

Hyper-heuristics Tutorial

Daniel R. Tauritz (dtauritz@acm.org)

Natural Computation Laboratory, Missouri University of Science and Technology (<http://web.mst.edu/~tauritzd/nc-lab/>)

John Woodward (John.Woodward@cs.stir.ac.uk)

CHORDS Research Group, Stirling University
(<http://www.maths.stir.ac.uk/research/groups/chords/>)

Permission to make digital or hard copies of part or all of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. Copyrights for third-party components of this work must be honored. For all other uses, contact the Owner/Author.

GECCO '17 Companion, July 15-19, 2017, Berlin, Germany

© 2017 Copyright is held by the owner/author(s).

ACM ISBN 978-1-4503-4939-0/17/07.

<http://dx.doi.org/10.1145/3067695.3067710>

2 May, 2017

Instructors

[Daniel R. Tauritz](#) is an Associate Professor and Associate Chair for Undergraduate Studies in the [Department of Computer Science](#) at the [Missouri University of Science and Technology \(S&T\)](#), a Contract Scientist for [Los Alamos National Laboratory \(LANL\)](#) and [Sandia National Laboratories](#), the founding director of [S&T's Natural Computation Laboratory](#), and founding academic director of the LANL/S&T Cyber Security Sciences Institute. He received his Ph.D. in 2002 from [Leiden University](#). His research interests include the design of hyper-heuristics and self-configuring evolutionary algorithms and the application of computational intelligence techniques in cyber security, critical infrastructure protection, and program understanding.



[John R. Woodward](#) is a Lecturer at the [University of Stirling](#), within the [CHORDS group](#) and is employed on the [DAASE project](#), and for the previous four years was a lecturer with the [University of Nottingham](#). He holds a BSc in Theoretical Physics, an MSc in Cognitive Science and a PhD in Computer Science, all from the [University of Birmingham](#). His research interests include Automated Software Engineering, particularly Search Based Software Engineering, Artificial Intelligence/Machine Learning and in particular Genetic Programming. He has worked in industrial, military, educational and academic settings, and been employed by EDS, CERN and RAF and three UK Universities.



2 May, 2017

John R. Woodward, Daniel R. Tauritz

2

John's perspective of hyper-heuristics

2 May, 2017

John R. Woodward, Daniel R. Tauritz

3

Metaheuristic

A metaheuristic

-Sample solutions

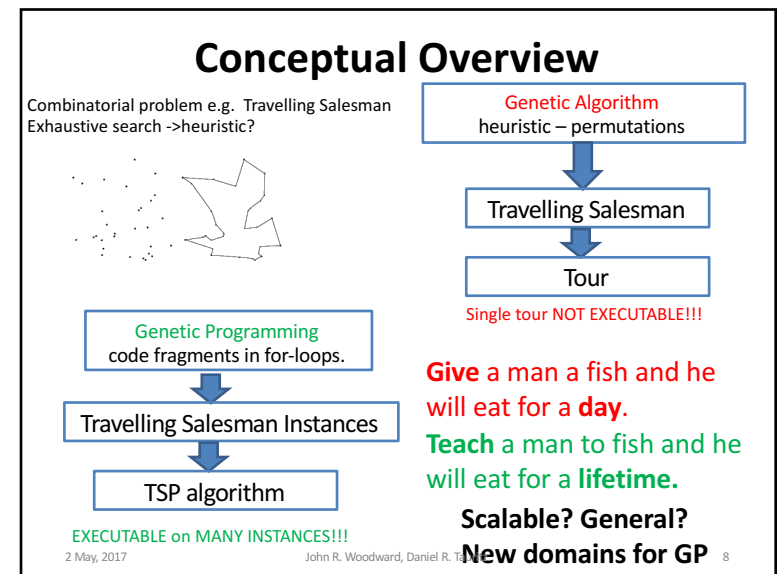
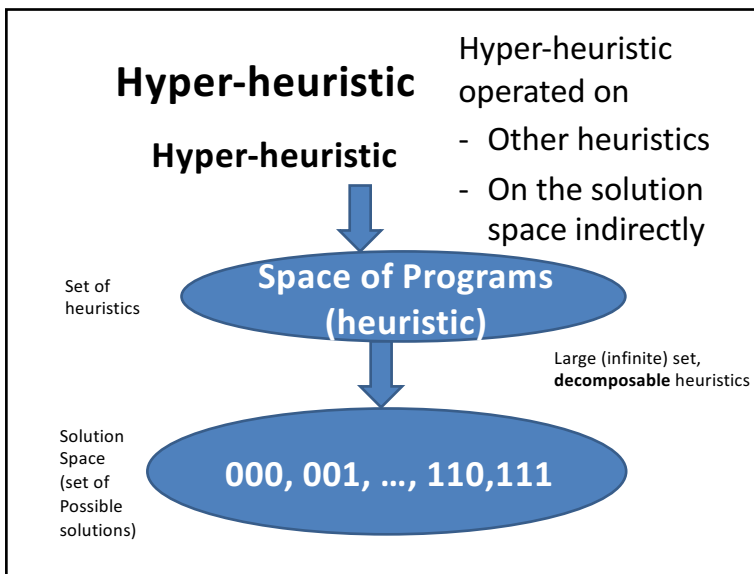
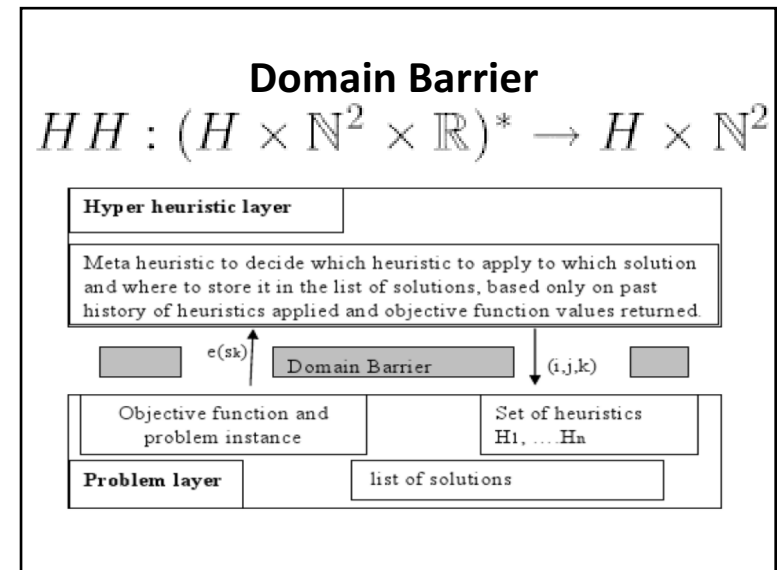
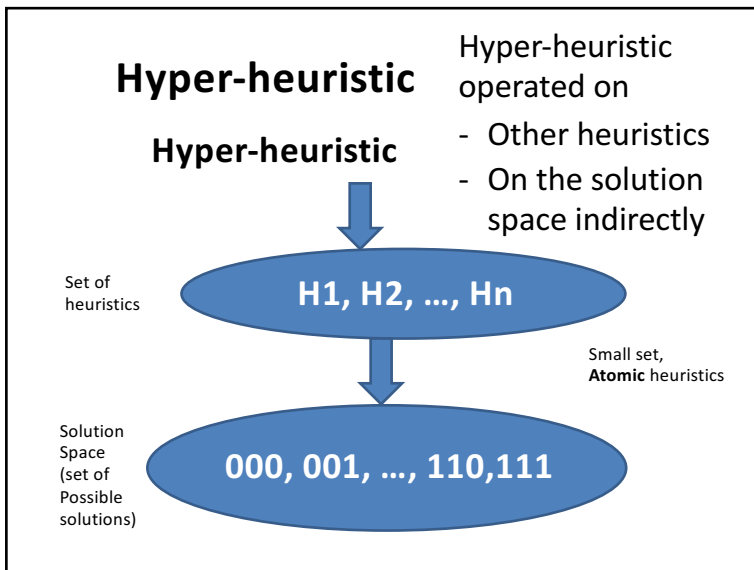
-Generates solutions

(Meta)heuristic

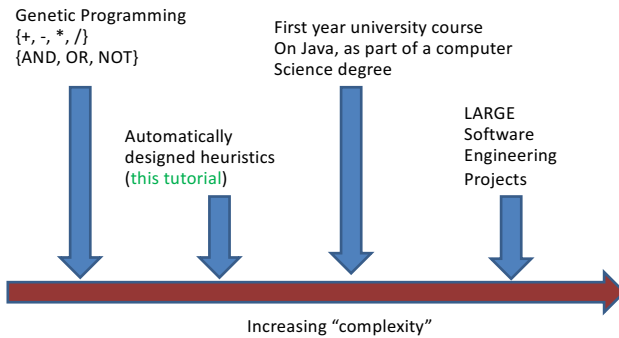


Solution Space
(set of Possible solutions)

000, 001, ..., 110, 111



Program-Complexity Spectrum

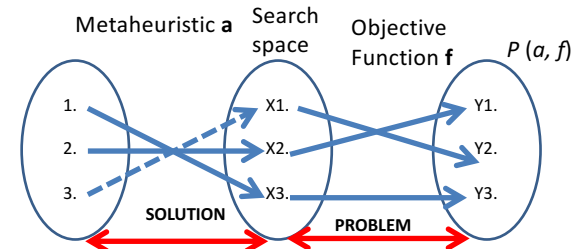


2 May, 2017

John R. Woodward, Daniel R. Tauritz

9

Theoretical Motivation 1



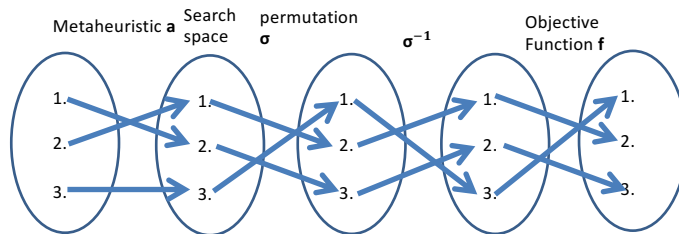
1. A **search space** contains the set of all possible solutions.
2. An **objective function** determines the quality of solution.
3. A (**Mathematical idealized**) **metaheuristic** determines the sampling order (i.e. enumerates i.e. without replacement). It is a (approximate) permutation. What are we learning?
4. **Performance measure** $P(a, f)$ depend only on y_1, y_2, y_3
5. **Aim find a solution with a near-optimal objective value using a Metaheuristic**. **ANY QUESTIONS BEFORE NEXT SLIDE?**

2 May, 2017

John R. Woodward, Daniel R. Tauritz

10

Theoretical Motivation 2



$$P(a, f) = P(a \sigma, \sigma^{-1} f) \quad P(A, F) = P(A \sigma, \sigma^{-1} F) \text{ (i.e. permute bins)}$$

P is a **performance measure**, (based only on output values).

σ, σ^{-1} are a permutation and inverse permutation.

A and F are probability distributions over algorithms and functions).

F is a **problem class**. **ASSUMPTIONS IMPLICATIONS**

1. Metaheuristic a applied to function $\sigma^{-1} f$ (that is f)

2. Metaheuristic $a \sigma$ applied to function $\sigma^{-1} f$ **precisely identical**.

2 May, 2017

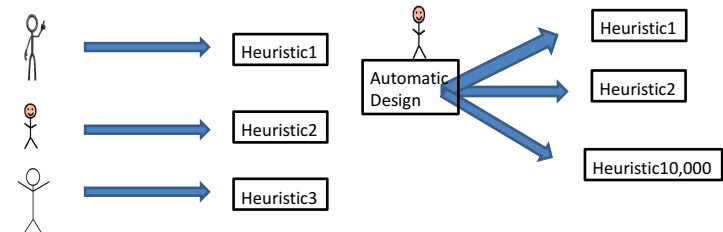
John R. Woodward, Daniel R. Tauritz

11

One Man – One/Many Algorithm

1. Researchers **design heuristics by hand** and test them on problem instances or arbitrary benchmarks off internet.
2. Presenting results at conferences and publishing in journals. In this talk/paper we propose a new algorithm...

1. **Challenge** is defining an algorithmic framework (set) that **includes** useful algorithms. **Black art**
2. Let Genetic Programming **select the best algorithm for the problem class at hand**. **Context!!!** Let the data speak for itself without imposing our assumptions. In this talk/paper we propose a 10,000 algorithms...



2 May, 2017

John R. Woodward, Daniel R. Tauritz

12

Daniel's perspective of hyper-heuristics

2 May, 2017

John R. Woodward, Daniel R. Tauritz

13

Real-World Challenges

- Researchers strive to make algorithms increasingly general-purpose
- But practitioners have very specific needs
- Designing custom algorithms tuned to particular problem instance distributions and/or computational architectures can be very time consuming

2 May, 2017

John R. Woodward, Daniel R. Tauritz

14

Automated Design of Algorithms

- Addresses the need for custom algorithms
- But due to high computational complexity, only feasible for repeated problem solving
- Hyper-heuristics accomplish automated design of algorithms by searching program space

2 May, 2017

John R. Woodward, Daniel R. Tauritz

15

Hyper-heuristics

- Hyper-heuristics are a special type of meta-heuristic
 - Step 1: Extract algorithmic primitives from existing algorithms
 - Step 2: Search the space of programs defined by the extracted primitives
- While Genetic Programming (GP) is particularly well suited for executing Step 2, other meta-heuristics can be, and have been, employed
- The type of GP employed matters [24]

2 May, 2017

John R. Woodward, Daniel R. Tauritz

16

Type of GP Matters: Experiment Description

- Implement five types of GP (tree GP, linear GP, canonical Cartesian GP, Stack GP, and Grammatical Evolution) in hyper-heuristics for evolving black-box search algorithms for solving 3-SAT
- Base hyper-heuristic fitness on the fitness of the best search algorithm generated at solving the 3-SAT problem
- Compare relative effectiveness of each GP type as a hyper-heuristic

GP Individual Description

- Search algorithms are represented as an iterative algorithm that passes one or more set of variable assignments to the next iteration
- Genetic program represents a single program iteration
- Algorithm runs starting with a random initial population of solutions for 30 seconds

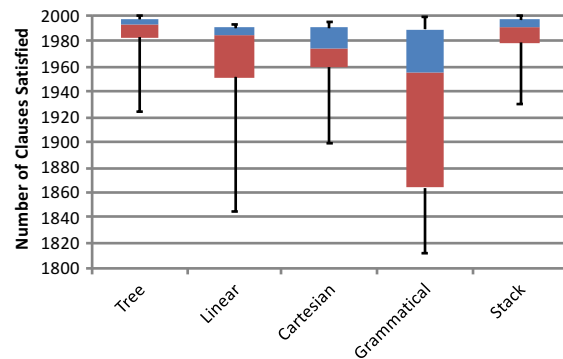
3-SAT Problem

- A subset of the Boolean Satisfiability Problem (SAT)
- The goal is to select values for Boolean variables such that a given Boolean equation evaluates as true (is satisfied)
- Boolean equations are in 3-conjunctive normal form
- Example:
 - $(A \vee B \vee C) \wedge (\neg A \vee \neg C \vee D) \wedge (\neg B \vee C \vee \neg D)$
 - Satisfied by $\neg A, B, C, \neg D$
- Fitness is the number of clauses satisfied by the best solution in the final population

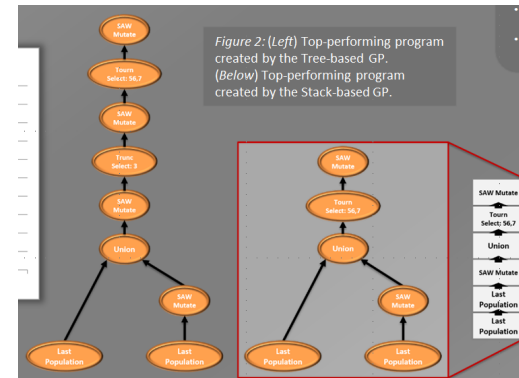
Genetic Programming Nodes Used

- Last population, Random population
- Tournament selection, Fitness proportional selection, Truncation selection, Random selection
- Bitwise mutation, Greedy flip, Quick greedy flip, Stepwise adaption of weights, Novelty
- Union

Results



Results [24]



22

Results

- Generated algorithms mostly performed comparably well on training and test problems
- Tree and stack GP perform similarly well on this problem, as do linear and Cartesian GP
- Tree and stack GP perform significantly better on this problem than linear and Cartesian GP, which perform significantly better than grammatical evolution

Conclusions

- The choice of GP type makes a significant difference in the performance of the hyper-heuristic
- The size of the search space appears to be a major factor in the performance of the hyper-heuristic

Case Study 1: The Automated Design of Crossover Operators [20]

2 May, 2017

John R. Woodward, Daniel R. Tauritz

25

Motivation

- Performance Sensitive to Crossover Selection
- Identifying & Configuring Best Traditional Crossover is Time Consuming
- Existing Operators May Be Suboptimal
- Optimal Operator May Change During Evolution

2 May, 2017

John R. Woodward, Daniel R. Tauritz

26

Some Possible Solutions

- Meta-EA
 - Exceptionally time consuming
- Self-Adaptive Algorithm Selection
 - Limited by algorithms it can choose from

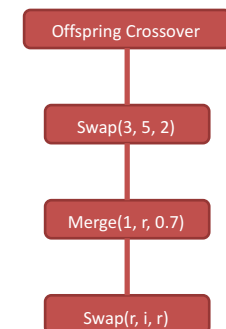
2 May, 2017

John R. Woodward, Daniel R. Tauritz

27

Self-Configuring Crossover (SCX)

- Each Individual Encodes a Crossover Operator
- Crossovers Encoded as a List of Primitives
 - Swap
 - Merge
- Each Primitive has three parameters
 - Number, Random, or Inline

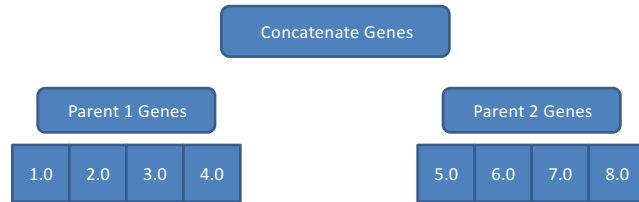


2 May, 2017

John R. Woodward, Daniel R. Tauritz

28

Applying an SCX



2 May, 2017

John R. Woodward, Daniel R. Tauritz

29

The Swap Primitive

- Each Primitive has a type
 - Swap represents crossovers that move genetic material



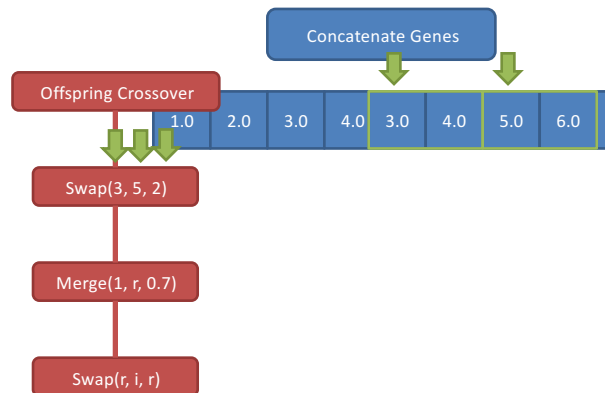
- First Two Parameters
 - Start 1 Position
 - Start 2 Position
- Third Parameter Primitive Dependent
 - Swaps use "Width"

2 May, 2017

John R. Woodward, Daniel R. Tauritz

30

Applying an SCX



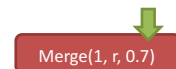
2 May, 2017

John R. Woodward, Daniel R. Tauritz

31

The Merge Primitive

- Third Parameter Primitive Dependent
 - Merges use "Weight"
- Random Construct
 - All past primitive parameters used the Number construct
 - "r" marks a primitive using the Random Construct
 - Allows primitives to act stochastically

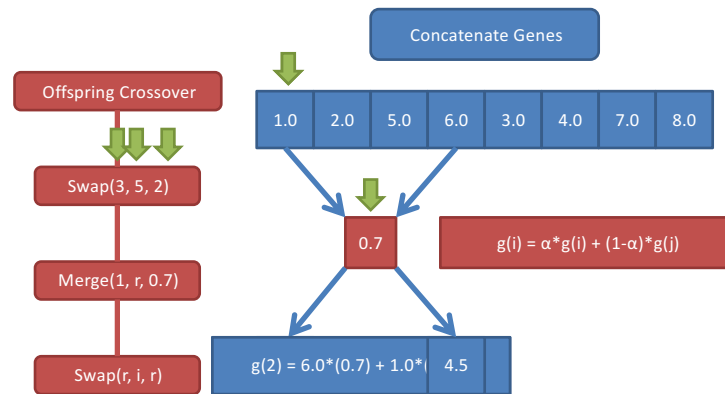


2 May, 2017

John R. Woodward, Daniel R. Tauritz

32

Applying an SCX



2 May, 2017

John R. Woodward, Daniel R. Tauritz

33

The Inline Construct

- Only Usable by First Two Parameters
- Denoted as “i”
- Forces Primitive to Act on the Same Loci in Both Parents

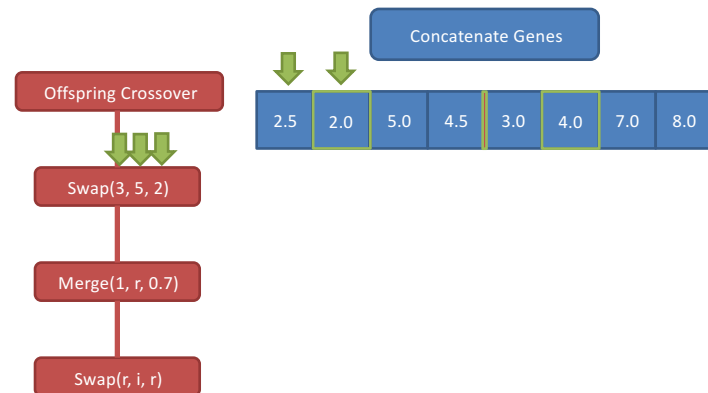


2 May, 2017

John R. Woodward, Daniel R. Tauritz

34

Applying an SCX



2 May, 2017

John R. Woodward, Daniel R. Tauritz

35

Applying an SCX

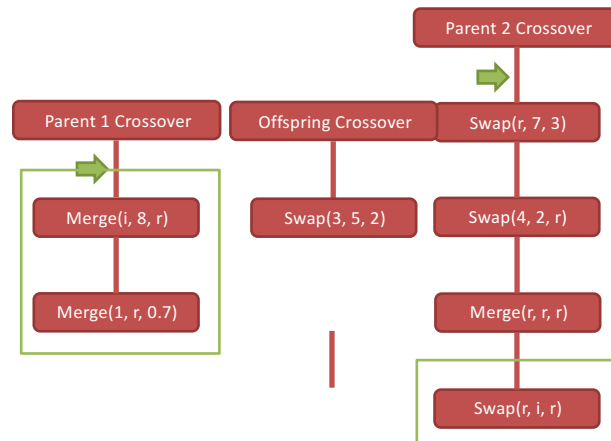


2 May, 2017

John R. Woodward, Daniel R. Tauritz

36

Evolving Crossovers



2 May, 2017

John R. Woodward, Daniel R. Tauritz

37

Empirical Quality Assessment

- Compared Against
 - Arithmetic Crossover
 - N-Point Crossover
 - Uniform Crossover

- On Problems
 - Rosenbrock
 - Rastrigin
 - Offset Rastrigin
 - NK-Landscapes
 - DTrap

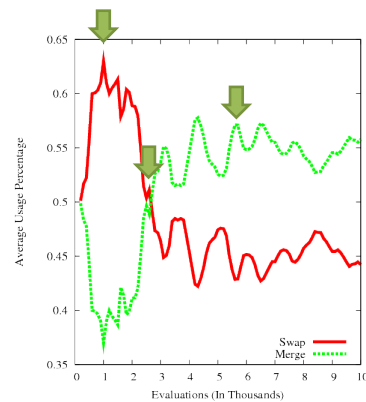
Problem	Comparison	SCX
Rosenbrock	-86.94 (54.54)	-26.47 (23.33)
Rastrigin	-59.2 (6.998)	-0.0088 (0.021)
Offset Rastrigin	-0.1175 (0.116)	-0.03 (0.028)
NK	0.771 (0.011)	0.8016 (0.013)
DTrap	0.9782 (0.005)	0.9925 (0.021)

2 May, 2017

John R. Woodward, Daniel R. Tauritz

38

Adaptations: Rastrigin

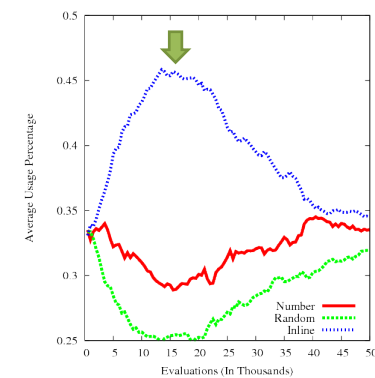


2 May, 2017

John R. Woodward, Daniel R. Tauritz

39

Adaptations: DTrap



2 May, 2017

John R. Woodward, Daniel R. Tauritz

40

SCX Overhead

- Requires No Additional Evaluation
- Adds No Significant Increase in Run Time
 - All linear operations
- Adds Initial Crossover Length Parameter
 - Testing showed results fairly insensitive to this parameter
 - Even worst settings tested achieved better results than comparison operators

2 May, 2017

John R. Woodward, Daniel R. Tauritz

41

Conclusions

- Remove Need to Select Crossover Algorithm
- Better Fitness Without Significant Overhead
- Benefits From Dynamically Changing Operator
- Promising Approach for Evolving Crossover Operators for Additional Representations (e.g., Permutations)

2 May, 2017

John R. Woodward, Daniel R. Tauritz

42

Case Study 2: The Automated Design of Mutation Operators for Evolutionary Programming

2 May, 2017

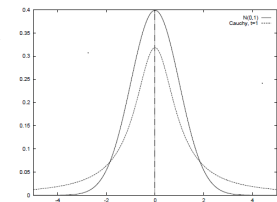
John R. Woodward, Daniel R. Tauritz

43

Designing Mutation Operators for Evolutionary Programming [18]

1. **Evolutionary programming** optimizes functions by evolving a population of real-valued vectors (genotype).
2. **Variation** has been provided (manually) by probability distributions (**Gaussian, Cauchy, Levy**).
3. We are **automatically generating** probability distributions (using genetic programming).
4. **Not from scratch**, but from already well known distributions (**Gaussian, Cauchy, Levy**). We are “**genetically improving probability distributions**”.
5. We are evolving mutation operators **for a problem class** (probability distributions over functions).
6. NO CROSSOVER

Genotype is
(1.3,...,4.5,...,8.7)
Before mutation



Genotype is
(1.2,...,4.4,...,8.6)
After mutation

2 May, 2017

John R. Woodward, Daniel R. Tauritz

44

(Fast) Evolutionary Programming

Heart of algorithm is mutation
SO LETS AUTOMATICALLY DESIGN

$$x_i'(j) = x_i(j) + \eta_i(j)D_j$$

1. EP mutates with a **Gaussian**
2. FEP mutates with a **Cauchy**
3. A **generalization** is mutate with a **distribution D** (generated with genetic programming)

2 May, 2017

John R. Woodward, Daniel R. Tauritz

45

1. Generate the initial population of μ individuals, and set $k = 1$. Each individual is taken as a pair of real-valued vectors, (x_i, η_i) , $\forall i \in \{1, \dots, \mu\}$.
2. Evaluate the fitness score for each individual (x_i, η_i) , $\forall i \in \{1, \dots, \mu\}$, of the population based on the objective function, $f(x_i)$.
3. Each parent (x_i, η_i) , $i = 1, \dots, \mu$, creates a single offspring (x_i', η_i') by: for $j = 1, \dots, n$,

$$x_i'(j) = x_i(j) + \eta_i(j)N(0, 1), \quad (1)$$

$$\eta_i'(j) = \eta_i(j) \exp(\tau'N(0, 1) + \tau N_j(0, 1)) \quad (2)$$
 where $x_i(j)$, $x_i'(j)$, $\eta_i(j)$ and $\eta_i'(j)$ denote the j -th component of the vectors x_i , x_i' , η_i and η_i' , respectively. $N(0, 1)$ denotes a normally distributed one-dimensional random number with mean zero and standard deviation one. $N_j(0, 1)$ indicates that the random number is generated anew for each value of j . The factors τ and τ' have commonly set to $(\sqrt{2\pi n})^{-1}$ and $(\sqrt{2\pi n})^{-1} [9, 8]$.
4. Calculate the fitness of each offspring (x_i', η_i') , $\forall i \in \{1, \dots, \mu\}$.
5. Conduct pairwise comparison over the union of parents (x_i, η_i) and offspring (x_i', η_i') , $\forall i \in \{1, \dots, \mu\}$. For each individual, q opponents are chosen randomly from all the parents and offspring with an equal probability. For each comparison, if the individual's fitness is no greater than the opponent's, it receives a "win".
6. Select the μ individuals out of (x_i, η_i) and (x_i', η_i') , $\forall i \in \{1, \dots, \mu\}$, that have the most wins to be parents of the next generation.
7. Stop if the stopping criterion is satisfied; otherwise, $k = k + 1$ and go to Step 3.

Optimization & Benchmark Functions

A set of 23 benchmark functions is typically used in the literature. **Minimization** $\forall x \in S : f(x_{min}) \leq f(x)$
We use them as **problem classes**.

Table 1: The 23 test functions used in our experimental studies, where n is the dimension of the function, f_{min} the minimum value of the function, and $S \subseteq R^n$.

Test function	n	S	f_{min}
$f_1(x) = \sum_{i=1}^n x_i^2$	30	$[-100, 100]^n$	0
$f_2(x) = \sum_{i=1}^n x_i + \prod_{i=1}^n x_i $	30	$[-10, 10]^n$	0
$f_3(x) = \sum_{i=1}^n (\sum_{j=1}^n x_j)^2$	30	$[-100, 100]^n$	0
$f_4(x) = \max_i \{ x_i , 1 \leq i \leq n \}$	30	$[-100, 100]^n$	0
$f_5(x) = \sum_{i=1}^n [100(x_{i+1} - x_i^2)^2 + (x_i - 1)^2]$	30	$[-30, 30]^n$	0
$f_6(x) = \sum_{i=1}^n [x_i^2 + 0.5]$	30	$[-100, 100]^n$	0
$f_7(x) = \sum_{i=1}^n ix_i^4 + random[0, 1]$	30	$[-1.28, 1.28]^n$	0
$f_8(x) = \sum_{i=1}^n ix_i \sin(\sqrt{ x_i })$	30	$[-500, 500]^n$	-12569.5
$f_9(x) = \sum_{i=1}^n [x_i^2 - 10 \cos(2\pi x_i) + 10]$	30	$[-5.12, 5.12]^n$	0
$f_{10}(x) = -20 \exp(-0.2 \sqrt{\frac{1}{n} \sum_{i=1}^n x_i^2}) - \exp(\frac{1}{n} \sum_{i=1}^n \cos 2\pi x_i) + 20 + e$	30	$[-32, 32]^n$	0

2 May, 2017

John R. Woodward, Daniel R. Tauritz

46

Function Class 1

1. Machine learning needs to generalize.
2. We generalize to function classes.
3. $y = x^2$ (**a function**)
4. $y = ax^2$ (parameterised function)
5. $y = ax^2$, $a \sim [1, 2]$ (**function class**)
6. We do this for all benchmark functions.
7. The mutation operators is evolved to fit the probability distribution of functions.

2 May, 2017

John R. Woodward, Daniel R. Tauritz

47

Function Classes 2

Function Classes	S	b	f_{min}
$f_1(x) = a \sum_{i=1}^n x_i^2$	$[-100, 100]^n$	N/A	0
$f_2(x) = a \sum_{i=1}^n x_i + b \prod_{i=1}^n x_i $	$[-10, 10]^n$	$b \in [0, 10^{-5}]$	0
$f_3(x) = \sum_{i=1}^n (a \sum_{j=1}^i x_j)^2$	$[-100, 100]^n$	N/A	0
$f_4(x) = \max_i \{ a x_i , 1 \leq i \leq n \}$	$[-100, 100]^n$	N/A	0
$f_5(x) = \sum_{i=1}^n [a(x_{i+1} - x_i^2)^2 + (x_i - 1)^2]$	$[-30, 30]^n$	N/A	0
$f_6(x) = \sum_{i=1}^n [(ax_i + 0.5)]^2$	$[-100, 100]^n$	N/A	0
$f_7(x) = a \sum_{i=1}^n ix_i^4 + random[0, 1]$	$[-1.28, 1.28]^n$	N/A	0
$f_8(x) = \sum_{i=1}^n -(x_i \sin(\sqrt{ x_i }) + a)$	$[-500, 500]^n$	N/A	$[-12629.5, -12599.5]$
$f_9(x) = \sum_{i=1}^n [ax_i^2 + b(1 - \cos(2\pi x_i))]$	$[-5.12, 5.12]^n$	$b \in [5, 10]$	0
$f_{10}(x) = -a \exp(-0.2 \sqrt{\frac{1}{n} \sum_{i=1}^n x_i^2}) - \exp(\frac{1}{n} \sum_{i=1}^n \cos 2\pi x_i) + a + e$	$[-32, 32]^n$	N/A	0

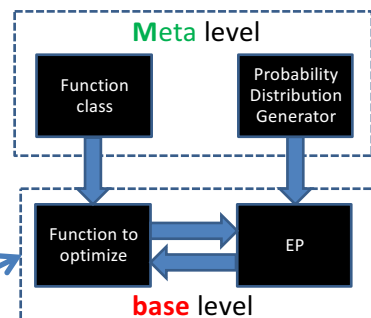
2 May, 2017

John R. Woodward, Daniel R. Tauritz

48

Meta and Base Learning

- At the **base** level we are learning about a **specific** function.
- At the **meta** level we are learning about the problem **class**.
- We are just doing “**generate and test**” at a higher level
- What is being passed with each **blue arrow**?
- Conventional EP**



2 May, 2017

John R. Woodward, Daniel R. Tauritz

49

Compare Signatures (Input-Output)

Evolutionary Programming

$$(R^n \rightarrow R) \rightarrow R^n$$

Input is a function mapping real-valued vectors of length n to a real-value.

Output is a (near optimal) real-valued vector (i.e. the solution to the problem instance)

Evolutionary Programming Designer

$$[(R^n \rightarrow R)] \rightarrow ((R^n \rightarrow R) \rightarrow R^n)$$

Input is a *list of functions* mapping real-valued vectors of length n to a real-value (i.e. sample problem instances from the problem class).

Output is a (near optimal) (mutation operator for) Evolutionary Programming

(i.e. the solution method to the problem class)

We are **raising the level of generality** at which we operate.

2 May, 2017

John R. Woodward, Daniel R. Tauritz

50

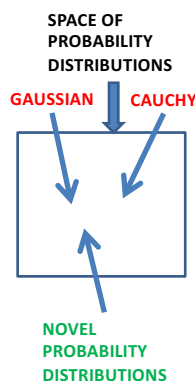
Genetic Programming to Generate Probability Distributions

- GP Function Set $\{+, -, *, \%\}$
- GP Terminal Set $\{N(0, \text{random})\}$

$N(0,1)$ is a normal distribution.

For example a Cauchy distribution is generated by $N(0,1)\%N(0,1)$.

Hence the search space of **probability distributions** contains the two existing probability distributions used in EP but also **novel probability distributions**.



2 May, 2017

John R. Woodward, Daniel R. Tauritz

51

Means and Standard Deviations

These results are good for two reasons.

- starting** with a manually designed distributions (Gaussian).
- evolving distributions **for each function class**.

Function Class	FEP			CEP			GP-distribution		
	Mean	Best	Std Dev	Mean	Best	Std Dev	Mean	Best	Std Dev
f_1	1.24×10^{-3}		2.69×10^{-4}	1.45×10^{-4}	9.95×10^{-5}		6.37×10^{-5}	5.56×10^{-5}	
f_2	1.53×10^{-1}		2.72×10^{-2}	4.30×10^{-2}	9.08×10^{-3}		8.14×10^{-4}	8.50×10^{-4}	
f_3	2.74×10^{-2}		2.43×10^{-2}	5.15×10^{-2}	9.52×10^{-2}		6.14×10^{-3}	8.78×10^{-3}	
f_4	1.79		1.84	1.75×10	6.10		2.16×10^{-1}	6.54×10^{-1}	
f_5	2.52×10^{-3}		4.96×10^{-4}	2.66×10^{-4}	4.65×10^{-5}		8.39×10^{-7}	1.43×10^{-7}	
f_6	3.86×10^{-2}		3.12×10^{-2}	4.40×10	1.42×10^2		9.20×10^{-3}	1.34×10^{-2}	
f_7	6.49×10^{-2}		1.04×10^{-2}	6.64×10^{-2}	1.21×10^{-2}		5.25×10^{-2}	8.46×10^{-3}	
f_8	-11342.0		3.26×10^2	-7894.6	6.14×10^2		-12611.6	2.30×10	
f_9	6.24×10^{-2}		1.30×10^{-2}	1.09×10^2	3.58×10		1.74×10^{-3}	4.25×10^{-4}	
f_{10}	1.67		4.26×10^{-1}	1.45	2.77×10^{-1}		1.38	2.45×10^{-1}	

2 May, 2017

John R. Woodward, Daniel R. Tauritz

52

T-tests

Table 5 2-tailed t-tests comparing EP with GP-distributions, FEP and CEP on f_1 - f_{10} .

Function Class	Number of Generations	GP-distribution vs FEP t -test	GP-distribution vs CEP t -test
f_1	1500	2.78×10^{-47}	4.07×10^{-2}
f_2	2000	5.53×10^{-62}	1.59×10^{-54}
f_3	5000	8.03×10^{-8}	1.14×10^{-3}
f_4	5000	1.28×10^{-7}	3.73×10^{-36}
f_5	20000	2.80×10^{-58}	9.29×10^{-63}
f_6	1500	1.85×10^{-8}	3.11×10^{-2}
f_7	3000	3.27×10^{-9}	2.00×10^{-9}
f_8	9000	7.99×10^{-48}	5.82×10^{-75}
f_9	5000	6.37×10^{-55}	6.54×10^{-39}
f_{10}	1500	9.23×10^{-5}	1.93×10^{-1}

2 May, 2017

John R. Woodward, Daniel R. Tauritz

53

Performance on Other Problem Classes

Table 8: This table compares the fitness values (averaged over 20 runs) of each of the 23 ADRs on each of the 23 function classes. Standard deviations are in parentheses.

ADRI	ADRI2	ADRI3	ADRI4	ADRI5	ADRI6	ADRI7	ADRI8	ADRI9	ADRI10	ADRI11	ADRI12	ADRI13	ADRI14	ADRI15	ADRI16	ADRI17	ADRI18	ADRI19	ADRI20	ADRI21	ADRI22	ADRI23
1	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
2	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
3	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
4	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
5	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
6	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
7	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
8	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
9	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
10	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
11	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
12	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
13	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
14	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
15	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
16	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
17	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
18	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
19	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
20	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
21	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
22	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01
23	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01	1.76462E-01

2 May, 2017

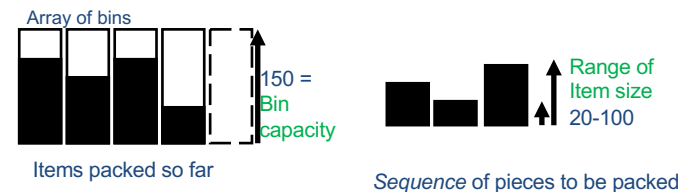
John R. Woodward, Daniel R. Tauritz

56

Case Study 3: The Automated Design of On-Line Bin Packing Algorithms

On-line Bin Packing Problem [9,11]

- A **sequence of items** packed into as few a bins as possible.
- Bin size is **150 units**, items uniformly distributed between **20-100**.
- Different to the off-line bin packing problem where the **set** of items.
- The “best fit” heuristic, places the current item in the space it fits best (leaving least slack).
- It has the property that this heuristic does not open a new bin unless it is forced to.

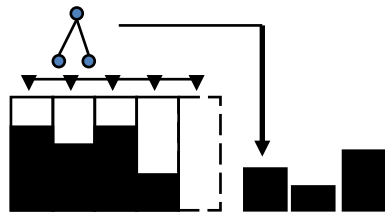


2 May, 2017

John R. Woodward, Daniel R. Tauritz

55

Genetic Programming applied to on-line bin packing



Not obvious how to link
Genetic Programming to
combinatorial problems.
The GP tree is applied to each
bin with the current item and
placed in the bin with
The maximum score

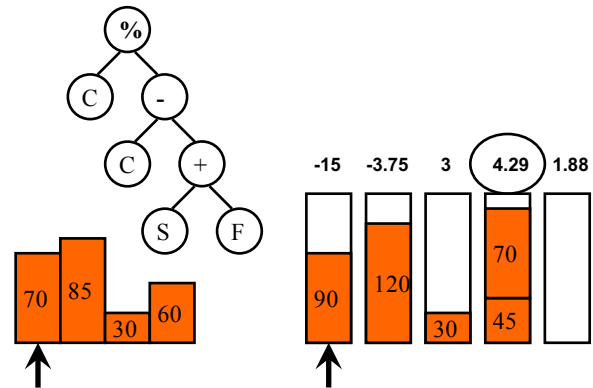


Terminals supplied to Genetic Programming
Initial representation {C, F, S}
Replaced with {E, S}, $E=C-F$

John R. Woodward, Daniel R. Tauritz

57

How the heuristics are applied (skip)



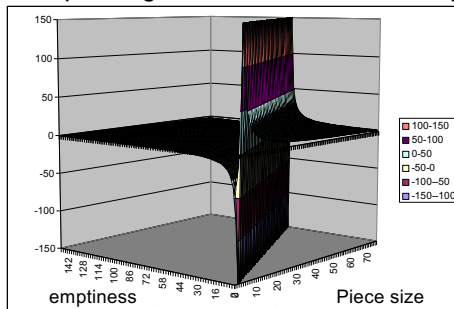
2 May, 2017

John R. Woodward, Daniel R. Tauritz

58

The Best Fit Heuristic

Best fit = $1/(E-S)$. Point out features.
Pieces of size S, which fit well into the space remaining E,
score well.
Best fit applied produces a set of points on the surface,
The bin corresponding to the maximum score is picked.

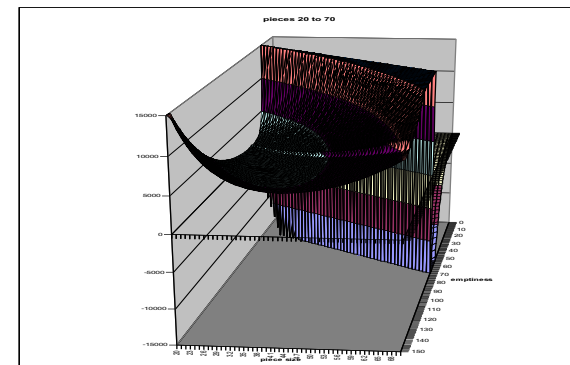


2 May, 2017

John R. Woodward, Daniel R. Tauritz

59

Our Best Heuristic





Similar shape to best fit – but curls up in one corner.
Note that this is rotated, relative to previous slide.

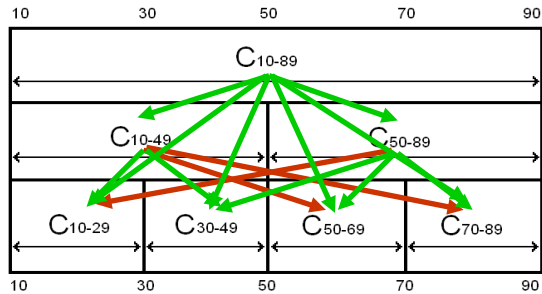
2 May, 2017

John R. Woodward, Daniel R. Tauritz

60

Robustness of Heuristics

 = all legal results
 = some illegal results



2 May, 2017

John R. Woodward, Daniel R. Tauritz

61

Testing Heuristics on problems of much larger size than in training

Table I	H trained 100	H trained 250	H trained 500
100	0.427768358	0.298749035	0.140986023
1000	0.406790534	0.010006408	0.000350265
10000	0.454063071	2.58E-07	9.65E-12
100000	0.271828318	1.38E-25	2.78E-32

Table shows p-values using the best fit heuristic, for heuristics trained on different size problems, when applied to different sized problems

1. As number of items trained on increases, the probability decreases (see next slide).
2. As the number of items packed increases, the probability decreases (see next slide).

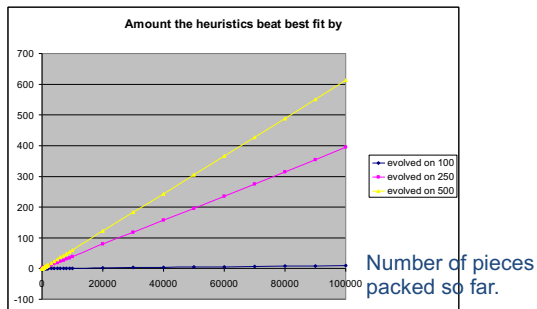
2 May, 2017

John R. Woodward, Daniel R. Tauritz

62

Compared with Best Fit

Amount evolved heuristics beat best fit by.



- Averaged over 30 heuristics over 20 problem instances
- Performance does not deteriorate
- The larger the training problem size, the better the bins are packed.

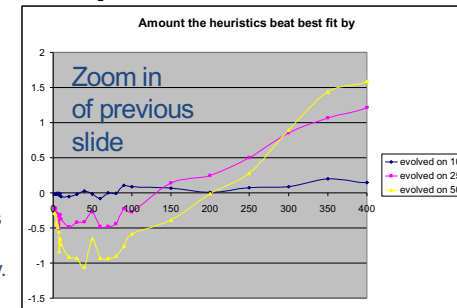
2 May, 2017

John R. Woodward, Daniel R. Tauritz

63

Compared with Best Fit

Amount evolved heuristics beat best fit by.



- The heuristic seems to learn the number of pieces in the problem
- Analogy with sprinters running a race – accelerate towards end of race.
- The “break even point” is approximately half of the size of the training problem size
- If there is a gap of size 30 and a piece of size 20, it would be better to wait for a better piece to come along later – about 10 items (similar effect at upper bound?).

2 May, 2017

John R. Woodward, Daniel R. Tauritz

64

Step by Step Guide to Automatic Design of Algorithms [8, 12]

1. Study the literature for **existing heuristics** for your chosen domain (manually designed heuristics).
2. Build an **algorithmic framework or template** which expresses the known heuristics.
3. Let metaheuristics (e.g. **Genetic Programming search for variations on the theme**).
4. **Train and test** on problem instances drawn from the same probability distribution (like machine learning). Constructing an optimizer is machine learning (**this approach prevents “cheating”**).

2 May, 2017

John R. Woodward, Daniel R. Tauritz

65

A Brief History (Example Applications) [5]

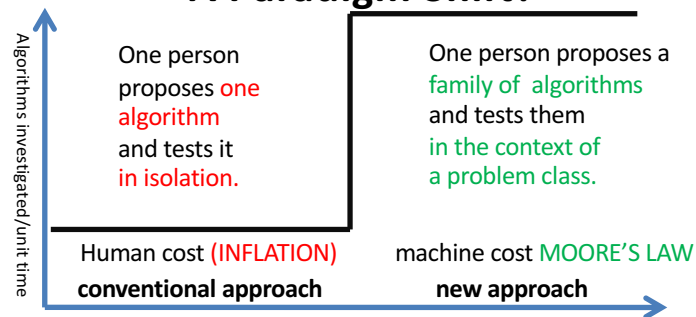
1. **Image Recognition** – Roberts Mark
2. **Travelling Salesman Problem** – Keller Robert
3. **Boolean Satisfiability** – Holger Hoos, Fukunaga, Bader-El-Den, Alex Bertels & Daniel Tauritz
4. **Data Mining** – Gisele L. Pappa, Alex A. Freitas
5. **Decision Tree** - Gisele L. Pappa et al
6. **Crossover Operators** – Oltean et al, Brian Goldman and Daniel Tauritz
7. **Selection Heuristics** – Woodward & Swan, Matthew Martin & Daniel Tauritz
8. **Bin Packing 1,2,3 dimension** (on and off line) Edmund Burke et. al. & Riccardo Poli et al
9. **Bug Location** – Shin Yoo
10. **Job Shop Scheduling** – Mengjie Zhang
11. **Black Box Search Algorithms** – Daniel Tauritz et al

2 May, 2017

John R. Woodward, Daniel R. Tauritz

66

A Paradigm Shift?



- Previously **one** person proposes **one** algorithm
- Now **one** person proposes **a set of** algorithms
- Analogous to “**industrial revolution**” from hand made to machine made. Automatic Design.

2 May, 2017

John R. Woodward, Daniel R. Tauritz

67

Conclusions

1. Heuristic are **trained to fit a problem class**, so are designed in context (like evolution). Let's close the feedback loop! **Problem instances live in classes**.
2. We can design algorithms on **small** problem instances and **scale** them apply them to **large** problem instances (TSP, child multiplication).

2 May, 2017

John R. Woodward, Daniel R. Tauritz

68

SUMMARY

1. We can automatically design algorithms that **consistently outperform human designed algorithms (on various domains)**.
2. The “best” heuristics **depends on the set of problem instances. (feedback)**
3. Resulting algorithm is **part man-made part machine-made** (synergy)
4. **not evolving from scratch like Genetic Programming,**
5. improve existing algorithms and adapt them to the new problem instances.
6. **Algorithms are reusable, “solutions” aren’t.** (e.g. tsp algorithm vs route)

2 May, 2017

John R. Woodward, Daniel R. Tauritz

69

Case Study 4: The Automated Design of Black Box Search Algorithms [21, 23, 25]

2 May, 2017

John R. Woodward, Daniel R. Tauritz

70

Approach

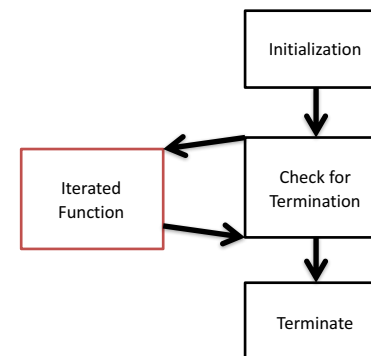
- Hyper-Heuristic employing Genetic Programming
- Post-ordered parse tree
- Evolve the iterated function

2 May, 2017

John R. Woodward, Daniel R. Tauritz

71

Our Solution



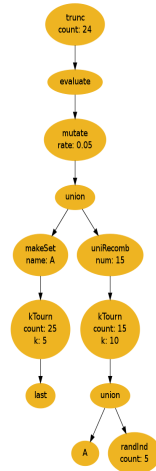
2 May, 2017

John R. Woodward, Daniel R. Tauritz

72

Our Solution

- Hyper-Heuristic employing Genetic Programming
- Post-ordered parse tree
- Evolve the iterated function
- High-level primitives



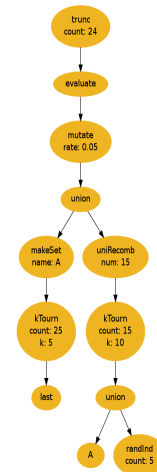
2 May, 2017

John R. Woodward, Daniel R. Tauritz

73

Parse Tree

- Iterated function
- Sets of solutions
- Function returns a set of solutions accessible to the next iteration



2 May, 2017

John R. Woodward, Daniel R. Tauritz

74

Primitive Types

- Variation Primitives
- Selection Primitives
- Set Primitives
- Evaluation Primitive
- Terminal Primitives

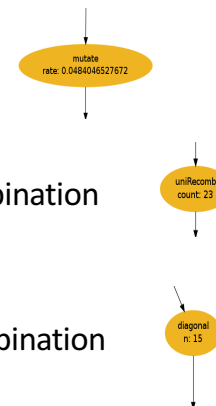
2 May, 2017

John R. Woodward, Daniel R. Tauritz

75

Variation Primitives

- Bit-flip Mutation
– *rate*
- Uniform Recombination
– *count*
- Diagonal Recombination
– *n*



2 May, 2017

John R. Woodward, Daniel R. Tauritz

76

Selection Primitives

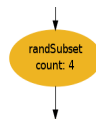
- Truncation Selection
 - *count*



- K-Tournament Selection
 - *k*
 - *count*



- Random Sub-set Selection
 - *count*



2 May, 2017

John R. Woodward, Daniel R. Tauritz

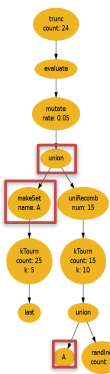
77

Set-Operation Primitives

- Make Set
 - *name*

- Persistent Sets
 - *name*

- Union



2 May, 2017

John R. Woodward, Daniel R. Tauritz

78

Evaluation Primitive

- Evaluates the nodes passed in
- Allows multiple operations and accurate selections within an iteration
 - Allows for deception

2 May, 2017

John R. Woodward, Daniel R. Tauritz

79

Terminal Primitives

- Random Individuals
 - *count*



- 'Last' Set



- Persistent Sets
 - *name*



2 May, 2017

John R. Woodward, Daniel R. Tauritz

80

Meta-Genetic Program

```
graph TD; A[Create Valid Population] --> C[Generate Children]; C --> D[Evaluate Children]; D --> B[Select Survivors]; B --> C; B --> A;
```

The flowchart illustrates the Meta-Genetic Program process. It begins with 'Create Valid Population' (highlighted with a green circle), which leads to 'Generate Children'. From 'Generate Children', the process moves to 'Evaluate Children' (highlighted with a red rectangle). 'Evaluate Children' then leads to 'Select Survivors'. 'Select Survivors' has two outgoing paths: one that loops back to 'Generate Children' and another that loops back to 'Create Valid Population'. The central steps 'Select Survivors', 'Check Termination', and 'Generate Children' are connected in a linear sequence, with 'Check Termination' acting as a decision point. The flowchart uses blue arrows to indicate the direction of the process.

[illegible]

Termination Conditions

- Evaluations
- Iterations
- Operations
- Convergence

2 May, 2017

John R. Woodward, Daniel R. Tauritz

83

Proof of Concept Testing

- Deceptive Trap Problem

The diagram illustrates a deceptive trap problem. At the top, a 1D lattice of 15 sites is shown, divided into three segments of five sites each by vertical lines. The sites are represented by boxes containing 0 or 1. The first segment contains the sequence 0, 0, 1, 1, 0. The second segment contains 0, 1, 0, 1, 0. The third segment contains 1, 1, 1, 1, 0. Below this, a line graph shows the fitness landscape. The x-axis is labeled '# of 1s' and ranges from 0 to 5. The y-axis is labeled 'Fitness' and ranges from 0 to 5. The fitness values for each number of 1s are: 0 (4), 1 (3.5), 2 (2), 3 (1), 4 (0), and 5 (5). The graph shows a deceptive trap where the fitness decreases as the number of 1s increases from 0 to 4, and then sharply increases at 5.

# of 1s	Fitness
0	4
1	3.5
2	2
3	1
4	0
5	5

2 May, 2017

John R. Woodward, Daniel R. Tauritz

84

Proof of Concept Testing (cont.)

- Evolved Problem Configuration
 - Bit-length = 100
 - Trap Size = 5
- Verification Problem Configurations
 - Bit-length = 100, Trap Size = 5
 - Bit-length = 200, Trap Size = 5
 - Bit-length = 105, Trap Size = 7
 - Bit-length = 210, Trap Size = 7

2 May, 2017

John R. Woodward, Daniel R. Tauritz

85

Results

BBSA	EA	Hill-Climber
1	+	+
2	+	+
3	+	+
4	-	-
5	+	+
6	+	+
7	+	+
8	-	-
9	-	-
10	-	-
11	+	+
12	-	-
13	+	+
14	+	+
15	-	-

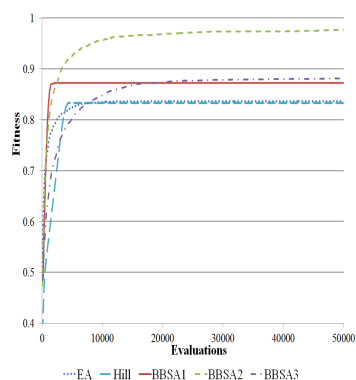
60% Success
Rate

2 May, 2017

John R. Woodward, Daniel R. Tauritz

86

Results: Bit-Length = 100 Trap Size = 5

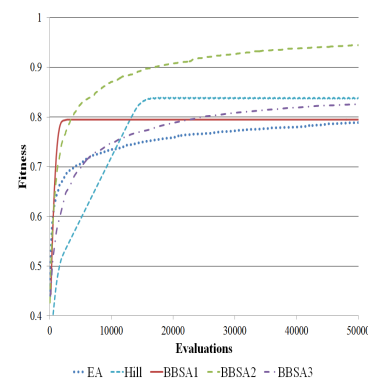


2 May, 2017

John R. Woodward, Daniel R. Tauritz

87

Results: Bit-Length = 200 Trap Size = 5

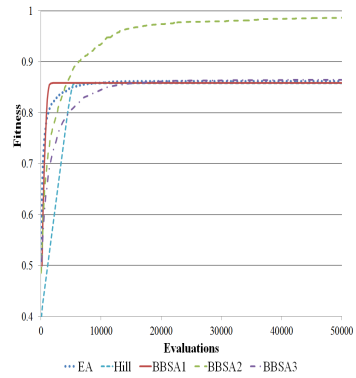


2 May, 2017

John R. Woodward, Daniel R. Tauritz

88

Results:
Bit-Length = 105
Trap Size = 7

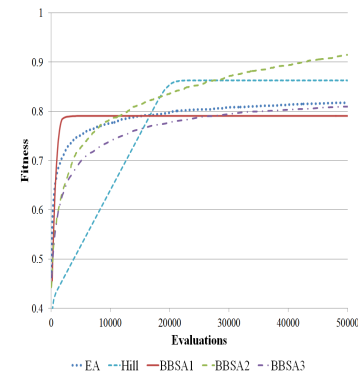


2 May, 2017

John R. Woodward, Daniel R. Tauritz

89

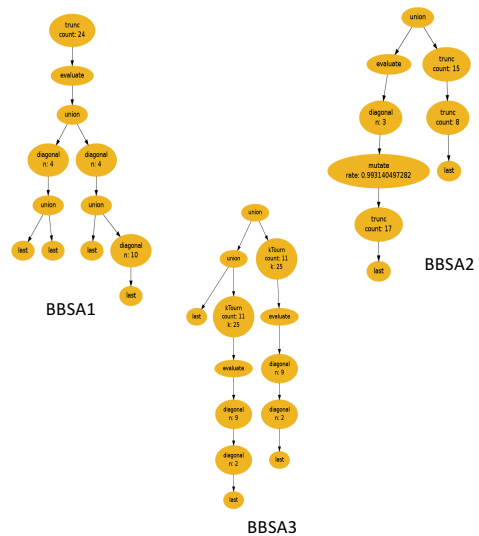
Results:
Bit-Length = 210
Trap Size = 7



2 May, 2017

John R. Woodward, Daniel R. Tauritz

90

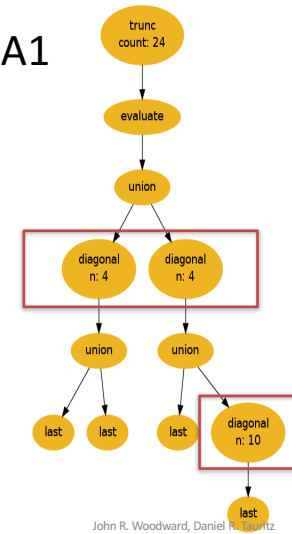


2 May, 2017

John R. Woodward, Daniel R. Tauritz

91

BBSA1

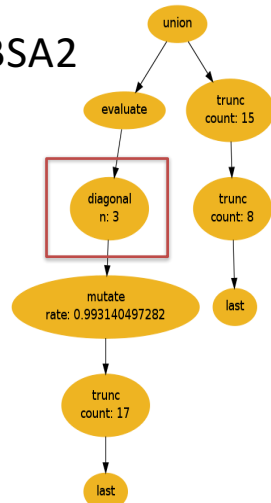


2 May, 2017

John R. Woodward, Daniel R. Tauritz

92

BBSA2

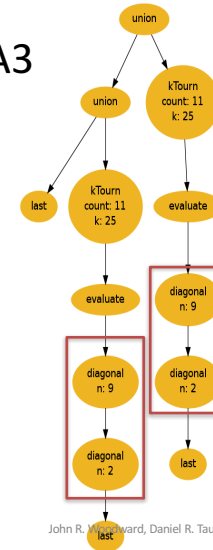


2 May, 2017

John R. Woodward, Daniel R. Tauritz

93

BBSA3

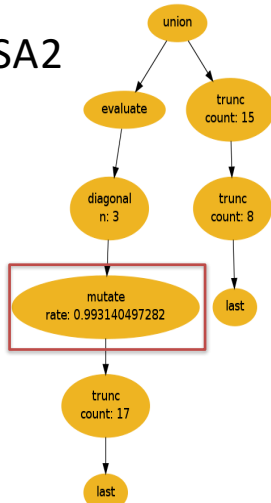


2 May, 2017

John R. Woodward, Daniel R. Tauritz

94

BBSA2

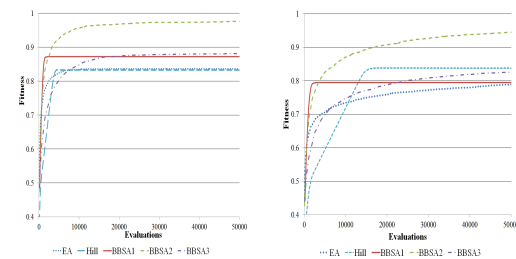


2 May, 2017

John R. Woodward, Daniel R. Tauritz

95

Over-Specialization



Trained Problem Configuration

Alternate Problem Configuration

2 May, 2017

John R. Woodward, Daniel R. Tauritz

96

Robustness

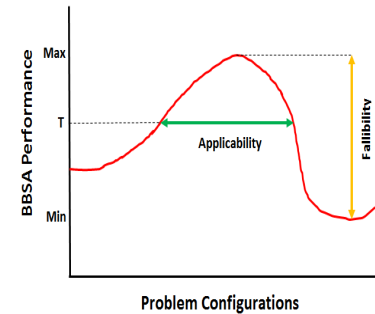
- Measures of Robustness
 - Applicability
 - Fallibility
- Applicability
 - What area of the problem configuration space do I perform well on?
- Fallibility
 - If a given BBSA doesn't perform well, how much worse will I perform?

2 May, 2017

John R. Woodward, Daniel R. Tauritz

97

Robustness



2 May, 2017

John R. Woodward, Daniel R. Tauritz

98

Multi-Sampling

- Train on multiple problem configurations
- Results in more robust BBSAs
- Provides the benefit of selecting the region of interest on the problem configuration landscape

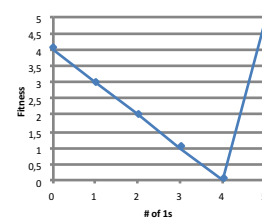
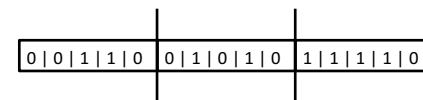
2 May, 2017

John R. Woodward, Daniel R. Tauritz

99

Multi-Sample Testing

- Deceptive Trap Problem



2 May, 2017

John R. Woodward, Daniel R. Tauritz

100

Multi-Sample Testing (cont.)

- Multi-Sampling Evolution
 - Levels 1-5
- Training Problem Configurations
 1. Bit-length = 100, Trap Size = 5
 2. Bit-length = 200, Trap Size = 5
 3. Bit-length = 105, Trap Size = 7
 4. Bit-length = 210, Trap Size = 7
 5. Bit-length = 300, Trap Size = 5

2 May, 2017

John R. Woodward, Daniel R. Tauritz

101

Initial Test Problem Configurations

1. Bit-length = 100, Trap Size = 5
2. Bit-length = 200, Trap Size = 5
3. Bit-length = 105, Trap Size = 7
4. Bit-length = 210, Trap Size = 7
5. Bit-length = 300, Trap Size = 5
6. Bit-length = 99, Trap Size = 9
7. Bit-length = 198, Trap Size = 9
8. Bit-length = 150, Trap Size = 5
9. Bit-length = 250, Trap Size = 5
10. Bit-length = 147, Trap Size = 7
11. Bit-length = 252, Trap Size = 7

2 May, 2017

John R. Woodward, Daniel R. Tauritz

102

Initial

Level	Run	Train Fit.	Test Fit.	Fallibility
1	1	1.0	0.976	0.094
1	2	1.0	0.999	8.33 E-3
1	3	0.944	0.883	0.082
1	4	0.976	0.894	0.224
2	1	0.997	0.996	0.023
2	2	0.992	0.959	0.130
2	3	0.966	0.970	0.054
2	4	0.979	0.947	0.120
3	1	0.965	0.966	0.050
3	2	0.984	0.980	0.065
3	3	0.899	0.886	0.059
3	4	0.926	0.898	0.073
4	1	0.976	0.999	5.00 E-3
4	2	0.973	0.969	.0903
4	3	0.982	0.975	0.059
4	4	0.993	0.999	5.00 E-3
5	1	0.973	0.977	0.050
5	2	0.893	0.879	0.035
5	3	0.850	0.850	0.045
5	4	0.955	0.986	0.029

Level	Run	+	~	-
1	1	11	0	0
1	2	11	0	0
1	3	11	0	0
1	4	6	2	3
2	1	11	0	0
2	2	11	0	0
2	3	11	0	0
2	4	11	0	0
3	1	11	0	0
3	2	11	0	0
3	3	11	0	0
3	4	11	0	0
4	1	11	0	0
4	2	11	0	0
4	3	11	0	0
4	4	11	0	0
5	1	11	0	0
5	2	10	1	0
5	3	7	4	0
5	4	11	0	0

2 May, 2017

John R. Woodward, Daniel R. Tauritz

103

Problem Configuration Landscape Analysis

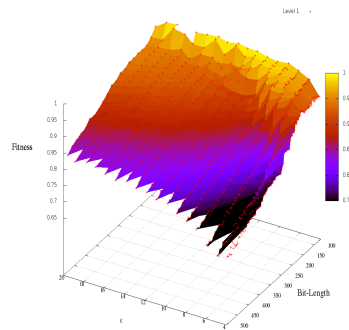
- Run evolved BBSAs on wider set of problem configurations
- Bit-length: ~75-~500
- Trap Size: 4-20

2 May, 2017

John R. Woodward, Daniel R. Tauritz

104

Results: Multi-Sampling Level 1

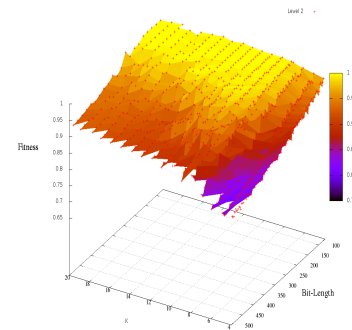


2 May, 2017

John R. Woodward, Daniel R. Tauritz

105

Results: Multi-Sampling Level 2

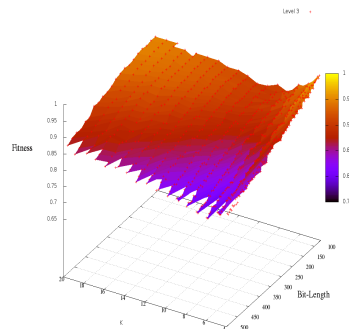


2 May, 2017

John R. Woodward, Daniel R. Tauritz

106

Results: Multi-Sampling Level 3

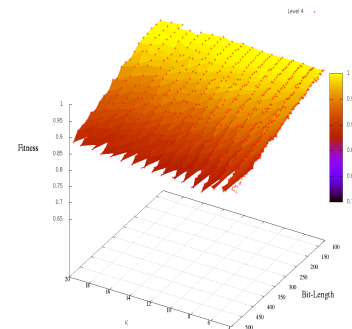


2 May, 2017

John R. Woodward, Daniel R. Tauritz

107

Results: Multi-Sampling Level 4

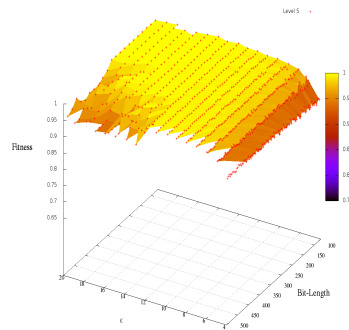


2 May, 2017

John R. Woodward, Daniel R. Tauritz

108

Results: Multi-Sampling Level 5

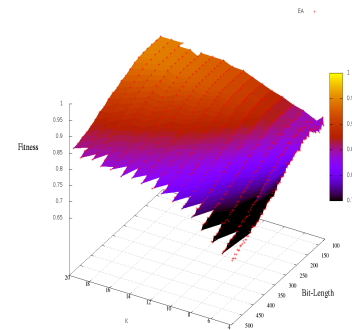


2 May, 2017

John R. Woodward, Daniel R. Tauritz

109

Results: EA Comparison



2 May, 2017

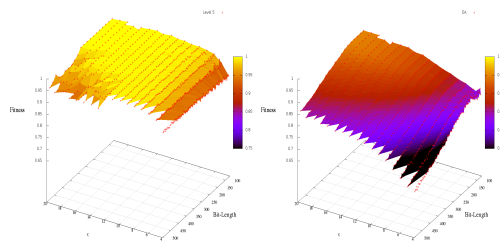
John R. Woodward, Daniel R. Tauritz

110

Robustness: Fallibility

Multi-Sample Level 5

Standard EA



2 May, 2017

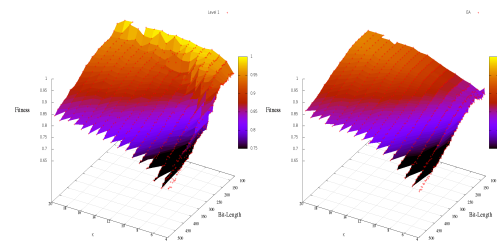
John R. Woodward, Daniel R. Tauritz

111

Robustness: Fallibility

Multi-Sample Level 1

Standard EA



2 May, 2017

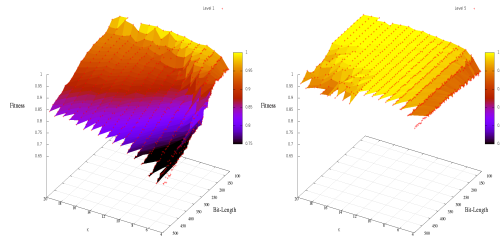
John R. Woodward, Daniel R. Tauritz

112

Robustness: Applicability

Multi-Sample Level 1

Multi-Sample Level 5



2 May, 2017

John R. Woodward, Daniel R. Tauritz

113

Robustness: Fallibility

Level	Run	Train Fit.	Test Fit.	Fallibility
5	1	0.973	0.977	0.050
5	2	0.893	0.879	0.035
5	3	0.850	0.850	0.045
5	4	0.955	0.986	0.029

2 May, 2017

John R. Woodward, Daniel R. Tauritz

114

Drawbacks

- Increased computational time
 - More runs per evaluation (increased wall time)
 - More problem configurations to optimize for (increased evaluations)

2 May, 2017

John R. Woodward, Daniel R. Tauritz

115

Summary of Multi-Sample Improvements

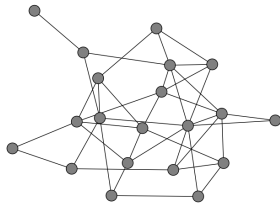
- Improved Hyper-Heuristic to evolve more robust BBSAs
- Evolved custom BBSA which outperformed standard EA and were robust to changes in problem configuration

2 May, 2017

John R. Woodward, Daniel R. Tauritz

116

Case Study 5: Evolving Random Graph Generators: A Case for Increased Algorithmic Primitive Granularity [27]



2 May, 2017

John R. Woodward, Daniel R. Tauritz

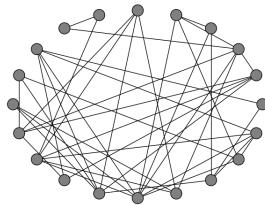
117

Random Graphs

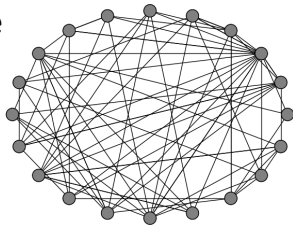
- Graphs are a powerful modeling tool
 - Computer and social networks
 - Transportation and power grids
- Algorithms designed for graphs
 - Community detection and graph partitioning
 - Network routing and intrusion detection
- Random graphs provide test data
- Prediction using random graphs
 - Spread of disease
 - Deployment of wireless sensors

Traditional Random Graph Models

- Erdős-Rényi



- Barabási-Albe



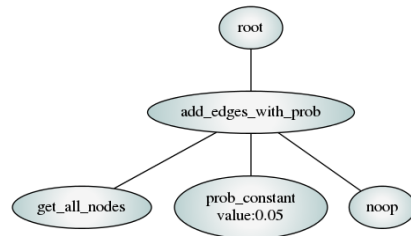
Automated Random Graph Model Design

- Random graph model needs to accurately reflect intended concept
- Model selection can be automated, but relies on having a good solution available
- Developing an accurate model for a new application can be difficult

Can the model design process be automated to produce an accurate graph model given examples?

Hyper-heuristic Approach

- Extract functionality from existing graph generation techniques
- Use Genetic Programming (GP) to construct new random graph algorithms



Previous Attempts at Evolving Random Graph Generators

- Assumes “growth” model, adding one node at a time
- Does well at reproducing traditional models
- Not demonstrated to do well at generating real complex networks
- Limits the search space of possible solutions

Increased Algorithmic Primitive Granularity

- Remove the assumed “growth” structure
- More flexible lower-level primitive set
- Benefit: Can represent a larger variety of algorithms
- Drawback: Larger search space, increasing complexity

Methodology

- NSGA-II evolves population of random graph models
- Strongly typed parse tree representation
- Centrality distributions used to evaluate solution
- quality (degree, betweenness, PageRank)

Primitive Operations

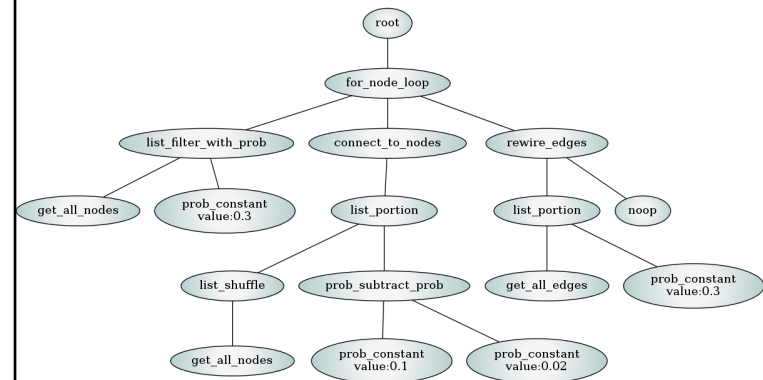
Terminals

- Graph elements: nodes, edges
- Graph properties: average degree, size, order
- Constants: integers, probabilities, Booleans, user inputs
- No-op terminators

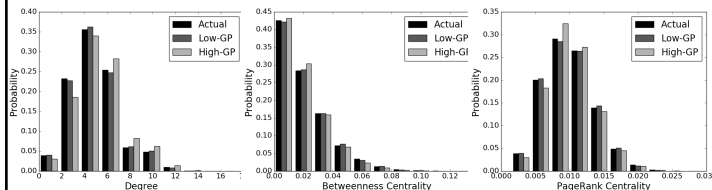
Functions

- Basic programming constructs: for, while, if-else
- Data structures: lists of values, nodes, or edges, list
- combining/selection/sorting
- Math and logic operators: add, multiply, <, ==, AND, OR
- Graph operators: add edges, add subgraph, rewire edges

Example Evolved Random Graph Generator



Reproducing Erdős-Rényi

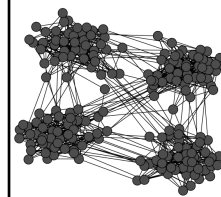


	Low-GP			High-GP	
Metric	Mean	σ	Comparison	Mean	σ
Degree	0.101	0.048	=	0.108	0.047
Betweenness	0.104	0.031	=	0.105	0.033
PageRank	0.110	0.032	=	0.112	0.029

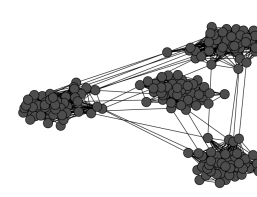
Reproducing Random Community Graphs

	Low-GP			High-GP	
Metric	Mean	σ	Comparison	Mean	σ
Degree	0.436	0.075	<	0.458	0.055
Betweenness	0.209	0.105	<	0.320	0.126
PageRank	0.127	0.029	<	0.150	0.036

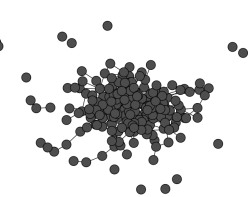
Actual Graph



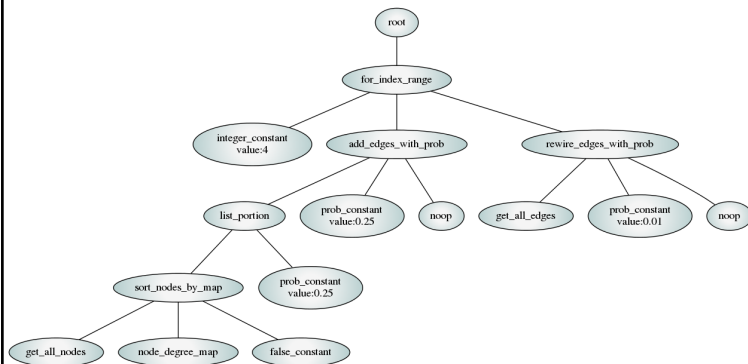
Low-GP



High-GP



Evolved Random Collaboration Network Generator



Conclusion

- Traditional random graph models do not always produce appropriate representations of certain concepts
- Accurate random graph model design can be automated using genetic programming
- More flexible set of low-level primitive operations increases resulting model accuracy
- Increase in a priori evolution time is amortized over repeated use of the evolved solutions

Some Final Thoughts

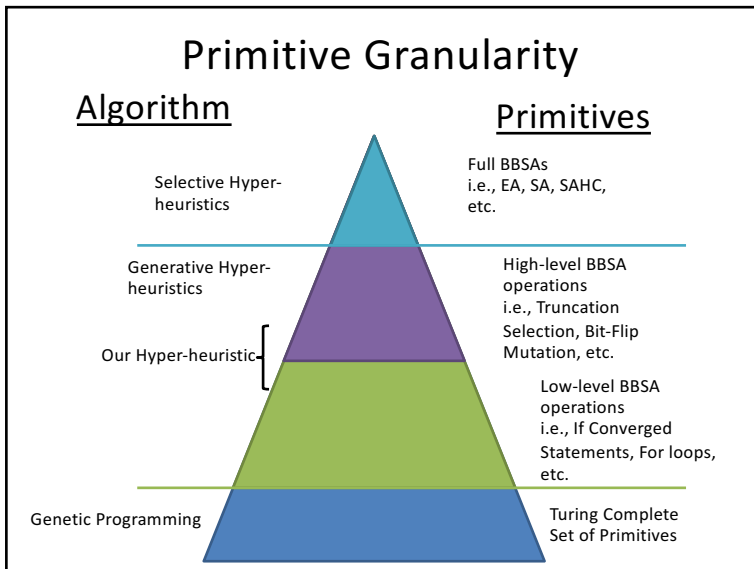
2 May, 2017

John R. Woodward, Daniel R. Tauritz

131

Challenges in Hyper-heuristics

- Hyper-heuristics are very computationally expensive (use Asynchronous Parallel GP [26,30])
- What is the best primitive granularity? (see next slide)
- How to automate decomposition and recomposition of primitives?
- How to automate primitive extraction?
- How does hyper-heuristic performance scale for increasing primitive space size? (see [25,27])



End of File ☺

- Thank you for listening !!!
 - We are glad to take any
 - comments (+,-)
 - suggestions/criticisms
- Please email us any missing references!
- John Woodward (<http://www.cs.stir.ac.uk/~jrw/>)
- Daniel Tauritz (<http://web.mst.edu/~tauritzd/>)

2 May, 2017

John R. Woodward, Daniel R. Tauritz

134

References 1

1. John Woodward. Computable and Incomputable Search Algorithms and Functions. IEEE International Conference on Intelligent Computing and Intelligent Systems (IEEE ICIS 2009), pages 871-875, Shanghai, China, November 20-22, 2009.
2. John Woodward. The Necessity of Meta Bias in Search Algorithms. International Conference on Computational Intelligence and Software Engineering (CiSE), pages 1-4, Wuhan, China, December 10-12, 2010.
3. John Woodward & Ruibin Bai. Why Evolution is not a Good Paradigm for Program Induction: A Critique of Genetic Programming. In Proceedings of the first ACM/SIGEVO Summit on Genetic and Evolutionary Computation, pages 593-600, Shanghai, China, June 12-14, 2009.
4. Jerry Swan, John Woodward, Ender Ozcan, Graham Kendall, Edmund Burke. Searching the Hyper-heuristic Design Space. Cognitive Computation, 6:66-73, 2014.
5. Gisele L. Pappa, Gabriela Ochoa, Matthew R. Hyde, Alex A. Freitas, John Woodward, Jerry Swan. Contrasting meta-learning and hyper-heuristic research. Genetic Programming and Evolvable Machines, 15:3-35, 2014.
6. Edmund K. Burke, Matthew Hyde, Graham Kendall, and John Woodward. Automating the Packing Heuristic Design Process with Genetic Programming. Evolutionary Computation, 20(1):63-89, 2012.
7. Edmund K. Burke, Matthew R. Hyde, Graham Kendall, and John Woodward. A Genetic Programming Hyper-Heuristic Approach for Evolving Two Dimensional Strip Packing Heuristics. IEEE Transactions on Evolutionary Computation, 14(6):942-958, December 2010.

2 May, 2017

John R. Woodward, Daniel R. Tauritz

135

References 2

8. Edmund K. Burke, Matthew R. Hyde, Graham Kendall, Gabriela Ochoa, Ender Ozcan and John R. Woodward. Exploring Hyper-heuristic Methodologies with Genetic Programming, Computational Intelligence: Collaboration, Fusion and Emergence, In C. Mumford and L. Jain (eds.), Intelligent Systems Reference Library, Springer, pp. 177-201, 2009.
9. Edmund K. Burke, Matthew Hyde, Graham Kendall and John R. Woodward. The Scalability of Evolved On Line Bin Packing Heuristics. In Proceedings of the IEEE Congress on Evolutionary Computation, pages 2530-2537, September 25-28, 2007.
10. R. Poli, John R. Woodward, and Edmund K. Burke. A Histogram-matching Approach to the Evolution of Bin-packing Strategies. In Proceedings of the IEEE Congress on Evolutionary Computation, pages 3500-3507, September 25-28, 2007.
11. Edmund K. Burke, Matthew Hyde, Graham Kendall, and John Woodward. Automatic Heuristic Generation with Genetic Programming: Evolving a Jack-of-all-Trades or a Master of One, In Proceedings of the Genetic and Evolutionary Computation Conference, pages 1559-1565, London, UK, July 2007.
12. John R. Woodward and Jerry Swan. Template Method Hyper-heuristics, Metaheuristic Design Patterns (MetaDeeP) workshop, GECCO Comp'14, pages 1437-1438, Vancouver, Canada, July 12-16, 2014.
13. Saemundur O. Haraldsson and John R. Woodward, Automated Design of Algorithms and Genetic Improvement: Contrast and Commonalities, 4th Workshop on Automatic Design of Algorithms (ECADA), GECCO Comp '14, pages 1373-1380, Vancouver, Canada, July 12-16, 2014.

2 May, 2017

John R. Woodward, Daniel R. Tauritz

136

References 3

14. John R. Woodward, Simon P. Martin and Jerry Swan. Benchmarks That Matter For Genetic Programming, 4th Workshop on Evolutionary Computation for the Automated Design of Algorithms (ECADA), GECCO Comp '14, pages 1397-1404, Vancouver, Canada, July 12-16, 2014.
15. John R. Woodward and Jerry Swan. The Automatic Generation of Mutation Operators for Genetic Algorithms, 2nd Workshop on Evolutionary Computation for the Automated Design of Algorithms (ECADA), GECCO Comp' 12, pages 67-74, Philadelphia, U.S.A., July 7-11, 2012.
16. John R. Woodward and Jerry Swan. Automatically Designing Selection Heuristics. 1st Workshop on Evolutionary Computation for Designing Generic Algorithms, pages 583-590, Dublin, Ireland, 2011.
17. Edmund K. Burke, Matthew Hyde, Graham Kendall, Gabriela Ochoa, Ender Ozcan, and John Woodward. A Classification of Hyper-heuristics Approaches, Handbook of Metaheuristics, pages 449-468, International Series in Operations Research & Management Science, M. Gendreau and J-Y Potvin (Eds.), Springer, 2010.
18. Libin Hong and John Woodward and Jingpeng Li and Ender Ozcan. Automated Design of Probability Distributions as Mutation Operators for Evolutionary Programming Using Genetic Programming. Proceedings of the 16th European Conference on Genetic Programming (EuroGP 2013), volume 7831, pages 85-96, Vienna, Austria, April 3-5, 2013.
19. Ekaterina A. Smorodkina and Daniel R. Tauritz. Toward Automating EA Configuration: the Parent Selection Stage. In Proceedings of CEC 2007 - IEEE Congress on Evolutionary Computation, pages 63-70, Singapore, September 25-28, 2007.

2 May, 2017

John R. Woodward, Daniel R. Tauritz

137

References 4

20. Brian W. Goldman and Daniel R. Tauritz. Self-Configuring Crossover. In Proceedings of the 13th Annual Conference Companion on Genetic and Evolutionary Computation (GECCO '11), pages 575-582, Dublin, Ireland, July 12-16, 2011.
21. Matthew A. Martin and Daniel R. Tauritz. Evolving Black-Box Search Algorithms Employing Genetic Programming. In Proceedings of the 15th Annual Conference Companion on Genetic and Evolutionary Computation (GECCO '13), pages 1497-1504, Amsterdam, The Netherlands, July 6-10, 2013.
22. Nathaniel R. Kamrath, Brian W. Goldman and Daniel R. Tauritz. Using Supportive Coevolution to Evolve Self-Configuring Crossover. In Proceedings of the 15th Annual Conference Companion on Genetic and Evolutionary Computation (GECCO '13), pages 1489-1496, Amsterdam, The Netherlands, July 6-10, 2013.
23. Matthew A. Martin and Daniel R. Tauritz. A Problem Configuration Study of the Robustness of a Black-Box Search Algorithm Hyper-Heuristic. In Proceedings of the 16th Annual Conference Companion on Genetic and Evolutionary Computation (GECCO '14), pages 1389-1396, Vancouver, BC, Canada, July 12-16, 2014.
24. Sean Harris, Travis Bueter, and Daniel R. Tauritz. A Comparison of Genetic Programming Variants for Hyper-Heuristics. In Proceedings of the 17th Annual Conference Companion on Genetic and Evolutionary Computation (GECCO '15), pages 1043-1050, Madrid, Spain, July 11-15, 2015.
25. Matthew A. Martin and Daniel R. Tauritz. Hyper-Heuristics: A Study On Increasing Primitive-Space. In Proceedings of the 17th Annual Conference Companion on Genetic and Evolutionary Computation (GECCO '15), pages 1051-1058, Madrid, Spain, July 11-15, 2015.

2 May, 2017

John R. Woodward, Daniel R. Tauritz

138

References 5

26. Alex R. Bertels and Daniel R. Tauritz. Why Asynchronous Parallel Evolution is the Future of Hyper-heuristics: A CDCL SAT Solver Case Study. In Proceedings of the 18th Annual Conference Companion on Genetic and Evolutionary Computation (GECCO '16), pages 1359-1365, Denver, Colorado, USA, July 20-24, 2016.
27. Aaron S. Pope, Daniel R. Tauritz and Alexander D. Kent. Evolving Random Graph Generators: A Case for Increased Algorithmic Primitive Granularity. In Proceedings of the 2016 IEEE Symposium Series on Computational Intelligence (IEEE SSCI 2016), Athens, Greece, December 6-9, 2016.
28. Aaron S. Pope, Daniel R. Tauritz and Alexander D. Kent. Evolving Multi-level Graph Partitioning Algorithms. In Proceedings of the 2016 IEEE Symposium Series on Computational Intelligence (IEEE SSCI 2016), Athens, Greece, December 6-9, 2016.
29. Islam Elnabrawy, Daniel R. Tauritz, Donald C. Wunsch. Evolutionary Computation for the Automated Design of Category Functions for Fuzzy ART: An Initial Exploration. To appear in Proceedings of the 19th Annual Conference Companion on Genetic and Evolutionary Computation (GECCO'17), Berlin, Germany, July 15-19, 2017.
30. Adam Harter, Daniel R. Tauritz, William M. Siever. Asynchronous Parallel Cartesian Genetic Programming To appear in Proceedings of the 19th Annual Conference Companion on Genetic and Evolutionary Computation (GECCO'17), Berlin, Germany, July 15-19, 2017.

2 May, 2017

John R. Woodward, Daniel R. Tauritz

139