Accelerating a multi-objective memetic algorithm for feature selection using hierarchical k-means indexes

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ABSTRACT

The (α, β) -k Feature Set Problem is a mathematical model proposed for multivariate feature selection. Unfortunately, addressing this problem requires a combinatorial search in a space that grows exponentially with the number of features. In this paper, we propose a novel index-based Memetic Algorithm for the Multi-objective (α, β) -*k* Feature Set Problem. The method is able to speed-up the search during the exploration of the neighborhood on the local search procedure. We evaluate our algorithm using six well-known microarray datasets. Our results show that exploiting the natural feature hierarchies of the data can have, in practice, a significant positive impact on both the solutions' quality and the algorithm's execution time.

CCS CONCEPTS

• Applied computing -> Multi-criterion optimization and decision -making;

KEYWORDS

Feature Set problem, Multi-Objective Optimization, Memetic Algorithm.

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1 INTRODUCTION

The (α, β) -*k* Feature Set Problem is a combinatorial optimization model proposed for finding a subset of features that can explain a certain dichotomy [3]. It is a generalization of the well-known k-Feature Set Problem which was proved to be NP-complete by Davies and Russell in 1994 [4]. The idea is to consider the effect of a subset of features over each pair of samples [3]. The α value represents the support of features for discriminating samples in the feature set of size k. In other words, the α value is the minimum number of features in the feature set that have different values on

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all pair of samples with different classes. The β value represents the support of features for describing samples within a class. The β value is the minimum number of features in the feature set of size *k* with the same value on all pair of samples with the same class.

This model has been widely used in bioinformatics to select a subset of features (e.g., biomarkers) to discriminate between samples in studies investigating prostate cancer [7], Parkinson's [8] and Alzheimer's diseases [12].

The most recent application of the (α, β) -k Feature Set Problem was presented in [9]. We proposed for the first time a multi-objective optimization algorithm to address the problem. We implemented a memetic algorithm to solve it, and we studied the impact of different local search algorithms and initialization heuristics. We proposed two novel clustering-based heuristics to improve the searching process of features. The clustering-based heuristic improved the performance of the algorithm; however, it increases the execution time of the algorithm in comparison with other alternatives. Thus, we propose a new algorithm to speed-up the optimization process.

SPEEDING UP THE LOCAL SEARCH 2 **EXPLORATION**

Search trees are data structures that can be used to search and store data [2]. In the literature, we can find several data structures of this type such as binary search trees, red-black trees, interval trees, among others. Overall, the advantage of this type of data structure is to perform search operations more efficiently. In particular, we based our strategy on a hierarchical *k*-means clustering tree [11] to speed-up the local search exploration. In addition, we employ nearest-neighbor queries to find similar features quickly. Combined, they form an indexing scheme called hierarchical k-means index [10].

In Algorithm 1, we present the pseudocode of our IndexLS heuris*tic* (*IndexLS*). The first stage aims to obtain the α *node* representation of the current individual, that we called remaining solution rs. For each pair of samples with different target value, the method computes how many features are needed to cover it α^* times (i.e., remainCoverage). Then, we normalize the remaining solution (rs) by the maximum observed value. Once we have the rs, we search in the tree of features (i.e., KNNSEARCH(rs, maxFeat)) for those with similar α node expressions (i.e., similar Features). We remove from the similarFeatures set all the features that are in the current individual. Since the similar Features set is defined, we need to generate the neighbors. We add the most similar feature until all the pair of samples with different target value satisfy the α^* .

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Input: current individual (<i>S</i>), alpha parameter (α^*), maximum number
features (maxFeat)
Output: improved individual (<i>S</i>)
$rs \leftarrow \emptyset$ //remaining solution
for all α node $\in \alpha$ nodes do
$remainCoverage \leftarrow \alpha^* - AlphaCover(\alpha \text{ node, } S)$
if remainCoverage > 0 then
$rs \leftarrow rs \cup (\alpha \text{ node, } remainCoverage)$
end if
end for
$maximum \leftarrow MaximumCoverage(rs)$
$rs \leftarrow Normalize(rs, maximum)$
$similarFeatures \leftarrow KnnSearch(rs, maxFeat) - S$
while $\alpha(S) < \alpha^* \& maxFeat \neq \emptyset$ do
$feature \leftarrow \text{GET}(similarFeatures, 0)$
while $feature \in S \& pos \le 3$ do
$feature \leftarrow GET(similarFeatures, pos)$
$pos \leftarrow pos + 1$
end while
$S \leftarrow S \cup feature$
$maxFeat \leftarrow maxFeat - 1$
$similarFeatures \leftarrow similarFeatures - feature$
if maxFeat > 0 & similarFeatures = 0 then
$similarFeatures \leftarrow KnnSearch(rs, maxFeat)$
end if
end while
return S

3 EXPERIMENTS AND RESULTS

To test our *IndexLS heuristic*, we use the same memetic algorithm for the multi-objective (α, β) -k Feature Set Problem presented on [9]. We represent the individual as a set of selected features (i.e., a bit array of size n where the position j $(1 \le j \le n)$ has the value of 1 if the feature is selected in the solution (S) (i.e., $f_j = 1$) and 0 otherwise.). We use the same genetic operators as [9] *RandomInit* initialization, DetBitFlip(3) mutation, *Intersect* recombination, and *Elitist* replacement strategy. We execute 30 trials for each dataset, and the algorithm runs for a maximum of 100 generations.

In our experiments, we use six real-world microarray datasets which were previously studied in [5, 9]. In Table 1, we present the average normalized hypervolume as quality indicator [1]. Higher hypervolume value means a better performance of the algorithm. In Table 1, we present the clustering-based results presented in [9]. We applied the Wilcoxon statistical test [6] to compare our results with the clustering-based experiments presented in [9].

Table 1: Normalized hypervolume using *IndexLS*. For each dataset, we present the average normalized hypervolume using our *IndexLS*, and the clustering-based results from [9].

Dataset	Previous clustering results [9]		IndexLS heuristic results	
	Hypervolume	Time	Hypervolume	Time
DownSyn	0.5318	108	0.4722	1
Smoking	0.5942	50,155	0.5993	13,958
Bruta	0.5451	2,642	0.5222	239
PdParkinson	0.4871	5,006	0.5774	154
Prostate	0.5852	45,482	0.6164	6,999
Parkinson	0.5216	82,332	0.5424	99,951

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For the datasets PdParkinson, Prostate, and Parkinson, our *In*dexLS heuristic is better than the clustering-based heuristics. In fact, the average hypervolume is significantly higher (Wilcoxon statistical test with a 5% of significance, $p = 9.3 \times 10^{-11}$, $p = 8.2 \times 10^{-7}$, and $p = 7.2 \times 10^{-5}$). Despite the fact that Smoking dataset does not show a significant difference (p = 0.561), we are still confident on the usefulness of the index-based heuristics, because it reduces the time significantly. Considering the execution time, we observe that our index-based heuristics is in average 28× faster than the clusteringbased heuristics. For instance, with our index-based heuristic we processed PdParkinson dataset approximately 32× faster.

4 CONCLUSIONS AND FUTURE WORK

We proposed a novel index-based heuristic for local search stages in a memetic algorithm. We found that our index-based heuristic have good performance when evaluated with microarray datasets.

Our proposed heuristic for local search, *IndexLS heuristic*, has a remarkably positive impact on the performance of the memetic algorithm. The execution time are significantly lower than the previous multi-objective solution presented in [9].

Although our results show that our *IndexLS heuristic* improves the performance, in the future, we will study the impact of *IndexLS* parameters; the effect of the implemented index structure; and an effective way to introduce this information during the initialization procedure.

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