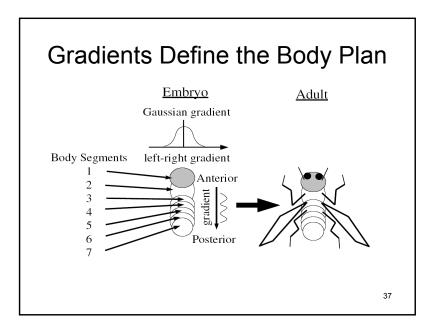
- Therefore, they know who needs to do what, and where
- Because where is now defined
- Gradients form a coordinate frame

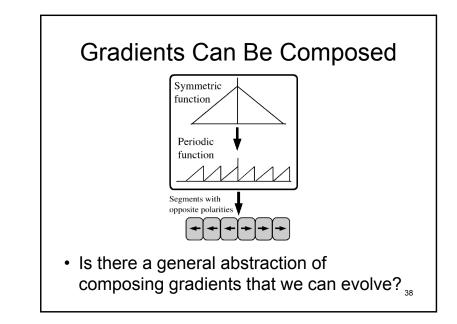


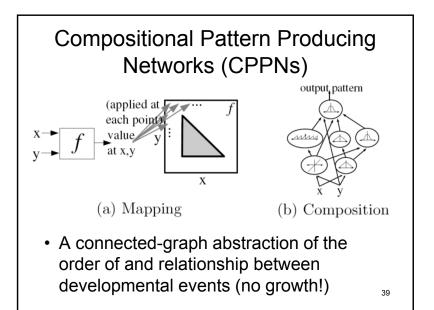


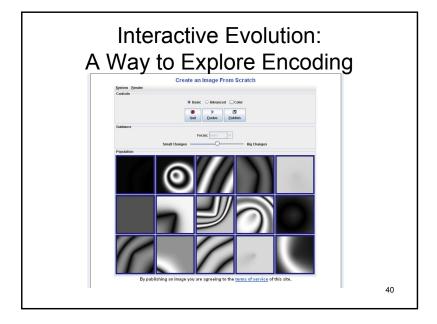


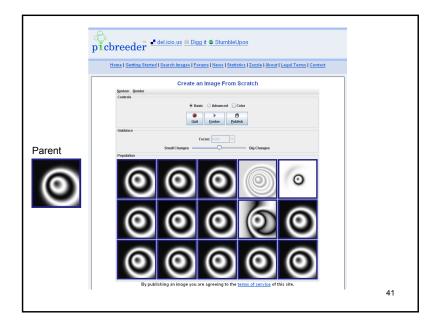




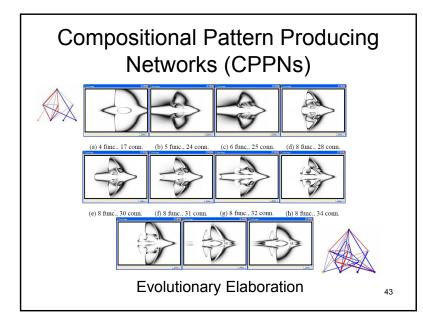


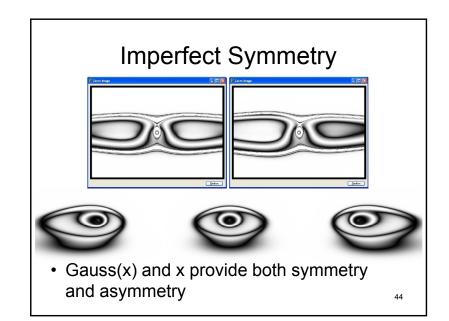


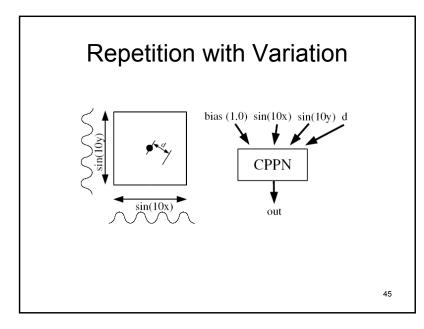




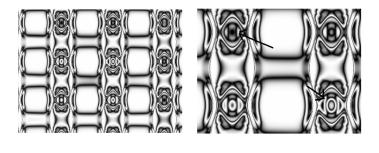








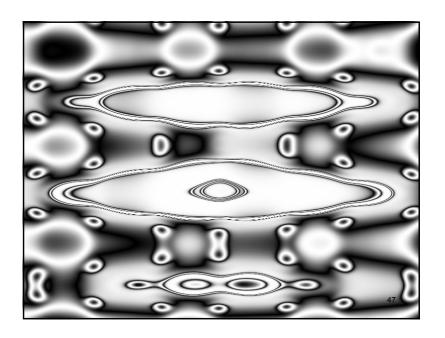
CPPNs:Repetition with Variation

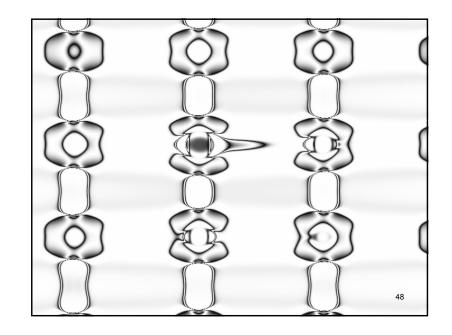


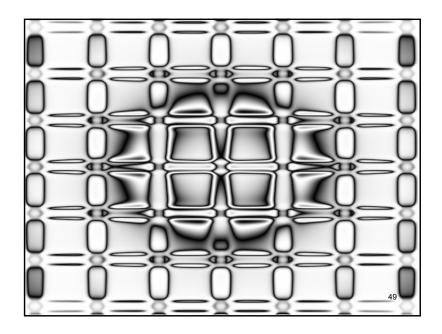
- Seen throughout nature
- A simple combination of periodic and absolute coordinate frames

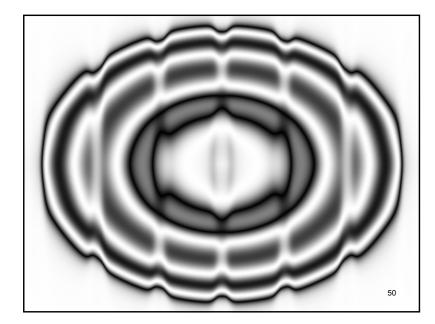
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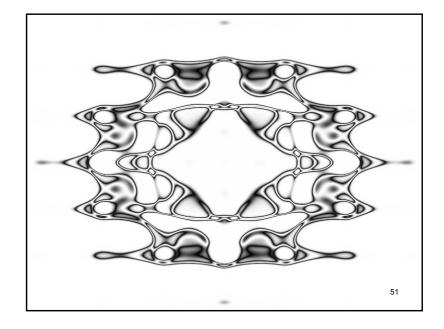
• A novel view: not a traditional subroutine

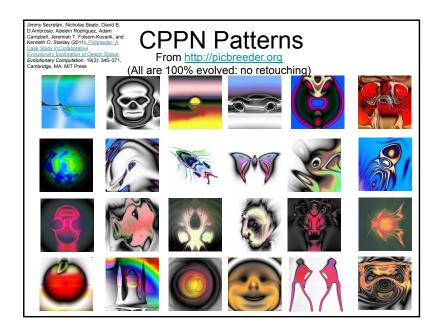


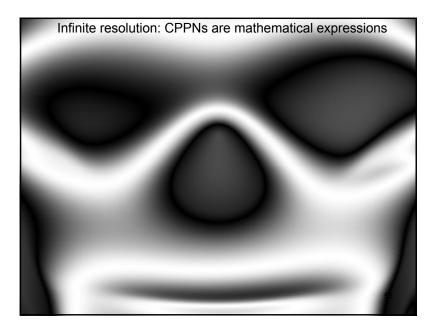


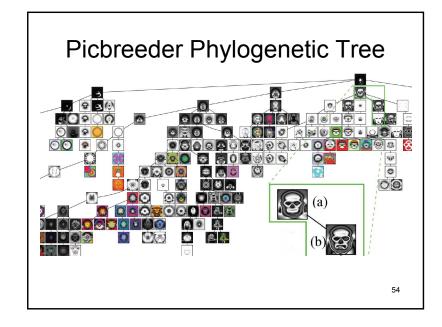












CPPNs Abstract Development out of Development!

- CPPN is decoded by querying each point in space *independently:* no local interaction
- The process of development need not be simulated
- Some Advantages:
 - Patterns stored at infinite resolution
 - Easily biased in fancy ways
 - Perfect regeneration of damaged structure

Is development really the essential property of developmental systems that we've been looking for? Or is there something more fundamental that is simply manifested through development? 55

Are Unfolding Over Time and Local Interaction Essential to Development?

- What is lost if they are abstracted away?
- What is the role of local interaction?
 - "Where am I?"
 - If I know where I am, do I need it?
- Response to CPPNs:
 - Some are arguing that *intermediate* information during development can be exploited by evolution T. Kowaliw and W. Banzhaf, Augmenting Artificial Development with Local Fitness. In IEEE CEC 2009

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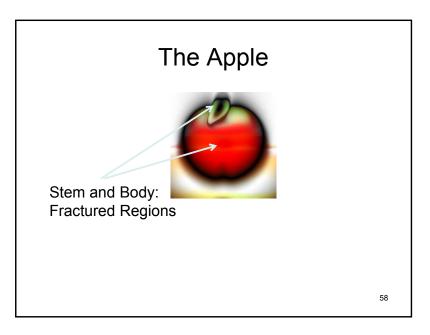
Still, CPPNs can be iterated over time
 – CPPNs can take environmental inputs

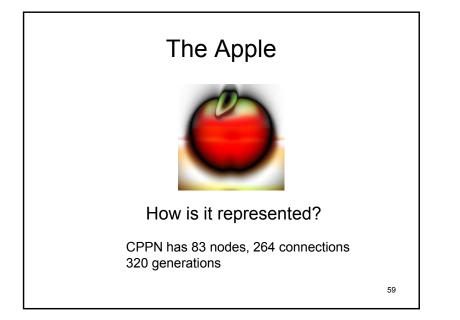
Representational Properties of CPPNs

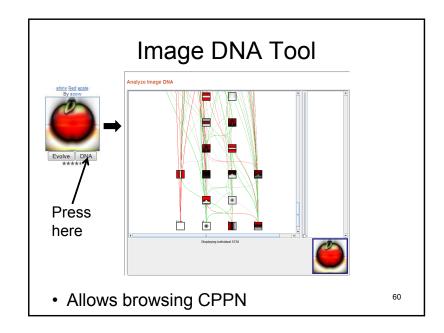
- Compositionality
 - One pattern can be built upon another (output of one function fed into another)
- Fracture
 - Discontinuous variation of patterns
 "fractured problems have a highly discontinuous mapping between states and optimal actions."
 Nate Kohl and Risto Mikkulainen (2009). Evolving Neural Networks for Strategic Decision-Making Problems. Neural Networks. Special Issue on Goal-Directed Neural Systems.

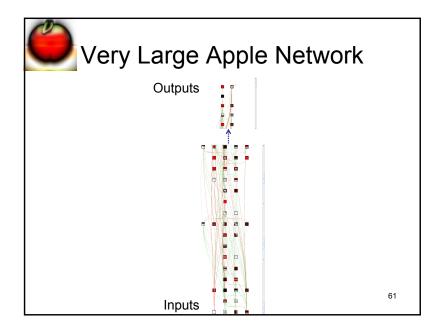


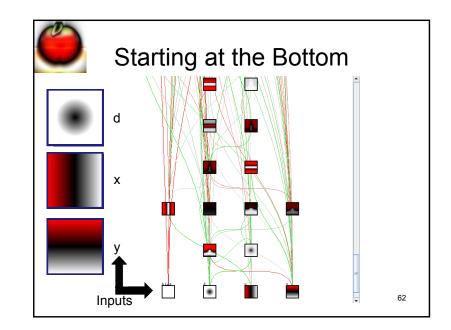
- Define different regions
- Builds incrementally over evolution

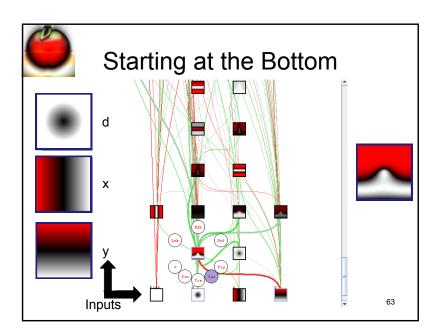


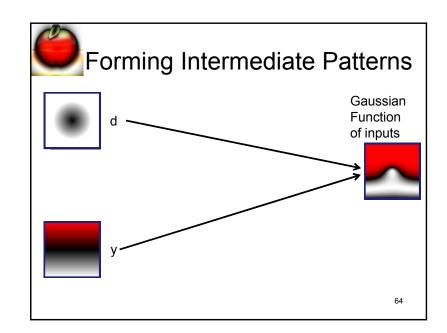


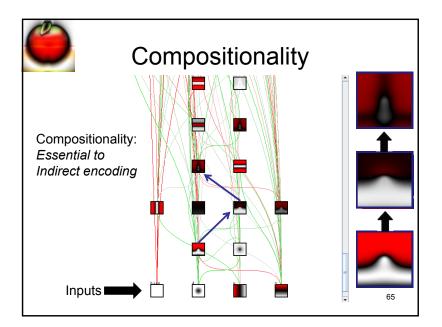


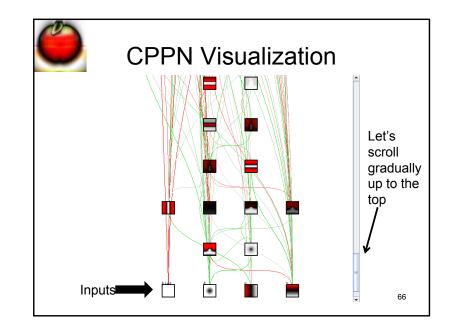


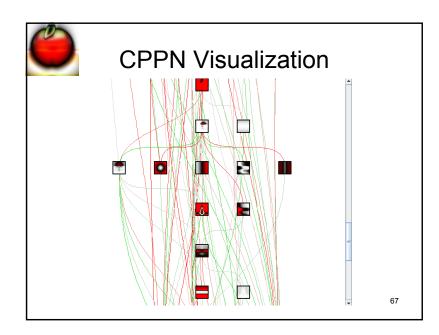


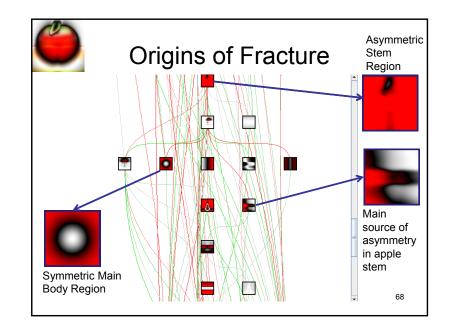


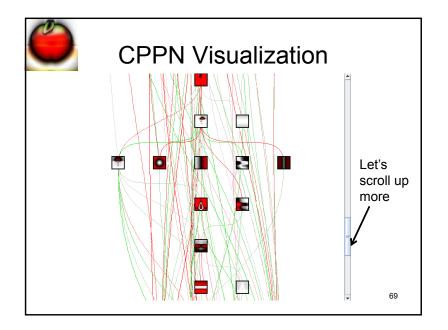


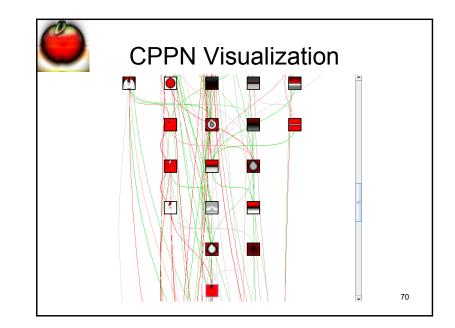


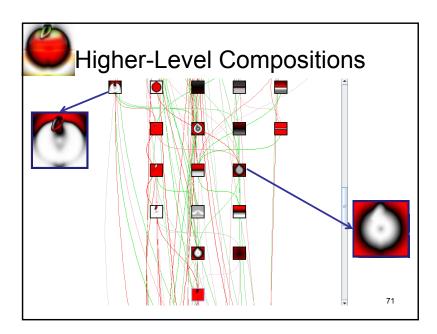


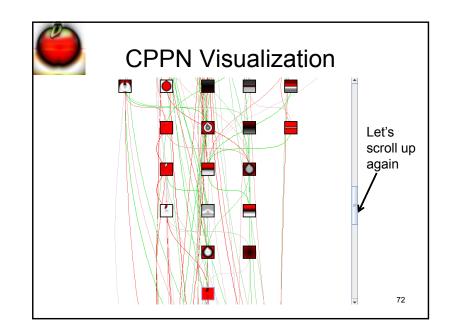


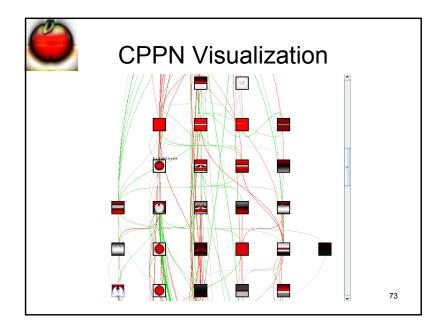


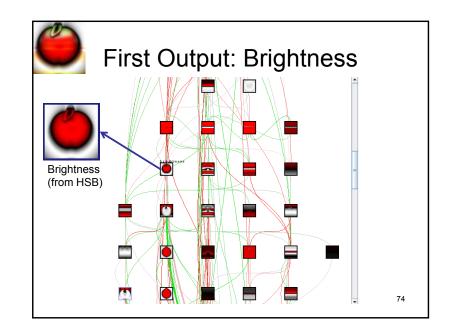


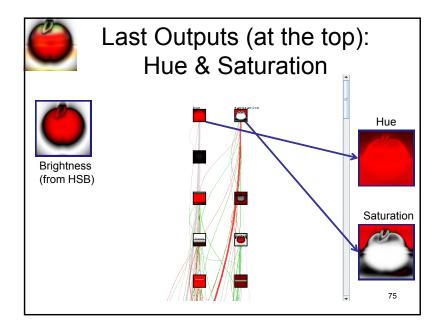


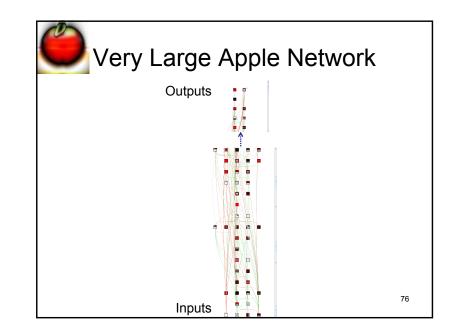


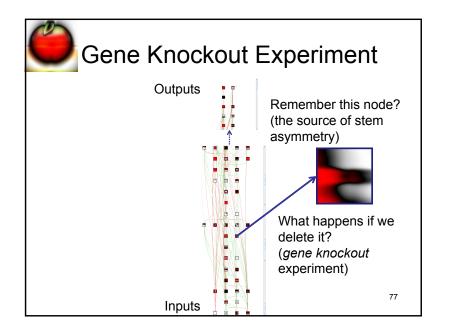


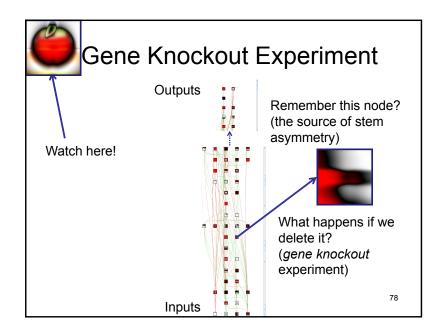


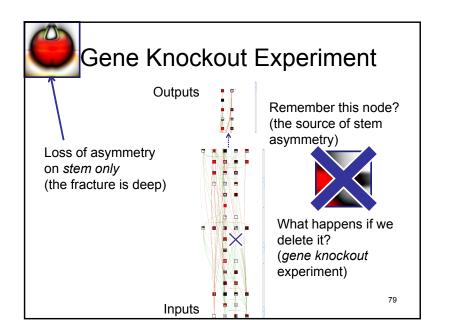


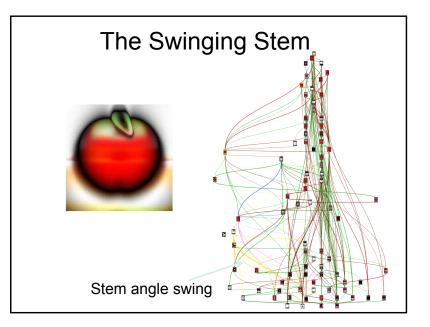












Other Notable Fracture

• Where would you split this image?

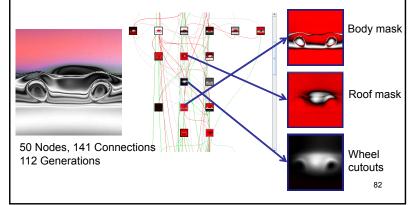


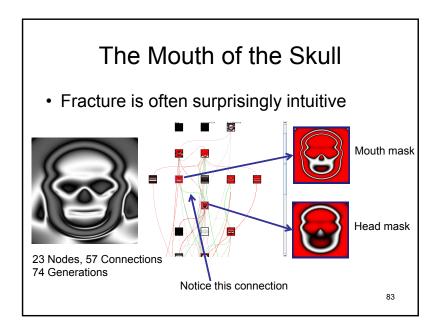
50 Nodes, 141 Connections 112 Generations

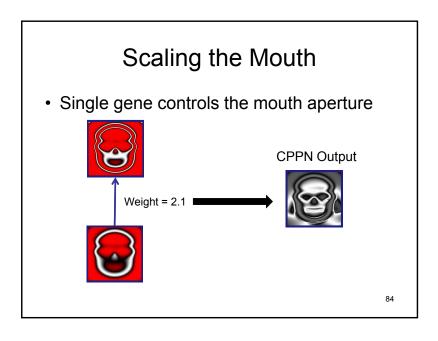
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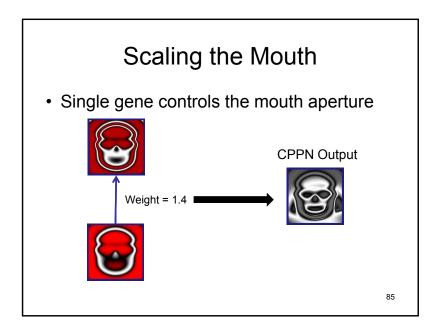
Other Notable Fracture

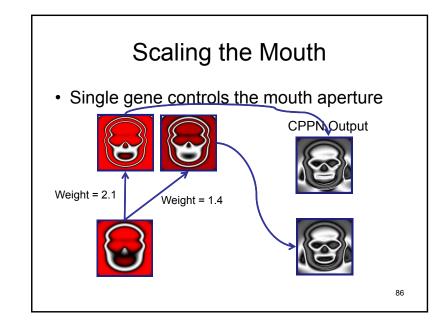
Masks for different parts inside the CPPN

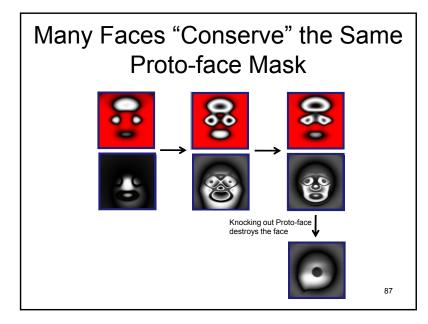


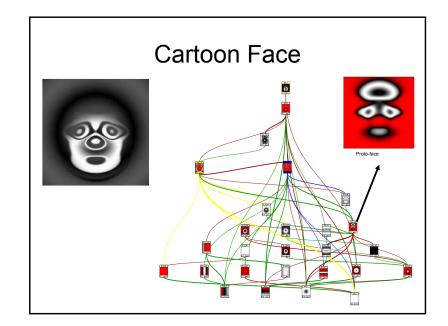


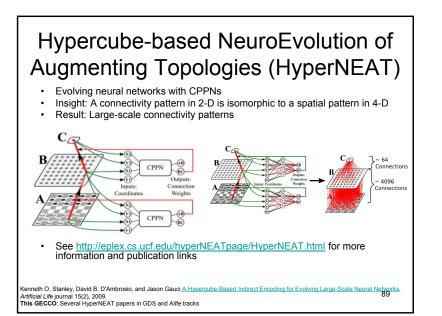


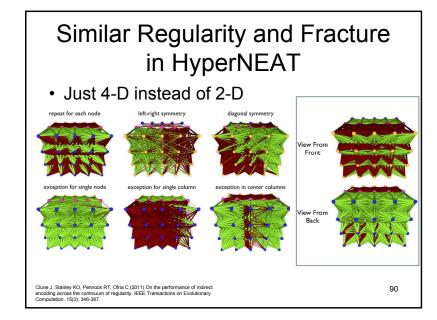


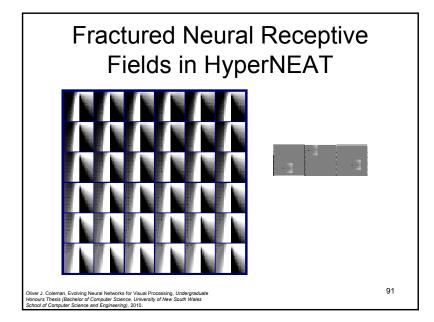


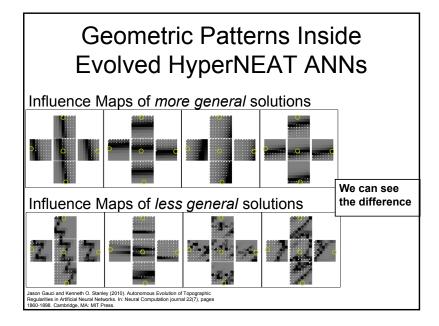


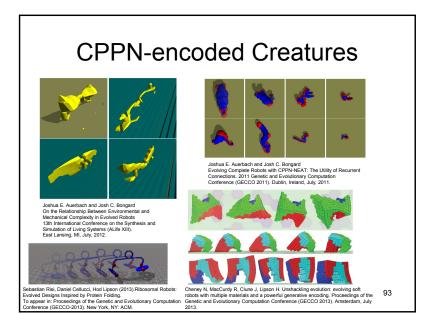












A Word of Caution: The Objective Paradox

- The full potential of an indirect encoding may not be revealed by testing whether it can evolve to satisfy a particular objective
- Reason: Fundamental discoveries (like symmetry) that are essential for further progress may yield no objective improvement on task fitness (like "walk far")

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Example: Evolve a Skull and a Butterfly with CPPNs

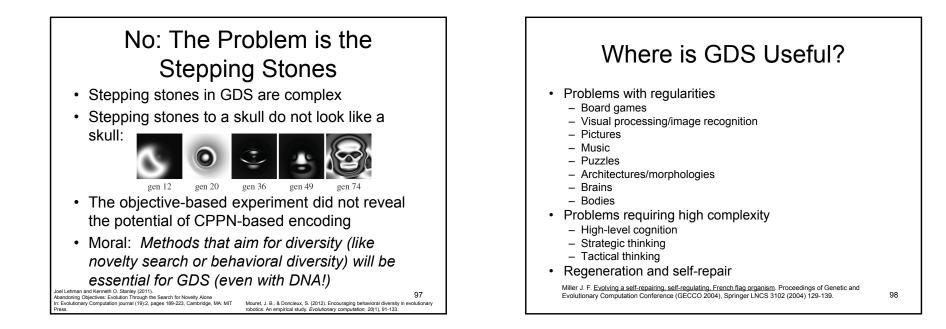


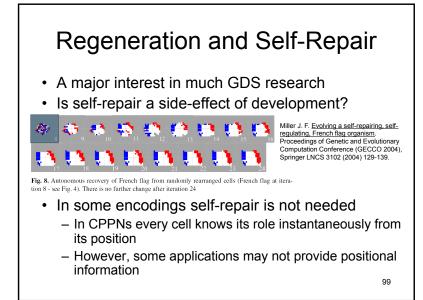


Target Image 1

Target Image 2

Results Are Terrible Priori Objectives on Evolution and Representation Evolutionary Computation Conference (GECCO-2 Typical best results given 30,000 generations (only odd runs shown) Skul 20f. 24c 20f, 29c 19f, 24c 22f, 28c 21f, 28c 16f, 22c 21f, 27c 23f, 29c 18f, 25c 25f. 28c failed Butterf Run 11 Run 13 Run 15 Run 9 21f. 27c 27f. 34c 21f 27c 22f 25c 20f 28c 18f 23c failed failed failed failed failed failed failed Question: Was it a bad fitness function?





Where is GDS not Useful?

- · Problems without regularity
- Simple high-precision domains
 Very small picture reproduction
- · Simple control tasks
 - Go to the food
 - Balance the pole (5-connection solution)

Long Term Issues

- What are the ultimate encodings?
- What are the ultimate applications?
- What application requires a structure of 100 million parts and actually utilizes the structure?
 - How can we formalize the problem?
- How can GDS combine with plasticity?
- How can we make progress despite the objective paradox?

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More information

- My Homepage: <u>http://www.cs.ucf.edu/~kstanley</u>
- NEAT Users Group: <u>http://groups.yahoo.com/group/neat</u>
- Evolutionary Complexity Research Group: <u>http://eplex.cs.ucf.edu</u>
- Picbreeder: <u>http://picbreeder.org</u>
- HyperNEAT Information: <u>http://eplex.cs.ucf.edu/hyperNEATpage/HyperNEAT.html</u>

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Email: kstanley@eecs.ucf.edu

References from Slides

Joshua E. Auerbach and Josh C. Bongard. On the Relationship Between Environmental and Mechanical Complexity in Evolved Robots Proceedings of the 13th International Conference on the Synthesis and Simulation of Living Systems (ALIF XIII). East Lansing, MI, July, 2012.

Joshua E. Auerbach and Josh C. Bongard. Evolving Complete Robots with CPPN-NEAT: The Utility of Recurrent Connections. Proceedings of the Genetic and Evolutionary Computation Conference (GECCO 2011). Dublin, Ireland, July, 2011.

Bongard, J. C. and R. Pfeifer (2003) <u>Evolving Complete Agents Using Artificial Ontogeny</u>. In: Hara, F. and R. Pfeifer, (eds.), Morpho-functional Machines: The New Species (Designing Embodied Intelligence) Springer-Verlag, pp. 237-258.

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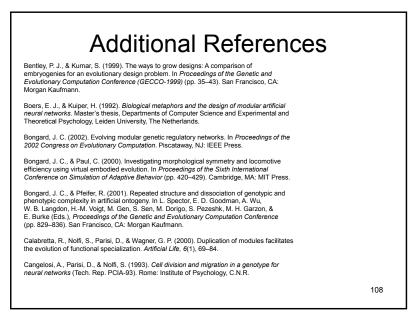
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