

Communication Networks, Algorithms & Probability Theory

Philippe Robert

École Polytechnique & INRIA, France

2011

Modeling

Observations of a system: M_0, M_1, \dots, M_n

- ▶ M_n random variable;
- ▶ M_n may depend, a priori, of M_0, \dots, M_{n-1} (and even of M_{n+1}, \dots)
- ▶ **Statistical data:**

Probability of a given sample path

$$\mathbb{P}(M_0 = x_0, M_1 = x_1, \dots, M_n = x_n), n \geq 1,$$

(x_i) sequence of the state space.

Modeling (II)

Problem

Mathematical Representation of (M_n)

- ▶ **Minimal**
not all probabilities of all sample paths.
- ▶ **Efficient**
mathematical analysis of asymptotic behavior of (M_n) .

Possible (Solution)

⇒ Markovian modeling

Framework

State space: \mathcal{S} finite or countable.

- ▶ $\mathcal{S} = \{1, \dots, N\}$;
- ▶ $\mathcal{S} = \mathbb{N}, \mathbb{Z}^d$;
- ▶ $\mathcal{S} = \{1, \dots, C\}^{(\mathbb{N})}$: finite sequences in $\{1, \dots, C\}$.

Transition Matrices (Booklet page 98)

A transition matrix

$$P = (p(x, y), x, y \in \mathcal{S})$$

is a matrix with non-negative coefficients such that

$$\sum_{y \in \mathcal{S}} p(x, y) = 1, \quad \forall x \in \mathcal{S}.$$

Linear Algebra: $P \cdot \mathbf{1} = \mathbf{1}$.

$\mathbf{1}$: right eigenvector for eigenvalue 1.

Markov Property

A sequence (M_n) of random variables has the Markov property if

$$\begin{aligned} \mathbb{P}(M_n = x_n | M_{n-1} = x_{n-1}, M_{n-2} = x_{n-2}, \dots, M_0 = x_0) \\ = \mathbb{P}(M_n = x_n | M_{n-1} = x_{n-1}). \end{aligned}$$

for $n \geq 1$.

Translation:

Given all past states visited, the last location is sufficient to determine the future evolution.

Markov property (II)

The Markov chain (M_n) is homogeneous if,

$$\begin{aligned} \mathbb{P}(M_n = y | M_{n-1} = x) \\ = \mathbb{P}(M_1 = y | M_0 = x) = p(x, y). \end{aligned}$$

for $n \geq 1$,

$(p(x, y), x, y \in \mathcal{S})$ is the transition matrix of the Markov chain.

Homogeneity:

Dynamics of (M_n) is invariant in time.

Example 1: independent variables

Successive coin tossing

$$M_0, M_1, \dots, M_n, \dots \in \{0, 1\}$$

- ▶ Bias $q \in [0, 1]$, $\mathbb{P}(M_k = 0) = q, \forall k \geq 0$.
- ▶ Independence \Rightarrow
 $\mathbb{P}(M_n=0|M_{n-1}, \dots, M_0)=q$
- ▶ Transition matrix

$$\begin{aligned}
 p(0, 0) &= P(M_1 = 0 | M_0 = 0) = q \\
 &= P(M_1 = 0 | M_0 = 1) = p(1, 0), \\
 p(0, 1) &= p(1, 1) = 1 - q.
 \end{aligned}$$

A trivial Markovian dependence

Example 2: Flip-flop chain

Observations in $\mathcal{S} = \{0, 1\}$.

0 \rightarrow 1 with proba a_0

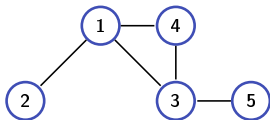
1 \rightarrow 0 with proba a_1

Transition Matrix

$$P = \begin{pmatrix} p(0, 0) & p(0, 1) \\ p(1, 0) & p(1, 1) \end{pmatrix} = \begin{pmatrix} 1 - a_0 & a_0 \\ a_1 & 1 - a_1 \end{pmatrix}$$

Example 3:

Random walk on a graph



$\mathcal{G} = \{1, 2, \dots, N\}$. If $x, y \in \mathcal{G}$ and $x \sim y$,

$$p(x, y) = P(M_1 = y | M_0 = x) = \frac{1}{d_x}$$

d_x degree of x .

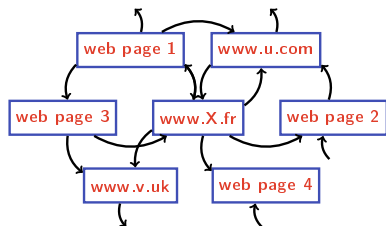
Random walk in \mathbb{Z}^d

Transition matrix:

$$p(x, x + e_i) = p(x, x - e_i) = \frac{1}{2d}$$

$e_i = (0, 0, \dots, 0, 1, \dots, 0)$, i th unit vector
 $1 \leq i \leq d$.

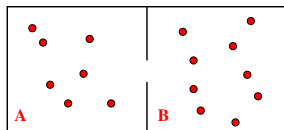
Asymmetrical random walk on the web



$p(x, y) = 1/d_x^{\rightarrow}$, d_x^{\rightarrow} : out-degree of x .
Model used by Google.

Example 4:

Ehrenfest Urn with N particles



Dynamics:

A particle taken at random change location

Example 4:

Ehrenfest Urn with N particles

M_n : nb of part. in A at $t=n$, $0 \leq M_n \leq N$.

(M_n) Markov transition matrix:

$p(x, x-1) = x/N$ and

$p(x, x+1) = 1 - x/N$

Example 5: Coupon collector problem

(X_n) ind. uniform var. on $\{1, \dots, N\}$

$$M_n = \text{card}\{X_1, \dots, X_n\}$$

(M_n) Markov with transition matrix,

$$p(x, x+1) = 1 - \frac{x}{N} \quad \text{and} \quad p(x, x) = \frac{x}{N}$$

Remark: $p(N, N) = 1$,
 N is an absorbing state.

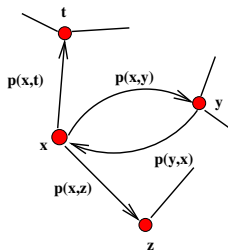
Example 6: Galton-Watson Process

- ▶ An individual gives birth to G children;
 G random variable.
- ▶ Z_n : nb. individuals of the n th generation, $Z_0 = 1$.
- ▶ (Z_n) Markov chain.

Transitions: $|u| < 1$,

$$\mathbb{E}(u^{Z_{n+1}} | Z_n = x) = (\mathbb{E}(u^G))^x$$

Representation in terms of graph of a Markov chain



Law of a Markov chain

(Booklet page 99)

If (M_n) is a Markov chain with transition matrix $P = (p(x, y))$

ν initial distribution: $\mathbb{P}(M_0 = x_0) = \nu(x_0)$.

Proba of a sample path

$$\begin{aligned} \mathbb{P}(M_0 = x_0, M_1 = x_1, \dots, M_n = x_n) \\ = \nu(x_0)p(x_0, x_1)p(x_1, x_2) \cdots p(x_{n-1}, x_n). \end{aligned}$$

for $x_1, \dots, x_n \in \mathcal{S}$.

Law of a Markov chain (II)

$$\begin{aligned} \mathbb{P}(M_n = y) \\ = \sum_{x_0, \dots, x_{n-1} \in \mathcal{S}} \nu(x_0)p(x_0, x_1)p(x_1, x_2) \cdots p(x_{n-1}, y). \end{aligned}$$

Matrix representation:

$$\mathbb{P}(M_n = y) = (\nu \cdot P^n)(y)$$

The powers of matrix P determine the distribution of (M_n) .

Law of a Markov chain (III)

Particular case:

$$\mathbb{P}(M_n = y | M_0 = x) = (P^n)(x, y)$$

probability of going from x to y in n steps.

$$p^n(x, y) \stackrel{\text{def.}}{=} \mathbb{P}(M_n = y | M_0 = x)$$

Markovian notation

- ▶ (M_n) Markov chain on \mathcal{S} ;
- ▶ ν Proba on \mathcal{S} .

\mathbb{P}_ν : law of (M_n) when

$$\mathbb{P}(M_0 \in A) = \nu(A), \text{ for } A \subset \mathcal{S}$$

$$\begin{aligned} \mathbb{P}_\nu(M_n \in A) &= \sum_{x_0 \in \mathcal{S}, y \in A} \nu(x_0) \mathbb{P}(M_n = y | M_0 = x_0) \\ &= \sum_{x_0 \in \mathcal{S}, y \in A} \nu(x_0) P^n(x_0, y) \end{aligned}$$

Markovian Notation (II)

If $x \in \mathcal{S}$,

$$\mathbb{P}_x(M_n \in A) = \mathbb{P}(M_n \in A | M_0 = x).$$

In fact

$$\mathbb{P}_x = \mathbb{P}_{\delta_x}$$

Properties of Markov chains

Definition: the past before time t

\mathcal{F}_t : set of events
before time t for the Markov chain (M_n) :

$$\mathcal{F}_t = \bigvee_{A_0, \dots, A_t \subset \mathcal{S}} \{M_0 \in A_0, M_1 \in A_1, \dots, M_t \in A_t\}$$

- ▶ (\mathcal{F}_t) ↗;
- ▶ $\bigcup_{t \geq 0} \mathcal{F}_t$: All events.

(\mathcal{F}_t) is the natural **filtration**
of the Markov chain.

The Markov property rewritten

$$\mathbb{P}(M_{n+1} \in A \mid \mathcal{F}_n) = \mathbb{P}(M_{n+1} \in A \mid M_n)$$

Irreducibility property

(Booklet page 105)

The Markov chain (M_n) is **irreducible** if,

$$\forall x, y \in \mathcal{S}, \exists n \geq 0 : \mathbb{P}(M_n = y \mid M_0 = x) > 0.$$

On the graph of the Markov chain:
there exists a path from x to y .

If **non-irreducible**:
Decomposition into irreducible components.

Equilibrium of Markov chains

Invariant Distribution

(Booklet page 114)

A Probability $(\pi(x) : x \in \mathcal{S})$ on \mathcal{S} is invariant for the transition matrix $(p(x, y))$ if

$$\pi(x) = \sum_y \pi(y)p(y, x), \forall x \in \mathcal{S}.$$

Matrix Notation: π invariant if

$$\pi = \pi \cdot P$$

π eigenvector for the eigenvalue 1.

Stationarity Property

If π is an invariant probability and (M_n) such that

$$\mathbb{P}(M_0 = x) = \pi(x) \quad \forall x \in \mathcal{S}$$

then

$$\mathbb{P}(M_n = x) = \pi(x) \quad \forall n \geq 1, \forall x \in \mathcal{S}$$

The distribution of the Markov chain does not change with time.

The Markov chain is at equilibrium.

Example: Flip-flop chain

Transition Matrix

$$\begin{pmatrix} 1 - a_0 & a_0 \\ a_1 & 1 - a_1 \end{pmatrix} \quad \pi(x) = \sum_y \pi(y)p(y, x)$$

Equation for invariant distribution:

$$\pi(0) = (1 - a_0)\pi(0) + a_1\pi(1)$$

$$\pi(1) = (1 - a_1)\pi(1) + a_0\pi(0)$$

and $\pi(1) + \pi(0) = 1$.

$$\pi(0) = \frac{a_1}{a_0 + a_1} \quad \pi(1) = \frac{a_0}{a_0 + a_1}$$

Example: Random walk on a graph

$$\mathcal{G} = \{1, 2, \dots, N\}$$

$$p(x, y) = \frac{1}{d_x}$$

if $x \sim y$, d_x degree of x .

Invariant distribution:

$$\pi(x) = Cd_x, \quad C = 1 / \sum_{y=1}^N d_y.$$

Example: Random walk on \mathbb{Z}

Transition Matrix

$$p(n, n+1) = p(n, n-1) = 1/2.$$

Solution of equations for invariant distribution

$$\pi(n) = C, \quad \forall n \in \mathbb{Z}.$$

Non-summable: no invariant probability.
No Equilibrium.

Uniqueness

Proposition

An **irreducible** Markov chain has **at most** one invariant probability.

Proposition

An **irreducible** Markov chain on a **finite** state space has a **unique** invariant probability.

Convergence in distribution

Theorem (Booklet page 118)

If (M_n) is an **irreducible** and **aperiodic** Markov chain with an invariant probability $(\pi(z), z \in \mathcal{S})$, then for $x \in \mathcal{S}$,

$$\lim_{n \rightarrow +\infty} \mathbb{P}(M_n = x) = \pi(x).$$

Expression of π :
powers of transition matrix $(p(x, y))$.

\Rightarrow in general: Difficult and inefficient.

Ergodic Theorem

Proposition (Booklet page 120)

If (M_n) is an **irreducible** Markov chain with invariant probability $(\pi(z), z \in \mathcal{S})$, then \mathbb{P} -almost surely

$$\lim_{n \rightarrow +\infty} \frac{1}{n} \sum_{i=1}^n f(M_i) = \mathbb{E}_\pi(f) \stackrel{\text{def.}}{=} \sum_{x \in \mathcal{S}} \pi(x) f(x)$$

for any function f such that $\mathbb{E}_\pi(|f|) < +\infty$.

Application

If $A \subset \mathcal{S}$, then

$$\lim_{n \rightarrow +\infty} \frac{1}{n} \sum_{i=1}^n 1_{\{M_i \in A\}} = \pi(A) = \sum_{x \in A} \pi(x)$$

$$\lim_{n \rightarrow +\infty} \frac{1}{n} \sum_{i=1}^n 1_{\{M_i = x\}} = \pi(x)$$

Basic Principle of simulation

A model of the web by Google

Importance of a web page

Search of "XYZT" on the Internet:

- ▶ Set E of pages with "XYZT";
Easy: Robots.
- ▶ Find a fn I such that $E = \{P_1, P_2, \dots\}$

$$I(P_1) > I(P_2) > \dots$$

$I(P)$: Importance of page P .

A good model for $I : P \mapsto I(P)$?

A model of the web by Google

Brin and Page (1997)

The model of the random surfer S

- ▶ S navigates at random on the web:
If $X(t) = P$, at $t + 1$, S chooses at random an outgoing-link of this page and goes to the corresponding web page, etc...

A model of the web by Google

Duration of navigation T , I defined by

$$I(P) \stackrel{\text{def.}}{=} \frac{1}{T} \sum_{n=1}^T \mathbb{1}_{\{X(n)=P\}}$$

If T large, ergodic theorem: $I(P) \sim \pi(P)$
 π : invariant proba of the random walk on the web.

$$\pi(x) = \sum_{y \sim x} \pi(y) / d_y^{\rightarrow}$$

Explicit Expression Unknown.

Strong Markov Property

Definition: Stopping Time

(Booklet page 93)

T random variable in $\mathbb{N} \cup \{+\infty\}$ is a stopping time if,

$$\{T = n\} \in \mathcal{F}_n, \quad n \geq 1,$$

Translation:

An observer who looks at successive states of (M_n) , knows when to stop at time T .

Stopping times: Examples

- ▶ $p \geq 0, T \equiv p$;
- ▶ Hitting time of a subset:
 $F \subset \mathcal{S}$,

$$T_F = \inf\{n : M_n = F\}$$

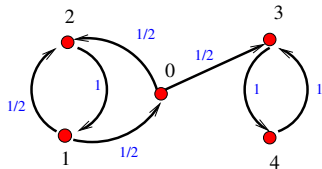
if $x \in \mathcal{S}$,

$$T_x = \inf\{n : M_n = x\}$$

- ▶ If \mathcal{S} finite: Cover time

$$\tau = \inf\{n : \{M_0, M_1, \dots, M_n\} = \mathcal{S}\}$$

Counter-example



$$M_0 = 0, \quad L = \sup\{n : M_n = 0\}$$

is not a stopping time.

The past before a stopping time T

$$\mathcal{F}_T = \bigvee_{t=0}^{+\infty} \bigvee_{A_0, \dots, A_t \subset \mathcal{S}}$$

$$\mathcal{P}(\{M_0 \in A_0, M_1 \in A_1, \dots, M_t \in A_t, T \geq t\})$$

\mathcal{F}_T : all events before time T

Strong Markov

A Markov chain (M_n) (Booklet page 94)

satisfies the strong Markov property:

If for any stopping time T :

$$\begin{aligned} \mathbb{P}(M_{T+n} = y \mid T < +\infty, M_T = x_T, \dots, M_0 = x_0) \\ = \mathbb{P}(M_{T+n} = y \mid T < +\infty, M_T = x_T). \end{aligned}$$

Strong Markov \equiv Markov at non deterministic instants: stopping times.

Strong Markov (II)

Translation:

$$\begin{aligned} P(M_{T+n} \in \cdot \mid \mathcal{F}_T, T < +\infty) \\ = \mathbb{P}(M_{T+n} \in \cdot \mid M_T, T < +\infty) \end{aligned}$$

Example

If $x \in \mathcal{S}$, $T_x = \inf\{n : M_n = x\}$

Assuming that $T_x < +\infty$ \mathbb{P} -a.s.

Strong Markov:

$$\begin{aligned} \mathbb{P}(M_{T_x+n} \in A \mid M_{T_x}, \dots, M_0) \\ = \mathbb{P}(M_{T_x+n} \in A \mid M_{T_x} = x) \\ = \mathbb{P}(M_n \in A \mid M_0 = x). \end{aligned}$$

The sequence (M_{n+T_x}) is independent of the variables M_{T_x-1}, \dots, M_0 .

Decomposition into independent cycles.