

# Evolution of Neural Networks

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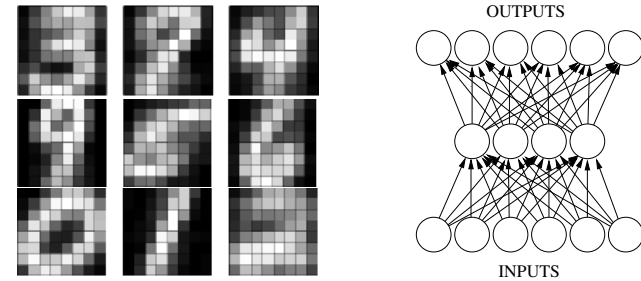
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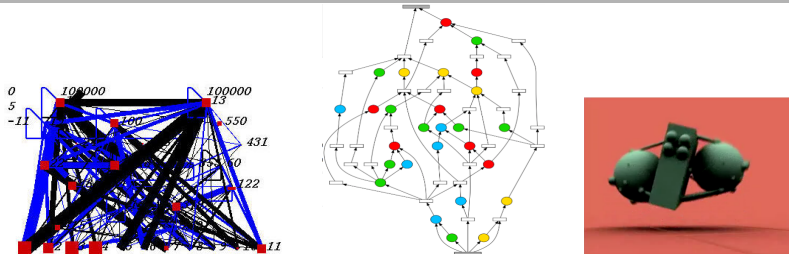
## Why Use Neural Networks?



- ▶ Neural nets powerful in many statistical domains
  - ▶ E.g. control, pattern recognition, prediction, decision making
  - ▶ Where no good theory of the domain exists
- ▶ Good supervised training algorithms exist
  - ▶ Learn a nonlinear function that matches the examples
  - ▶ Utilize big datasets

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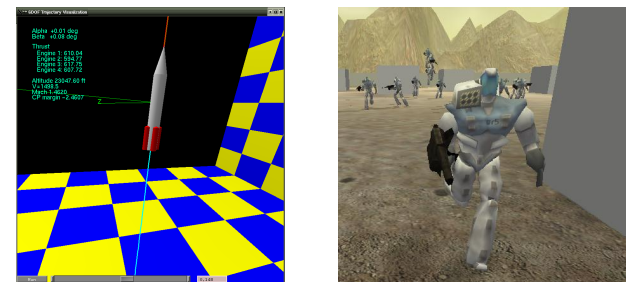
## Why Evolve Neural Networks?



- ▶ I. Original role (since 1990s): Sequential Decision Tasks
  - ▶ Both the structure and the weights evolved (no training)
  - ▶ Power from recurrency: POMDP tasks; behavior
- ▶ II. A new role (since 2016): Optimization of Deep Learning Nets
  - ▶ Architecture, hyperparameters, functions evolved; weights trained
  - ▶ Power from complexity
- ▶ III. A possible future role: Emergence of intelligence
  - ▶ Body/brain co-evolution; Competitive co-evolution
  - ▶ Evolution of memory, language, learning

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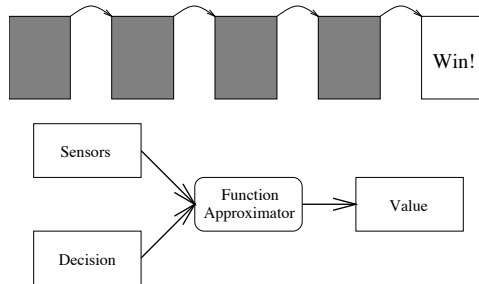
## I. Sequential Decision Tasks



- ▶ A sequence of decisions creates a sequence of states
  - ▶ States are only partially known
  - ▶ Optimal outputs are not known
  - ▶ We can only tell how well we are doing
- ▶ Exist in many important real-world domains
  - ▶ Robot/vehicle/traffic control
  - ▶ Computer/manufacturing/process optimization
  - ▶ Game playing; Artificial Life; Biological Behavior

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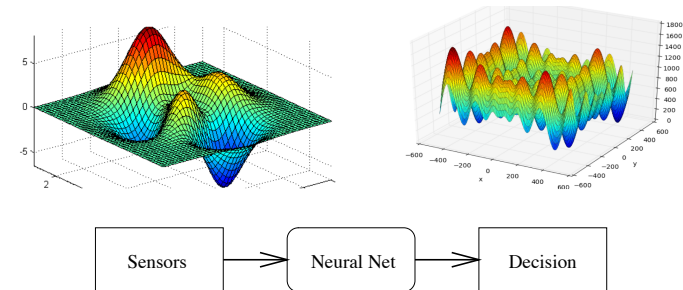
## Value-Function Reinforcement Learning



- ▶ E.g. Q-learning, Temporal Differences
  - ▶ Generate targets through prediction errors
  - ▶ Learn when successive predictions differ
- ▶ Predictions represented as a value function
  - ▶ Values of alternatives at each state
- ▶ Difficult with large/continuous state and action spaces
- ▶ Difficult with hidden states

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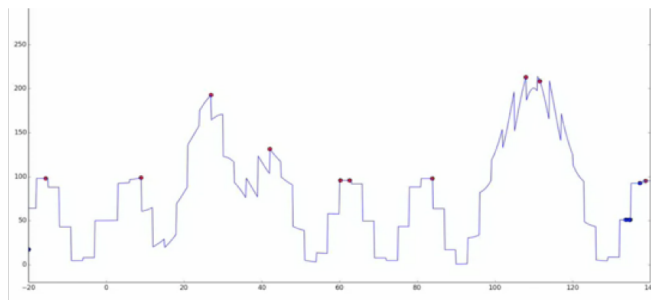
## Policy-Search Reinforcement Learning



- ▶ E.g. REINFORCE, policy gradients
- ▶ The policy is optimized directly through hill climbing
- ▶ Works well in simple cases
  - ▶ Large/continuous states and actions possible
  - ▶ Hidden states (in POMDP) disambiguated through memory
  - ▶ Does not scale well

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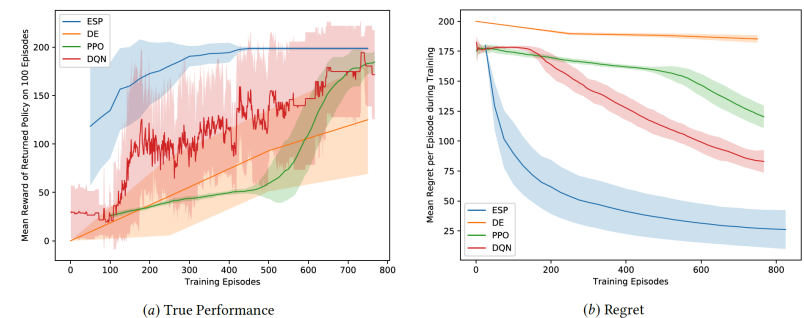
## Neuroevolution Reinforcement Learning



- ▶ Takes advantage of population-based search
  - ▶ In essence, multiple interacting searches
  - ▶ Each discover building blocks that are combined
  - ▶ Extensive exploration possible
- ▶ Makes it possible to scale up:
  - ▶ to large spaces (e.g.  $2^{270}$  states<sup>45</sup>)
  - ▶ to high dimensionality (e.g. up to  $1B^9$ )
  - ▶ to deceptive landscapes (with e.g. multiobj and novelty<sup>66</sup>)

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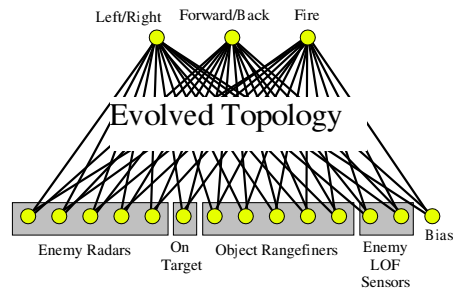
## How Well Does It Work?



- ▶ In the OpenAI Gym CartPole-v0 benchmark vs. PPO, DQN
  - ▶ NE converges faster, has lower variance, lower regret
  - ▶ NE is more efficient, reliable, and safer<sup>12</sup>
- ▶ In a double-pole benchmark vs. Sarsa, Q-MLP, etc.
  - ▶ The only method that can find solutions to 1m, 0.1m, POMDP<sup>17</sup>

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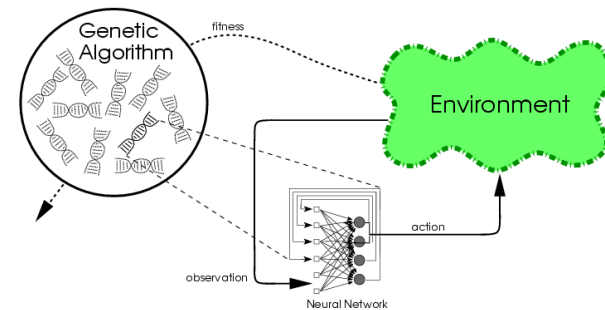
## Neuroevolution for POMDP



- ▶ Input variables describe the state observed through sensors
- ▶ Output variables describe actions
- ▶ Network between input and output:
  - ▶ Recurrent connections implement memory
  - ▶ Memory helps with POMDP

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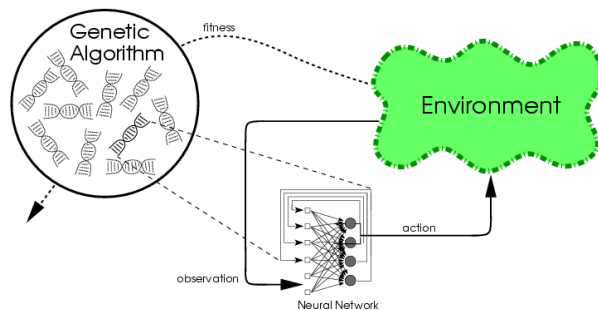
## Basic Neuroevolution (1)



- ▶ Evolving connection weights in a population of networks <sup>49,61,84,85</sup>
- ▶ Chromosomes are strings of connection weights (bits or real)
  - ▶ E.g. 10010110101100101111001
  - ▶ Usually fully connected, fixed topology
  - ▶ Initially random

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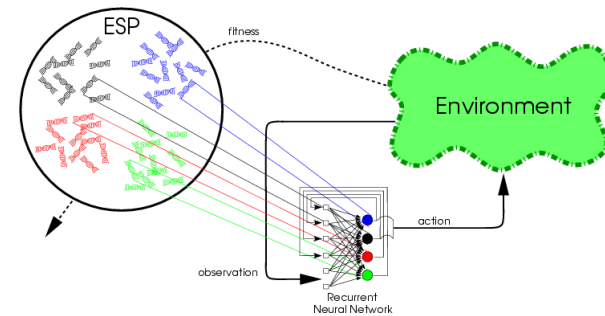
## Basic Neuroevolution (2)



- ▶ Parallel search for a solution network
  - ▶ Each NN evaluated in the task
  - ▶ Good NN reproduce through crossover, mutation
  - ▶ Bad thrown away
- ▶ Natural mapping between genotype and phenotype
  - ▶ GA and NN are a good match!

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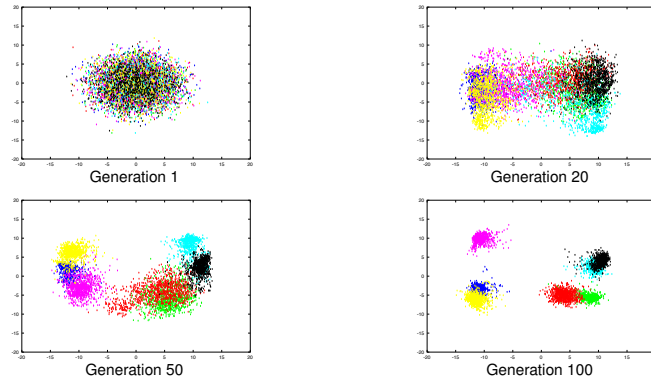
## Advanced NE 1: Evolving Partial Networks



- ▶ Evolving individual neurons to cooperate in networks <sup>1,50,53</sup>
- ▶ E.g. Enforced Sub-Populations (ESP <sup>15</sup>)
  - ▶ Each (hidden) neuron in a separate subpopulation
  - ▶ Fully connected; weights of each neuron evolved
  - ▶ Populations learn compatible subtasks
- ▶ Can be applied at the level of weights, and modules <sup>17</sup>

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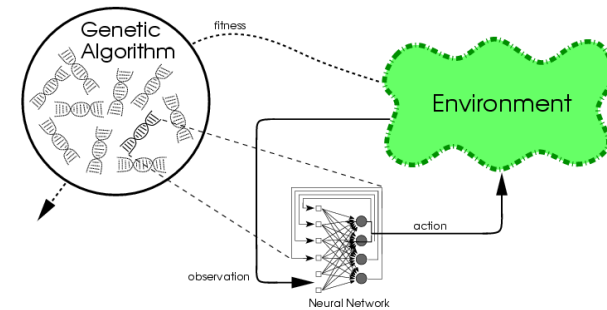
## Evolving Neurons with ESP



- ▶ Evolution encourages diversity automatically
  - ▶ Good networks require different kinds of neurons
- ▶ Evolution discourages competing conventions
  - ▶ Neurons optimized for compatible roles
- ▶ Large search space divided into subtasks
  - ▶ Optimize compatible neurons

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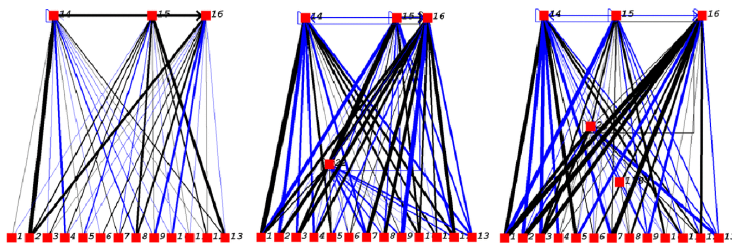
## Advanced NE 2: Evolutionary Strategies



- ▶ Evolving complete networks with ES (CMA-ES<sup>22</sup>)
- ▶ Small populations, no crossover
- ▶ Instead, intelligent mutations
  - ▶ Adapt covariance matrix of mutation distribution
  - ▶ Take into account correlations between weights
- ▶ Smaller space, less convergence, fewer conventions

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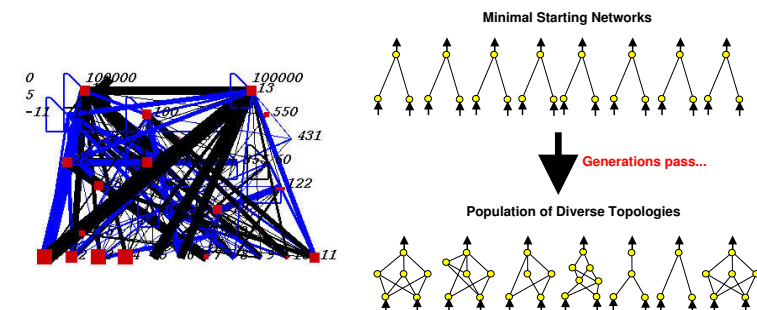
## Advanced NE 3: Evolving Network Structure



- ▶ Optimizing connection weights and network topology<sup>2,10,13,86</sup>
- ▶ E.g. Neuroevolution of Augmenting Topologies (NEAT<sup>69,72</sup>)
- ▶ Based on *Complexification*
- ▶ Of networks:
  - ▶ Mutations to add nodes and connections
- ▶ Of behavior:
  - ▶ Elaborates on earlier behaviors

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## Why Complexification?

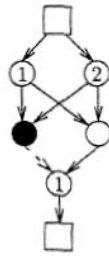
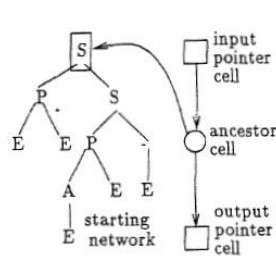


- ▶ Challenge with NE: Search space is very large
- ▶ Complexification keeps the search tractable
  - ▶ Start simple, add more sophistication
- ▶ Incremental construction of intelligent agents

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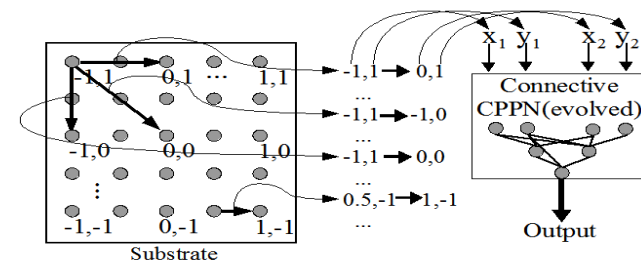
## Advanced NE 4: Indirect Encodings (1)



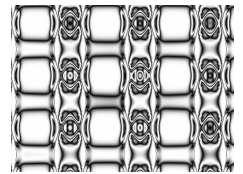
- Instructions for constructing the network evolved
  - Instead of specifying each unit and connection<sup>2,10,48,67,86</sup>
- E.g. Cellular Encoding (CE<sup>20</sup>)
- Grammar tree describes construction
  - Sequential and parallel cell division
  - Changing thresholds, weights
  - A “developmental” process that results in a network

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## Indirect Encodings (2)

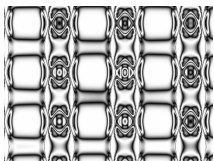
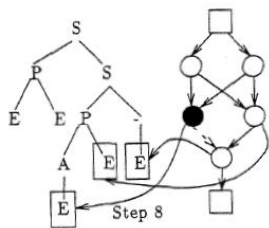


- Encode the networks as spatial patterns
- E.g. Hypercube-based NEAT (HyperNEAT<sup>7</sup>)
- Evolve a neural network (CPPN) to generate spatial patterns
  - 2D CPPN:  $(x, y)$  input  $\rightarrow$  grayscale output
  - 4D CPPN:  $(x_1, y_1, x_2, y_2)$  input  $\rightarrow w$  output
  - Connectivity and weights can be evolved indirectly
  - Works with very large networks (millions of connections)



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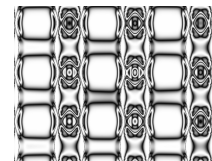
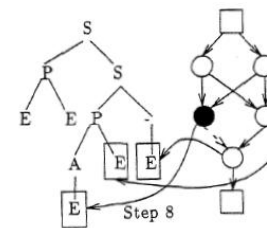
## Properties of Indirect Encodings (1)



- Smaller search space
- Avoids competing conventions
- Describes classes of networks efficiently
- Modularity, reuse of structures
  - Recurrency symbol in CE: XOR  $\rightarrow$  parity
  - Repetition with variation in CPPNs
  - Useful for evolving morphology

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## Properties of Indirect Encodings (2)



- Not fully explored (yet)
  - See e.g. CS track at GECCO
- Promising current work
  - More general L-systems; developmental codings; embryogeny<sup>73</sup>
  - Scaling up spatial coding<sup>8,14</sup>
  - Genetic Regulatory Networks<sup>57</sup>
  - Evolution of symmetries<sup>79</sup>

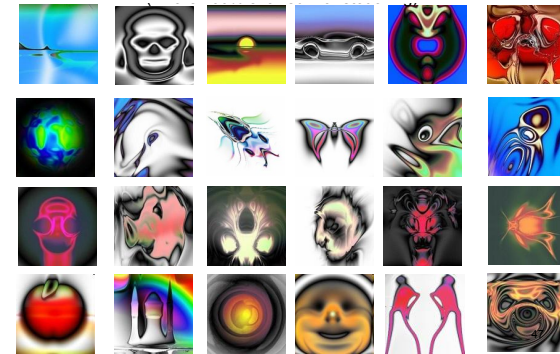
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## Further NE Techniques

- ▶ Incremental and multiobjective evolution<sup>16,64,78,85</sup>
- ▶ Utilizing population culture<sup>3,39,76</sup>
- ▶ Utilizing evaluation history<sup>38</sup>
- ▶ Evolving NN ensembles and modules<sup>24,37,52,58,82</sup>
- ▶ Evolving transfer functions and learning rules<sup>6,59,74</sup>
- ▶ Bilevel optimization of NE<sup>35</sup>
- ▶ Evolving LSTMs for strategic behavior<sup>30</sup>
- ▶ Combining learning and evolution<sup>5,11,39,51,70,76,83</sup>
- ▶ Evolving for novelty

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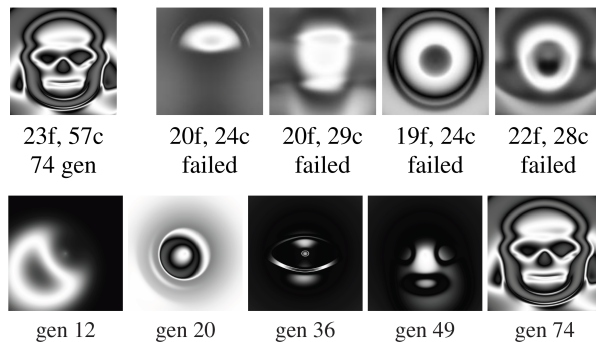
## Evolving for Novelty



- ▶ Motivated by humans as fitness functions
- ▶ E.g. picbreeder.com, endlessforms.com<sup>65</sup>
  - ▶ CPPNs evolved; Human users select parents
- ▶ No specific goal
  - ▶ Interesting solutions preferred
  - ▶ Similar to biological evolution?

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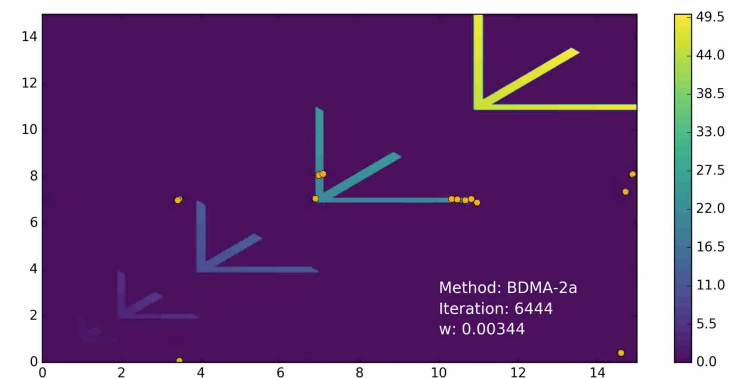
## Novelty Search



- ▶ Evolutionary algorithms maximize a performance objective
  - ▶ But sometimes hard to achieve it step-by-step
- ▶ Novelty search rewards candidates that are simply different<sup>27,71</sup>
  - ▶ Stepping stones for constructing complexity

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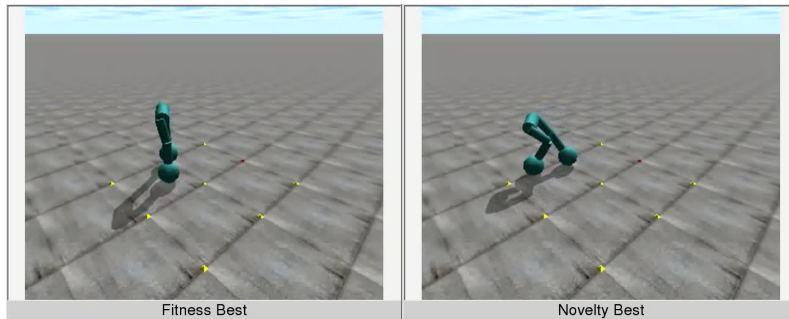
## Novelty Search Demo (1)



- ▶ Illustration of stepping stones<sup>40,41</sup>
  - ▶ Nonzero fitness on “feet” only; stepwise increase
  - ▶ Top and right “toes” are stepping stones to next “foot”
  - ▶ Difficult for fitness based search; novelty can do it
- ▶ DEMO

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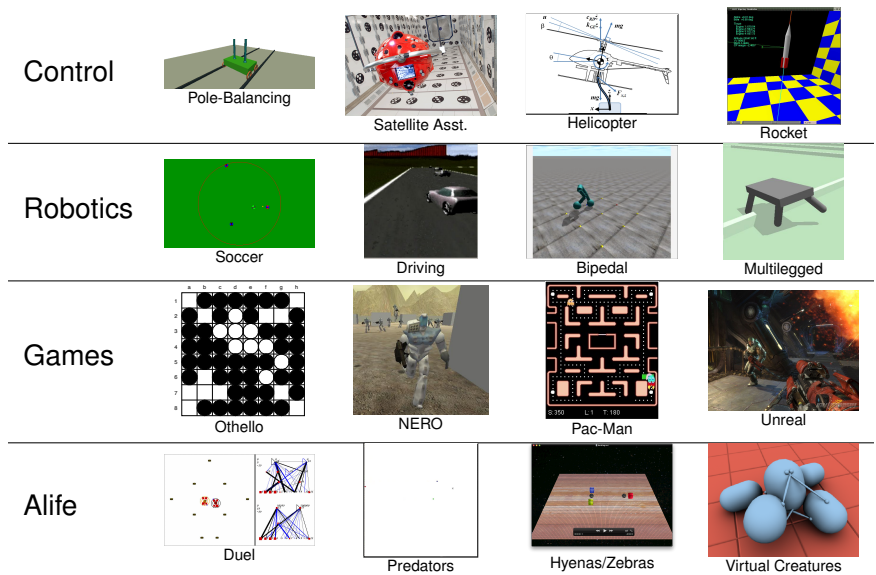
## Novelty Search Demo (2)



- ▶ Fitness-based evolution is rigid
  - ▶ Requires gradual progress
- ▶ Novelty-based evolution is more innovative, natural<sup>27,71</sup>
  - ▶ Allows building on stepping stones
  - ▶ As a secondary objective—or even the only one!
- ▶ DEMO

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## Neuroevolution Applications



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## Games: Evolving Humanlike Behavior



- ▶ Botprize competition, 2007-2012
  - ▶ Turing Test for game bots (\$10,000 prize)
- ▶ Three players in Unreal Tournament 2004:
  - ▶ Human confederate: tries to win
  - ▶ Software bot: pretends to be human
  - ▶ Human judge: tries to tell them apart!

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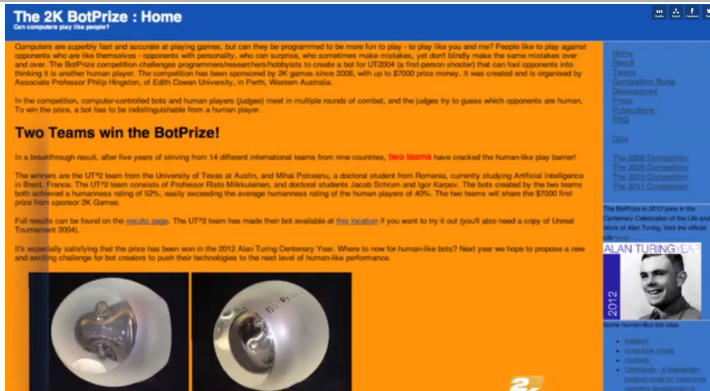
## Evolving an Unreal Bot



- ▶ Evolve effective fighting behavior<sup>63</sup>
  - ▶ Human-like with resource limitations (speed, accuracy...)
- ▶ Also scripts & learning from humans (unstuck, wandering...)
- ▶ 2007-2011: bots 25-30% vs. humans 35-80% human
- ▶ 6/2012 best bot better than 50% of the humans
- ▶ 9/2012...?

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Success!!!



- ▶ In 2012, two teams reach the 50% mark!
- ▶ Fascinating challenges remain:
  - ▶ Judges can still differentiate in seconds
  - ▶ Judges lay cognitive, high-level traps
  - ▶ Team competition: collaboration as well
- ▶ DEMO

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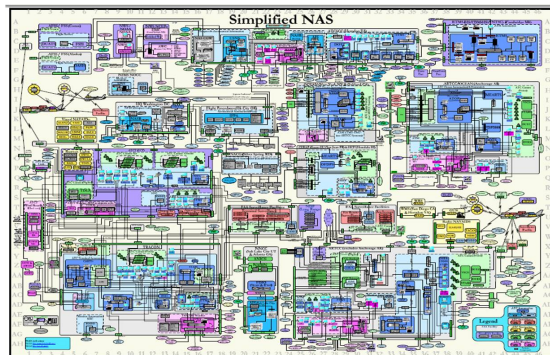
## II. Optimization of DL Architectures



- ▶ Big Data and Big Compute available since 2000s
  - ▶ Machine learning systems have scaled up
- ▶ E.g. Deep Learning ideas existed since the 1990s
  - ▶ With million times more data & compute, they now work!
- ▶ A new problem: How to configure such systems?

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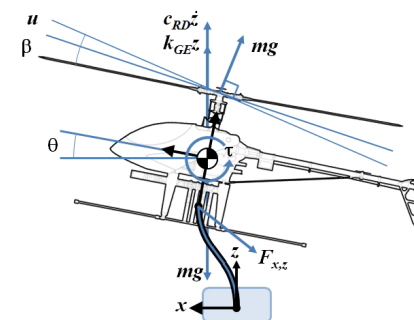
## Configuring Complex Systems



- ▶ A new general approach to engineering
  - ▶ Humans design just the framework
  - ▶ Machines optimize the details
- ▶ Programming by optimization<sup>21</sup>

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## E.g. Optimizing NE in Helicopter Hovering

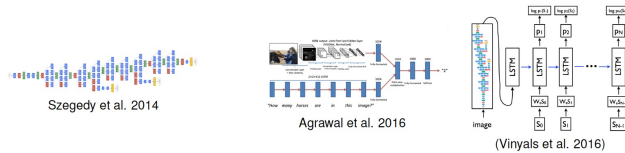


- ▶ A challenging benchmark
  - ▶ RL, NE solutions exist
- ▶ Eight parameters optimized by hand<sup>25</sup>
  - ▶ Hard for a human designer to do more
- ▶ With EA, increased to 15
  - ▶ → Significantly better performance<sup>35</sup>

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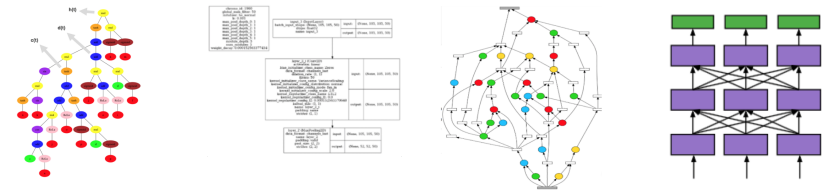


## Designing Deep Learning Architectures



- Different architectures work better in different tasks
  - Structure matters!
- Too complex to be discovered by hand
  - How to discover principles of organization?
  - How to cover enough of the space?

## How to Discover Network Structure?



Evolutionary Neural Architecture Search is a natural fit:

- Population-based search covers the space
- Crossover between structures discovers principles
- Novelty search maximizes exploration

Building on Neuroevolution work since the 1990s  
Hyperparameters; nodes; modules; topologies; multiple tasks

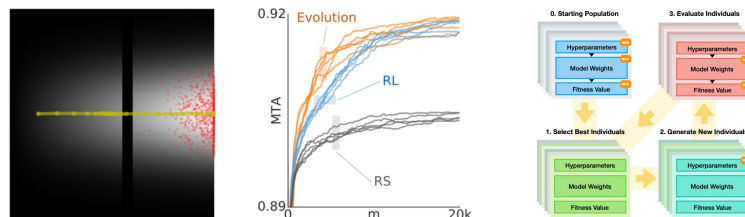
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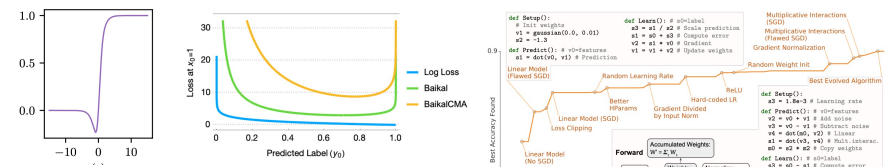
## Progress in Evolutionary Deep Learning



Understanding ES and GAs in RL (Uber, OpenAI)<sup>26,60,75</sup>

- ES provides more exploration than gradients; GA more than ES
- Scaling and regularization (Google)<sup>55</sup>
- State-of-the art in CIFAR-10, CIFAR-100, ImageNet
- Population-based training (DeepMind, Cognizant)<sup>23,32</sup>
- Continual training and evolution

## Progress in Evolutionary Deep Learning (2)



Optimizing activation functions and loss functions (Cognizant)<sup>4,18,19,32</sup>

- Regularization and refinement (Gonzalez et al. GECCO'21; Liang et al. GECCO21)
- Designing machine learning algorithms with GP (Google)<sup>36,56</sup>
- Adapts to different task types
  - Discovering new layer types

Coevolution of multiple aspects of network design?

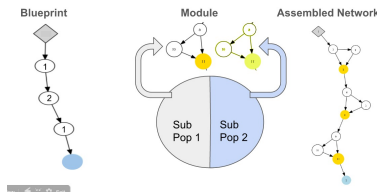
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## E.G. Neural Architecture Search with CoDeepNEAT



Evolution at three levels<sup>46</sup>

- Module subpopulations optimize building blocks
- Blueprint population optimizes their combinations
- Hyperparameter evolution optimizes their instantiation

Fitness of the complete network drives evolution

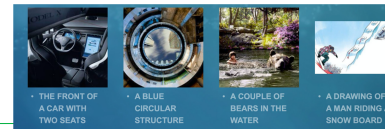
Applies to both CNN (vision), LSTM (language) networks

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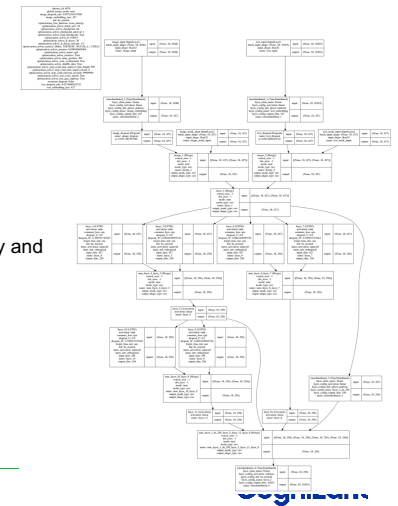
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## Improve Human Design

- E.g. image captioning:
  - Start with a state-of-the-art design: Show&Tell<sup>80</sup>
  - Search in the space of similar elements
  - 5% improvement
  - A prototype service on the web
- Best-performing AI defies human notions of symmetry and patterns of organization
- AI designing AI: could we automate it?



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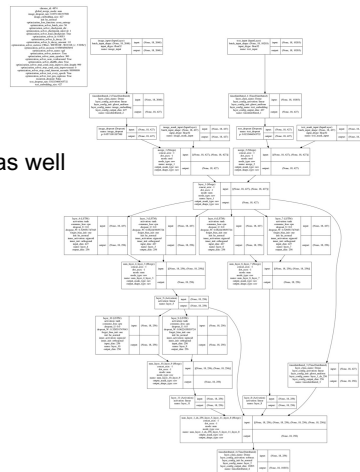


## Evolutionary AutoML

Current AutoML: Hyperparameter optimization

Evolutionary AutoML: Architectures and modules as well

1. Improve over naïve baseline  
20% or more with little effort
2. Improve state of the art  
With more expertise & compute
3. Minimize network resources  
Train and run networks faster
4. Extend small datasets  
Multitasking with related datasets

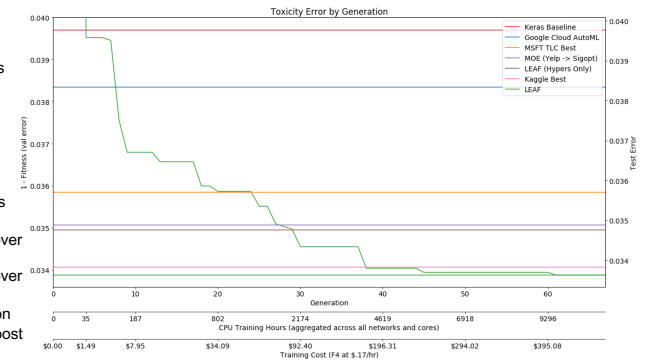


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## 1 and 2: Improve Performance

- Domain: Wikipedia Toxic Comment Identification
  - Why: Toxicity is bad for business
  - Data: 160K labeled comments
  - Challenge: highly diverse vocabulary, style, and length
- Layer Types: Conv1D, LSTM, GRU
- LEAF Results:<sup>33</sup>
  - With minimal compute: Improves over naïve Keras baseline
  - With more compute: Improves over other AutoML methods
  - With more compute: Improves over SOTA hand-designed model.
  - LEAF Hyperparameter Search on final architecture gives a final boost
- Similar results on Age Estimation<sup>47</sup> (Miikkulainen et al. GECCO-21)



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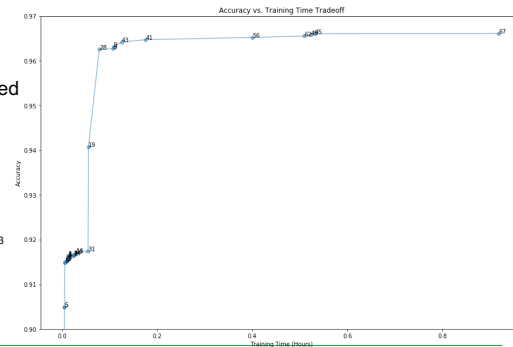


### 3. Minimize Network Resources

- Evolution adds complexity only if needed
- Favors minimal solutions
- Over evolution a range of sizes explored
- Approximation of the Pareto front

- Small networks found that perform well
- Minimization with little cost
- E.g. 0.38% drop with 1/12<sup>th</sup> of the size

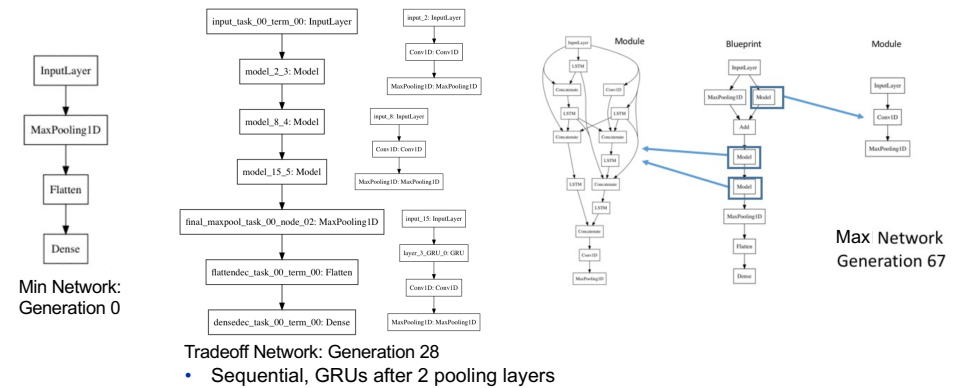
Adding a size objective will explore more



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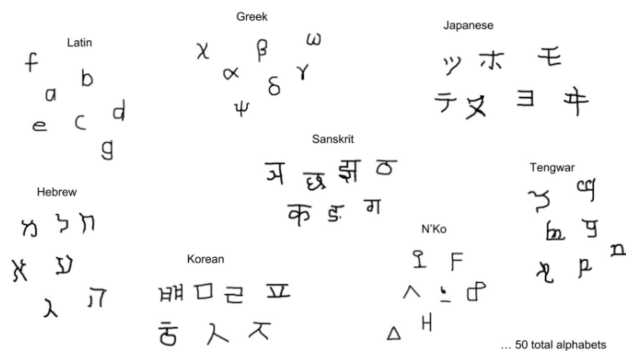
### Example Performance/Size Tradeoffs



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### 4. Extend Small Datasets

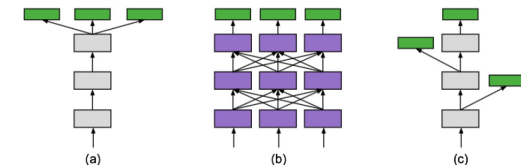


- Recoanize characters in 50 alphabets

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### Harnessing Multiple Datasets through Multitasking



- Learning in multiple tasks at once
  - More generalizable embeddings <sup>34,43</sup>
  - Each task can learn better
- Network structure can have a large effect
  - A good domain to test neuroevolution of structure

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Cognizant

### III. Emergence of Intelligence

#### Multitasking Benchmarks

State-of-the-art in two ML benchmarks:

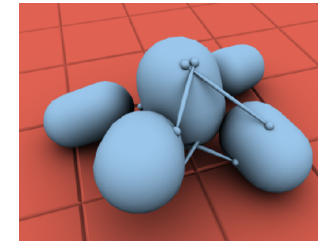
- Omniglot multialphabet character recognition <sup>34</sup>
  - Improved state-of-the-art 31%
  - Demo: [evolution.ml/demos/omnidraw](http://evolution.ml/demos/omnidraw)
- CelebA multiattribute face classification <sup>42</sup>
  - Improved state-of-the-art 0.75%
  - Demo: [evolution.ml/demos/celebmatch](http://evolution.ml/demos/celebmatch)

Improves learning in each task

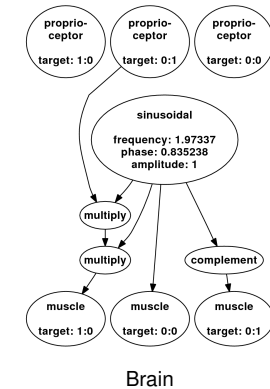
- Even when little data available



Cognizant



Body

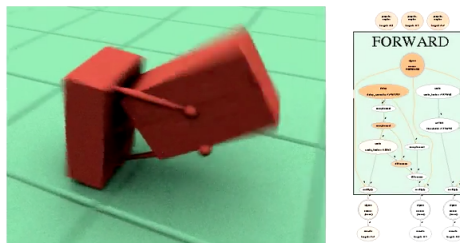


Brain

- Origins of intelligence: Embodied optimization
- Body-Brain Coevolution <sup>28,29,68</sup>
  - Body: Blocks, muscles, joints, sensors
  - Brain: A neural network (with general nodes)
  - Evolved together in a physical simulation
- Encapsulation, Pandemonium, Syllabus

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#### Encapsulation

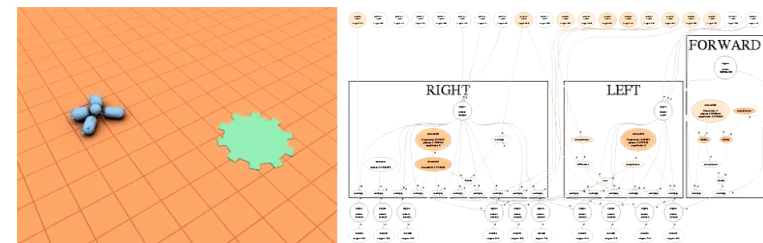


- Once evolved, a trigger node is added
- DEMO

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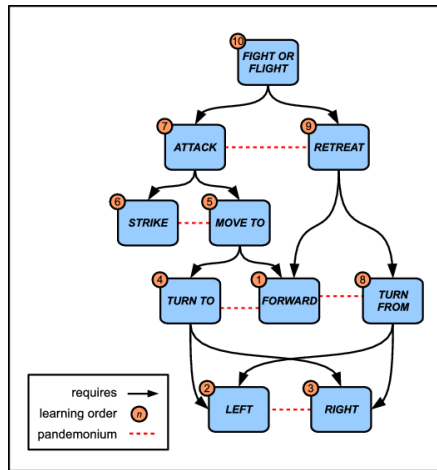
#### Pandemonium



- Conflicting behaviors: Highest trigger wins
- DEMO

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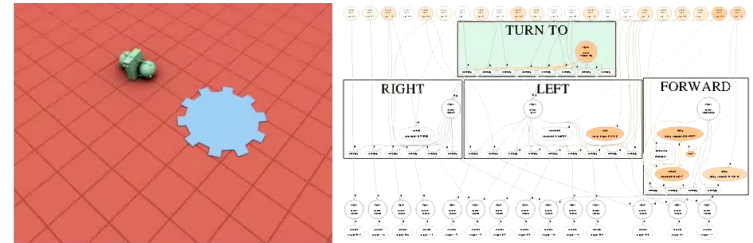
## Syllabus



- Step-by-step construction of complex behavior
- Primitives and three levels of complexity
- Constructed by hand; body and brain evolved together

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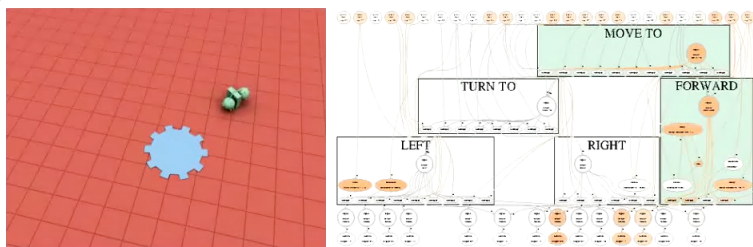
## Turn to Light



- First level of complexity
- Selecting between alternative primitives

50/60

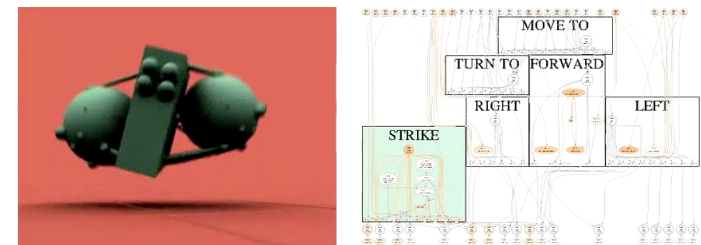
## Move to light



- First level of complexity (Sims 1994)
- Selecting between alternative primitives

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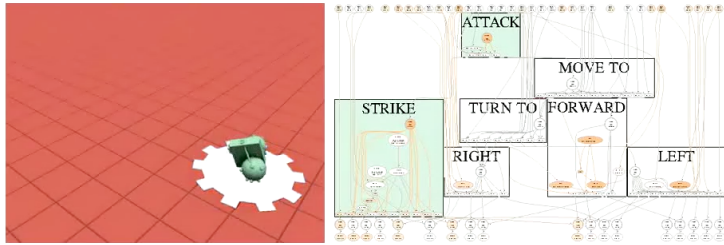
## Strike



- Alternative behavior primitive

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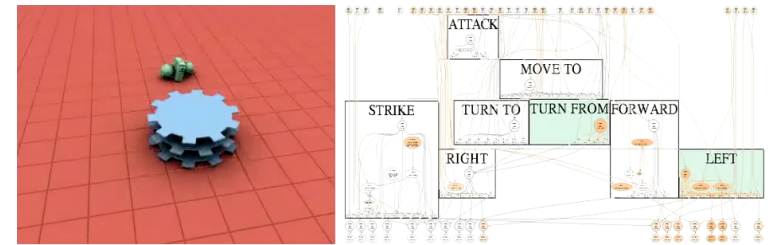
## Attack



- Second level of complexity (beyond Sims and others)

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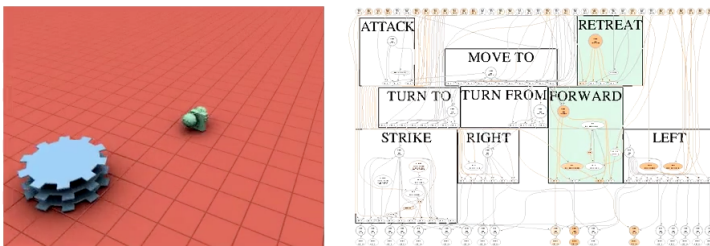
## Turn from Light



- Alternative first-level behavior

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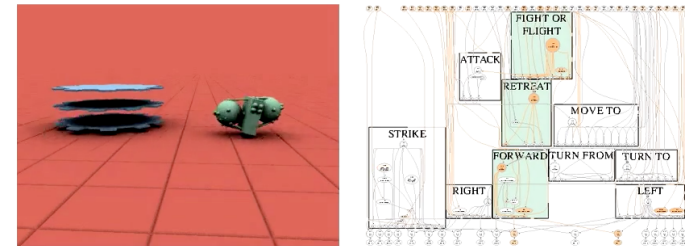
## Retreat



- Alternative second-level behavior

55/60

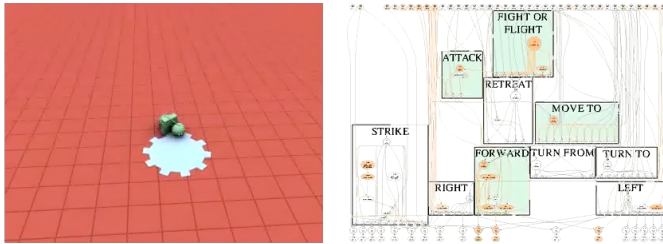
## Fight or Flight



- Third level of complexity

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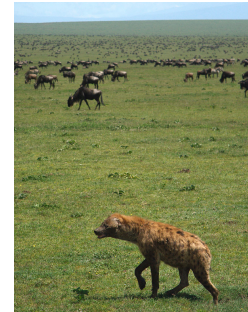
## Insight: Body/Brain Coevolution



- ▶ Evolving body and brain together poses strong constraints
  - ▶ Behavior appears believable
  - ▶ Worked well also in BotPrize (Turing test for game bots)<sup>63</sup>
- ▶ Possible to construct innovative, situated behavior

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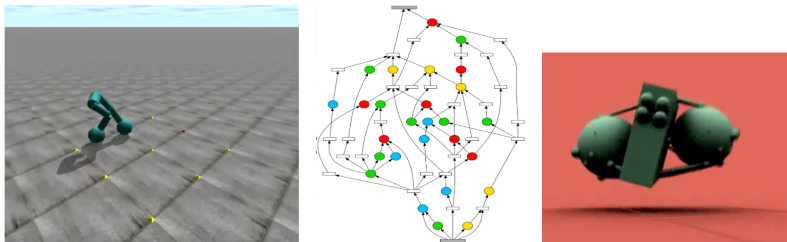
## Constructing Intelligent Systems



- ▶ Believable, complex behavior in embedded environments
  - ▶ Open-ended “arms race”<sup>54</sup>
- ▶ Similar to self-play e.g. in AlphaGo Zero
  - ▶ Complexity beyond human ability to design it
- ▶ If we can build open ended environments, we should be able to build more complex solutions
  - ▶ Co-evolve environments and behaviors? (e.g. POET<sup>81</sup>, EUREQA<sup>62</sup>)

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## Conclusion



- ▶ AI extending from prediction to creativity
  - ▶ i.e. from modeling to optimization
  - ▶ i.e. from Deep Learning to Evolution/RL
- ▶ Evolutionary optimization of neural networks can
  - ▶ Discover novel and strategic behavior
  - ▶ Discover useful complexity for Deep Learning
  - ▶ Gain insight into origins of intelligence

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## Further Material

- ▶ [www.cs.utexas.edu/users/risto/talks/enn-tutorial](http://www.cs.utexas.edu/users/risto/talks/enn-tutorial)
  - ▶ Slides and references
  - ▶ Demos
  - ▶ A step-by-step neuroevolution exercise (evolving behavior in the NERO game)
- ▶ <http://nn.cs.utexas.edu/?miikkulainen:encyclopedia20-new>
  - ▶ A short summary of neuroevolution
- ▶ [www.nature.com/articles/s42256-018-0006-z](http://www.nature.com/articles/s42256-018-0006-z)
  - ▶ Nature Machine Intelligence survey on Neuroevolution
- ▶ [arxiv.org/abs/1902.09635](https://arxiv.org/abs/1902.09635)
  - ▶ Proposal for NAS benchmark

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