

# On stability of special solutions for quasi-linear equations of traffic flow

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# Main parameters

$\rho(x, t)$  — flow density,

$v(x, t)$  — flow velocity,

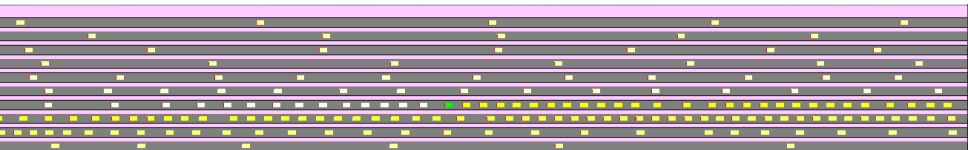
$q(x, t)$  — flow rate.



$x$

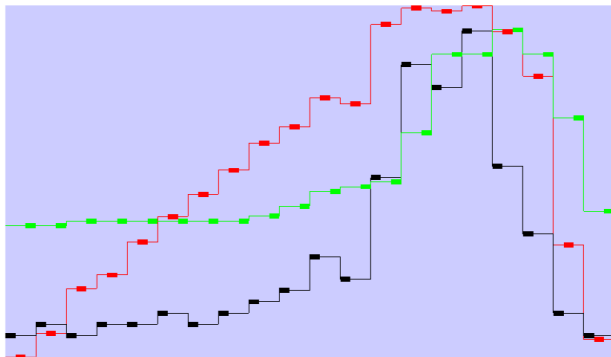
Moscow, MRR, north.

# Interface of the program "Cars"

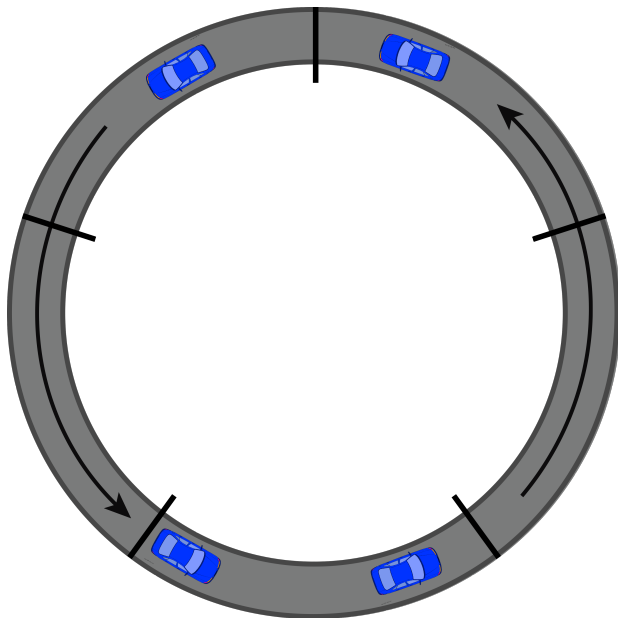


Прошло времени (мс) 1516027  
Время машины (сек) 15.9 мин. / 953.9 сек.  
Средняя скорость 5,735 м/с / 20,645 км/ч  
Количество машин: 180  
Начальная скорости: 0  
Длина кольца: 5000  
Количество отрезков: 20

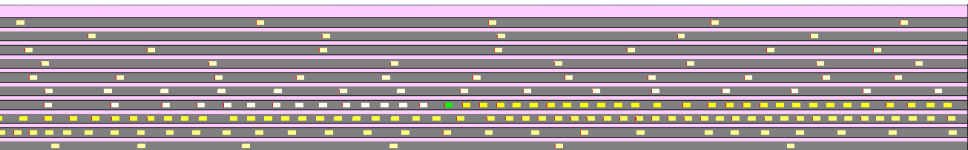
В зависимости от X  Зависимость между Rho, V и Q  
 Скорость  Поток  Плотность



# Ring road

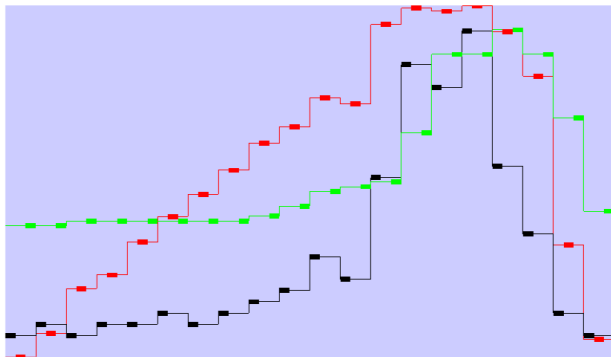


# Interface of the program "Cars"



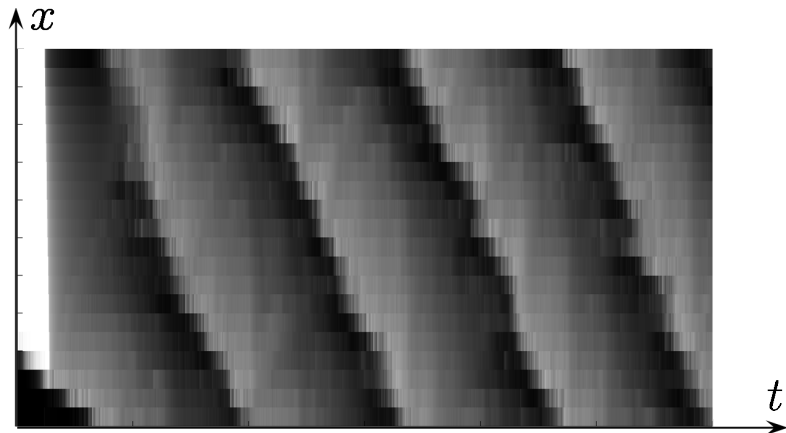
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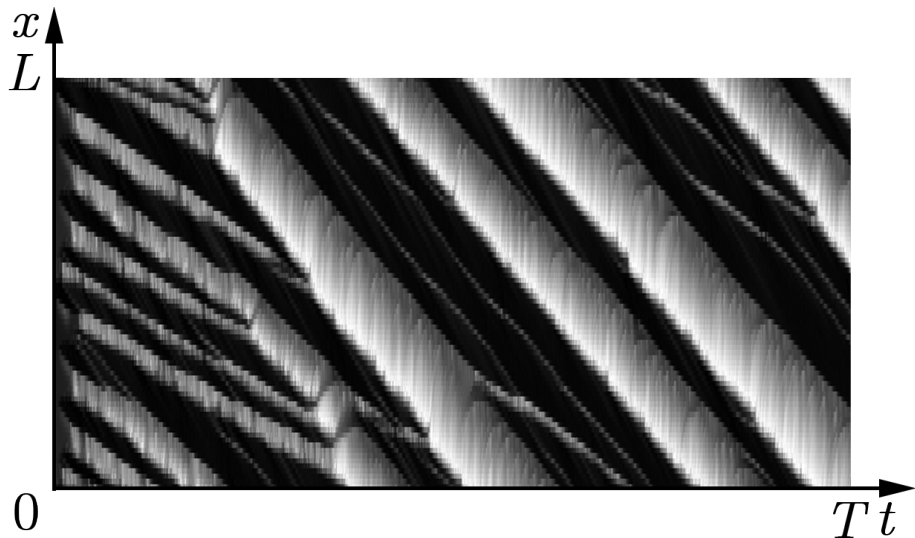


# Jam movement on ring road

( $N = 140$  cars,  $L = 5$  km,  $T = 3$  hours)

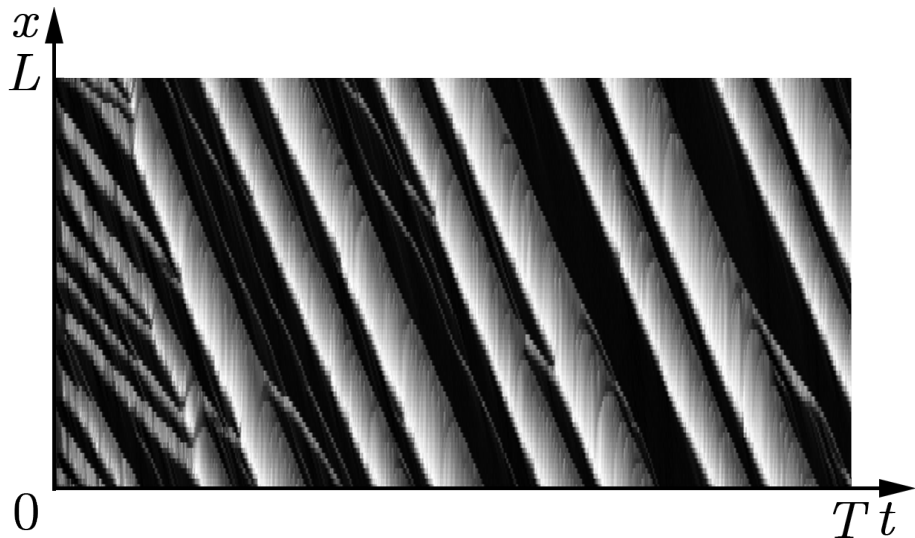


# Tendency to stable condition



$$L = 20 \text{ km}, \quad T = 6 \text{ h.}$$

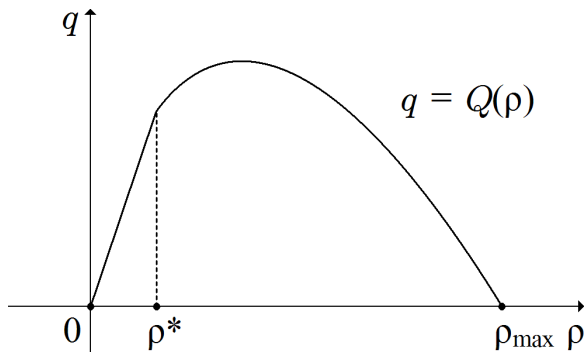
# Tendency to stable condition



$$L = 20 \text{ km}, \quad T = 12 \text{ h.}$$



# Fundamental diagram



$q = Q(\rho)$ ,  $Q$  is concave function,

$$Q(\rho) > 0, \quad 0 < \rho < \rho_{\max},$$

$$Q(0) = 0, \quad Q(\rho_{\max}) = 0.$$

# Quasi-linear differential equation

Main equation of road traffic:

$$\frac{\partial \rho}{\partial t} + \frac{\partial Q(\rho)}{\partial x} = 0, \quad \rho = \rho(x, t).$$

Integral identity:

$$\frac{d}{dt} \int_{\alpha}^{\beta} \rho(x, t) dx = Q(\rho(\alpha, t)) - Q(\rho(\beta, t)),$$

for a.e.  $\alpha, \beta \in \mathbb{R}$ ,  $t \geq 0$ .

## Cauchy problem

$$\begin{cases} \frac{\partial \rho}{\partial t} + \frac{\partial Q(\rho)}{\partial x} = 0, & x \in \mathbb{R}, \quad t > 0, \\ \rho(x, 0) = \mu(x), \end{cases}$$

with initial function

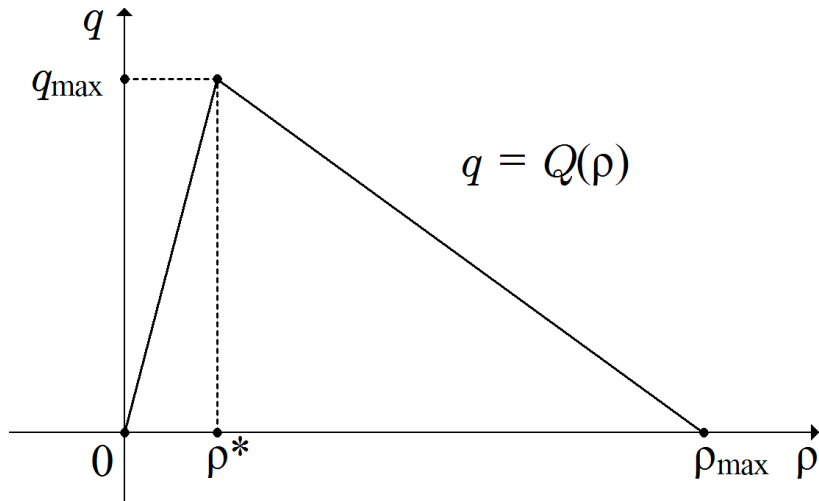
$$0 \leq \mu(x) \leq \rho_{\max}, \quad x \in \mathbb{R}.$$

Technical solution of this problem is

$$\rho = \mu(x - k(\rho)t),$$

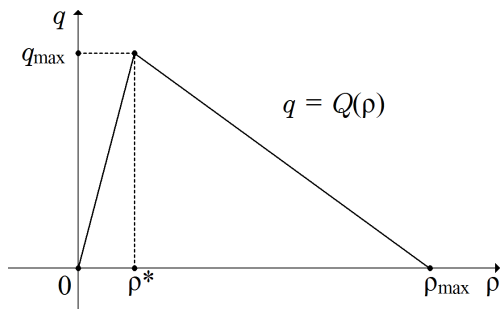
where  $k = k(\rho) = Q'(\rho)$  is a slope of the characteristic.

# Nagel–Schreckenberg diagram



K. Nagel, M. Schreckenberg. *A cellular automaton model for freeway traffic*.  
Journal de Physique I France. 1992. Vol. 2. No 12. P. 2221–2229.

# Analytical representation



$$Q(\rho) = \begin{cases} k_1 \rho, & 0 \leq \rho \leq \rho^*, \\ k_2 (\rho_{\max} - \rho), & \rho^* \leq \rho \leq \rho_{\max}. \end{cases}$$

$$k_1 = \frac{q_{\max}}{\rho^*}, \quad k_2 = \frac{q_{\max}}{\rho_{\max} - \rho^*}.$$

# Typical solutions

- 1 If  $\mu(x) \leq \rho^*$  on  $\mathbb{R}$ , then

$$\rho(x, t) = \mu(x - k_1 t)$$

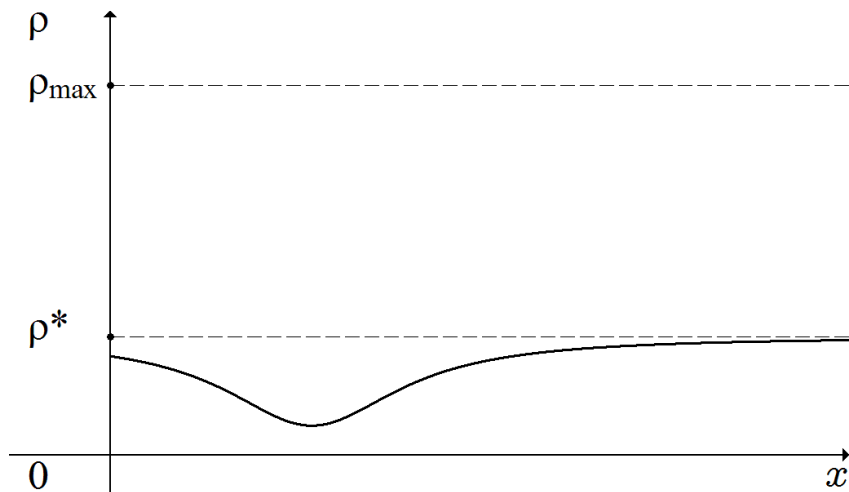
(forward wave).

- 2 If  $\mu(x) \geq \rho^*$  on  $\mathbb{R}$ , then

$$\rho(x, t) = \mu(x + k_2 t)$$

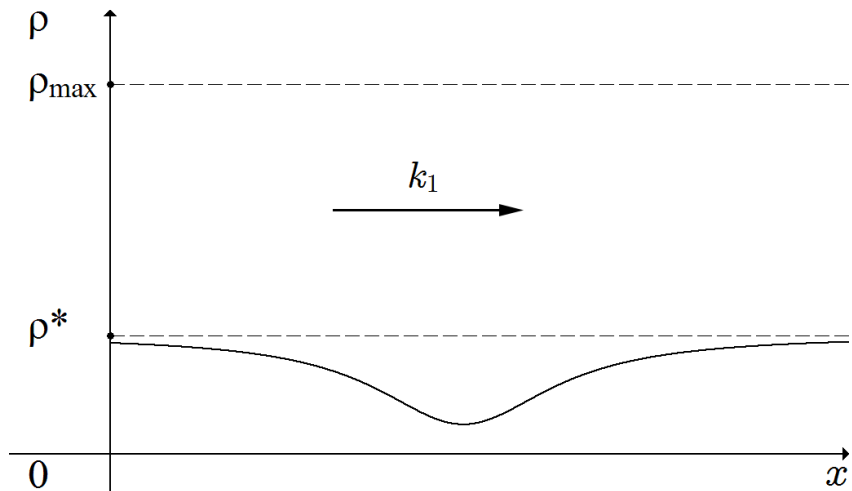
(backward wave).

# Forward wave



for  $t = 0$

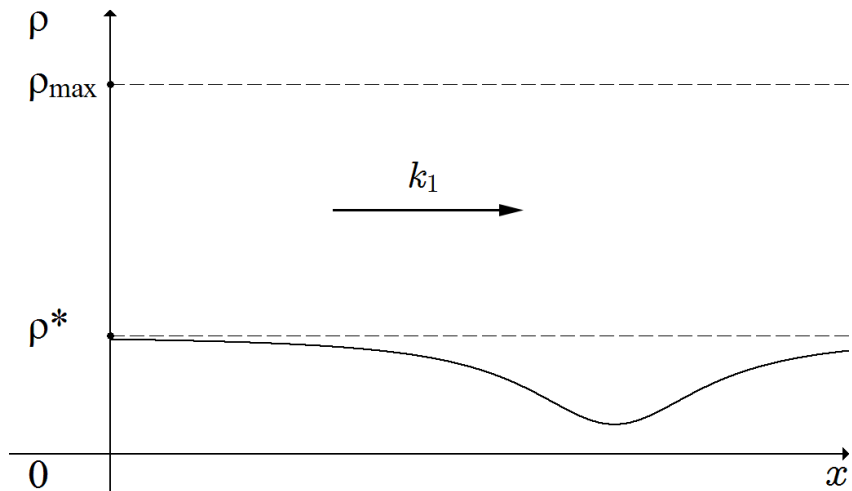
# Forward wave



for  $t = 0.3$

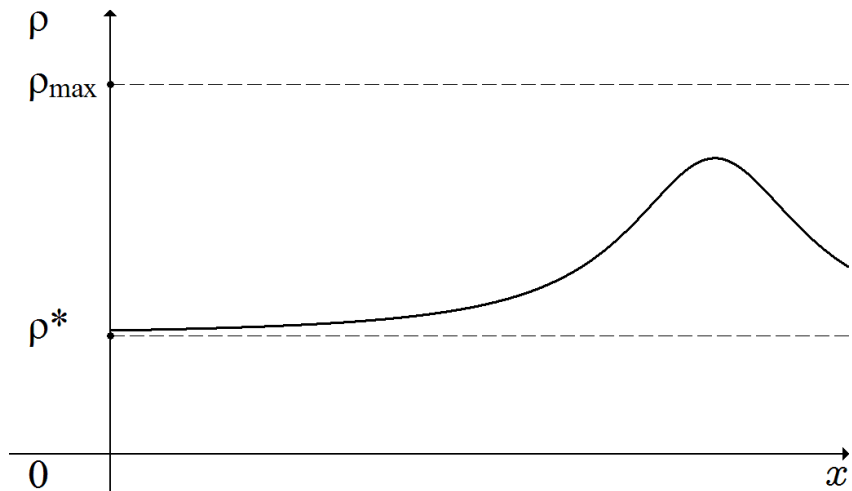


# Forward wave



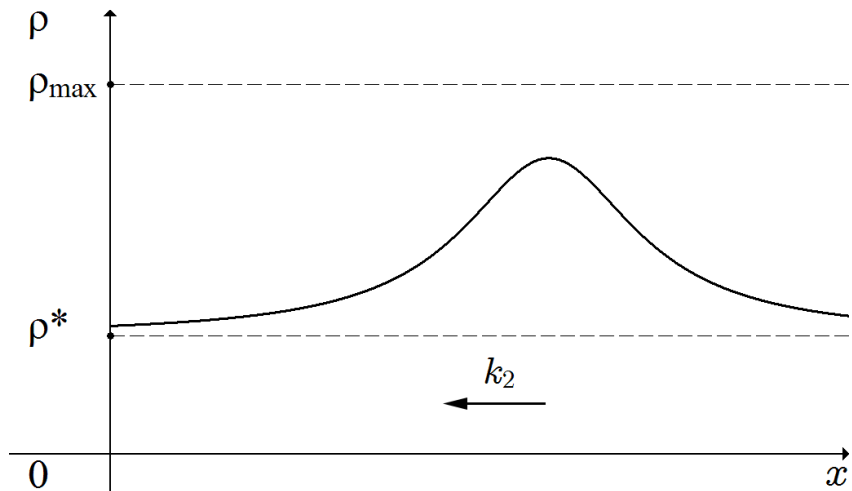
for  $t = 0.6$

# Backward wave



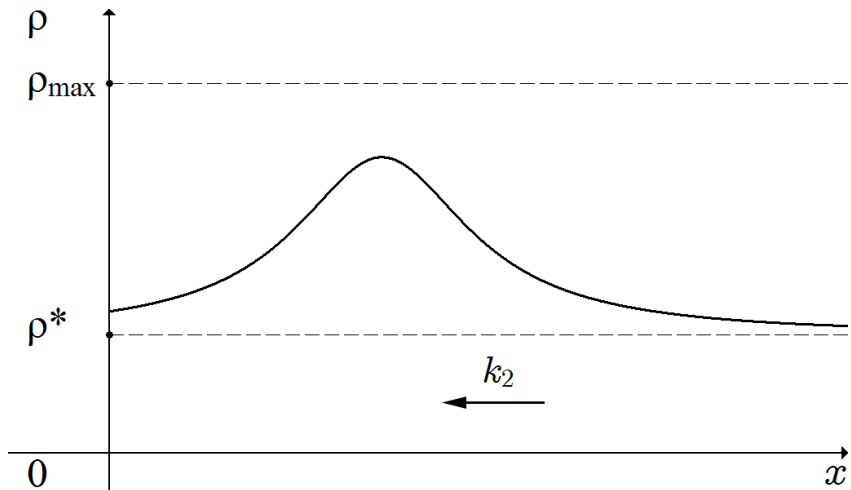
for  $t = 0$

# Backward wave



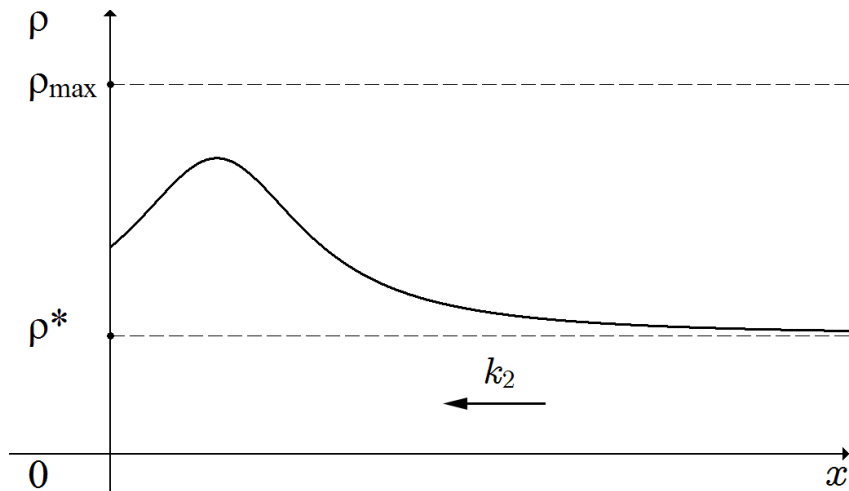
for  $t = 0.7$

# Backward wave



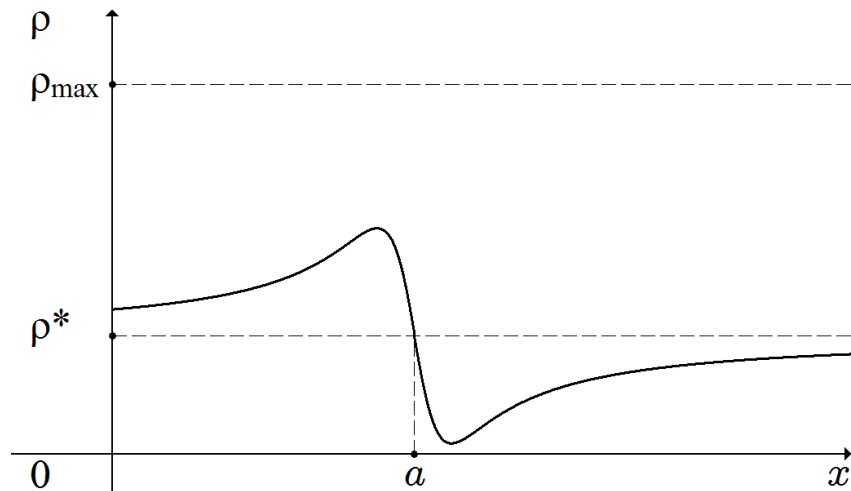
for  $t = 1.4$

# Backward wave



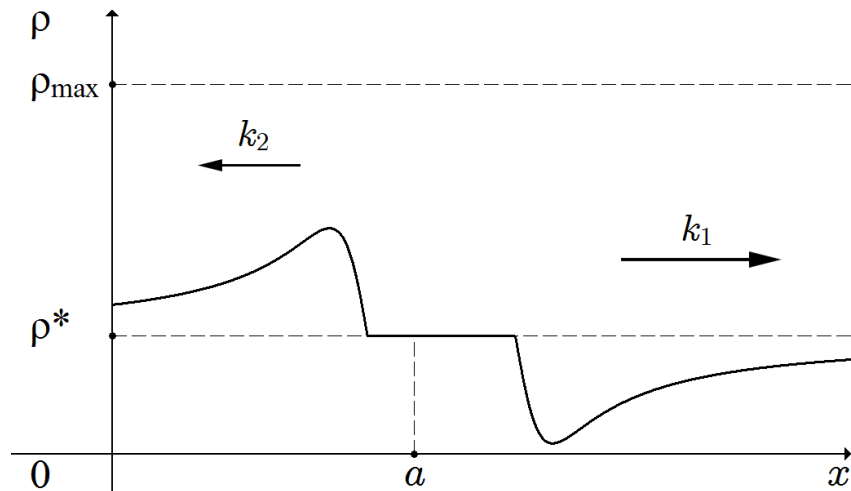
for  $t = 2.1$

# Combined solution: depression wave



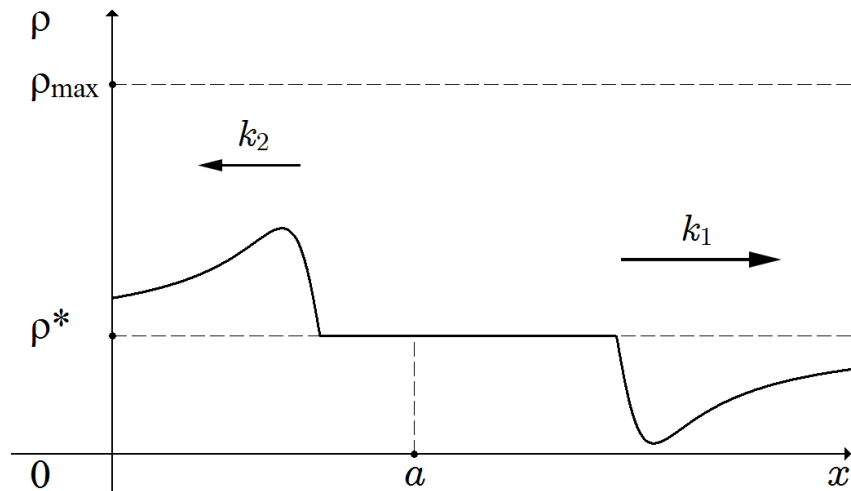
for  $t = 0$

# Combined solution: depression wave



for  $t = 0.2$

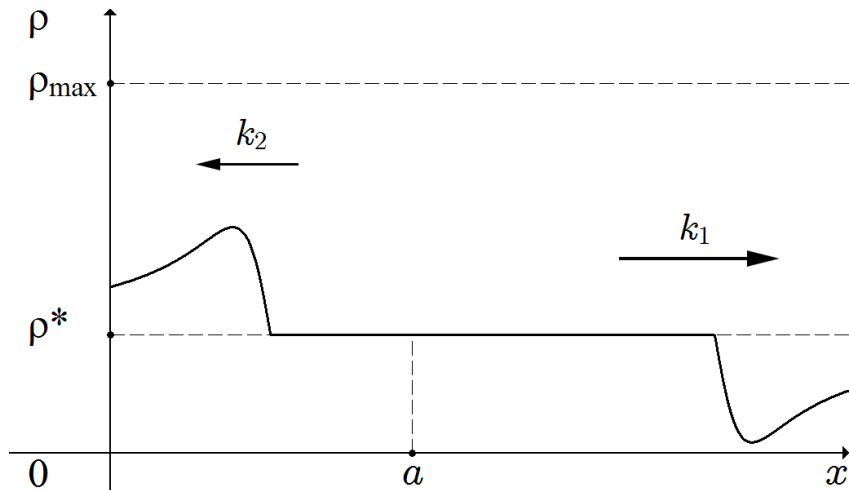
# Combined solution: depression wave



for  $t = 0.4$

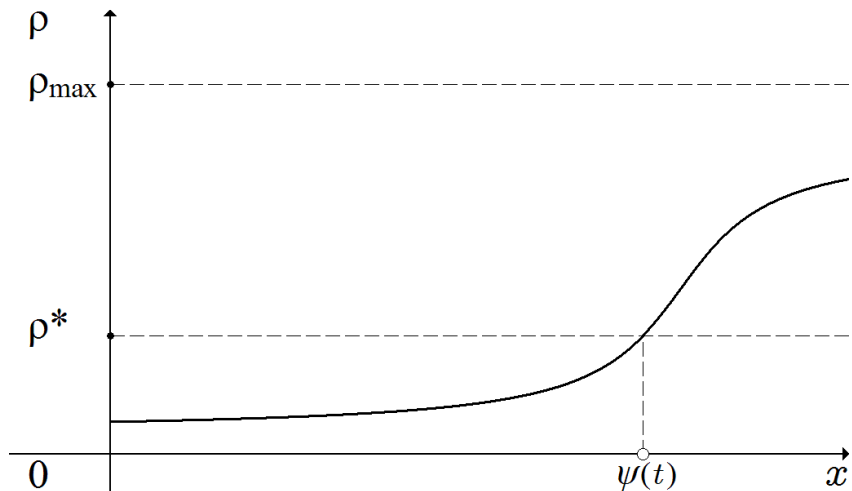


# Combined solution: depression wave



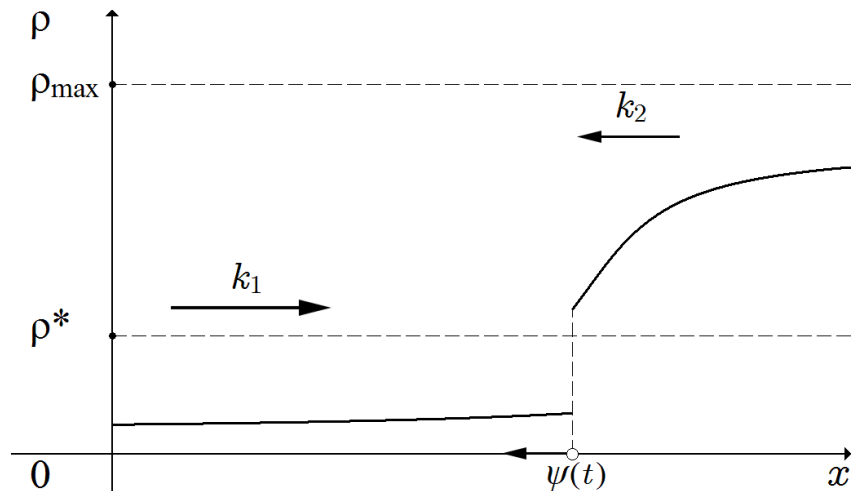
for  $t = 0.6$

# Combined solution: shock wave



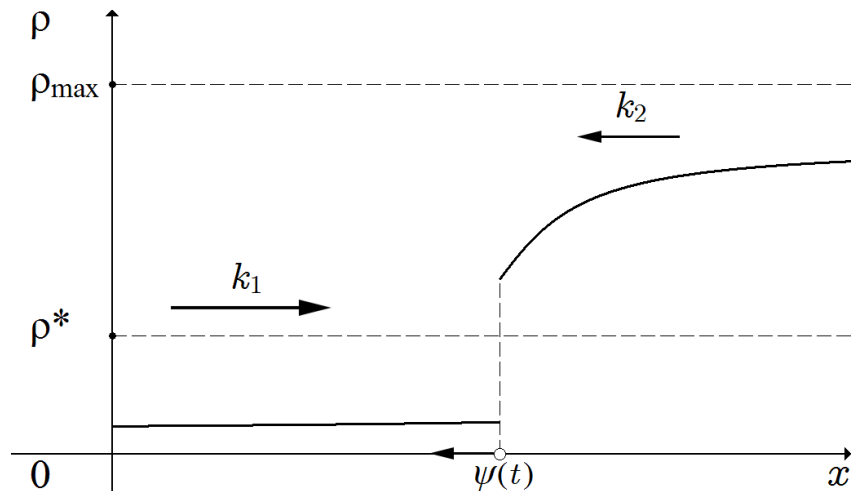
for  $t = 0$

# Combined solution: shock wave



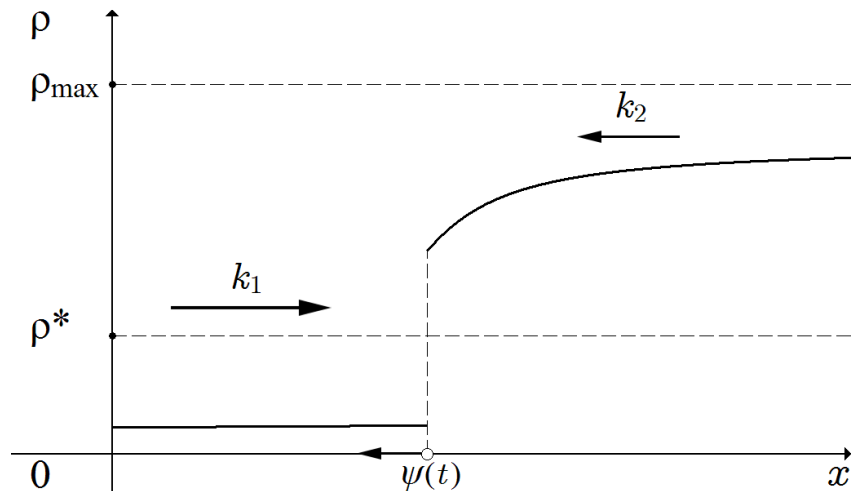
for  $t = 0.4$

# Combined solution: shock wave



for  $t = 0.8$

# Combined solution: shock wave



for  $t = 1.2$

# Hugoniot condition

Speed of the shock wave is

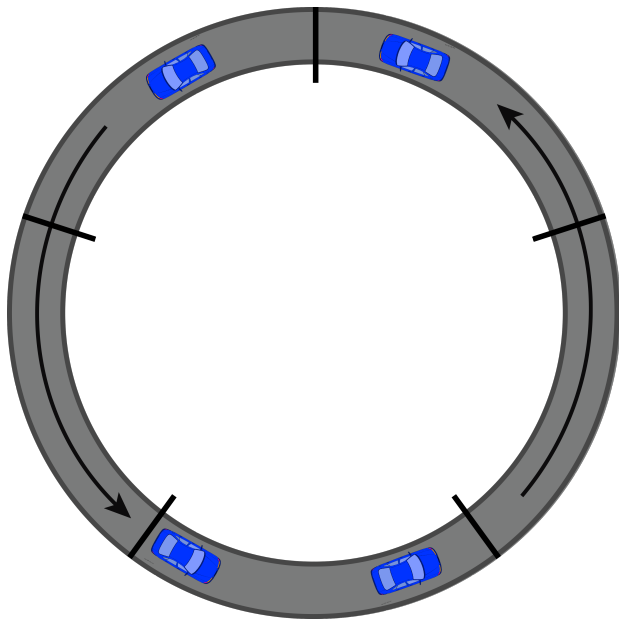
$$\psi'(t) = \frac{Q(\rho_{\text{right}}) - Q(\rho_{\text{left}})}{\rho_{\text{right}} - \rho_{\text{left}}},$$

where  $\psi(t)$  is a boundary of the shock wave.

Integral identity:

$$\frac{d}{dt} \int_{\alpha}^{\beta} \rho(x, t) dx = Q(\rho(\alpha, t)) - Q(\rho(\beta, t)).$$

# Ring road idea



# Specifics of the ring road

$L$  is length of the ring road.

All functions are  $L$ -periodic for  $x$ .

The amount of cars on the road is main value

$$M \equiv \int_0^L \mu(x) dx.$$

Two cases:

- 1  $M < \rho^* L$  (almost free movement);
- 2  $M > \rho^* L$  (crowded traffic).



# Stability of solutions on $t \rightarrow \infty$

$$M \equiv \int_0^L \mu(x) dx.$$

## Theorem

*There is an alternative.*

- ① *If  $M < L\rho^*$ , then  $\exists t^* > 0$  such that*

$$\rho(x, t) = f(x - k_1 t), \quad \forall t \geq t^*,$$

*where  $0 \leq f(s) \leq \rho^*$  for  $\forall s \in \mathbb{R}$ .*

- ② *If  $M > L\rho^*$ , then  $\exists t^* > 0$  such that*

$$\rho(x, t) = g(x + k_2 t), \quad \forall t \geq t^*,$$

*where  $\rho^* \leq g(s) \leq \rho_{\max}$  for  $\forall s \in \mathbb{R}$ .*

# Combinatorial result

## Lemma

*In every set of real numbers*

$$a_1, a_2, \dots, a_n,$$

*with*

$$a_1 + a_2 + \dots + a_n > 0,$$

*there exists a dominant element  $a_k$ , such as*

$$a_k > 0,$$

$$a_k + a_{k+1} > 0,$$

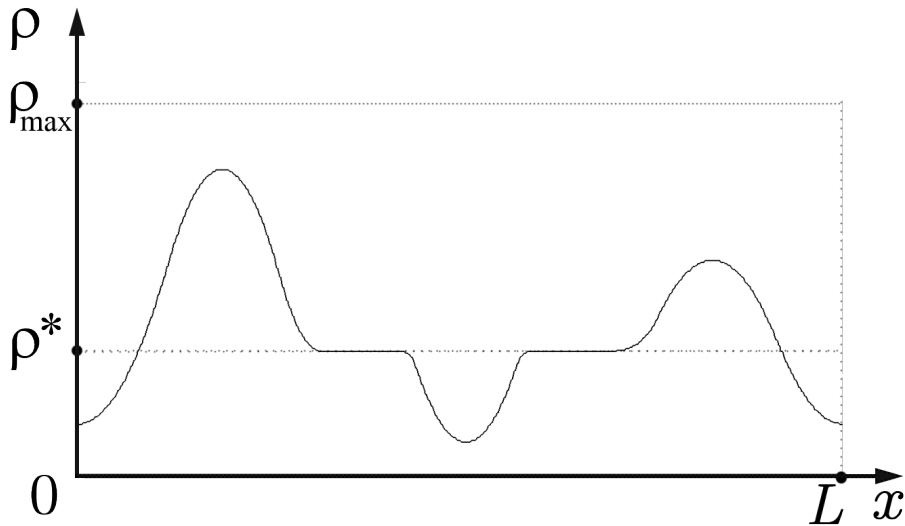
$$a_k + a_{k+1} + a_{k+2} > 0,$$

.....

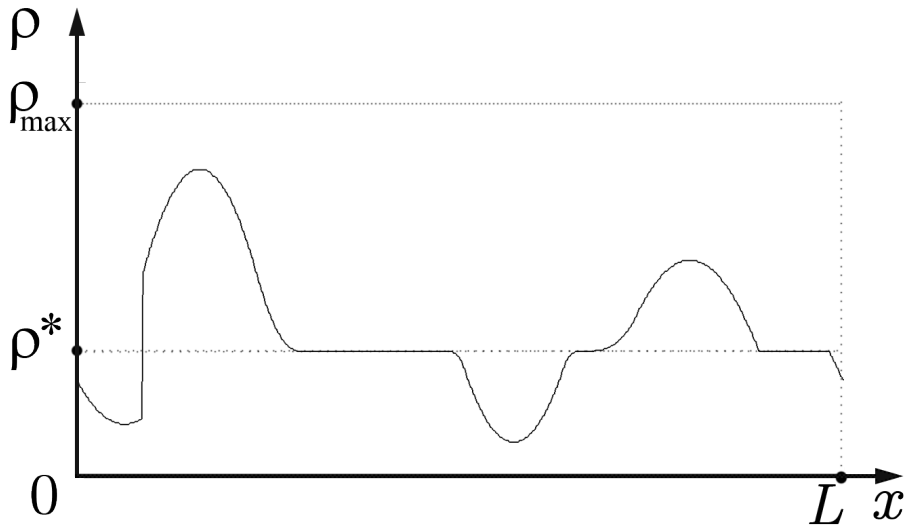
$$a_k + a_{k+1} + a_{k+2} + \dots + a_{k+n-1} > 0.$$

*Index changes cyclically.*

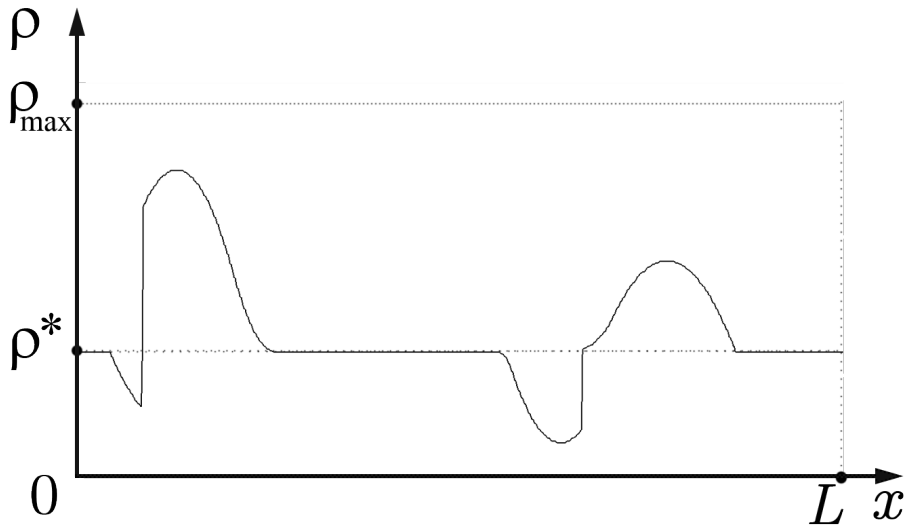
# Example



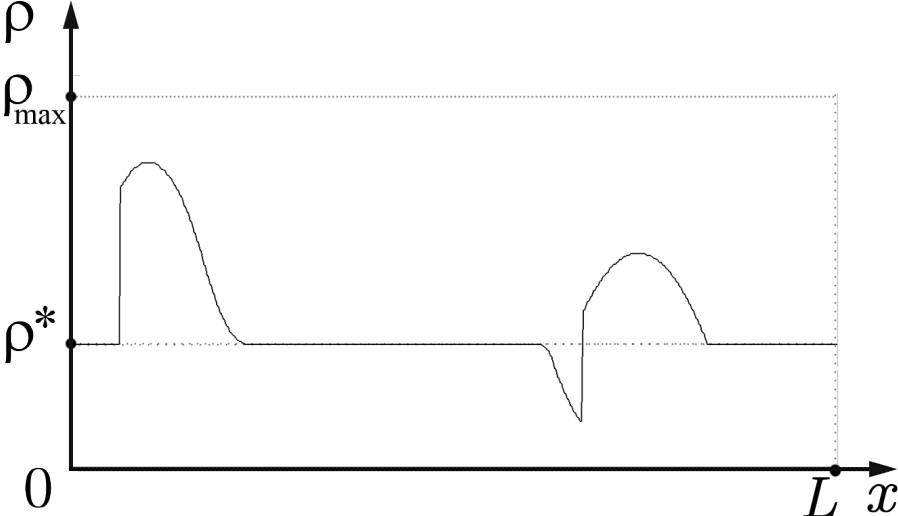
# Example



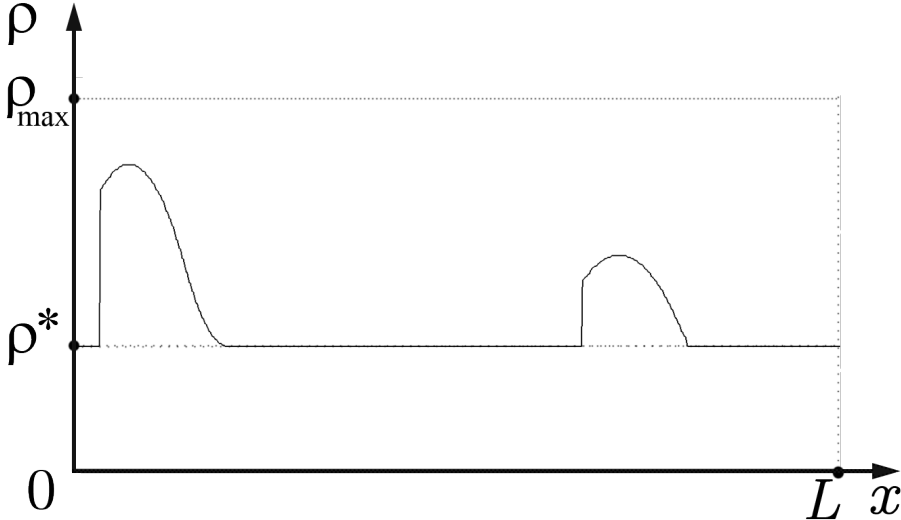
# Example



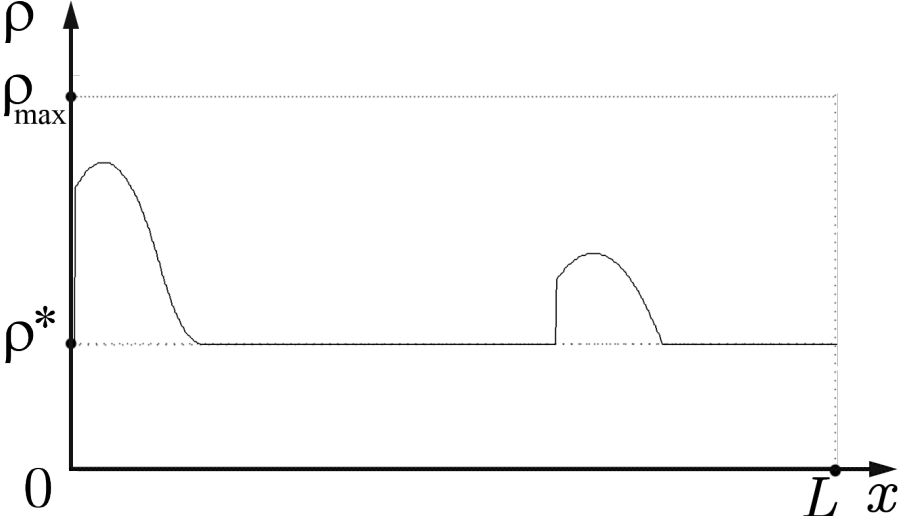
# Example



# Example

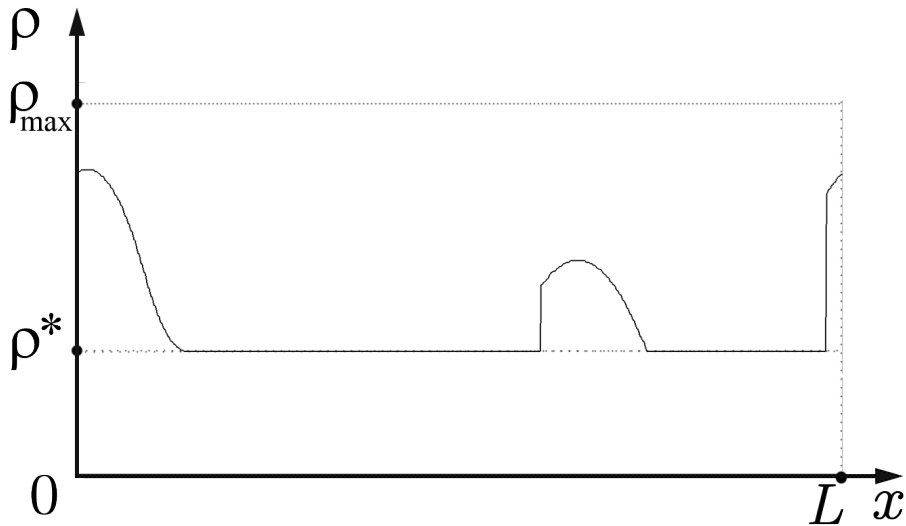


# Example

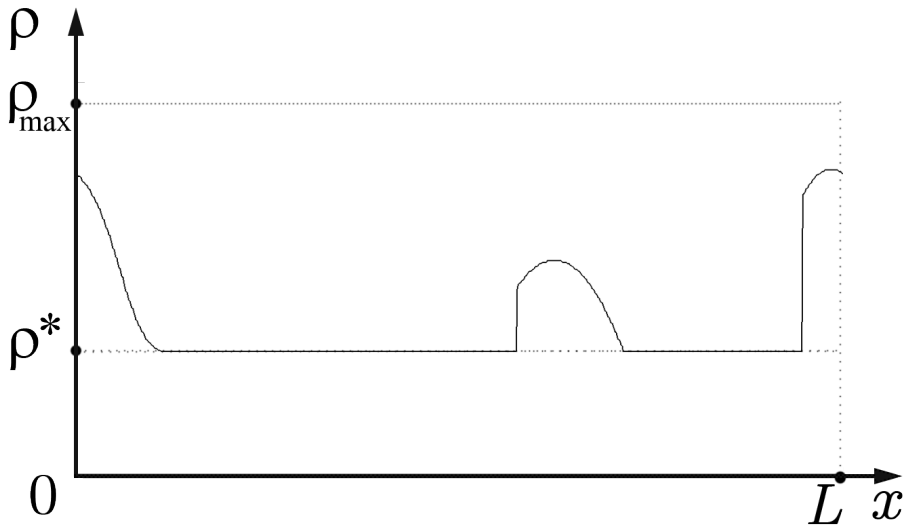




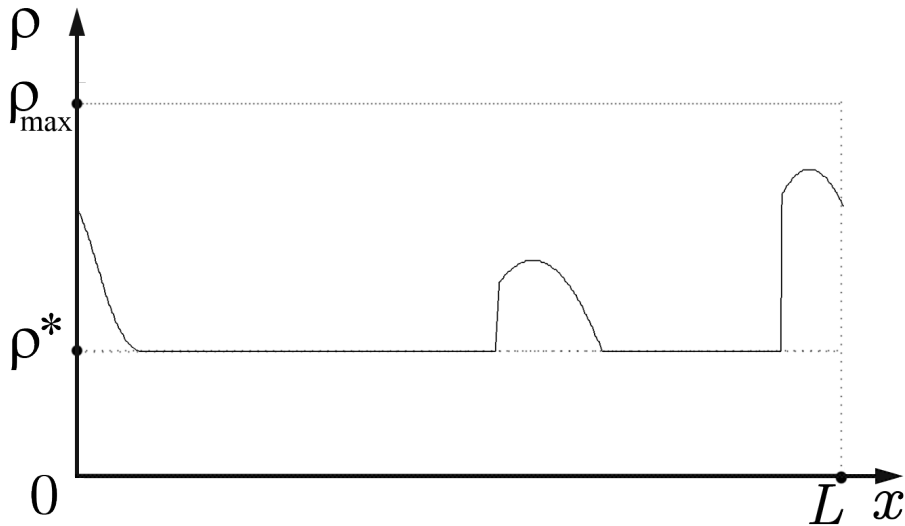
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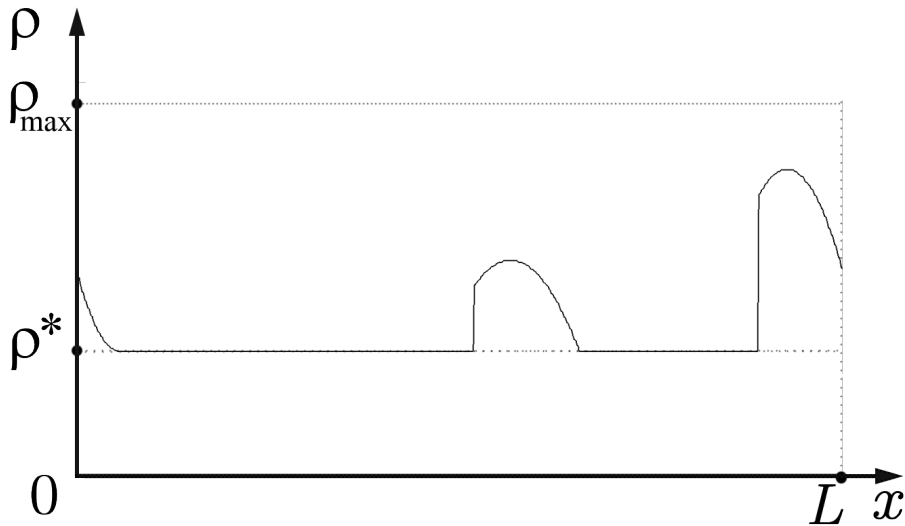
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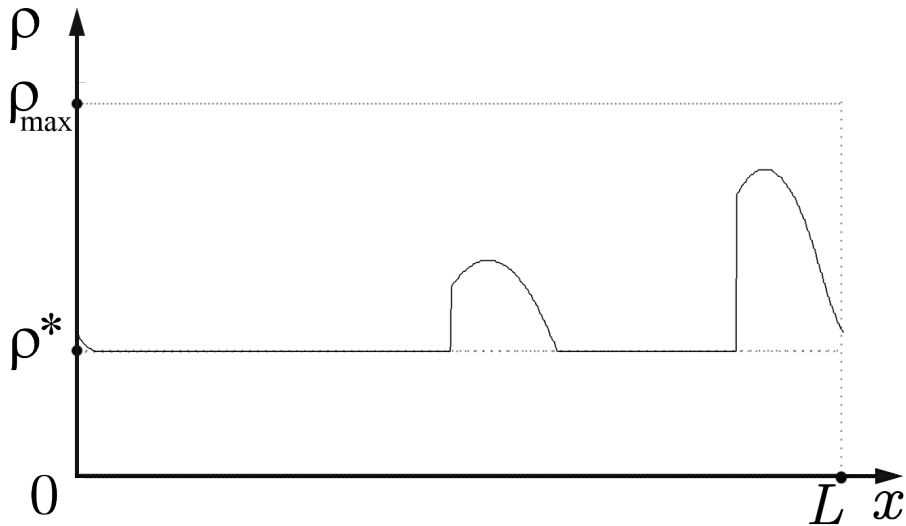
# Example



# Example



# Example





Thank you for your attention!