

Aims and Goals of this Tutorial The scope of this tutorial is restricted to population-based generational, non-elitist EAs (first part), and steady-state, elitist EAs (second part). This tutorial will provide an overview of the goals of runtime analysis of EAs selected, generally applicable techniques You should attend if you wish to theoretically understand the behaviour and performance of the EAs you design

- familiarise yourself with some of the techniques used
- pursue research in the area
- enable you or enhance your ability to
 - 1. understand theoretically population-dynamics of EAs on different problems
 - perform time complexity analysis of population-based EAs on common toy problems
 - 3. have the basic skills to start independent research in the area

Evolutionary Algorithms



Outline

Introduction

Runtime Analysis Drift Analysis

Upper bounds for Non-elitist, Generational EAs

The Level Based Theorem (μ, λ) GA on OneMax Noisy and Uncertain Fitness

Lower Bounds for Non-elitist, Generational EAs

Negative Drift Theorem for Populations Mutation-Selection Balance Self-adaptation Negative Drift with Crossover

Upper Bounds for Elitist, Steady-state EAs

- (1+1) EA and Artificial Fitness Levels
- $(\mu+1)$ Genetic Algorithm and OneMax
- $(\mu+1)$ Genetic Algorithm and Jump

Black Box Optimisation Algorithms and Runtime

Runtime Analysis of Evolutionary Algorithms



- An unknown optimisation problem f is chosen, possiby adversarily, from a problem class F known to the algorithm.
- For every $t \in \mathbb{N}$, using the obtained information $(x_1, f(x_1)), \ldots, (x_t, f(x_t))$, the algorithm queries a new search point x_{t+1} to obtain $f(x_{t+1})$ from the oracle.

Definition

The runtime of algorithm A on fitness function² $f: \{0,1\}^n \to \mathbb{R}$ is

$$T_{A,f} := \min_{t \in \mathbb{N}} \left\{ t \mid \forall y \in \{0,1\}^n, \ f(x_t) \ge f(y) \right\}.$$

The worst case expected runtime of algorithm A on problem class F is

$$T_{A,F} := \max_{f \in F} \mathbf{E} \left[T_{A,f} \right]$$

Droste, Jansen, and Wegener [2006]

 $^2 {\rm This}$ definition assumes that the objective is to maximise the fitness function.

Image: Springer

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Runtime Analysis of (1, λ) **EA on LeadingOnes**

Theorem

The (1, λ) EA with $\lambda = n$ optimises LEADINGONES in $O(n^2)$ expected time. Proof

- **Distance:** let d(x) = n i where *i* is the number of leading ones;
- ► Drift:

$$\mathbf{E}\left[d(X_t) - d(X_{t+1})|d(X_t) = n - i\right]$$

$$\geq 1 \cdot \left(1 - \left(1 - \frac{1}{n}\left(1 - \frac{1}{n}\right)^{n-1}\right)^{\lambda}\right) - n \cdot \left(1 - \left(1 - \frac{1}{n}\right)^n\right)^{\lambda}$$

$$= c_1 - n \cdot c_2^n = \Omega(1)$$

Hence,

$$\mathbf{E}\left[T\right] \leq \lambda \cdot \frac{\mathsf{max \ distance}}{\mathsf{drift}} = \lambda \cdot \frac{n}{\Omega(1)} = O(n^2)$$

Outline of a Non-elitist, Generational Evolutionary Algorithm⁵

Why consider non-elitism?

Biological plausibility
Mathematical tractability (disputed)
Beneficial in uncertain environments

Noisy optimisation [Dang and Lehre, 2016a]
Dynamical optimisation [Dang, Jansen, and Lehre, 2017b]

Help populations overcome local optima

Exponential speedup with self-adaptation on a a peaked problem [Dang and Lehre, 2016d]
Non-elitist EAs excel in fitness landscapes with sparse deceptive regions and dense valleys (GECCO'2021 Theory Track)

Appropriate algorithm configuration critical with non-elitism.

Both (μ,λ) EA and (μ+λ) EA optimises JUMPin⁶ Θ(n^k) [Doerr, 2020]

⁶Under certain conditions on μ , λ , and k.

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⁷Corus, Dang, Eremeev, and Lehre [2018]

Level-based Analysis

Problem

 \blacktriangleright Given any target set $B \subset \mathcal{X}$ (e.g. global optima), let

 $T_B := \min\{\lambda t \mid P_t \cap B
eq \emptyset\}$

where P_0, P_1, \ldots are the populations generated by the algorithm.

• How does $\mathbf{E}[T_B]$ depend on \mathcal{D} and λ ? Informally, how much time does the algorithm require to discover the target set.

Level-based Theorem (LBT)

 If *D* and λ satisfy certain conditions, then LBT provides an upper bound for E [*T_B*].

Level Partitioning of Search Space ${\cal X}$

Definition

 (A_1,\ldots,A_m) is a level-partitioning of search space ${\mathcal X}$ if

- $\bigcup_{j=1}^{m} A_j = \mathcal{X}$ (together, the levels cover the search space)
- $\blacktriangleright A_i \cap A_j = \emptyset$ whenever i
 eq j (the levels are nonoverlapping)
- $\blacktriangleright\,$ the last level A_m covers the optima for the problem

We write $A_{\geq j}$ to denote everything in level j and higher, i.e.,

Level-based Theorem⁷

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Notation

For any population $P = (y_1, \dots, y_\lambda) \in \mathcal{X}^\lambda$ and $j \in [m]$, let $|P \cap A_{\geq j}| := |\{i \mid y_i \in A_{\geq j}\}|,$ i.e, the number of individuals in P that is in subset $A_{\geq j}$.

Example

 $|P\cap A_{\geq 4}|=5$ where $A_{\geq 4}$ corresponds to the red region.

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Current level of a population P wrt $\gamma_0 \in (0,1)$

Definition

The unique integer $j \in [m-1]$ such that

$$|P\cap A_{>j}|\geq \gamma_0\lambda>|P\cap A_{>j+1}|$$

Example

Current level wrt $\gamma_0 = \frac{1}{2}$ is4.

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Level-based Theorem via Multiplicative Up-drift⁸

Theorem ([Doerr and Ktzing, 2020] via multiplicative up-drift) If (G1), (G2), and (G3b): $\lambda \geq \frac{256}{\gamma_0 \delta} \ln(8t_0)$ where

$$t_0 := rac{7000}{\delta} \left(m + rac{1}{1-\gamma_0} \sum_{j=1}^{m-1} \log_2\left(rac{2\gamma_0 oldsymbol{\lambda}}{1+rac{z oldsymbol{\lambda}}{D_0}}
ight) + rac{1}{oldsymbol{\lambda}} \sum_{j=1}^{m-1} rac{1}{z_j}
ight)$$

the $\mathrm{E}\left[T
ight]=8\lambda t_{0}$.

Theorem ([Corus et al., 2018]) If (G1), (G2), and (G3): $\lambda \ge \left(\frac{4}{\gamma_0 \delta^2}\right) \ln\left(\frac{128m}{z_{min}\delta^2}\right)$ then $\mathbf{E}\left[T\right] \le \left(\frac{8}{\delta^2}\right) \sum_{j=1}^{m-1} \left(\lambda \ln\left(\frac{6\delta\lambda}{4+z_j\delta\lambda}\right) + \frac{1}{z_j}\right).$

⁸Note that "multiplicative up-drift" was already used in Corus et al. [2018] (Corollary 22).

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Suggested recipe for application of level-based theorem

- 1. Find a partition (A_1, \ldots, A_m) of \mathcal{X} that reflects the state of the algorithm, and where A_m consists of all goal states.
- 2. Find parameters γ_0 and δ and a configuration of the algorithm (e.g., mutation rate, selective pressure) such that whenever $|P \cap A_{\geq i+1}| = \gamma \lambda > 0$, condition (G2) holds, i.e.,

 $\Pr\left(y \in A_{>j+1}\right) \geq \gamma(1+\delta)$

3. For each level $j \in [m-1]$, estimate a lower bound $z_j \in (0,1)$ such that whenever $|P \cap A_{>j+1}| = 0$, condition (G1) holds, i.e.,

$$\Pr\left(y \in A_{>j+1}\right) \geq \boldsymbol{z}_{j}$$

- 4. Calculate the sufficient population size λ from condition (G3).
- 5. Read off the bound on expected runtime.

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The Level-Based Theorem (LBT) is "tight"⁹ Theorem For any valid set of parameters $\Theta = (A, \gamma_0, \delta, z)$ for LBT, there exists a mapping \mathcal{D}_{slow} satisfying (G1) and (G2) of LBT st. $E[T_{A_m}] \ge \left(\frac{2}{3\delta}\right) \sum_{j=1}^{m-2} \left(\lambda \ln\left(\frac{\gamma_0 \delta \lambda}{1/\delta + 2z_j \delta \lambda}\right) + \frac{1}{z_j}\right)$ $E[T_{A_m}] \le \left(\frac{8}{\delta^2}\right) \sum_{j=1}^{m-1} \left(\lambda \ln\left(\frac{6\delta \lambda}{4 + z_j \delta \lambda}\right) + \frac{1}{z_j}\right).$

More info about $\boldsymbol{\mathcal{D}}$ required for more precise bounds

All algorithms

Logical structure of LBT

For all parameter settings Θ , and all mappings $\mathcal{D} \in \mathcal{A}(\Theta)$

 $\mathrm{E}\left[T_{\mathcal{D}}
ight] \leq f(\Theta) + arepsilon.$ Also, there exists $\mathcal{D} \in \mathcal{A}(\Theta)$ st $\mathrm{E}\left[T_{\mathcal{D}}
ight] \geq f(\Theta) - arepsilon$

Assume you have applied the LBT to your algorithm, how precise is the bound?

- The only LBT knows about your algorithm D is that it satisfies the conditions for the parameters Θ. (Many other processes satisfy the conditions for the same Θ.)
- The lower bound implies that the LBT gives the best possible (±ε) runtime bound for your algorithm given the information that is available.
- Some algorithms in A(Θ), including yours, could be faster than f(Θ). However, more information about the algorithm required to prove so, i.e.,
 - \blacktriangleright a more precise set of parameters Θ' , or
 - \blacktriangleright a different way of characterising algorithms than $\mathcal{A}(\Theta)$

⁹Corus, Dang, Eremeev and Lehre (IEEE TEVC 2018) https://arxiv.org/abs/1407.7663

Example application – (μ, λ) GA on Onemax

(μ,λ) Genetic Algorithm (GA)

for $t = 0, 1, 2, \ldots$ until termination condition do for i = 1 to λ do Select a parent x from population P_t acc. to (μ, λ) -selection Select a parent y from population P_t acc. to (μ, λ) -selection Apply uniform crossover to x and y, i.e. z := crossover(x, y)Create $P_{t+1}(i)$ by flipping each bit in z with probability χ/n .

Theorem

If $\lambda > c \ln(n)$ for a sufficiently large constant c > 0, and $\frac{\lambda}{\mu} > 2e^{\chi}(1+\delta)$ for any constant $\delta > 0$, then the expected runtime of (μ, λ) GA on ONEMAX is $O(n\lambda)$.

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(μ, λ) -selection mechanism P_1 P_2 P_3 1. Sort the current population $P = (x_1, \ldots, x_\lambda)$ such that $f(x_1) > f(x_2) > \ldots > f(x_{\lambda})$ 2. return $\text{Unif}(x_1,\ldots,x_\mu)$ 29 / 73

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Application of the Level-based Theorem

If for all populations $P\in \mathcal{X}^\lambda$, an individual $y\sim \mathcal{D}(P)$ has

$$\Pr\left(\boldsymbol{y} \in \boldsymbol{A}_{\geq j+1}\right) \geq \boldsymbol{z}_{\boldsymbol{j}},\tag{G1}$$

$$\Pr\left(y \in A_{\geq j+1}\right) \geq \gamma(1+\delta),\tag{G2}$$

where $j \in [m-1]$ is the current level of population P, i.e.,

$$|P\cap A_{\geq j}|\geq \gamma_0\lambda>|P\cap A_{\geq j+1}|=\gamma\lambda,$$

and the population size $oldsymbol{\lambda}$ is bounded from below by

$$\lambda \ge \left(\frac{4}{\gamma_0 \delta^2}\right) \ln\left(\frac{128m}{z_{\min}\delta^2}\right),\tag{G3}$$

then the algorithm reaches the last level $oldsymbol{A}_m$ in expected time

$$\mathrm{E}\left[T_{A_m}
ight] \leq \left(rac{8}{\delta^2}
ight) \sum_{j=1}^{m-1} \left(\lambda \ln\left(rac{6\delta\lambda}{4+z_j\delta\lambda}
ight) + rac{1}{z_j}
ight)$$

Bounding the first term (first attempt, imprecise) $\sum_{j=0}^{n-1} \ln\left(\frac{6\delta\lambda}{4+z_j\delta\lambda}\right) < \sum_{j=0}^{n-1} \ln\left(\frac{6\delta\lambda}{4}\right) = \mathcal{O}(n\ln(\lambda)).$ • This upper bound is imprecise because it does not exploit that the upgrade probabilities z_i are large for small j.

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Bounding the first term (second attempt, more precise)

$$\sum_{j=0}^{n-1} \ln\left(rac{6\delta\lambda}{4+z_j\delta\lambda}
ight) < \sum_{j=0}^{n-1} \ln\left(rac{6}{z_j}
ight)$$

using $\ln(a) + \ln(b) = \ln(ab)$ and defining $c := rac{12e^{\chi}}{(1-\delta)\chi}$

$$= \ln \left(\prod_{j=0}^{n-1} rac{cn}{n-j}
ight) = \ln \left(rac{(cn)^n}{n!}
ight)$$

and using the lower bound $n! > (n/e)^n$

$$< \ln\left(rac{(cn)^n e^n}{n^n}
ight) = n \ln(ec) = \mathcal{O}(n).$$

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Bounding the second term

Recall the definition of the n-th Harmonic number

$$H_n:=\sum_{i=1}^nrac{1}{i}=\mathcal{O}(\ln(n)).$$

The second term can therefore be bounded as

$$\sum_{j=0}^{n-1} \frac{1}{z_j} = \mathcal{O}\left(\sum_{j=0}^{n-1} \frac{n}{n-j}\right) = \mathcal{O}(n\ln(n))$$

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Completing the proof

Theorem

If $\lambda > c \ln(n)$ for a sufficiently large constant c > 0, and $\frac{\lambda}{\mu} > 2e^{\chi}(1 + \delta)$ for any constant $\delta > 0$, then the expected runtime of (μ, λ) GA on ONEMAX is

$$igg(rac{8}{\delta^2}igg)\left(\lambda\sum_{j=0}^{n-1}\ln\left(rac{6\delta\lambda}{4+z_j\delta\lambda}
ight)+\sum_{j=0}^{n-1}rac{1}{z_j}
ight) \ =\mathcal{O}(n\lambda)+\mathcal{O}(n\ln n)=\mathcal{O}(n\lambda).$$

3. Noisy fitness (Prügel-Bennet, Rowe, Shapiro, 2015)

Sufficient with mutation rate $\delta/(3n)$ and

$$\Pr\left(x ext{ choosen } \mid f(x) > f(y)
ight) \geq rac{1}{2} + \delta \quad ext{with } 1/\delta \in ext{poly}(n)$$

Dang and Lehre [2015] and Dang and Lehre [2016b]

Lower Bounds

Problem

Consider a sequence of populations P_1, \ldots over a search space \mathcal{X} , and a target region $A \subset \mathcal{X}$ (e.g., the set of optimal solutions), let

$$T_A := \min\{ \lambda t \mid P_t \cap A \neq \emptyset \}$$

We would like to prove statements on the form

$$\Pr\left(T_A \le t(n)\right) \le e^{-\Omega(n)}.\tag{1}$$

- i.e., with overwhelmingly high probability, the target region A has not been found in t(n) evaluations
- lower bounds often harder to prove than upper bounds
- will present an easy to use method that is applicable in many situations

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Reproductive rate¹⁰ **Definition** For any population $P = (x_1, \ldots, x_\lambda)$ let $p_{sel}(x_i)$ be the probability that individual x_i is selected from the population PThe reproductive rate of individual x_i is $\lambda \cdot p_{sel}(x_i)$. The reproductive rate of a selection mechanism

is bounded from above by $lpha_0$ if

$$orall P \in \mathcal{X}^{\lambda}, \hspace{0.1 in} orall x \in P \hspace{0.1 in} \lambda \cdot p_{\mathsf{sel}}(x) \hspace{0.1 in} \leq \hspace{0.1 in} lpha_{0}$$

(i.e., no individual gets more than α_0 offspring in expectation)

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 $^{^{10}}$ The reproductive rate of an individual as defined here corresponds to the notion of "fitness" as used in the field of population genetics, i.e., the expected number of offspring.

Negative Drift Theorem for Populations (informal)

If individuals closer than b of target has reproductive rate $\alpha_0 < e^{\chi}$, then it takes exponential time $e^{c(b-a)}$ to reach within a of target.

The worst individuals have low reproductive rate

Lemma

Consider any selection mechanism which for $x,y\in P$ satisfies

- (a) If f(x) > f(y), then $p_{sel}(x) \ge p_{sel}(y)$. (selection probabilities are monotone wrt fitness)
- (b) If f(x) = f(y), then $p_{sel}(x) = p_{sel}(y)$. (ties are drawn randomly)

If $f(x) = \min_{y \in P} f(y)$, then $p_{sel}(x) \le 1/\lambda$. (individuals with lowest fitness have reproductive rate ≤ 1)

Proof.

▶ By (a) and (b),
$$p_{sel}(x) = \min_{y \in P} p_{sel}(y)$$
.

•
$$1 = \sum_{x \in P} p_{\mathsf{sel}}(x) \geq \lambda \cdot \min_{y \in P} p_{\mathsf{sel}}(y) = \lambda \cdot p_{\mathsf{sel}}(x)$$

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Example 1: Needle in the haystack

Definition

$$ext{NEEDLE}(x) = egin{cases} 1 & ext{if } x = 1^n \ 0 & ext{otherwise.} \end{cases}$$

Theorem

The optimisation time of the non-elitist EA with any selection mechanism satisfying the properties above¹¹ on NEEDLE is at least e^{cn} with probability $1 - e^{-\Omega(n)}$ for some constant c > 0.

¹¹From black-box complexity theory, it is known that NEEDLE is hard for all search heuristics (Droste et al 2006).

Example 1: Needle in the haystack (proof¹²**)**

- Apply negative drift theorem with a(n) := 1.
- ▶ By previous lemma, can choose $\alpha_0 = 1$ for any b(n), hence $\psi = \ln(\alpha)/\chi + \delta = \delta < 1$ for all χ and $\delta < 1$.
- \blacktriangleright Choosing the parameters $\delta:=1/10$ and b(n):=n/6 give

$$\min\left\{rac{n}{5},rac{n}{2}\left(1-\sqrt{\psi(2-\psi)}
ight)
ight\}=rac{n}{5}>b(n).$$

• It follows that $\Pr\left(T \leq e^{c(b(n)-a(n))}\right) \leq e^{-\Omega(n)}.$

 12 For simplicity, we assume that $\chi \leq 6,$ thus $b(n)=n/6 \leq n/\chi$ holds.

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When the best individuals have low reproductive rate

Remark

 The negative drift conditions hold trivially if α₀ < e^χ holds for all individuals.

Example (Insufficient selective pressure)

Selection mechanism	Parameter settings
Linear ranking selection k -tournament selection (μ, λ) -selection Any in cellular EAs	$egin{aligned} \eta < e^{\chi} \ k < e^{\chi} \ \lambda < \mu e^{\chi} \ \Delta(G) < e^{\chi} \end{aligned}$

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Other Example Applications

Expected runtime of EA with bit-wise mutation rate χ/n

Selection Mechanism	High Selective Pressure	Low Selective Pressure
Fitness Proportionate Linear Ranking	$egin{aligned} & u > f_{ ext{max}} \ln(2e^{\chi}) \ & \eta > e^{\chi} \ & u > \chi \end{aligned}$	$ u < \chi/\ln 2$ and $\lambda \geq n^3$ $\eta < e^{\chi}$
(μ, λ) Cellular EAs	$k>e^{\lambda} \lambda>\mu e^{\chi}$	$egin{array}{ll} \kappa < e^{\chi} \ \lambda < \mu e^{\chi} \ \Delta(G) < e^{\chi} \end{array}$
Onemax	$O(n\lambda)$	$e^{\Omega(n)}$
LeadingOnes	$O(n\lambda \ln(\lambda) + n^2)$	$e^{\Omega(n)}$
Linear Functions	$O(n\lambda \ln(\lambda) + n^2)$	$e^{\Omega(n)}$
r-Unimodal	$O(r\lambda \ln(\lambda) + nr)$	$e^{\Omega(n)}$
JUMP r	$O(n\lambda + (n/\chi)^r)$	$e^{\Omega(n)}$

Self-adaptive Evolutionary Algorithms¹³

¹³Dang and Lehre [2016c]

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• search space is $\{\chi_1, \chi_2\} \times \{0, 1\}^n$, where $\chi_1, \chi_2 \in \Theta(n)$ are two mutation rates

₽4 \mathcal{D}

parent selection via binary tournament selection

X2 0 1 0 0

X1 0 1 1 0

 \triangleright mutation rate switched with probability p, and obtain offspring by mutation with new mutation rate

Intuition

- Low mutation rate (or elitist selection mechanism) \implies exponential time to escape local optimum
- Mutation rate above error threshold \implies exponential runtime via negative population drift (L., PPSN 2010)

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Results imply benefit of non-elitism and self-adaptation¹⁴

Mutation control Runtime Proof idea $e^{\Omega(n)}$ Fixed rate χ_{low} Most individuals remain on the peak. Too low selective pressure among sub-optimal individuals. (Negative drift in populations). $e^{\Omega(n)}$ Most individuals fall off the peak, but mutation rate Fixed rate χ_{high} is too high wrt selective pressure to reach opt. (Negative drift in populations). $e^{\Omega(n)}$ Uniform mixing Most individuals fall off the peak, but the effective mutation rate is too high wrt selective pressure. (Negative drift in populations). $\mathcal{O}(n^2)$ Most individuals fall off the peak. Peak individuals do not Self-adaptation dominate. A sub-population surviving off the peak switches to low mutation rate. (Level-based analysis). $e^{\Omega(n)}$ $(\mu + \lambda) EA$ Elitism prevents escape from peak. Dang and Lehre [2016c]

Interactive Simulation of Results

 14 The results assume appropriate choices of the mutation rates χ_1 and χ_2 , the strategy parameter p, and the problem parameter m.

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Fitness proportional selection + crossover Oliveto and Witt [2014, 2015]

Definition (Simple Genetic Algorithm (SGA) (Goldberg 1989))

for t = 0, 1, 2, ... until termination condition do for i = 1 to λ do Select two parents x and y from P_t proportionally to fitness Obtain z by applying uniform crossover to x and y with p = 1/2Flip each position in z independently with p = 1/n. Let the *i*-th offspring be $P_{t+1}(i) := x$. (i.e., create offspring by crossover followed by mutation)

Application to OneMax Expected Behaviour Backward drift due to mutation close to the optimum no positive drift due to crossover selection too weak to keep positive fluctuations Difficulties When Introducing Crossover: Variance of offspring distribution # flipping bits due to mutation Poisson-distributed → variance O(1) # of one-bits created by crossover binomially distributed according to Hamming distance of parents and 1/2 → deviation Ω(√n) possible

Negative Drift Theorem With Scaling

Let $X_t, t \geq 0$, random variable describing a stochastic process over finite state space $S \subseteq \mathbb{R};$

If there \exists interval [a, b] and, possibly depending on $\ell := b - a$, bound $\epsilon(\ell) > 0$ and scaling factor $r(\ell)$ st.

- (C1) $E(X_{t+1} X_t \mid X_0, \ldots, X_t \land \boldsymbol{a} < X_t < \boldsymbol{b}) \geq \epsilon$,
- (C2) $\operatorname{Prob}(|X_{t+1} X_t| \geq jr \mid X_0, \ldots, X_t \land a < X_t) \leq e^{-j}$ for $j \in \mathbb{N}_0$,

(C3) $1 \leq r \leq \min\{\epsilon^2 \ell, \sqrt{\epsilon \ell / (132 \log(\epsilon \ell))}\}.$

then

$$\Pr\left(T \leq e^{\epsilon \ell/(132r^2)}\right) = O(e^{-\epsilon \ell/(132r^2)})$$

Potential Function

For drift theorem, capture whole population in one value: For $X = \{x_1, \ldots, x_\mu\}$ let $g(X) := \sum_{i=1}^{\mu} e^{\kappa_{\text{ONEMAX}}(x_i)}$.

Problem: maybe
$$r(\ell) = \Omega(\sqrt{\ell})$$

Solution

Find bits that are "converged" within population, i.e., either ones or zeros only. Crossover is irrelevant for these.

Diversity

Assume uniform selection (and no mutation). Then:

- The probability crossover produces an individual with 1 in the fixed position is (X_t = k):
- $\blacktriangleright \frac{k}{\mu} \cdot \frac{k}{\mu} + 2 \cdot \frac{1}{2} \cdot \frac{k(\mu-k)}{\mu^2} = \frac{k}{\mu}$
- $\blacktriangleright \{X_t\} \approx B(\mu, k/\mu) \rightsquigarrow E(X_t \mid X_{t-1} = k) = k \text{ (martingale)}$
- But random fluctuations \sim absorbing state 0 or μ due to the variance

Compare fitness-prop. and uniform selection:

- Basically no difference for small population bandwidth (difference of best and worst ONEMAX-value in pop.)
- $E(X_t \mid X_{t-1} = k) = k \pm 1/(7\mu)$

Diversity

 X_t : # individuals with 1 in some fixed position at time t

Assume uniform selection (and no mutation). Then:

- The probability crossover produces an individual with 1 in the fixed position is (X_t = k):
- $\blacktriangleright \frac{k}{\mu} \cdot \frac{k}{\mu} + 2 \cdot \frac{1}{2} \cdot \frac{k(\mu-k)}{\mu^2} = \frac{k}{\mu}$
- $\blacktriangleright \ \{X_t\} \approx B(\mu,k/\mu) \rightsquigarrow E(X_t \mid X_{t-1} = k) = k \ (\mathsf{martingale})$
- But random fluctuations \sim absorbing state 0 or μ due to the variance $(E(T_{0\lor\mu}) = O(\mu \log \mu) \text{ [drift analysis]}).$
- Progress by crossover is at most n^{1/2+\epsilon} w.o.p. (Chernoff Bounds when ones are n/2).
- If $\mu \leq n^{1/2-\epsilon}$ a bit has converged to 0 before optimum is found w.o.p.

Result

Let $\mu \leq n^{1/8-\epsilon}$ for an arbitrarily small constant $\epsilon > 0$. Then with probability $1 - 2^{-\Omega(n^{\epsilon/9})}$, the SGA on ONEMAX does not create individuals with more than $(1+c)\frac{n}{2}$ or less than $(1-c)\frac{n}{2}$ one-bits, for arbitrarily small constant c > 0, within the first $2^{n^{\epsilon/10}}$ generations. In particular, it does not reach the optimum then.

Overall Proof Structure

Not a loop, but in each step only exponentially small failure prob.

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Steady-state GA

Algorithm 1: $(\mu+1)$ GA

1 F	$P_1 \leftarrow \mu$ individuals, uniformly at random from $\{0,1\}^n$;
2 t	$\leftarrow \mu;$
зr	epeat
4	Select $x, y \in P_t$ uniformly at random with replacement ;
5	$z \leftarrow uniform \ crossover(x, y);$
6	$z \leftarrow mutate(z);$
7	$P_{t+1} \leftarrow P_t \cup \{z\};$
8	Remove the element with lowest fitness from P_{t+1} , breaking ties at random;
9	$t \leftarrow t + 1;$
10 U	intil optimum is found;

Uniform crossover:

Picks the value for each bit position from one parent or the other uniformly at random (i.e., from each parent with probability 1/2).

Algorithm 3 (1+1) EA

Sample one search points $x \in \{0, 1\}^n$ uniformly at random.

for $t \leftarrow 1, 2, \dots$ do

Create y by flipping each bit of x independently with probability 1/n. If $f(y) \ge f(x)$ then x := y.

end for

Artificial Fitness Levels [D]W 2002]Image: Image: Ima

By showing that with high probability the algorithm does not skip too many levels then it can be proven that E(T) is also at least e n ln n + O(n); [Sudholt, IEEE TEVC 2013]

(µ+1)-EA for OneMax via Artificial Fitness Levels (2)

Let:

- T_o be the expected time for a fraction $\chi(i)$ of the population to be in level A_i
- s_i be the probability to leave level A_i for A_j with j > i given $\chi(i)$ in level A_i
- Then:

2 $t \leftarrow \mu$;

4

5

6

7

$$E(T) \le \sum_{i=1}^{m-1} \left(\frac{1}{s_i} + T_o\right)$$

x:010101	f(x) = 3
y:011100	f(y) = 3
z:01101	f(z) = 4 (p=1/4)

(µ+1)-GA for OneMax via Artificial Fitness Levels

Proof Idea

I) We divide the search space in canonical fitness levels $L_i = \{x \in \{0,1\}^n | \text{ONEMAX}(x) = i\}$;

2) Each level *i* is represented by a Markov Chain (and all individuals are at least in *Li*);

 S_1 : no diversity; S_2 : at least one diverse individual; S_3 : at least one individual in Li+1 or higher.

3) The runtime is upper bounded by the time it takes to discover the next level E[Li] + the time it takes for the entire population to take over the level ($E[T_{takeover}] = O(\mu \log \mu)$).

$$E[T] \leq \sum_{i=0}^{n-1} \left(E[L_i] + E[T_{takeover}] \right)$$

But the exact transition probabilities are tedious to calculate!

The Runtime of the Steady-state GA [Corus, Oliveto - GECCO 2019]

▶ **Theorem 1.** The expected runtime for the $(\mu+1)$ GA with $\mu = o(\sqrt{\log n})$ using an unbiased mutation operator mutate(x) that flips i bits with probability p_i with $p_0 \in \Omega(1)$ and $p_1 \in \Omega(1)$ to optimise the ONEMAX function is:

- 1. $E[T] \leq (1+o(1))n \ln n \frac{1}{p_1+p_2 \frac{2(1-\xi_2)\mu}{(d+1)}}$ if the quality of each offspring is evaluated,
- 2. $E[T] \leq (1+o(1))n \ln n \frac{(1-p_0)}{p_1+p_2}$ if the quality of offspring identical to their parents is not evaluated for their quality is known;

I) The statements are very general as they provide upper bounds on the expected runtime for each value of the population size (up to $\mu = o(\sqrt{\log n})$) and any unbiased mutation operator.

2) The preciseness of the analysis allows to appreciate the importance of the population for optimising unimodal functions (the upper bounds **decrease** with the population size)!

3) For each population size we can **derive the mutation rate** that provides the best upper bound on the expected runtime!

Best Upper Bounds ($p_2 = 1-\epsilon$, $p_1 = \epsilon/2$ $p_0 = \epsilon/2$)

Figure 1 The leading constant from the second statement of Theorem 1 versus the population size. The best leading constant achievable by any unary unbiased algorithm is 1.

Corollary: Standard Bit Mutation

▶ Corollary 2. Let ξ_2 be as defined in Theorem 1. The expected runtime for the $(\mu+1)$ GA with $\mu = o(\sqrt{\log n})$ using standard bit-mutation with mutation rate c/n, $c = \Theta(1)$ to optimise the ONEMAX function is:

- **1.** $E[T] \leq (1+o(1))n \ln n \frac{e^{c}}{c+\frac{c^{2}\mu}{c+c^{2}\mu}}$ if the quality of each offspring is evaluated,
- 2. $E[T] \leq (1+o(1))n \ln n \frac{(1-e^{-c})e^{c}}{c+\frac{c^{2}\mu}{(\mu+1)}(1-\xi_{2})}$ if the quality of offspring identical to their parents is not evaluated for their quality is known;

Standard bit mutation: c/n with best c for each μ

Figure 2 The leading constant from the first statement of Corollary 2 versus the population size. The best mutation-only variant has a the leading constant of $e \approx 2.71$.

If the offspring has the same genotype as one of its parents then it is not necessary to evaluate it again!

An open problem for a long time (1994)

When Will a Genetic Algorithm Outperform Hill Climbing?

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Abstract

We analyze a simple hill-climbing algorithm (RMHC) that was previously shown to outperform a genetic algorithm (GA) on a simple "Royal Road" function. We then analyze an "idealized" genetic algorithm (IGA) that is significantly faster than RMHC and that gives a lower bound for GA speed. We identify the features of the IGA that give is to this speedup, and discuss how these features can be incorporated into a real GA.

In J. D. Cowan, G. Tesauro, and J. Alspector (editors), Advances in Neural Information Processing Systems 6. San Mateo, CA: Morgan Kaufmann, 1994.

Summary

- Runtime analysis of evolutionary algorithms
 - mathematically rigorous statements about EA performance
 - most previous results on simple EAs, such as (1+1) EA
 - special techniques developed for population-based EAs
- Drift Analysis
- Level-based method [Corus et al., 2014]
 - EAs analysed from the perspective of EDAs
 - Upper bounds on expected optimisation time
 - Example applications include crossover, noise, and self-adaptation
- Negative drift theorem [Lehre, 2011a]
 - reproductive rate vs selective pressure
 - exponential lower bounds
 - mutation-selection balance
- Diversity + Bandwidth analysis for fitness proportional selection [Oliveto and Witt, 2014, 2015]
 - analysis of crossover
 - Iow selection pressure
 - exponential lower bounds
- Speed-up via crossover for steady state GAs to hillclimb ONEMAX and escape local optima [Dang, Friedrich, Kötzing, Krejca, Lehre, Oliveto, Sudholt, and Sutton, 2017a, Corus and Oliveto, 2017]

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