Supplement Material

Unit-aware Multi-objective Genetic Programming for the Prediction of the Stokes Flow around a

Sphere

Heiner Zille Sanaz Mostaghim Otto von Guericke University Magdeburg {heiner.zille|sanaz.mostaghim}@ovgu.de

ACM Reference Format:

Heiner Zille, Sanaz Mostaghim, Fabien Evrard, and Berend van Wachem. 2021. Supplement Material: Unit-aware Multi-objective Genetic Programming for the Prediction of the Stokes Flow around a Sphere. In 2021 Genetic and Evolutionary Computation Conference Companion (GECCO '21 Companion), July 10–14, 2021, Lille, France. ACM, New York, NY, USA, 1 page. https://doi.org/10.1145/3449726.3459408

A TEST INSTANCES

Table 1 shows the six test instances with the corresponding input features and predicted values. In more detail, the instances are composed as follows.

(1) **Instance 1:** Predict $|\vec{u}|$ from u_x and u_y .

$$\vec{u}| = \sqrt{u_x^2 + u_y^2} \tag{1}$$

(2) **Instance 2:** Predict $|\vec{u}|$ from u_r , u_{θ} and θ .

$$|\vec{u}| = \sqrt{(u_r \cdot \cos(\theta) - u_\theta \cdot \sin(\theta))^2 + (u_r \cdot \sin(\theta) + u_\theta \cdot \cos(\theta))^2}$$
(2)

However, this equation reduces to

$$\vec{u}| = \sqrt{u_r^2 + u_\theta^2} \tag{3}$$

(3) **Instance 3:** Predict u_x from u_r , u_{θ} and θ .

$$u_x = u_r \cdot \cos(\theta) - u_\theta \cdot \sin(\theta) \tag{4}$$

(4) **Instance 4:** Predict u_u from u_r , u_{θ} and θ .

$$u_{\eta} = u_r \cdot \sin(\theta) + u_{\theta} \cdot \cos(\theta) \tag{5}$$

(5) **Instance 5:** Predict u_r from u_{∞} , θ , *a* and *r*.

$$u_r = u_{\infty} \cdot \cos(\theta) \cdot \left(1 + \frac{a^3}{2 \cdot r^3} - \frac{3 \cdot a}{2 \cdot r}\right) \tag{6}$$

ACM ISBN 978-1-4503-8351-6/21/07.

https://doi.org/10.1145/3449726.3459408

Fabien Evrard Berend van Wachem Otto von Guericke University Magdeburg {fabien.evrard|berend.vanwachem}@ovgu.de

(6) **Instance 6:** Predict u_{θ} from u_{∞} , θ , *a* and *r*.

$$u_{\theta} = -u_{\infty} \cdot \sin(\theta) \cdot \left(1 - \frac{a^3}{4 \cdot r^3} - \frac{3 \cdot a}{4 \cdot r}\right) \tag{7}$$

B PARAMETER AND EXPERIMENT SETTINGS

For running the GP algorithm, we use the following experimental and parameter settings.

- (1) Number of Iterations of the main loop: 20.
- (2) Each Iteration consists of 15 generations of a normal GP (Phase
- 1), followed by 20 generations of a Mutation-only GP (Phase 2)
- (3) The reproduction scheme follows the $(\mu + \lambda)$ -approach
- (4) In phase 1, the crossover-probability is 0.5 and the mutation-probability is 0.5.

(5) In phase 2, the crossover-probability is 0.0 and the mutation-probability is 1.0.

(6) Initial population is created using a half-and-half scheme of growing iterative trees and creating full trees of a certain depth. The maximum depth of the initial solution is 4.

(7) During the experiments, created solutions are restricted to a maximum length of 50 and a maximum height of 17.

(8) The crossovers in Phase 1 are chosen uniformly at random among one-point crossover and a leaf-based one-point crossover with a probability to select leaves (terminals) for the crossover of 0.9.

(9) The mutations in Phase 1 are chosen uniformly at random from uniform mutation, node-replacement mutation, insert mutation and shrink mutation.

(10) The mutations in Phase 2 are chosen among node-replacement with probability of 2/3 and shrink mutation with a probability of 1/3.

(11) The population size is 2000.

(12) A numerically perfect solution is considered if the max absolute fitness (f_i) is smaller than 1e-15.

Instance No.	Predicted Value	Input Features
1	$ \vec{u} $	u_x, u_y
2	$ \vec{u} $	u_r, u_{θ}, θ
3	u_x	u_r, u_{θ}, θ
4	u _y	u_r, u_{θ}, θ
5	u _r	u_{∞}, θ, a, r
6	$u_{ heta}$	u_{∞}, θ, a, r

Table 1: Configuration of 6 created Test Instances.

Permission to make digital or hard copies of part or all of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. Copyrights for third-party components of this work must be honored. For all other uses, contact the owner/author(s).

GECCO '21 Companion, July 10-14, 2021, Lille, France

^{© 2021} Copyright held by the owner/author(s).